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# **Motion Magnification**

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#### **SUMMARY**



- 1.1 Goal of motion magnification
- 1.2 Problem Statement
- 1.3 Network

#### 2. Application on real data

- 2.1 Baby breathing
- 2.2 Guitar

#### 3. Issues

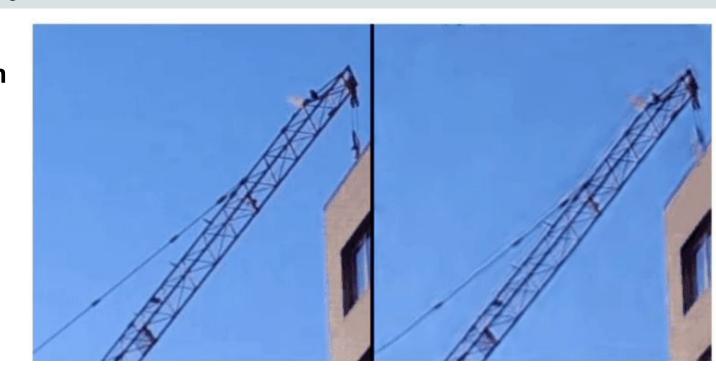
- 3.1 Noise
- 3.2 Camera motion





1.1 Goal of motion magnification

- Amplify motion by a factor α.
- Make small motion visible





*Example:* effect of the wind on a crane  $\alpha$ =50

#### **Introduction to Motion Magnification**

1.2 Problem Statement

#### Original images :

$$I(x,t) = f(x,t)$$

$$I(x,t+dt) = f(x,t+dt) = f(x+\delta(t),t)$$

Two input images

One output frame

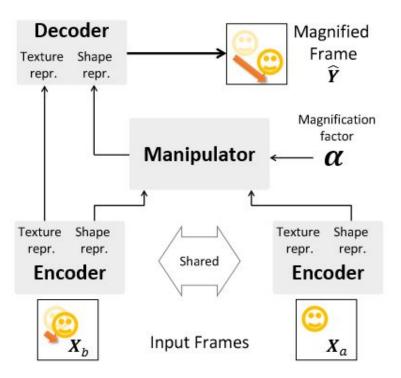
#### Magnified frame :

$$I_{magnified}(x,t+dt) = f(x+(1+lpha)\delta(t),t)$$



### **Learning-Based Motion Magnification**

#### 1.3 Network



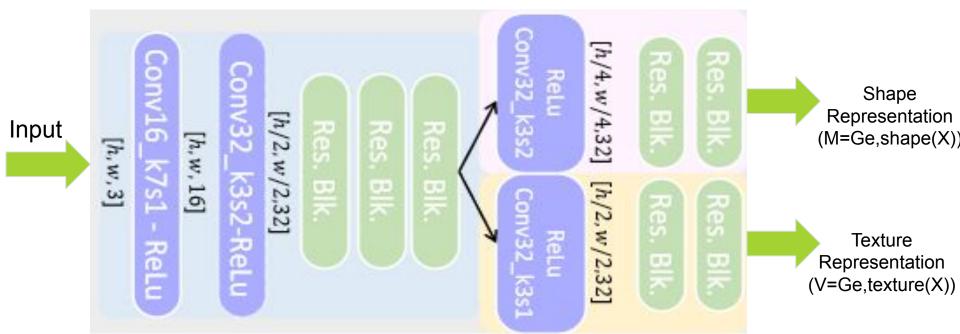
$$Loss = \left| \hat{Y} - Y 
ight| + \lambda (Regularisation)$$

- Trained of synthetic data. (Hard to reproduce the ground truth data in real life)
- Separate the shape and texture representation of each image



1.3 Network

### **Encoder**







1.3 Network

Why this division? Shape Representation Texture Representation (M) (V) Contains motion-related Contains intensity-related information information



Avoid intensity Magnification



1.3 Network

### **Manipulator** - 2 Frames

$$G_m(\mathbf{M}_a, \mathbf{M}_b, \alpha) = \mathbf{M}_a + h\left(\alpha \cdot g(\mathbf{M}_b - \mathbf{M}_a)\right)$$

Where

Ma: Shape representation of the first frame A

Mb: Shape representation of the second frame B

 $\alpha$ : Magnification factor

h(.): 3\*3 conv + residual block

g(.): 3\*3 conv + RELU





**2.0** The use of a GitHub code of the implementation

<u>https://github.com/ZhengPeng7/motion\_magnification\_learning-based</u>: A 3-years old implementation, but up to date

Unfortunately, the official implementation: 2018, not up to date, issues of past libraries

Many potential applications... => choice of a direction



2.1 Baby breathing

Video

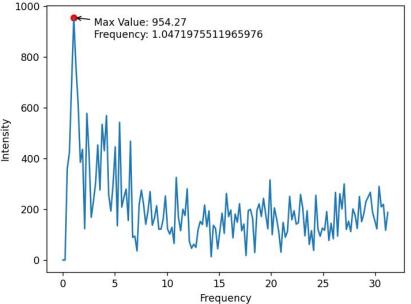


#### 2.1 Baby breathing

- Extract variation of the light intensity in certains points of the image.
- Retrieve the frequency at which the baby is breathing







The Baby is breathing every second



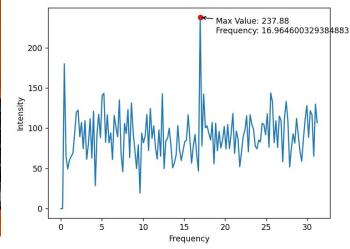
## **Application on real data** 2.2 Guitar

Video



## **Introduction to Motion Magnification** 2.2 Guitar







This is lower than what we expect, ie at least 82 Hz
Though we still have the right order of magnitude



### Issue of the current Network



- Noise with high value of α.
- Camera has to be stable



## Thank you for your attention

