# 'MATH+ECON+CODE' MASTERCLASS ON MATCHING MODELS, OPTIMAL TRANSPORT AND APPLICATIONS

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Block 12. Dynamic discrete choice

## LEARNING OBJECTIVES: BLOCK 12

- ► Finite-horizon Rust's model
- ▶ identification and estimation
- ► normalization issues

#### REFERENCES FOR BLOCK 12

- Rust (1987), "Optimal replacement of GMC bus engines: an empirical model of Harold Zurcher. Econometrica.
- ► Chiong, Galichon and Shum (2016). Duality in discrete choice models. *Quantitative economics*.

## Section 1

**THEORY** 

#### RUST'S MODEL

- Recall the dynamic programming model seen in block 3. The setting is the same: there are  $n_x$  units (buses) in state x at the initial period (t=1); at each period, one must choose for each unit some alternative  $y \in \mathcal{Y}$ ; the probability of transiting to state x' at period t+t conditional on being in state x and choosing alternative y at time t is  $P_{x'|xy}^t$ .
- ▶ The difference with the setting seen in block 3 is that, following Rust, the utility associated with choosing y in state x at t is no longer deterministic, but includes an additional random term  $\varepsilon_y \sim \mathbf{P}_{xt}$ , so it is

$$u_{xy}^t + \varepsilon_y$$
.

The stochastic structure is such that  $x_t$ ,  $(x_t, \varepsilon)$ ,  $(x_t, y_t)$  is a Markov chain – which rules out persistent shocks, i.e. there cannot be correlaton between  $\varepsilon_t$  and  $\varepsilon_{t+1}$  conditional on  $(x_{t+1}, y_{t+1})$ .

## **BELLMAN EQUATION**

► As a result of the random utility term, Bellman's equation becomes

$$U_{x}^{t} = \mathbb{E}_{\mathbf{P}_{xt}} \left[ \max_{y \in \mathcal{Y}} \left\{ u_{xy}^{t} + \sum_{x'} U_{x'}^{t+1} P_{x'|xy} + \varepsilon_{y} \right\} \right]$$
$$= G_{xt} \left( u_{x.}^{t} + \sum_{x'} U_{x'}^{t+1} P_{x'|x.} \right).$$

▶ Set  $W_{xt}(U) = G_{x(t-1)}(u_{x.}^{t-1} + \sum_{x'} U_{x'}^{t} P_{x'|x.})$  for 1 < t < T, the equation becomes

$$U_{x}^{t-1}=W_{xt}\left( U^{t}\right) .$$

► Note that

$$\frac{\partial W_{xt}(U)}{\partial U_{x'}} = \sum_{y} P_{x'|xy} \sigma_{x(t-1),y}$$

is the conditional probability of a transition to x' given being at x at time t-1, denoted  $\mu_{x'\mid x}^{t-t}$ .

## BELLMAN EQUATION, LOGIT CASE

► In the logit case, one has

$$U_x^t = \log \sum_{y \in \mathcal{Y}} \exp \left( u_{xy}^t + \sum_{x'} U_{x'}^{t+1} P_{x'|xy} \right)$$

▶ Setting  $V_x^t = \exp(U_x^t)$  and  $v_{xy}^t = \exp(v_{xy}^t)$ , this becomes an algebraic expression

$$V_{x}^{t} = \sum_{y \in \mathcal{V}} v_{xy}^{t} \prod_{x' \in \mathcal{X}} \left(V_{x}^{t}\right)^{P_{x'}|_{xy}}.$$

#### **DUAL PROBLEM**

► The dual problem can be expressed as:

$$\min_{U_x^t, \ x \in \mathcal{X}} \sum_{x \in \mathcal{X}} n_x U_x^1 
s.t. \ U_x^{t-1} = W_{xt}(U^t) \ 1 < t \le T 
U_x^T = G_{xT}(u_{x.}^T)$$
(1)

▶ In the logit case, with  $V_x^t = \exp(U_x^t)$  and  $v_{xy}^t = \exp(v_{xy}^t)$ , one has

$$\begin{aligned} \min_{U_x^t, \ t \in \mathcal{T}, \ x \in \mathcal{X}} \sum_{x \in \mathcal{X}} n_x \log V_x^1 \\ s.t. \ V_x^t &= \sum_{y \in \mathcal{Y}} v_{xy}^t \prod_{x' \in \mathcal{X}} \left(V_x^t\right)^{P_{x'}|_{xy}}, \ t < T \\ V_x^T &= \sum_{y \in \mathcal{Y}} v_{xy}^t. \end{aligned}$$

#### **DUAL PROBLEM: FIRST ORDER CONDITIONS**

▶ Set  $n_X^t$  the Lagrange multipliers associated with the constraints. First order conditions in the dual problem yield

$$\begin{aligned} n_{x} &= n_{x}^{1} \\ n_{x}^{t} &= \sum_{x'} \frac{\partial W_{x(t-1)}}{\partial U_{x'}^{t-1}} n_{x'}^{t-1}, 1 < t \leq T \end{aligned}$$

► The second line are Kolmogorov-forward equations (forward propagation of mass)

$$\sum_{x'} \mu_{x'|x}^{t-t} n_{x'}^{t-1} = n_x^t.$$

#### PRIMAL PROBLEM

- ▶ Let  $W_t\left(U^t; n^{t-1}\right) = \sum_x n_x^{t-1} W_{xt}(U_x^t)$ , and let  $W_t^*\left(n^t; n^{t-1}\right)$  be its Legendre transform with respect its first variable.
- ► Theorem: the value of the primal problem is

$$\max_{n^t} \left\{ \sum_{x \in \mathcal{X}} n_x^T G_{xt}(u_{x.}^T) - \sum_{\substack{x \in \mathcal{X} \\ 1 < t \le T}} W_t^* \left( n^t; n^{t-1} \right) \right\}$$
s.t.  $n_x^1 = n_x$ 

#### Proof of the duality

► Start from the dual

$$\min_{U_x^t} \sum_{x \in \mathcal{X}} n_x U_x^1 
s.t. \ U_x^{t-1} = W_{xt}(U^t) \ 1 < t \le T 
U_x^T = G_{xT}(u_x^T)$$
(2)

► Write the saddlepoint formulation

$$\min_{U^t} \max_{n^t} \left\{ \begin{array}{l} \sum_{x \in \mathcal{X}} n_x U_x^1 - \sum_{x,1 \leq t \leq T} n_x^t U_x^t \\ + \sum_{x,1 < t \leq T} n_x^{t-1} W_{xt}(U^t) \\ + \sum_{x} n_x^T G_{xT}(u_x^T) \end{array} \right\}$$

## PROOF OF THE DUALITY (CONTINUED)

Saddlepoint rewrites

$$\max_{n^{t}} \min_{U^{t}} \left\{ \begin{array}{l} \sum_{x} n_{x}^{T} G_{xt}(u_{x.}^{T}) + \sum_{x} (n_{x} - n_{x}^{1}) U_{x}^{1} \\ + \sum_{1 < t \le T} n_{x}^{t-1} W_{xt}(U_{x}^{t}) - n_{x}^{t} U_{x}^{t} \end{array} \right\}$$

▶ Recall that  $W_t\left(U^t; n^{t-1}\right) = \sum_x n_x^{t-1} W_{xt}(U_x^t)$ , and  $W_t^*\left(n^t; n^{t-1}\right)$  be its Legendre transform with respect its first variable, one has

$$\max_{\substack{n_{x}^{t}, t \geq 1 \\ s.t. \ n_{x}^{t} = n_{x}}} \left\{ \sum_{t < T} n_{x}^{T} G_{xt}(u_{x.}^{T}) - \sum_{1 < t \leq T} W_{t}^{*} \left( n^{t}; n^{t-1} \right) \right\}$$

QED.

#### PRIMAL PROBLEM: FIRST ORDER CONDITIONS

Recall

$$\max_{\substack{n_{x}^{t}, t \geq 1 \\ s.t. \ n_{x}^{t} = n_{x}}} \left\{ \sum_{t < T} n_{x}^{T} G_{xt}(u_{x.}^{T}) - \sum_{1 < t \leq T} W_{t}^{*} \left( n^{t}; n^{t-1} \right) \right\}$$

 $\blacktriangleright$  For  $1 \le t < T$ , one has

$$\frac{\partial W_t^*}{\partial n_x^t} \left( n^t; n^{t-1} \right) + \frac{\partial W_{t+1}^*}{\partial n_x^t} \left( n^{t+1}; n^t \right) = 0,$$

and note that

$$\frac{\partial W_t^*}{\partial n_v^*} = U_x^t \text{ and } \frac{\partial W_{t+1}^*}{\partial n_v^*} \left( n^{t+1}; n^t \right) = -W_{xt+1}(U^{t+1})$$

hence the first order condition recovers the Bellman equation.

#### PRIMAL PROBLEM: LOGIT CASE

► One has

$$W_t\left(U; n^{t-1}\right) = \sum_{x} n_x^{t-1} \log \sum_{y \in \mathcal{Y}} \exp\left(u_{xy}^{t-1} + \sum_{x'} U_{x'}^t P_{x'|xy}\right)$$

and thus

$$\begin{aligned} & W_t\left(n^t; n^{t-1}\right) \\ &= \max_{U} \left\{ \sum_{x} n_x^t U_x - \sum_{x} n_x^{t-1} \log \sum_{y \in \mathcal{Y}} \exp\left(u_{xy}^{t-1} + \sum_{x'} U_{x'}^t P_{x'|xy}\right) \right\} \end{aligned}$$

► Sadly, no closed-form formula.

#### Infinite-horizon version

▶ Rust studies the infinite-horizon version of the problem, in which case  $u^t_{xy}$  does not depend on t, and, if  $\beta>0$  is a discount factor, then the intertemporal utility is given by the set of equations

$$U_{x} = W_{x}(\beta U),$$

where 
$$W_x(\beta U) = \mathbb{E}\left[\max_y\left\{u_{xy} + \sum_{x'}\beta U_{x'}P_{x'|xy} + \varepsilon_y
ight\}\right]$$
.

▶ It's possible to show that  $(U_x) \to (W_x(\beta U))$  is a contraction mapping, so the above equation has a unique solution.

## IDENTIFICATION IN INFINITE-HORIZON RUST'S MODEL

Assume agents choose actions  $y \in \mathcal{Y}$  from a finite space  $\mathcal{Y} = \{0, 1, \dots, m\}$ . At each period, agents get utility flow from choosing y given by

$$u_{xy} + \varepsilon_y$$

where  $\varepsilon_y$  denotes the utility shock associated to action y, which differs across agents and is assumed to be i.i.d. Gumbel distributed.

- ► Assume the model is stationary, so dependence on time is omitted.
- In Rust's setting, y is the decision to perform maintenance on the bus (y=1 if maintenance, y=0 if not); x is the mileage of the bus since last maintenance (reset to zero if maintenance and random otherwise);  $u_{x1}$  is the average profit if no maintenance and mileage x, and  $u_{0x}$  if maintenance.

## DYNAMIC CHOICE AND CONTINUATION VALUE

- ▶ In a one-period context, agents would simply maximize  $u_{xy} + \varepsilon_y$  over y as in static discrete choice framework just seen.
- ▶ However, the action chosen at time t,  $y_t$ , has an impact on the state  $x_t$  at the next period. Agents take this into account and optimize instead

$$u_{xy} + \varepsilon_y + \beta \mathbb{E} \left[ \bar{U}_{x'} \left( \varepsilon' \right) | x, y \right]$$

over  $y \in \mathcal{Y}$ , where  $\beta \mathbb{E}\left[\bar{U}_{x'}\left(\varepsilon'\right)|x,y\right]$  is the expected discounted payoff from later periods conditional on being at state x and choosing action y at the current period.  $\bar{U}$  is defined recursively.

▶ We use primes (') to denote next-period values.

#### CONDITIONAL INDEPENDENCE ASSUMPTION

▶ We make the following conditional independence assumption on the evolution of  $(x, \varepsilon)$ :

$$Pr(x', \varepsilon'|y, x, \varepsilon) = Pr(\varepsilon'|x', y, x, \varepsilon) \cdot Pr(x'|y, x, \varepsilon)$$
$$= Pr(\varepsilon'|x') \cdot Pr(x'|y, x).$$

which means that the distribution of  $\varepsilon'$  only depends on x', and the distribution of x' only depends on y and x at the previous period.

▶ The discount rate is  $\beta$ . At each period, agents do

$$y \in \arg\max_{y \in \mathcal{Y}} \left\{ u_{xy} + \varepsilon_y + \beta \mathbb{E} \left[ \bar{U}_{x'} \left( \varepsilon' \right) | x, y \right] \right\}, \tag{3}$$

where the value function  $\bar{U}$  is defined in a recursive manner as

$$\bar{U}_{x}\left(\varepsilon\right) = \max_{y \in \mathcal{Y}} \left\{ u_{xy} + \varepsilon_{y} + \beta \mathbb{E}\left[\left.\bar{U}_{x'}\left(\varepsilon'\right)\right|x,y\right] \right\}.$$

#### **EX-ANTE VALUE FUNCTION**

▶ Introduce U(x), the ex-ante (or integrated) value function, defined as:

$$U_{x} = \mathbb{E}\left[\bar{U}_{x}\left(\varepsilon\right)|x\right].$$

► The choice-specific value functions therefore consists of two terms: the per-period utility flow and the discounted continuation payoff:

$$w_{xy} \equiv u_{xy} + \beta \mathbb{E} \left[ U_{x'} | x, y \right].$$

and

$$U_{x} = \log \sum_{y \in \mathcal{Y}} e^{w_{xy}} \tag{4}$$

#### **NORMALIZATION**

► The problem here is that we cannot impose the normalization  $w_{0y}=0$  as we did before. Indeed,  $w_{0y}\equiv u_{0x}+\beta\mathbb{E}\left[U_{x'}|x,0\right)$ ; but the second term of the rhs is endogenous. Instead, we can e.g. normalize

$$u_{0x} = 0$$

which is an exogenous quantity.

▶ Then, the log-odds ratio formula implies that

$$\log \frac{\pi_{y|x}}{\pi_{y|0}} = w_{xy} - w_{0y}$$

thus

$$w_{xy} = \log \frac{\pi_{y|x}}{\pi_{y|0}} + w_{0y} \tag{5}$$

where the  $\log (...)$  term is known, and the  $w_{0y}$  is to be identified.

## **EQUATION FOR THE EX-ANTE VALUE FUNCTION**

▶ Plugging in the expression of  $w_{xy}$  into (4) yields

$$U_{x} = \log \sum_{y \in \mathcal{Y}} \frac{\pi_{y|x}}{\pi_{y|0}} + w_{0y}$$

thus

$$U_{x} = w_{0y} - \log \pi_{y|0} \tag{6}$$

► One has by definition of w

$$w_{0y} = \beta \mathbb{E} \left[ U_{x'} | x, 0 \right], \tag{7}$$

thus, combining (6) and (7),

$$U_{x} = \beta \mathbb{E}\left[U_{x'}|x,0\right] - \log \pi_{y|0}$$

hence

$$\mathbb{E}\left[\beta U_{x'} - U_x | x, 0\right] = \log \pi_{v|0}.$$

(8)

#### SOLVING THE MODEL

▶ Let W be the column vector whose general term is  $\left(\log \pi_{y|0}\right)_{x \in \mathcal{X}}$ , let U be the column vector whose general term is  $(U_x)_{x \in \mathcal{X}}$ , and let  $\Pi$  be the  $|X| \times |X|$  matrix whose general term is

$$\Pi_{iy} = Pr(x_{t+1} = y | x_t = i, y = 0).$$

Equation (8), rewritten in matrix notation, is

$$W = (\beta \Pi - I) U$$

▶ It is possible to show that for  $\beta < 1$ , matrix  $I - \beta \Pi^0$  is invertible. Thus Equation (8) becomes

$$U = (\beta \Pi - I)^{-1} W. \tag{9}$$

▶ Therefore  $U_x$  is identified from data.

## SOLVING THE MODEL (CTD)

▶ It follows that all the remaining quantities are also identified by

$$w_{0y} = U_x + \log \pi_{y|0}$$
  
 $w_{xy} = w_{0y} + \log \frac{\pi_{y|x}}{\pi_{y|0}}$   
 $u_{xy} = w_{xy} - \beta \mathbb{E} [U_{x'}|x, y]$ 

Section 2

**CODING** 

## **APPLICATION**

 $\,\blacktriangleright\,$  Today's application is based on Rust's (1994) bus engine dataset.