

Alexis Balayre

High Performance Technical Computing Assignment

School of Aerospace, Transport and Manufacturing Computational Software of Techniques Engineering

> MSc Academic Year: 2023 - 2024

Supervisor: Dr Irene Moulitsas 5th February 2024

Abstract

Replace with your abstract text of not more than 300 words.

Acknowledgements

The author would like to thank ...

Table of Contents

Al	ostrac	t			i		
A	Acknowledgements Table of Contents List of Figures						
Ta							
Li							
Li	st of T	ables			vii		
1	Intro	oduction	n		1		
2	Metl	ıodolog	y		2		
	2.1	Sequen	r itial Algor	ithm	2		
		2.1.1		tity Analysis			
			2.1.1.1	Temporal Complexity			
			2.1.1.2	Spatial Complexity			
		2.1.2	Example				
	2.2	Line-B	ased Paral	llelism			
		2.2.1		city Analysis			
			2.2.1.1	Temporal Complexity			
			2.2.1.2	Spatial Complexity			
	2.3	Colum	n-Wise Pa	ırallelism			
		2.3.1		city Analysis			
			2.3.1.1	Temporal Complexity			
			2.3.1.2	Spatial Complexity			
	2.4	Non-Z	ero Eleme	nt Parallelism	9		
		2.4.1 Complexity Analysis					
			2.4.1.1	Temporal Complexity			
			2.4.1.2	Spatial Complexity			
3	Con	clusion			11		
A	Documentation						
	A.A	Project	tree		12		
	A.B	A.B Getting Started					
		_		s of Functions			

В	Source Codes				
	B.A Sequential Algorithm Source Code	14			

List of Figures

List of Tables

Chapter 1

Introduction

Chapter 2

Methodology

2.1 Sequential Algorithm

The algorithm for multiplying a sparse matrix by a dense vector can be efficiently implemented using the Compressed Sparse Row (CSR) format. The CSR format represents a sparse matrix using three arrays: values, col_indices, and row_pointers. Given a sparse matrix M in CSR format and a dense vector v, the product $M \times v$ is computed as follows:

Algorithm 1 Sequential algorithm

2.1.1 Complexity Analysis

The complexity analysis of the algorithm for multiplying a sparse matrix by a dense vector focuses on two main aspects: temporal complexity and spatial complexity.

2.1.1.1 Temporal Complexity

The temporal complexity of the algorithm depends on how the sparse matrix is stored and the number of non-zero elements in the matrix.

• Traversing Rows: The algorithm traverses each row of the matrix. If the matrix has m rows, this step has a complexity of O(m).

• Traversing Non-Zero Elements: Inside each row, the algorithm traverses the non-zero elements. If the total number of non-zero elements in the matrix is n_{nz} , the traversal of all these elements has a complexity of $O(n_{nz})$.

The total temporal complexity is therefore $O(m + n_{nz})$. However, in practice, this complexity is often considered as $O(n_{nz})$, as the number of non-zero elements is usually the dominating factor, especially in very sparse matrices.

2.1.1.2 Spatial Complexity

The spatial complexity is related to the amount of memory required by the algorithm.

- Storing the Sparse Matrix: The way the sparse matrix is stored affects the spatial complexity. Generally, storage formats like CSR or COO allow storing a sparse matrix with a complexity of $O(n_{nz})$, where n_{nz} is the number of non-zero elements.
- **Dense Vector:** The dense vector has a spatial complexity of O(n), where n is the size of the vector.
- **Result Vector:** The result vector also has a size of O(m), where m is the number of rows in the matrix.

The total spatial complexity is therefore $O(n_{nz} + m + n)$, but in practice, the focus is mainly on the $O(n_{nz})$ term as it is generally the most significant.

2.1.2 Example

Dans le format CSR, la matrice est représentée par trois vecteurs : values, rows, et cols. Pour notre exemple, ces vecteurs sont définis comme suit:

- values = $\{1, 2, 3, 4\}$
- $rows = \{0, 2, 3, 3, 4\}$
- $cols = \{0, 2, 1, 3\}$

La matrice creuse correspondante peut être visualisée comme:

$$\begin{bmatrix}
1 & 0 & 2 & 0 \\
0 & 0 & 3 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 4
\end{bmatrix}$$

Le vecteur dense est simplementq:

La multiplication de la matrice creuse par le vecteur dense est effectuée ligne par ligne. Le résultat peut être visualisé comme :

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix} \times \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 1 \times 1 + 0 \times 2 + 2 \times 3 + 0 \times 4 \\ 0 \times 1 + 0 \times 2 + 3 \times 3 + 0 \times 4 \\ 0 \times 1 + 0 \times 2 + 0 \times 3 + 0 \times 4 \\ 0 \times 1 + 0 \times 2 + 0 \times 3 + 4 \times 4 \end{bmatrix} = \begin{bmatrix} 7 \\ 9 \\ 0 \\ 16 \end{bmatrix}$$

2.2 Line-Based Parallelism

This algorithm partitions a sparse matrix into row chunks and distributes these chunks across multiple processes for parallel computation in a line-based manner.

```
Algorithm 2 Line-based parallel sparse matrix-vector multiplication
Require: M is an m \times n sparse matrix
Require: v is an n \times k vector
Require: numProcs is the number of processes
Require: rank is the rank of the current process
Ensure: Result is a part of the m \times k matrix computed by this process
  rowsPerProc \leftarrow m/numProcs
  startRow \leftarrow rank \times rowsPerProc
  endRow \leftarrow startRow + rowsPerProc
  Result \leftarrow zero matrix of size rowsPerProc \times k
  for i \leftarrow startRow to endRow - 1 do
      for each non-zero element (i, value) in row i of M do
          for l \leftarrow 0 to k-1 do
              Result[i - startRow][l] \leftarrow Result[i - startRow][l] + (value \times v[j][l])
          end for
      end for
  end for
  if rank \neq 0 then
      Send Result to process 0
  else
      FinalResult \leftarrow zero matrix of size m \times k
      Copy Result into FinalResult
      for p \leftarrow 1 to numProcs - 1 do
          Receive partial Result from process p
          Copy received Result into appropriate position in FinalResult
      end for
  end if
  if rank = 0 then return FinalResult
```

2.2.1 Complexity Analysis

2.2.1.1 Temporal Complexity

- MPI Initialisation and Rank and Size Determination: This step is generally fast, with a complexity close to O(1), as it mainly involves setup operations.
- Calculation of the Number of Rows per Process: This operation also has a complexity of O(1) as it requires only simple arithmetic based on the total size of the matrix and the number of processes.
- Calculation of Start and End Indices for Each Process: Again, this step has a complexity of O(1) as it involves simple arithmetic calculations.

- Scatter of Rows of M and Vector v: The complexity of this step depends on the MPI implementation and data distribution. In general, it can be considered as $O(\frac{n_{nz}}{p})$, where n_{nz} is the total number of non-zero elements in the matrix and p is the number of processes.
- Local Computation in Each Process: Each process performs the matrix-vector product computation for its assigned portion of the matrix. The complexity of this step is $O(\frac{n_{nz}}{p})$ in the ideal case where the non-zero elements are evenly distributed among the processes.
- Gather of Local Results r_{local} : The gather operation can vary in complexity, but generally, it is proportional to the total number of elements to be gathered and depends on the efficiency of communication between processes.

2.2.1.2 Spatial Complexity

- Storage of Sparse Matrix and Dense Vector: The storage of the matrix and vector remains $O(n_{nz} + m + n)$, where m and n are the dimensions of the matrix.
- Local Result Vectors r_{local} : Each process stores a local result vector of a size proportional to the portion of the matrix it processes, approximately $O(\frac{m}{p})$.

2.3 Column-Wise Parallelism

This algorithm distributes the non-zero elements of a sparse matrix among different processes, enabling parallel computation focused on each non-zero element.

Algorithm 3 Column-wise Parallelization using MPI for Sparse Matrix-Fat Vector Multiplication

```
Require: M is an m \times n sparse matrix
Require: v is an n \times k vector
Require: numProcs is the number of processes
Require: rank is the rank of the current process
Ensure: PartialResult is a part of the m \times k matrix computed by this process
         colsPerProc \leftarrow k/numProcs
        startCol \leftarrow rank \times colsPerProc
        endCol \leftarrow startCol + colsPerProc
        PartialResult \leftarrow zero matrix of size m \times colsPerProc
        for i \leftarrow 0 to m-1 do
                     for each non-zero element (j, value) in row i of M do
                                    for l \leftarrow startCol to endCol - 1 do
                                                 PartialResult[i][l - startCol] \leftarrow PartialResult[i][l - startCol] + (value \times learned) 
         v[j][l]
                                    end for
                     end for
        end for
        if rank \neq 0 then
                      Send PartialResult to process 0
         else
                      FinalResult \leftarrow zero matrix of size m \times k
                     Copy PartialResult into appropriate position in FinalResult
                      for p \leftarrow 1 to numProcs - 1 do
                                    Receive partial PartialResult from process p
                                   Copy received PartialResult into appropriate position in FinalResult
                      end for
        end if
        if rank = 0 then return FinalResult
```

2.3.1 Complexity Analysis

2.3.1.1 Temporal Complexity

- MPI Initialisation and Rank and Size Determination: Similar to the line-based approach, this step has a complexity of approximately O(1), involving basic setup operations.
- **Distribution of Non-Zero Elements of** *M***:** This step involves distributing the non-zero elements among the processes. The complexity depends on the distribution

mechanism but is generally proportional to the number of non-zero elements, n_{nz} , and the efficiency of the distribution algorithm used.

- Scatter of Vector v to All Processes: Scattering the vector v to all processes can be done efficiently in MPI and typically has a complexity proportional to the size of the vector, O(n).
- Computation of Products for Assigned Non-Zero Elements: Each process computes the products for its assigned non-zero elements. Assuming an even distribution, the complexity for each process would be $O(\frac{n_{nz}}{p})$, where p is the number of processes.
- MPI Atomic Operations and Reduction: The use of atomic operations and reduction to form the final result vector can introduce additional complexity, depending on the implementation and efficiency of these operations in MPI.

2.3.1.2 Spatial Complexity

- Storage of Sparse Matrix and Dense Vector: The storage requirements remain the same as in the line-based approach, $O(n_{nz} + m + n)$.
- Local Result Vectors r_{local} : Each process maintains a local result vector, but since the computation is based on non-zero elements, the storage requirement for each r_{local} might be smaller, depending on the distribution of non-zero elements.

2.4 Non-Zero Element Parallelism

This algorithm combines line-based and non-zero element-based approaches by distributing chunks of rows to each process and then performing parallel computations on the non-zero elements within those chunks.

Algorithm 4 Non-Zero Element Parallelization using MPI for Sparse Matrix-Fat Vector Multiplication

```
Require: M is an m \times n sparse matrix stored in a format that allows iterating over non-
   zero elements (e.g., COO, CSR)
Require: v is an n \times k vector
Require: numProcs is the number of processes
Require: rank is the rank of the current process
Ensure: PartialResult is a part of the m \times k matrix computed by this process
  numNonZeroElements \leftarrow total number of non-zero elements in M
  elementsPerProc \leftarrow numNonZeroElements/numProcs
  startIndex \leftarrow rank \times elementsPerProc
  endIndex \leftarrow startIndex + elementsPerProc
  PartialResult \leftarrow zero matrix of size m \times k
  NonZeroElements \leftarrow list of non-zero elements in M from startIndex to endIndex - 1
  for each (i, j, value) in NonZeroElements do
      for l \leftarrow 0 to k-1 do
          PartialResult[i][l] \leftarrow PartialResult[i][l] + (value \times v[j][l])
      end for
  end for
  if rank \neq 0 then
      Send PartialResult to process 0
  else
      FinalResult \leftarrow zero matrix of size m \times k
      Copy PartialResult into FinalResult
      for p \leftarrow 1 to numProcs - 1 do
          Receive partial PartialResult from process p
          Add received PartialResult into FinalResult
      end for
  end if
  if rank = 0 then return FinalResult
```

2.4.1 Complexity Analysis

2.4.1.1 Temporal Complexity

- MPI Initialisation and Rank and Size Determination: As with other MPI-based algorithms, this step has a complexity of approximately O(1).
- Scattering Chunks of Rows of M to Each Process: This step distributes parts of the matrix to different processes. Its complexity depends on the number of rows

and the distribution method, typically around $O(\frac{m}{p})$, where m is the number of rows and p is the number of processes.

- Scatter of Vector v to All Processes: This operation generally has a complexity of O(n), where n is the size of the vector.
- Local Computations for Non-Zero Elements: Each process computes the products for the non-zero elements in its assigned rows. Assuming an even distribution of non-zero elements, the complexity for each process is approximately $O(\frac{n_{nz}}{p})$.
- Gather of Local Results r_{local} into Final Result Vector r: This step combines the partial results from all processes and typically has a complexity proportional to the total number of elements in r.

2.4.1.2 Spatial Complexity

- Storage of Sparse Matrix and Dense Vector: The overall storage requirements remain $O(n_{nz} + m + n)$, as in other sparse matrix-vector multiplication methods.
- Local Result Vectors r_{local} : Each process stores a local result vector for its chunk of rows, with the size depending on the distribution of rows and non-zero elements.

Complexity and Considerations

Each of these parallel algorithms aims to exploit different aspects of parallelism, with the primary goal of reducing the overall computation time. The actual performance gain depends on the characteristics of the sparse matrix, the number of available processing units, and the specific implementation details. Moreover, care must be taken to manage concurrency issues, such as race conditions and proper synchronization, to ensure correct and efficient execution.

Chapter 3

Conclusion

Appendix A

Documentation

Appendix A.A Project tree

```
lib/
    collecting.py
    processing.py
    storing.py
scripts/
    get_iam_credentials.sh
    start_spark_job.sh
services/
    get_iam_credentials.service
    spark_python_job.service
test/
    artillery_load_test.yml
    monitoring.py
    metrics.csv
    results.json
    visualisation_load_test.ipynb
main.py
README. md
requirements.txt
```

Appendix A.B Getting Started

To run the program, follow these steps:

- 1. Create a virtual environment using python3 -m venv venv.
- 2. Activate the virtual environment using source venv/bin/activate.
- 3. Install the required dependencies using pip3 install -r requirements.txt.
- 4. Run the program using python3 main.py.
- 5. Visualise the results using visualisation.ipynb (Jupyter Notebook).

Appendix A.C Detailed Features of Functions

collecting.py

• fetch_sensors_data(sparkSession): Function to ingest the latest data from the sensors and returns it as a Spark DataFrame.

processing.py

- get_aqi_value_p25(value): Function for calculating the AQI value for PM2.5.
- get_aqi_value_p10(value): Function for calculating the AQI value for PM10.
- computeAQI(df): Function for calculating the AQI value for each particulate matter sensor and returning the DataFrame with the AQI column.

storing.py

- keepOnlyUpdatedRows(database_name, table_name, df): Function for keeping only the rows that have been updated in the DataFrame.
- _print_rejected_records_exceptions(err): Internal function for printing the rejected records exceptions.
- write_records(database_name, table_name, client, records): Internal function for writing a batch of records to the Timestream database.
- writeToTimestream(database_name, table_name, partionned_df): Function for writing the DataFrame to the Timestream database.

Appendix B

Source Codes

Appendix B.A Sequential Algorithm Source Code

```
#include "SparseMatrixDenseVectorMultiply.h"
  /**
   * @brief Function to execute the sparse matrix-dense vector
      multiplication using sequential algorithm
   * @param sparseMatrix Sparse matrix
   * Oparam denseVector Dense vector
   * @param vecCols Number of columns in the dense vector
   * Oreturn DenseVector Result of the multiplication
  {\tt DenseVector\ sparseMatrixDenseVectorMultiply(const}
     SparseMatrix &sparseMatrix,
                                                 const DenseVector
                                                     &denseVector,
                                                     int vecCols)
       // Initialisation of the result vector
14
      DenseVector result(sparseMatrix.numRows, std::vector<
15
          double > (vecCols, 0.0));
       // Iterate over the rows of the sparse matrix
      for (int i = 0; i < sparseMatrix.numRows; ++i)</pre>
           // Iterate over the non-zero elements in the current
           for (int j = sparseMatrix.rowPtr[i]; j < sparseMatrix</pre>
20
              .rowPtr[i + 1]; ++j)
           {
               // Iterate over the columns of the dense vector
22
               for (int k = 0; k < vecCols; ++k)</pre>
23
24
                   result[i][k] += sparseMatrix.values[j] *
                      denseVector[sparseMatrix.colIndices[j]][k
```