

Chapter 1

Methodology

1.1 Software used

The tables of bolometric corrections were generated using a FORTRAN 77 code incorporating the steps described in Section ??, inputs with tables describing the response functions of all three filter systems at short*** wavelength intervals and ATLAS9 model atmosphere tables at the same wavelengths, with the number of tables for each stellar metallicity value equal to the total number of (**Teff,, log(g)) combinations available (see Table 1 of Castelli & Kurucz (2004) for details of the coverage in Teff-log(g) parameter space).

Once the bolometric correction tables were produced, all subsequent processes were written in Python 2.7.

The isochrones used were generated using the latest Bag of Stellar Tricks and Isochrones (BaSTI) web interface (Hidalgo et al., 2018). The filter systems whose throughput data were employed by BaSTI to generate the fluxes for the isochrones were ACS, WFC3 and Gaia-DR2. It should be noted that the WFC3 isochrone output does not include flux magnitudes for the F300X filter.

1.2 Extinction data

When calculating the bolometric corrections, the reference values taken by the parameters for Vega were:

Parameter / unit	Minimum	Maximum	Number of values
T_{eff} / K	3500	50000	76
$\log(g)$ / cm s^{-2}	0.0	5.0	11
[Fe/H]	-2.0	0.5	4

Table 1.1: Ranges for the input parameters for ATLAS9 atmospheric models

1. $m_X^0 = 0.03$ for the Gaia filters
2. $m_X^0 = 0.00$ for the Hubble WFC3 filters

together with $M_{\text{bol},\odot} = 4.75$. Equation ??, with the different wavelength regimes for $a(x)$ and $b(x)$ described by CCM89, was used with the A_V calibration values to simulate the extinction parameter in Equation ?. R_V was set to a value of 3.1, the standard value for the diffuse interstellar medium. The integration was carried out by iteratively adding the integrand results at regular small wavelength intervals. The non-zero calibration value of $A_V = 1$ was chosen, as this allows for significant changes in A_X/A_V from Equation (?), while also being close enough to zero to avoid significant changes in A_X/A_V due to the Forbes effect (Girardi et al., 2008).

The Forbes effect occurs as a broadband beam of light, such as that passes through an extended partially-transparent medium, such as a series of glass plates, the Earth's atmosphere or an interstellar gas cloud. It states that the greater the distance travelled by a light beam through the medium, the more penetrating the beam becomes (Forbes, 1842). If we use the case of the glass plates as an example, this means that the fraction of the light incident on the n th plate in the series which is separated by that plate from the original path is always greater than the corresponding fraction at the $(n + 1)$ th plate. The physical basis for the Forbes effect is that those photons in the original beam with wavelengths that make them the most likely to be absorbed or refracted are separated from the beam earlier. Therefore, as the beam travels through the medium, its constituent photons are progressively less likely to be separated. Since a higher fraction of its photons are retained as the distance through the medium increases, the beam is more penetrating.

The Forbes effect thus has an impact on the non-zero A_V value used because if a uniform medium is assumed, as here, where R_V is held constant at the standard diffuse ISM value of 3.1****, a larger A_V value implies a longer path through the ISM, and thus a stronger Forbes effect. According to Girardi et al. (2008), any ****significant impact from the Forbes effect on the values of A_X/A_V occurs for a chosen $A_V \gtrsim 4$. They found that the effect was particularly strong for stars with $T_{\text{eff}} \lesssim 3000\text{K}$ and that, unsurprisingly, it became greater as the filter wavelength range increased. Therefore, the choice of $A_V = 1$ made for this project should avoid serious problems from the Forbes effect.

To generate extinction-coefficient ratios A_X/A_V from the bolometric correction data, Equation ?? was used to****

1.3 Finding & fitting functions

In order to find usable functions, ****required prioritising which parameters to model first, as increasing the number of stellar parameters would cause an increase in the number of coefficients to fit for the function being tested. This would create a higher

risk of degeneracies between coefficients and increase the fitting output errors such that the errors obscure any useful information about the coefficients themselves.

A property found in the data for some filters, more pronounced at higher metallicity but with a possible slight dependence on surface gravity, is the tendency of the gradient of A_X/A_V with increasing T_{eff} to become significantly less positive at the lowest temperatures in the data, typically 4000K and below. The spread in A_X/A_V values for different $\log(g)$ is typically about 0.2-0.4, with a linear progression from $\log(g) = 5.0$ at the lowest end to $\log(g) = 0.0$ at the highest. In some filters, at the highest metallicity employed ($[\text{Fe}/\text{H}] = 0.5$), this phenomenon causes the gradient to become significantly negative, reversing the trend everywhere else in the data, including for the same filters at lower metallicity. Due to the shape of the resulting point-to-point line in these axes, it has been dubbed the “tail-flick” phenomenon. For filters with a small total range of A_X/A_V , this was ignored as an artefact from the numerical integration required for Equation ?? for the BCs at both chosen A_V values.

The bolometric flux of a black body can be calculated as the total area under the curve described by the Planck function per unit wavelength/frequency as a function of wavelength/frequency. Since stellar emission spectra can be reasonably approximated by a black body emission with absorption lines, it can be seen from Equation ?? that the greatest effect on stellar spectra, and therefore on the extinction coefficient, will come from effective temperature. Therefore, the initial functions to be fitted were simple analytical functions of T_{eff} only:

$$A_{\text{pow}}(T_{\text{eff}}) = a(T_4)^b + c \quad (1.1)$$

$$A_{\text{exp}}(T_{\text{eff}}) = a \exp(bT_4) + c \quad (1.2)$$

where, as before, $T_4 = 10^{-4} \times T_{\text{eff}}$. The fitting operation was carried out on the data for solar metallicity ($[\text{Fe}/\text{H}] = 0.0$) and, because it gave the greatest number of T_{eff} data points, $\log(g) = 5$. This dataset will be referred to as the basic fitting data (BFD).

Many filters, particularly bluer filters, exhibited

For filters whose data could not support an accurate**** fit on this data or could not keep accuracy across all combinations of $\log(g)$ and $[\text{Fe}/\text{H}]$ using A_{pow} or A_{exp} , more ****complicated functions were sought, including functions with dependences on g and $[\text{Fe}/\text{H}]$. For these filters, several unsuccessful approaches were made before an acceptable function was found for each filter. These included:

- Using a polynomial fit for the BFD, for filter which could not be accurately described in the BFD in the first instance.
- Fitting all the data in the ****parameter space in two steps, by fitting the residuals from the A_{pow} and A_{exp} fits to a new function with explicit variations in $[\text{Fe}/\text{H}]$ and $\log(g)$. The ****functions included second fittings of A_{pow} and A_{exp} , damped-oscillator functions and oscillating power-law functions, among others.

When fitted to the residuals, this meant an oscillation with amplitude decaying with increasing T_{eff}

A more successful approach was to individually**** tailor the form of the function for each filter. All the available data for each filter was plotted, in multiple 2D and 3D axes, and the trends seen in the data were transcribed to find not only an overarching model template, akin to the status of A_{pow} and A_{exp} , but also individual sub-functions, such as describing an exponential decay coefficient using a linear combination of $\log(g)$ and $[\text{Fe}/\text{H}]$ terms. ****Add other functions here!

For the four UV filters in WFC3, the final form for the overarching template for A_X/A_V was a logistic function in T_{eff} , shown in Equation 1.5. For a general logistic function in T_{eff} , there are four principle parameters:

- The global maximum value, denoted in this case by A_{max} ;
- The global minimum value, A_{min} ;
- The exponential decay coefficient, k ;
- The T_{eff} -coordinate of the sigmoid midpoint, in this case T_0 .

This form was chosen on the basis of its ability to model the low- T_{eff} change in gradient for these filters, which appears to be more significant in these filters than for others, as can be seen in Figures 1.4 and 1.3, even after accounting for the difference in scale between the maxima and minima in each filter. In particular, the T_{eff} gradient prior to the plateau appears to lead to an asymptote at lower, but still potentially-feasible temperatures. This issue is resolved by the change in gradient, which can be accurately modelled using a logistic curve, while also maintaining accuracy in modelling the gradient change during the transition to the plateau.

However, the problems regarding the significant changes in extinction ratios with surface gravity and metallicity required addressing. Therefore, upon inspection of the data over all combinations of both parameters, the logistic coefficients T_0 and k were expressed as simple functions of g and $[\text{Fe}/\text{H}]$, shown in Equations 1.3 and 1.4, respectively. Therefore, the overall function A_{logis} is sensitive to all three input stellar atmosphere parameters, with effective temperature having the greatest effect and the effects of the other parameters dependent on the best-fit values of the relevant coefficients.

$$T_0 = a \log(g) + b \left(\frac{[\text{Fe}/\text{H}]}{||[\text{Fe}/\text{H}]||^{1/2}} \right) + c \quad (1.3)$$

$$k = d \log(g) + e[\text{Fe}/\text{H}] + f \quad (1.4)$$

$$A_{\text{logis}}(T_{\text{eff}}, g, [\text{Fe}/\text{H}]) = \frac{(A_{\text{max}} - A_{\text{min}})}{(1 + \exp(-10^{-4}k(T_{\text{eff}} - T_0)))} + A_{\text{min}} \quad (1.5)$$

Isochrone (Age/Myr , [Fe/H])	T_{eff} minimum	T_{eff} maximum	$\log(g)$ minimum	$\log(g)$ maximum
500,0.002	2870	9640	0.886	5.137
1000,0.002	2824	8035	1.608	5.184
5000,-1.049	3118	7112	0.456	5.318
10000,-1.049	3086	6412	0.286	5.332

Table 1.2: Ranges of effective temperature and surface gravities in selected BaSTI isochrones

In general, the longer the effective wavelength of a given filter throughput, the smaller the value of A_X/A_V . This conforms with the expectation resulting from the fact that the physical mechanisms causing extinction in the ISM preferential affect photons with shorter wavelengths.

1.4 Isochrone data fitting

To obtain isochrones from the BaSTI online database, the desired age range, initial metallicity and filter system must be specified. Therefore, the values of these quantities are shared by all stellar objects. For the stages in stellar evolution prior to the main-sequence turn-off, any changes in atmospheric metallicity are insignificant, due to the factors discussed in Section ??.

The output from the BaSTI database for each model stellar object gives the model's initial mass and current mass (i.e. after a time equal to the isochrone age), together with the logarithms of the stellar luminosity in solar units ($\log(L/L_\odot)$) and of the effective temperature in K ($\log(T_{\text{eff}})$), followed by the absolute magnitudes (with zero extinction) of the object in each filter of the system. To derive the surface gravity g , we must combine Equation ??, to derive the stellar radius, and Equation ??. Equation 1.6 shows the resultant definition of g :

$$g = \frac{4\pi G M_* \sigma_{\text{SB}} T_{\text{eff}}^4}{L_*} \quad (1.6)$$

After this had been completed, each object had a co-ordinate in $(T_{\text{eff}}, \log(g))$ parameter space, plus the metallicity of the overall isochrone model. The functions described in Section 1.3 were then applied to the dataset of stellar objects, producing values of $M_{\text{eff},X}$ for each filter for all objects.

DR2 Babusiaux data, errors****

****However, the filter magnitudes in the photometric data were the original apparent magnitudes, not absolute magnitudes. Therefore, to match the attributes**** of the observational and isochrone datasets, it was necessary to correct the observational fluxes**** for distance and add extinction to the isochrone data, ****as is done by observers. Thus, we were comparing the $M_{\text{ext},X}$ values for the isochrones and the

observational data.

The errors in the parallax data for objects assigned to NGC 6793 were significant, particularly for stars in the lower main-sequence - understandably, since they are the faintest objects in the data and therefore are more difficult to track against the background light sources. This leads to errors in the predicted $M_{ext,X}$ magnitudes, which is calculated by rearranging Equation ??.

****The significance of the parallax errors in the main sequence is such that even when assuming no errors in the observed fluxes from the photometric filters, any differences between isochrones with similar parameters are rendered insignificant.

Since the table for photometric fluxes did not include photometric errors, the parallax errors alone accounted for the total error in the calculated $M_{ext,X}$. Therefore, the errors on the flux measurements were exactly equal in all filters for a given star. The errors on the $(G_{bp} - G_{rp})$ color index were calculated as standard, by adding the individual filter errors in quadrature, giving the color errors which were a factor of $\sqrt{2}$ greater than those for the individual filter fluxes.

When comparing the two approaches to extinction, in order to test for any differences in projected isochrone age via the MSTO, a range of ages must be considered. A “primary” age was utilised as the true cluster isochrone age. This primary isochrone was subjected to both the function-based and standard extinction approaches. Two isochrones with ages equidistant from the primary were subjected to the standard approach only. All four of the resulting $M_{ext,X}$ isochrones were plotted together in the four chosen CMD axes, together with the original (zero-extinction) isochrone for visual reference.

As can be seen in the data****, in all the filters studied in this project, above $T_{\text{eff}} \approx 12000\text{-}15000$ K, the values of A_X/A_V are constant or near-constant as a function of all three input parameters, reflected in the choice of decay functions for fitting the data****. This will be referred to henceforth as the “extinction plateau”.

This**** was repeated for two values of the standard treatment. Both were extracted from the ATLAS9 data tables, for a $\log(g)$ value of 5.0, thus**** representing a main-sequence star, highly desirable when comparing MSTO positions. The ATLAS9 metallicity chosen for these values**** was that which best matched the metallicity of the isochrone to which the coefficient was applied, ****which we will call $[\text{Fe}/\text{H}]_{CM}$. The first value was equal to $(A_X/A_V)_{plat} = (A_X/A_V)(T_{\text{eff}} = 50,000\text{K}, \log(g) = 5.0, [\text{Fe}/\text{H}]_{CM})$, and the second was equal to $(A_X/A_V)_{MS} = (A_X/A_V)(T_{\text{eff}} = 5,000\text{K}, \log(g) = 5.0, [\text{Fe}/\text{H}]_{CM})$. This was done to reflect the fact that, on one hand, the assumption of a constant extinction coefficient is valid in the plateau region and, on the other, given the position of the MSTO in terms of stellar model T_{eff} values, it would be more prudent to ensure that the upper main sequences resulting from both approaches to extinction coincide in the CMD, making it easier to see disagreements in the turn-off ages****. For each of these plots****, A_V was fixed at a value of 1.0.

For the open cluster NGC 6793, the isochrone fitting was done by eye. Using the values of $E(B - V)$ and age from Gaia Collaboration et al. (2018), a standard-case isochrone was derived, assuming a diffuse ISM (i.e., $R_V = 3.1$). This was tested for

both $(A_X/A_V)_{MS}$ and $(A_X/A_V)_{plat}$. The fitting process was carried out in sequential stages:

1. First, the upper main sequence of the function-based**** extinction isochrone was fitted to that of the standard-case isochrone by varying the value of A_V used for the function-based**** extinction coefficient.
2. Next, the age of the FBE*** isochrone was varied to match the observed turn-off location in the NGC 6793 data as far as possible.
3. Finally, the FBE isochrone metallicity was varied in an attempt match the observed lower main-sequence.

The isochrone with the resulting parameters were then plotted alongside the standard-case isochrones using both $(A_X/A_V)_{MS}$ and $(A_X/A_V)_{plat}$. The resulting curves were compared to each other for accuracy with respect to the observational data.

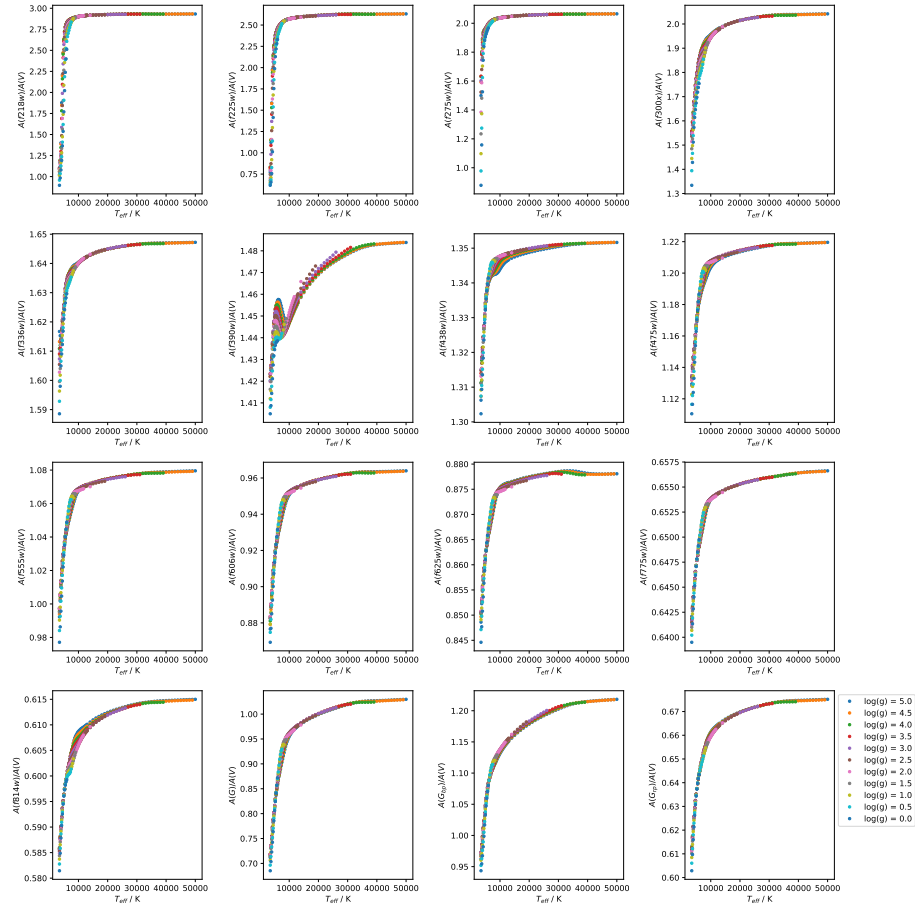
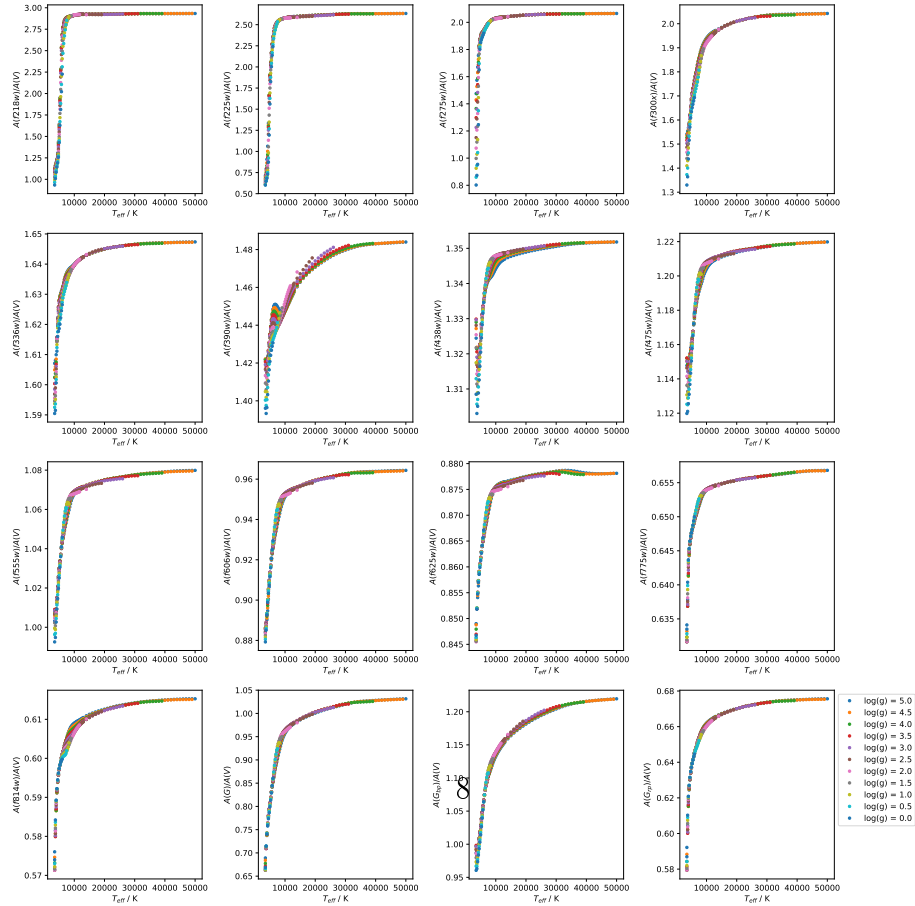


Figure 1.1: ***Monochromatic flux of a black body for different stellar effective temperatures. The black dashed lines mark the approximate limits of the visible part of the EM spectrum. The green curve represents the distributed of the maxima for the other curves.



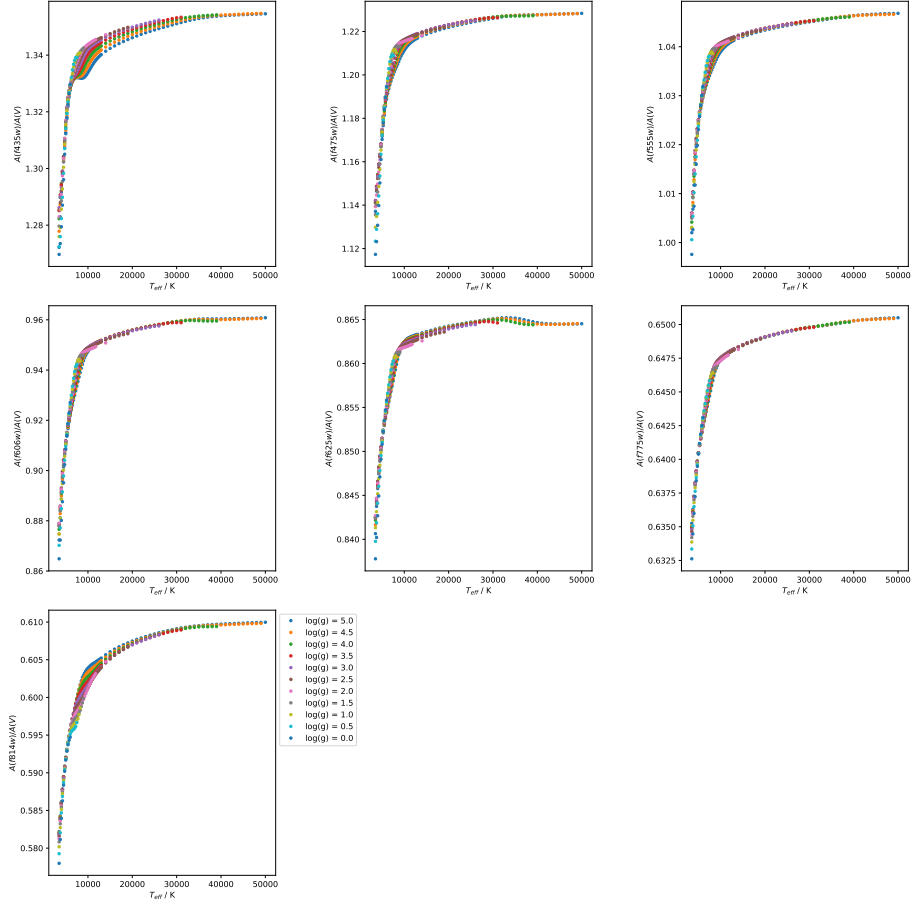
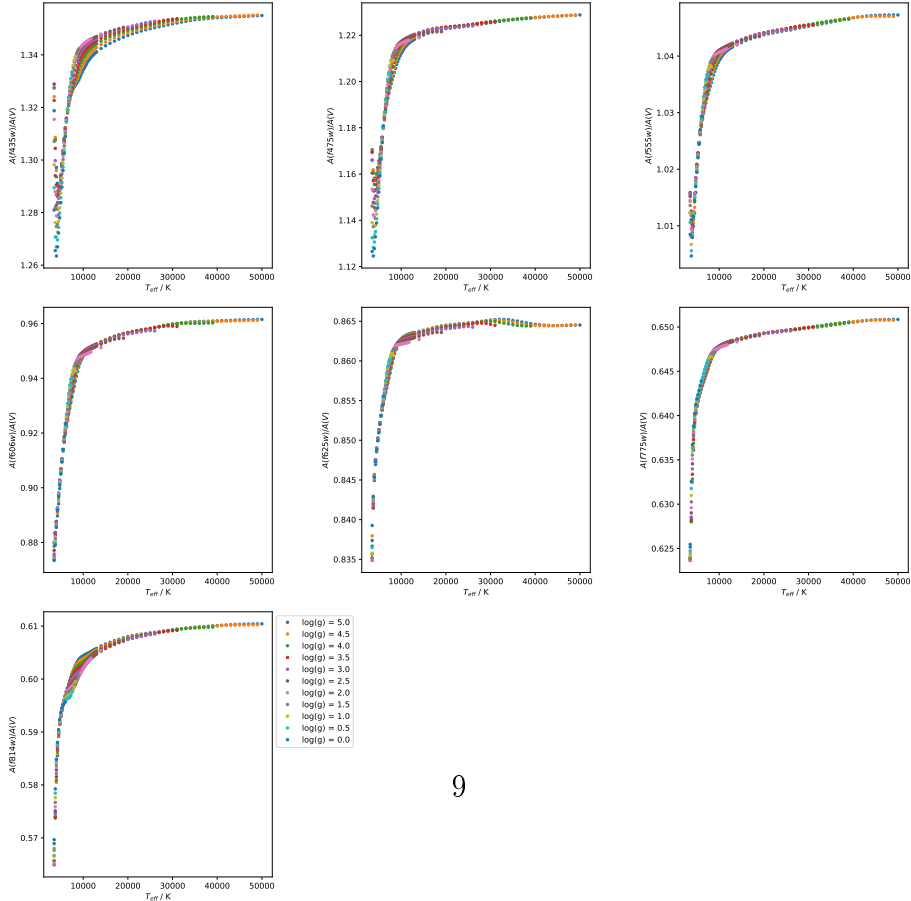


Figure 1.3: ***Monochromatic flux of a black body for different stellar effective temperatures. The black dashed lines mark the approximate limits of the visible part of the EM spectrum. The green curve represents the distributed of the maxima for the other curves.



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