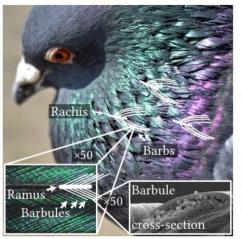
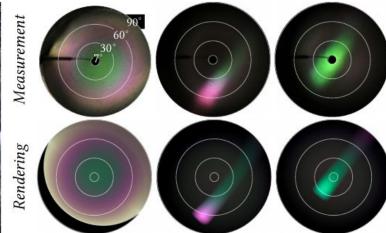
### Rendering Iridescent Rock Dove Neck Feathers

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Sebastian Merzbach University of Bonn Bonn, Germany merzbach@cs.uni-bonn.de Clara Callenberg
University of Bonn
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callenbe@cs.uni-bonn.de

Doekele G. Stavenga University of Groningen Groningen, Netherlands d.g.stavenga@rug.nl Matthias B. Hullin University of Bonn Germany hullin@cs.uni-bonn.de







# Pourquoi?



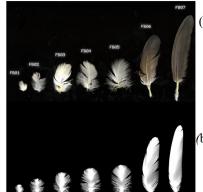






#### Travaux antérieurs

Splitting – imitates the splitting seen on feathers
Scraggle - random noise used to displace the barbs
Tangle – a scraggle that accumulates down the barb
Clipping - takes random cuts along the length of the barbs

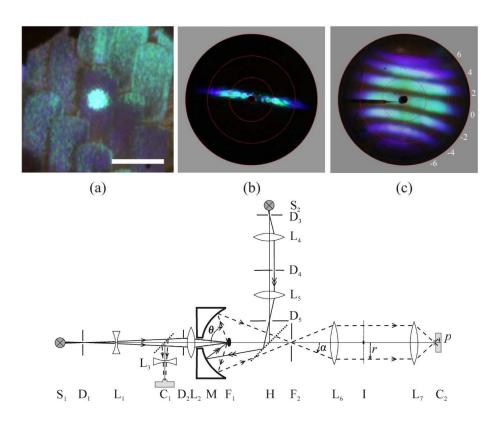


(a) Real

(b) Procedural

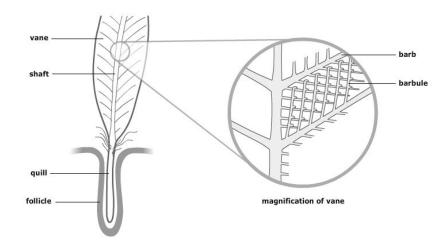


Rendertime Procedural Feathers Through Blended Guide Meshes, 2008

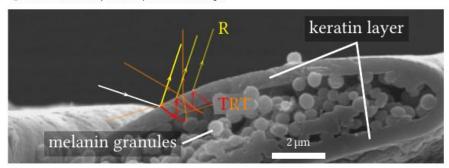


Imaging scatterometry of butterfly wing scales, 2009

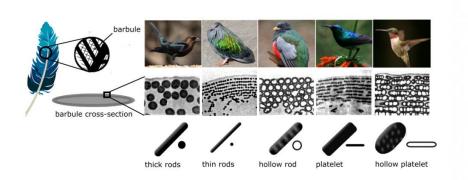
### Géométrie des Plumes

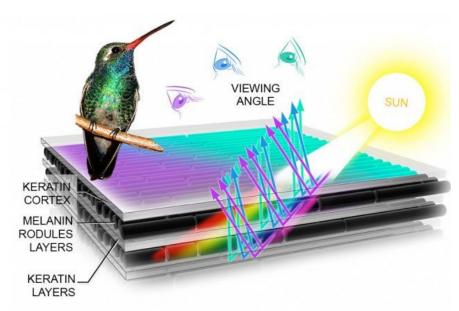


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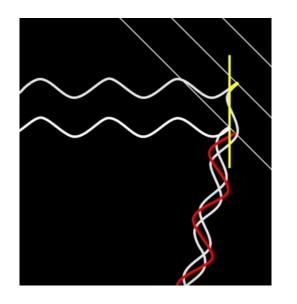


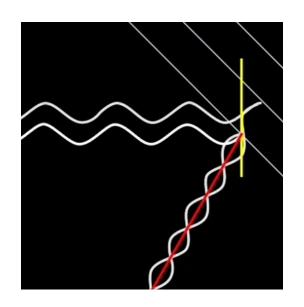
### Iridescence

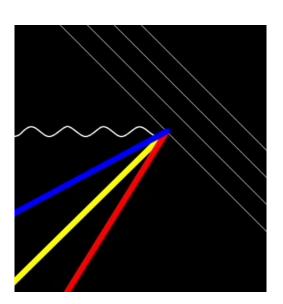




### Iridescence

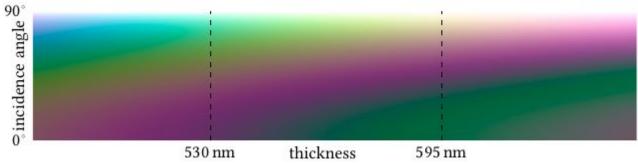


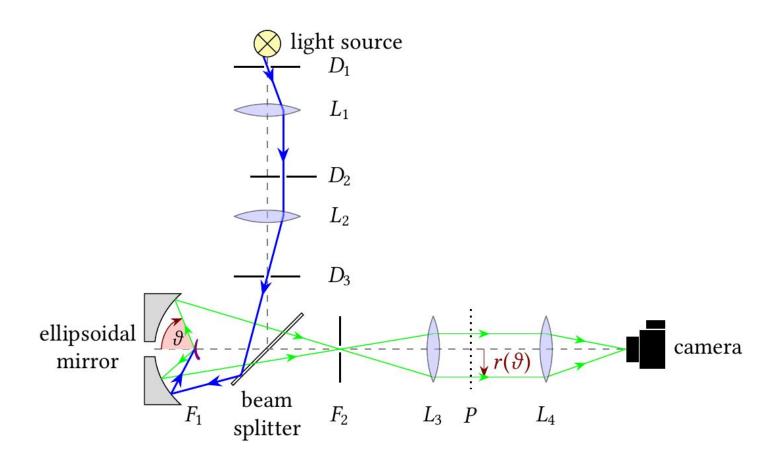


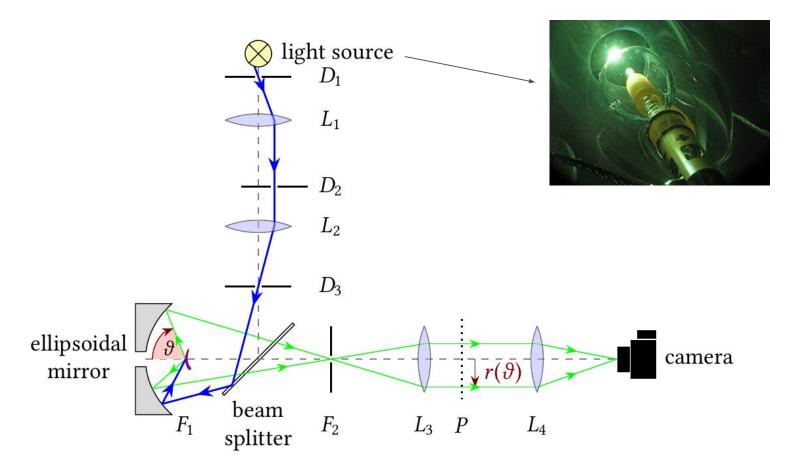


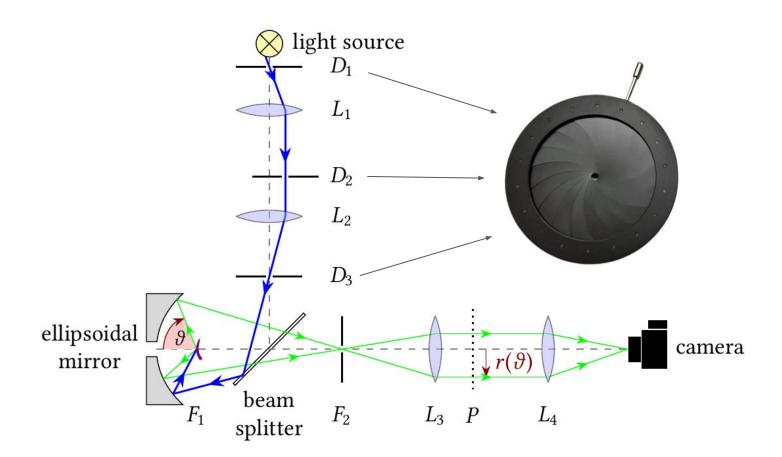
### Iridescence

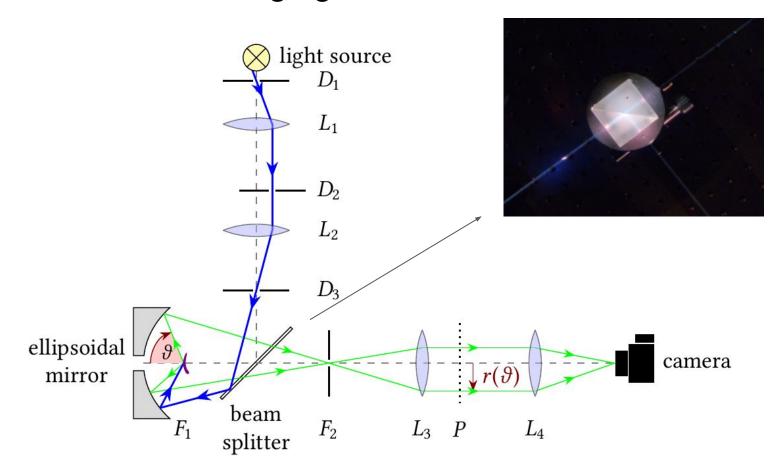


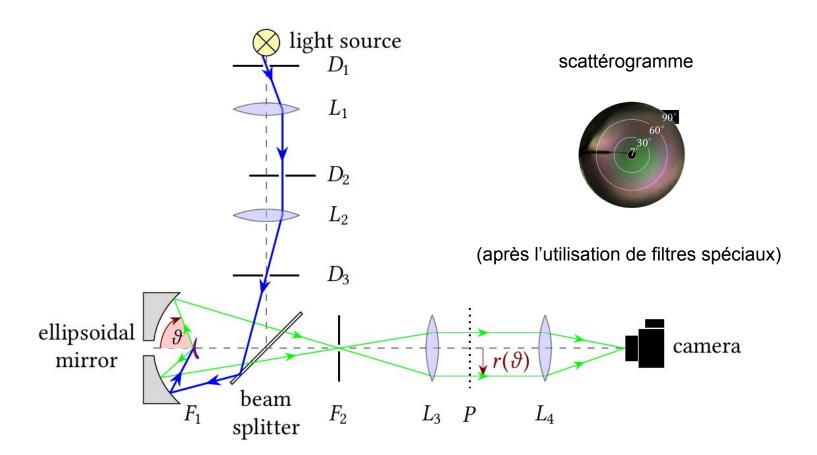




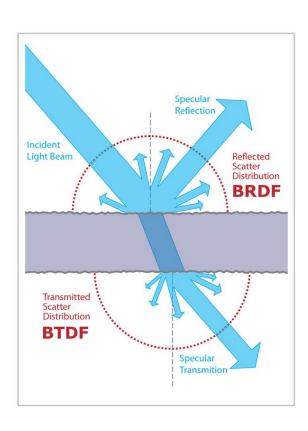




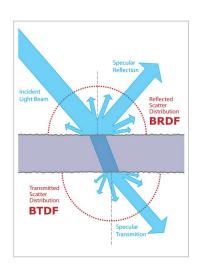




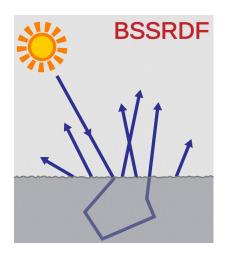
### **BSDF**

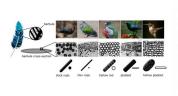


# Pourquoi un BSDF?

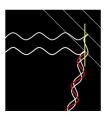


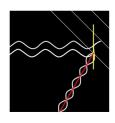


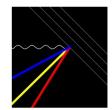






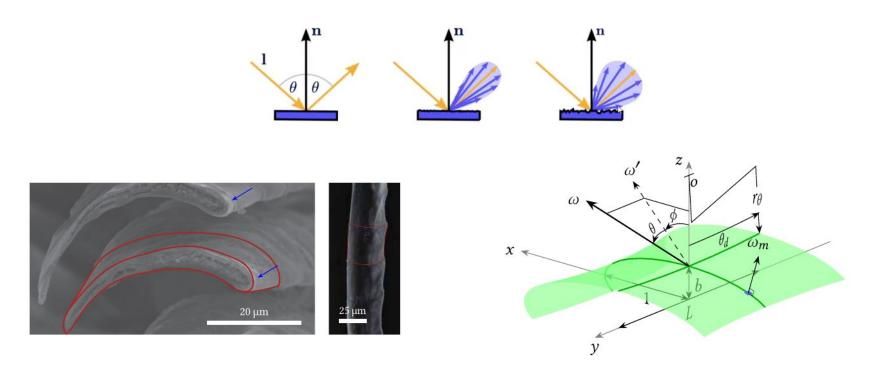






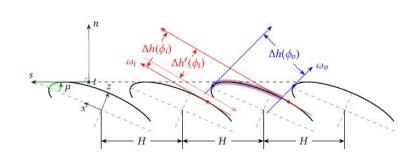
### Construire le BRDF : Microfacet BRDF

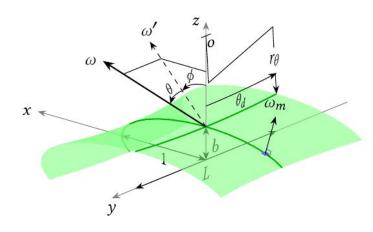
$$S_{\mathrm{R}}(\omega_{i},\omega_{o},\lambda) = \frac{I_{\mathrm{R}}(\omega_{i},\omega_{o},\lambda)D(\omega_{m})G(\omega_{i},\omega_{m},\omega_{o})}{4\langle\omega_{i},\vec{n}\rangle\langle\omega_{o},\vec{n}\rangle}$$
 Fonction Géométrique

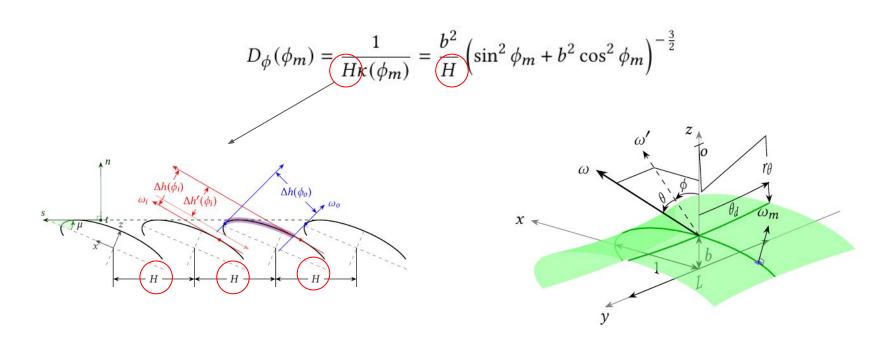


$$D(\omega_m) = \frac{b^2}{2H\sin\theta_d\cos\theta_m} \left(\sin^2\phi_m + b^2\cos^2\phi_m\right)^{-\frac{3}{2}}$$

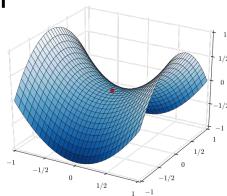
$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$

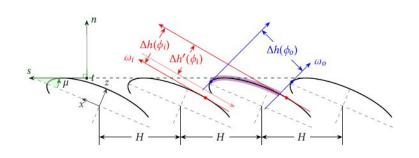


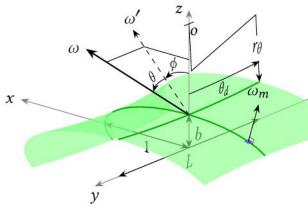




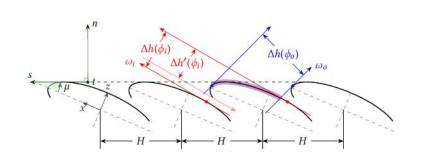
$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$

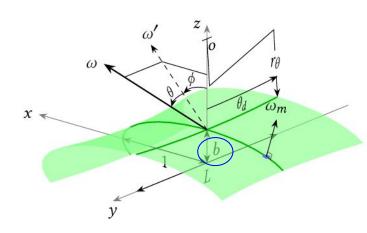






$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$



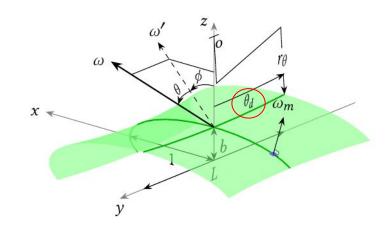


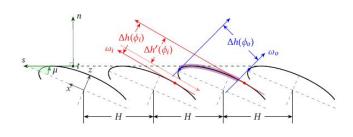
$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$

$$D_{\theta}(\theta_m) = \frac{1}{2\sin\theta_d}.$$

$$D(\omega_m) = D_{\theta}(\theta_m) D_{\phi}(\phi_m) (\cos \theta_m)^{-1}$$

$$D(\omega_m) = \frac{b^2}{2H\sin\theta_d\cos\theta_m} \left(\sin^2\phi_m + b^2\cos^2\phi_m\right)^{-\frac{3}{2}}$$



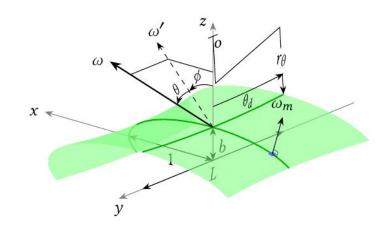


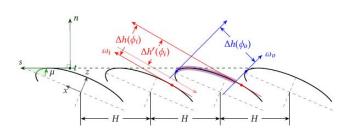
$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$

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$$D(\omega_m) = \frac{b^2}{2H\sin\theta_d\cos\theta_m} \left(\sin^2\phi_m + b^2\cos^2\phi_m\right)^{-\frac{3}{2}}$$



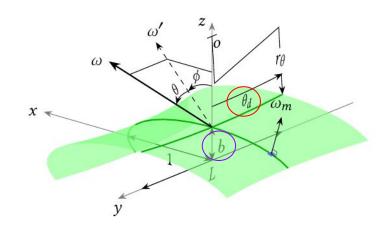


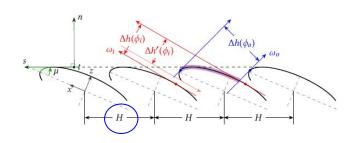
$$D_{\phi}(\phi_m) = \frac{1}{H\kappa(\phi_m)} = \frac{b^2}{H} \left(\sin^2 \phi_m + b^2 \cos^2 \phi_m\right)^{-\frac{3}{2}}$$

$$D_{\theta}(\theta_m) = \frac{1}{2\sin\theta_d}.$$

$$D(\omega_m) = D_{\theta}(\theta_m) D_{\phi}(\phi_m) (\cos \theta_m)^{-1}$$

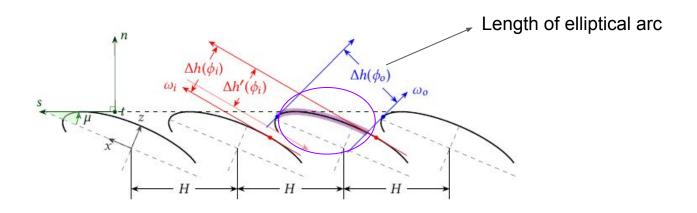
$$D(\omega_m) = \frac{b^2}{2H \sin\theta_d \cos\theta_m} \left(\sin^2\phi_m + b^2 \cos^2\phi_m\right)^{-\frac{3}{2}}$$





# Fonction géométrique : Fonction de visibilité

G = 0 ou 1



#### Réflectance et Iridescence

A Practical Extension to Microfacet Theory for the Modeling of Varying Iridescence

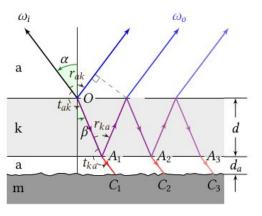
LAURENT BELCOUR, Unity Technologies PASCAL BARLA, Inria







A MARINE C



$$r=r_{ak}+\frac{t_{ak}r_{ka}t_{ka}e^{i\Delta\psi}}{1-r_{ka}^{2}e^{i\Delta\psi}}, \qquad t=\frac{t_{ak}t_{ka}}{1-r_{ka}^{2}e^{i\Delta\psi}}$$

$$\Delta \psi = \frac{2\pi \mathcal{D}}{\lambda} = \frac{4\pi d\eta_k \cos\beta}{\lambda}$$



#### Réflectance et Iridescence

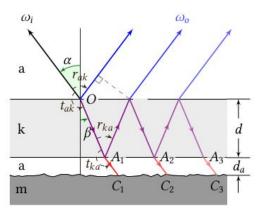
A Practical Extension to Microfacet Theory for the Modeling of Varying Iridescence

LAURENT BELCOUR, Unity Technologies PASCAL BARLA, Inria



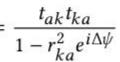






$$r = r_{ak} + \frac{t_{ak}r_{ka}t_{ka}e^{i\Delta\psi}}{1 - r_{ka}^2e^{i\Delta\psi}}, \qquad t = \frac{t_{ak}t_{ka}}{1 - r_{ka}^2e^{i\Delta\psi}}$$

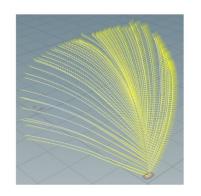
$$\Delta \psi = \frac{2\pi \mathcal{D}}{\lambda} = \frac{4\pi d\eta_k \cos \beta}{\lambda}$$



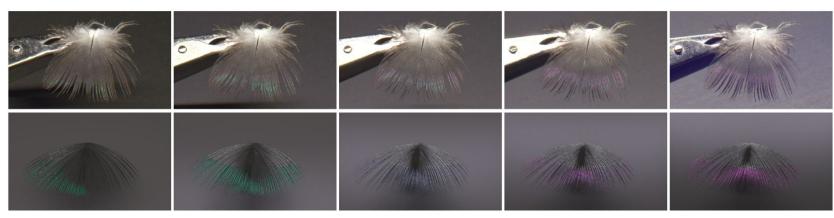




### Résultats







# Résultats



