

Decision trees

Bagging

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Outline

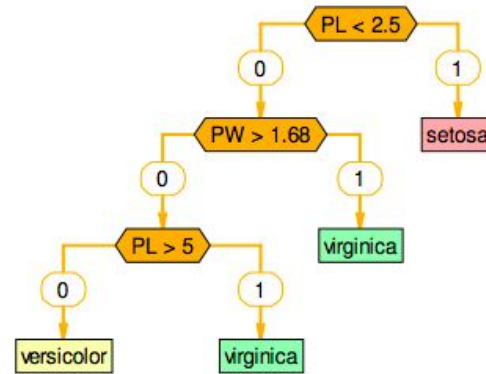
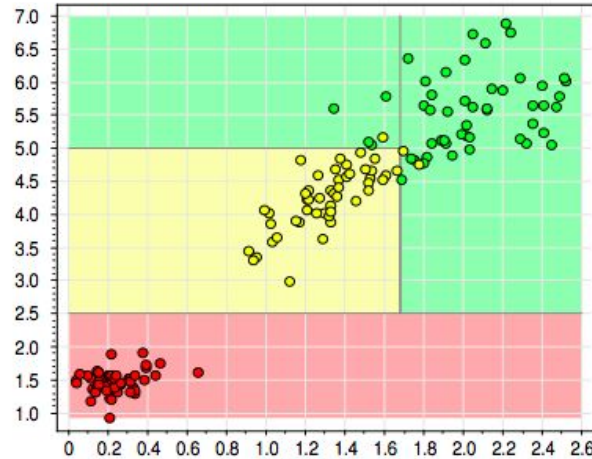
1. Intuition
2. Construction procedure
3. Information criteria
4. Special highlights
 - Dealing with missing data
 - Binarization
 - Decision tree as linear model
 - Standards
 - Hyperparameters
5. Bootstrap and Bagging
6. Random Forest

Decision Tree: intuition

girafe
ai

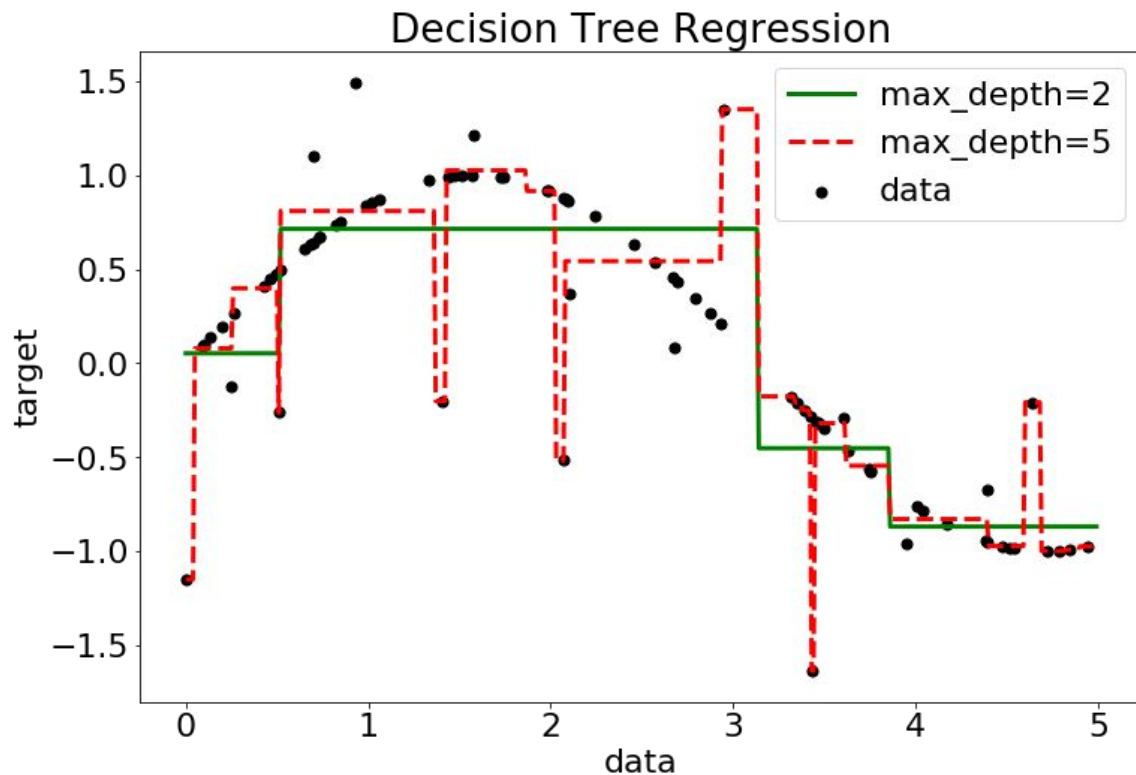
01

Decision tree for Iris data set



setosa	$r_1(x) = [PL \leq 2.5]$
virginica	$r_2(x) = [PL > 2.5] \wedge [PW > 1.68]$
virginica	$r_3(x) = [PL > 5] \wedge [PW \leq 1.68]$
versicolor	$r_4(x) = [PL > 2.5] \wedge [PL \leq 5] \wedge [PW < 1.68]$

Decision tree in regression



Green - decision tree of depth 2

Red - decision tree of depth 5

Every leaf corresponds to some constant.

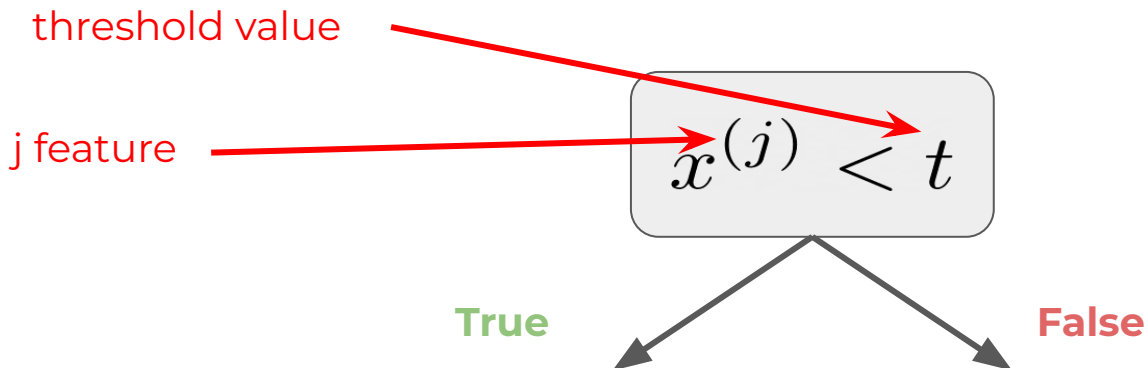
Construction procedure

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02



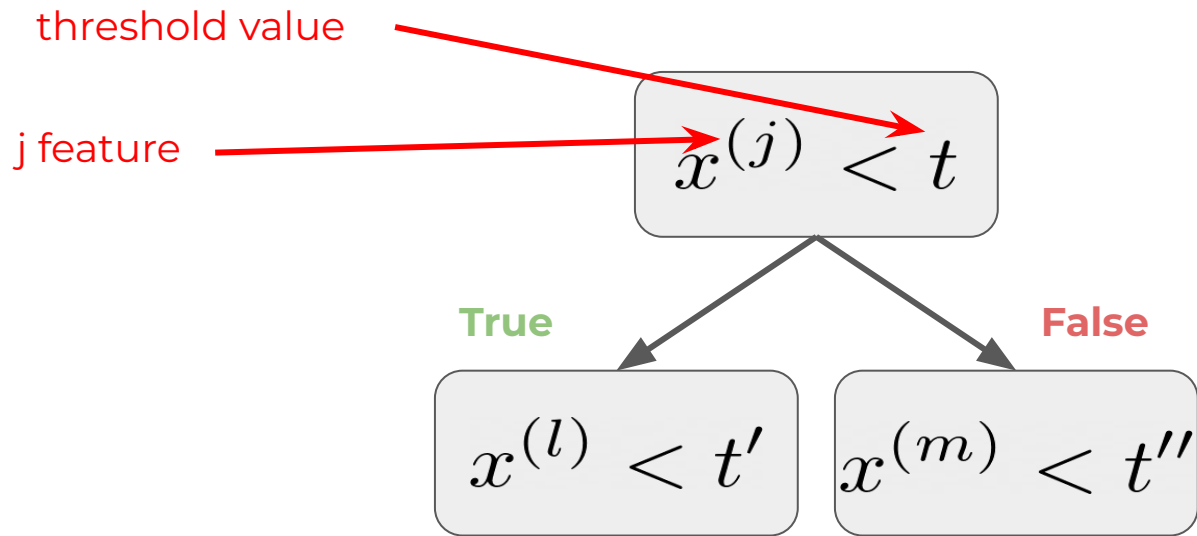
Constructing decision trees



1. Make a split



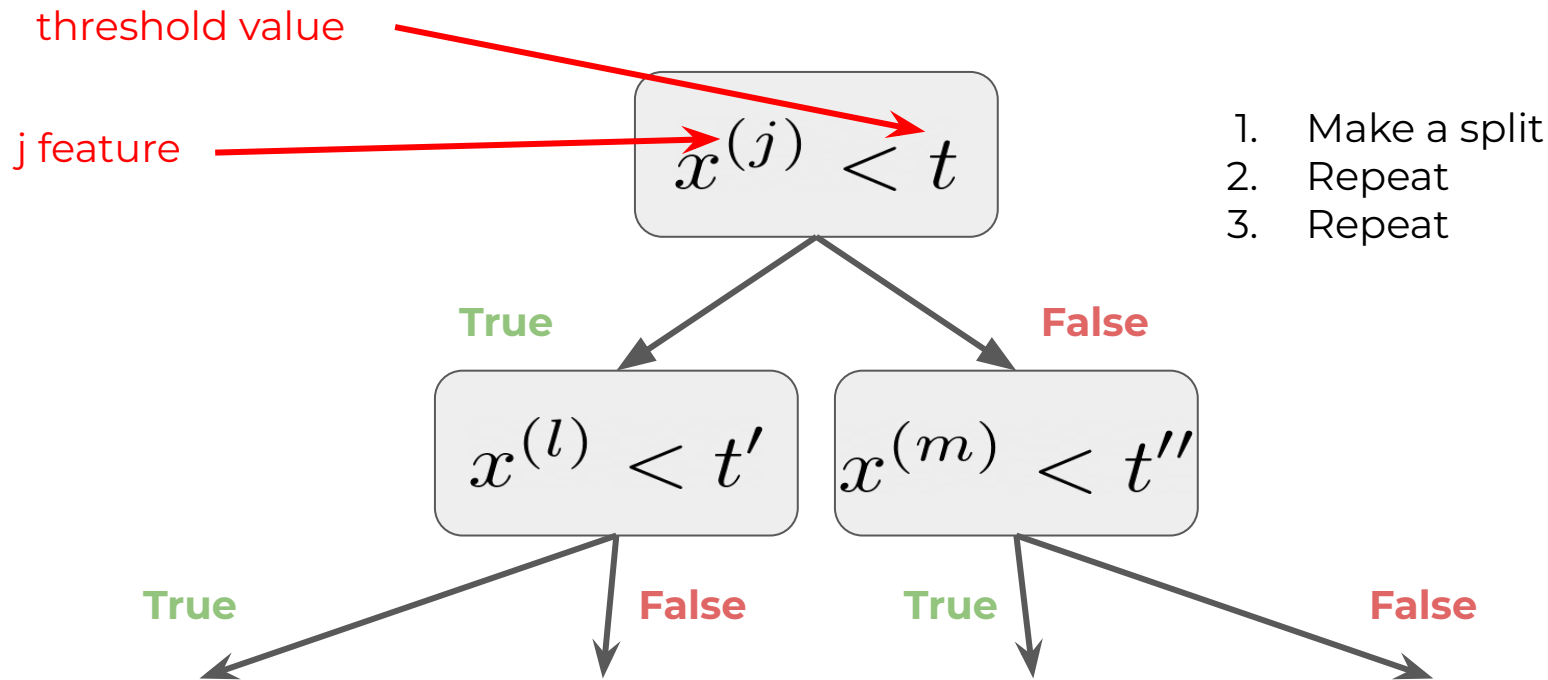
Constructing decision trees



1. Make a split
2. Repeat

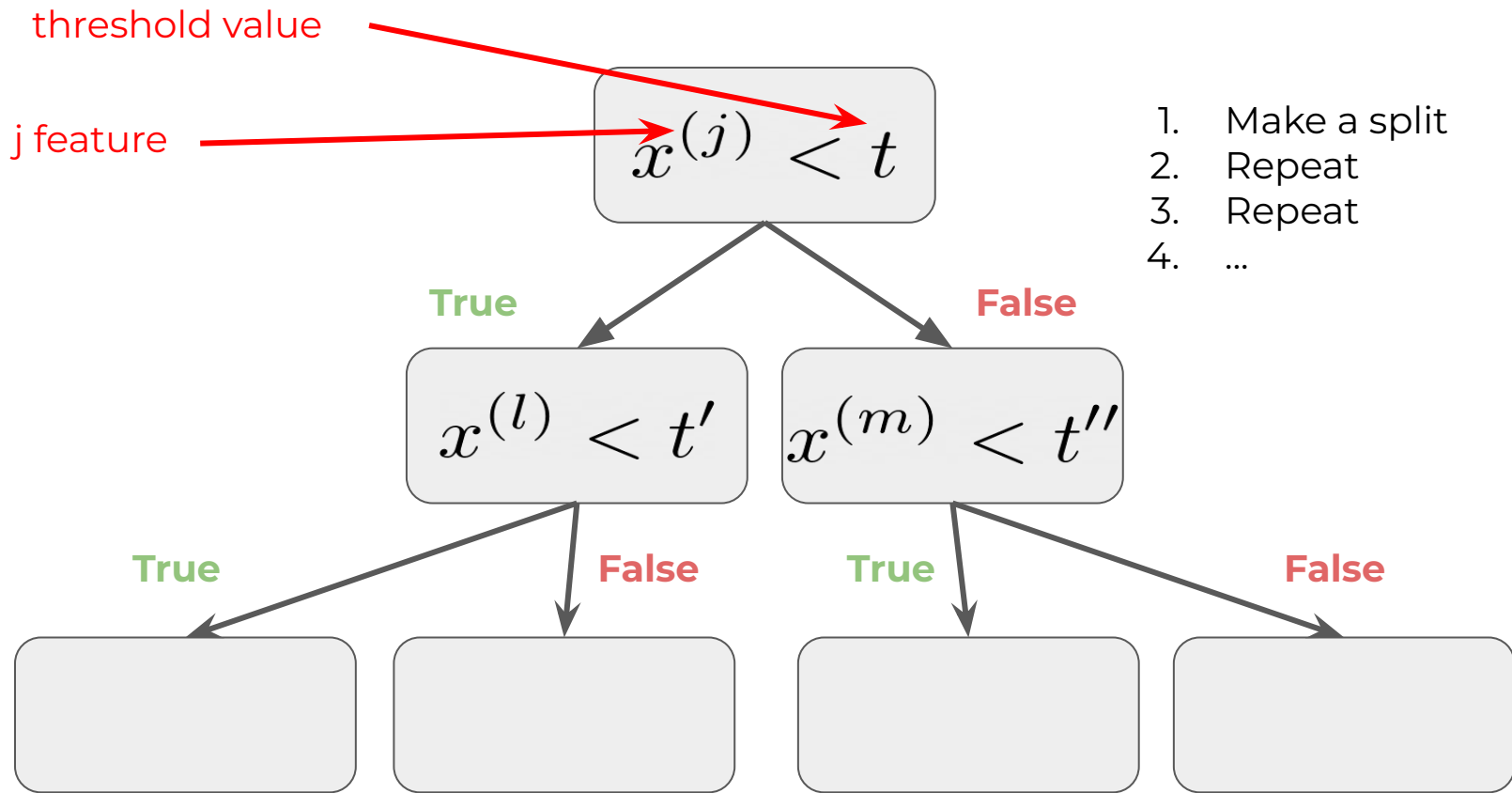


Constructing decision trees





Constructing decision trees

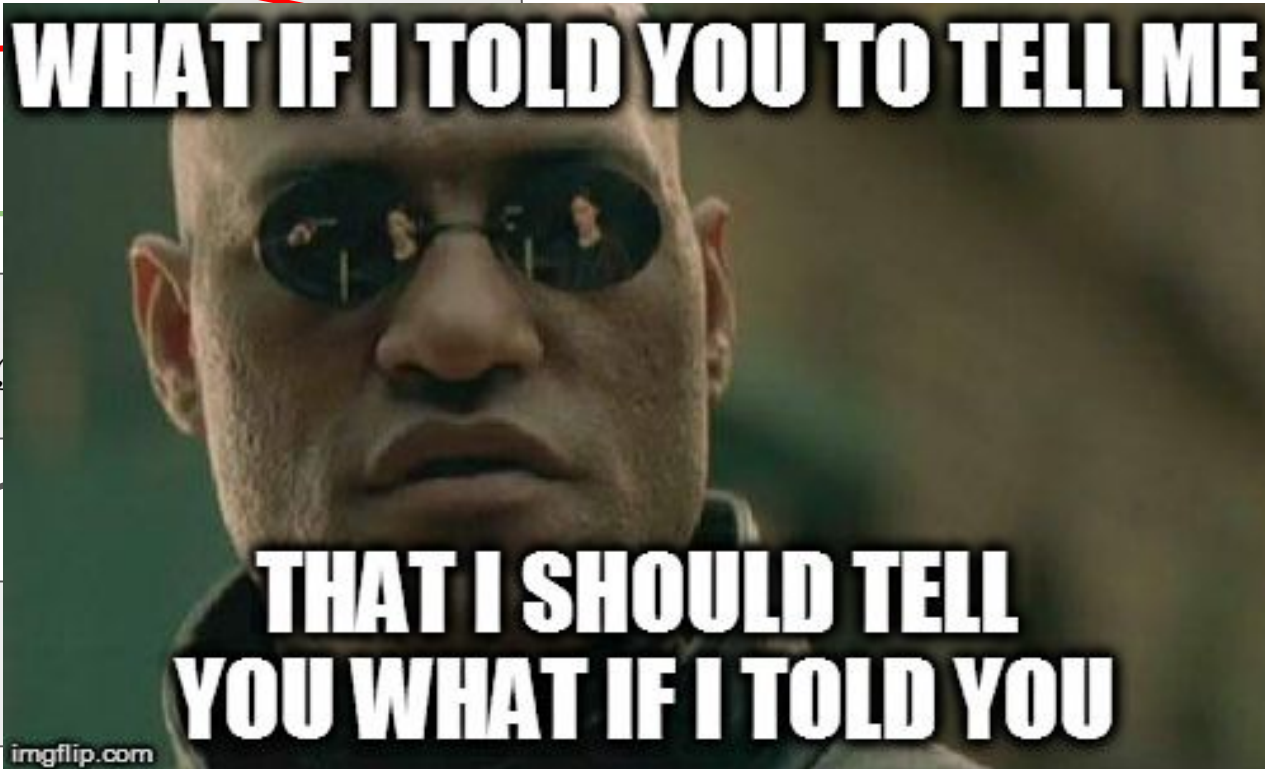




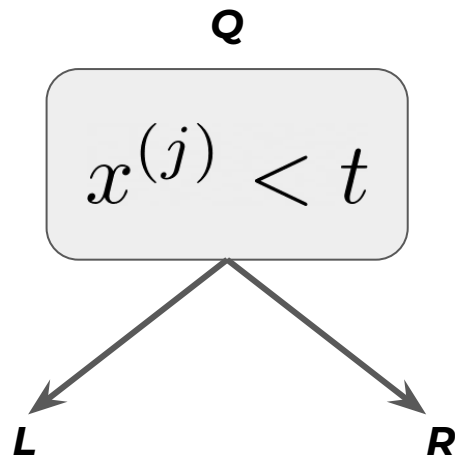
threshold value

j feature

True



How to split data properly?



What is H?

$$\frac{|L|}{|Q|} H(L) + \frac{|R|}{|Q|} H(R) \longrightarrow \min_{j,t}$$

Information criteria

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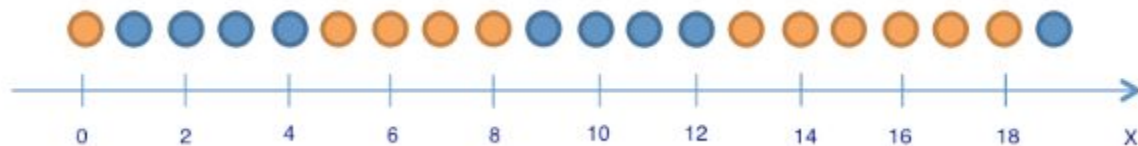
03



Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider binary classification problem:

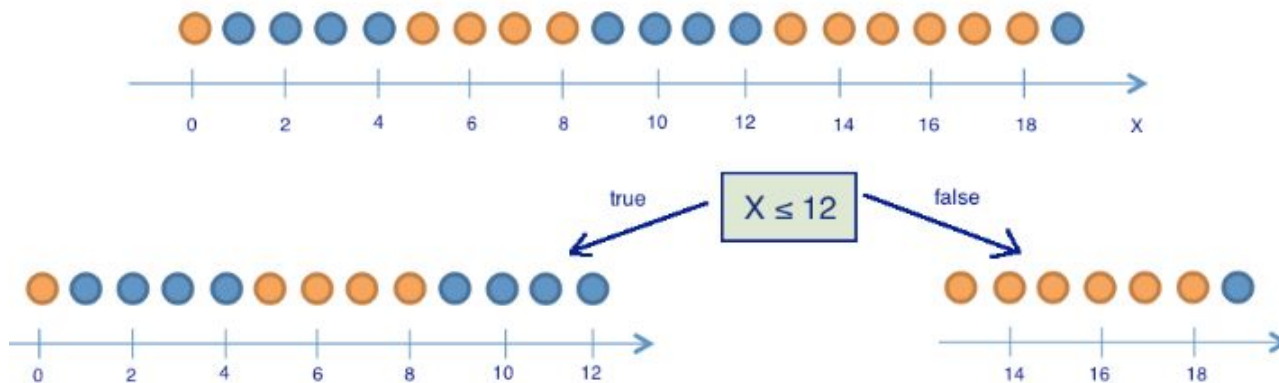




Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider binary classification problem:





Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider **binary classification** problem:

Obvious way:

$$H(R) = 1 - \max\{p_0, p_1\}$$

Misclassification criteria:

1. Entropy criteria: $H(R) = -p_0 \log p_0 - p_1 \log p_1$

2. Gini impurity: $H(R) = 1 - p_0^2 - p_1^2 = 1 - 2p_0p_1$



Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider **multiclass classification** problem:

Obvious way:

$$H(R) = 1 - \max_k \{p_k\}$$

Misclassification criteria:

1. Entropy criteria:

$$H(R) = - \sum_{k=0}^K p_k \log p_k$$

2. Gini impurity:

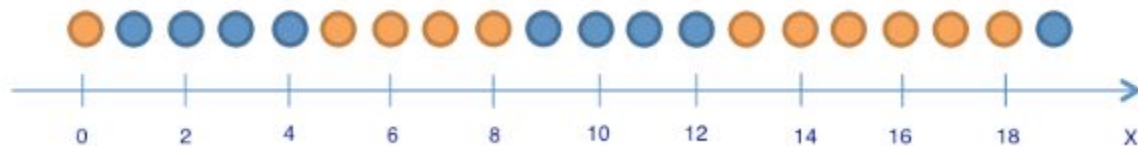
$$H(R) = 1 - \sum_k (p_k)^2$$



Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider binary classification problem:

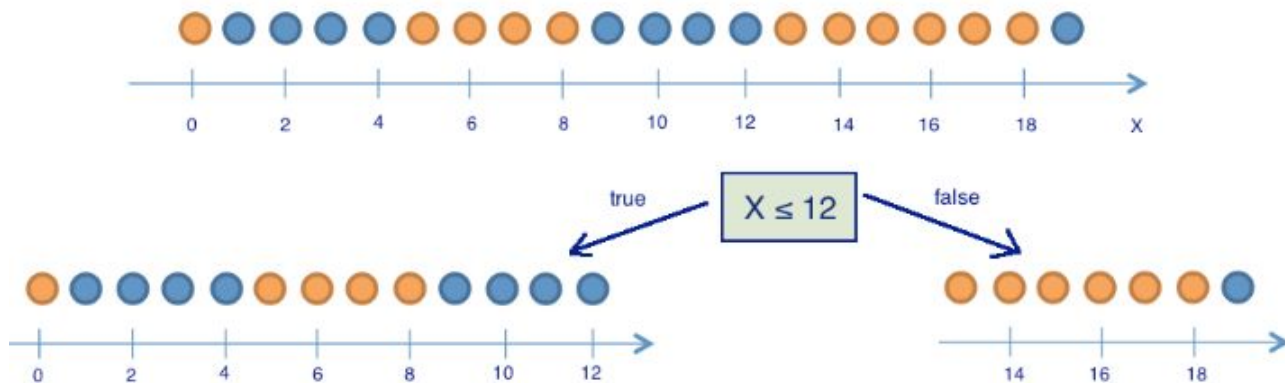




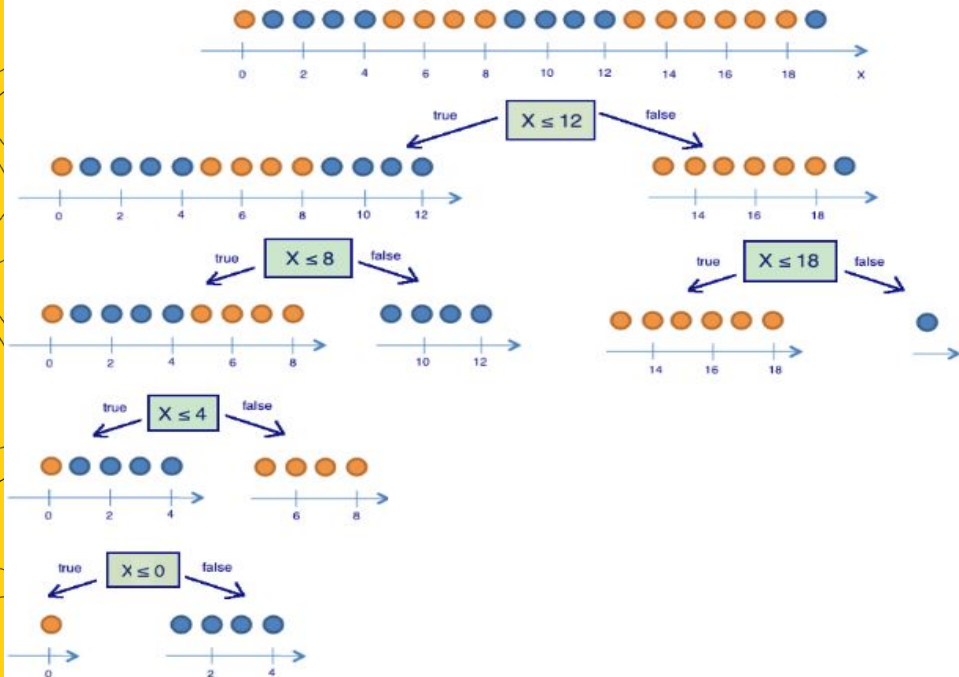
Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider binary classification problem:



Information criteria: Entropy



$$S = -M \sum_{k=0}^K p_k \log p_k$$

In binary case $N = 2$

$$S = -p_+ \log_2 p_+ - p_- \log_2 p_- = -p_+ \log_2 p_+ - (1 - p_+) \log_2 (1 - p_+)$$

source: <https://habr.com/ru/company/ods/blog/322534/>

Information criteria: Gini impurity



$$G = 1 - \sum_k (p_k)^2$$

In binary case $N = 2$

$$G = 1 - p_+^2 - p_-^2 = 1 - p_+^2 - (1 - p_+)^2 = 2p_+(1 - p_+)$$



Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

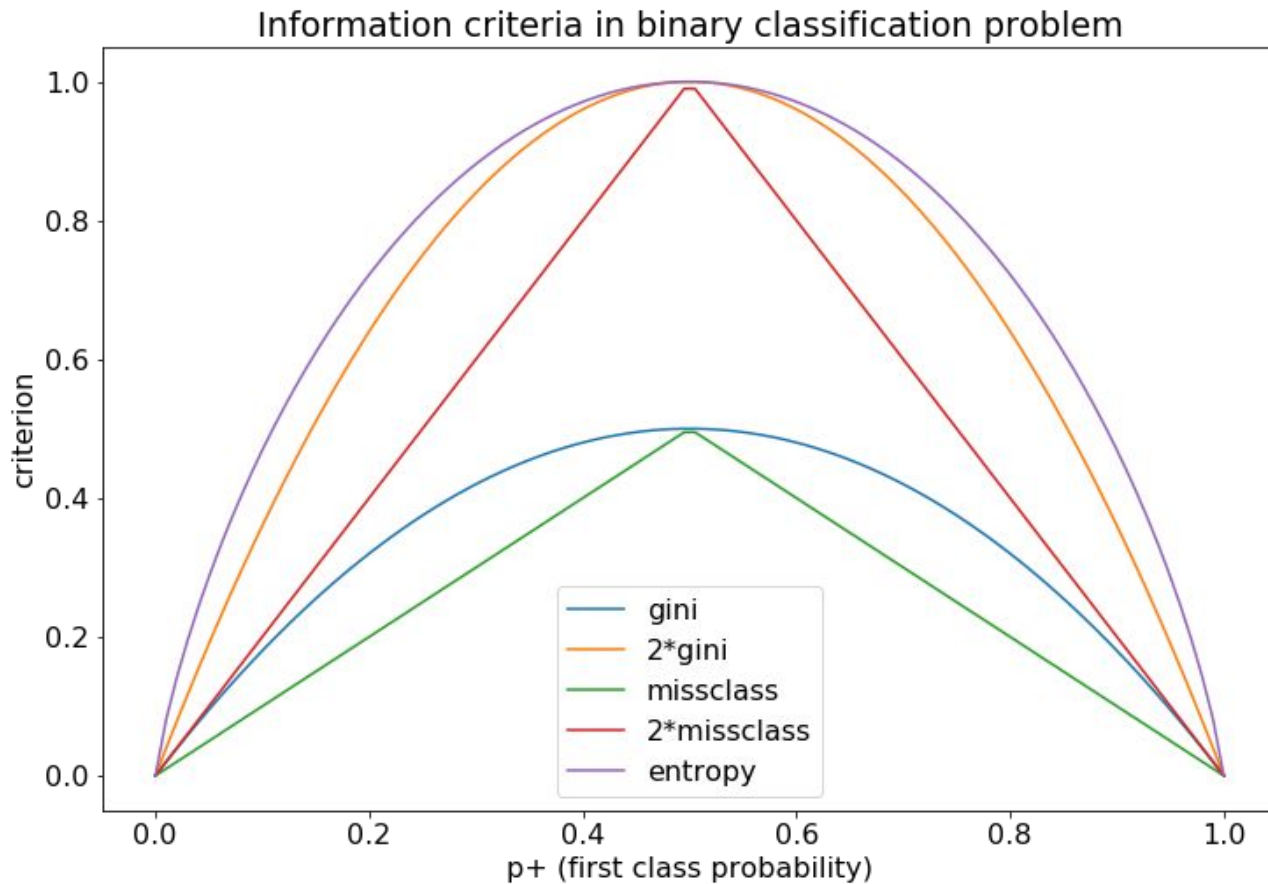
Consider **multiclass classification** problem:

Obvious way: Misclassification criteria: $H(R) = 1 - \max_k \{p_k\}$

1. Entropy criteria: $H(R) = - \sum_k p_k \log_2 p_k$

2. Gini impurity: $H(R) = 1 - \sum_k (p_k)^2$

Information criteria





Information criteria

$H(R)$ is measure of “heterogeneity” of our data.

Consider **regression** problem:

1. Mean squared error

$$H(R) = \min_c \frac{1}{|R|} \sum_{(x_i, y_i) \in R} (y_i - c)^2$$

What is the constant?

$$c^* = \frac{1}{|R|} \sum_{y_i \in R} y_i$$

Special highlights

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04

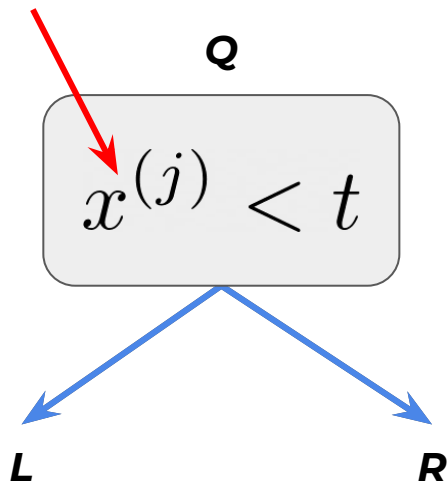
Missing values in Decision Trees



If the value is missing, one might use both sub-trees and average their predictions.

But this will negatively affect model computational performance.

Missing value



$$\hat{y} = \frac{|L|}{|Q|} \hat{y}_L + \frac{|R|}{|Q|} \hat{y}_R$$

Missing values in Catboost



Forbidden: Missing values are not supported, their presence is interpreted as an error

Min: Missing values are processed as the minimum value (less than all other values) for the feature. It is guaranteed that a split that separates missing values from all other values is considered when selecting trees.

Max: Missing values are processed as the maximum value (greater than all other values) for the feature. It is guaranteed that a split that separates missing values from all other values is considered when selecting trees.

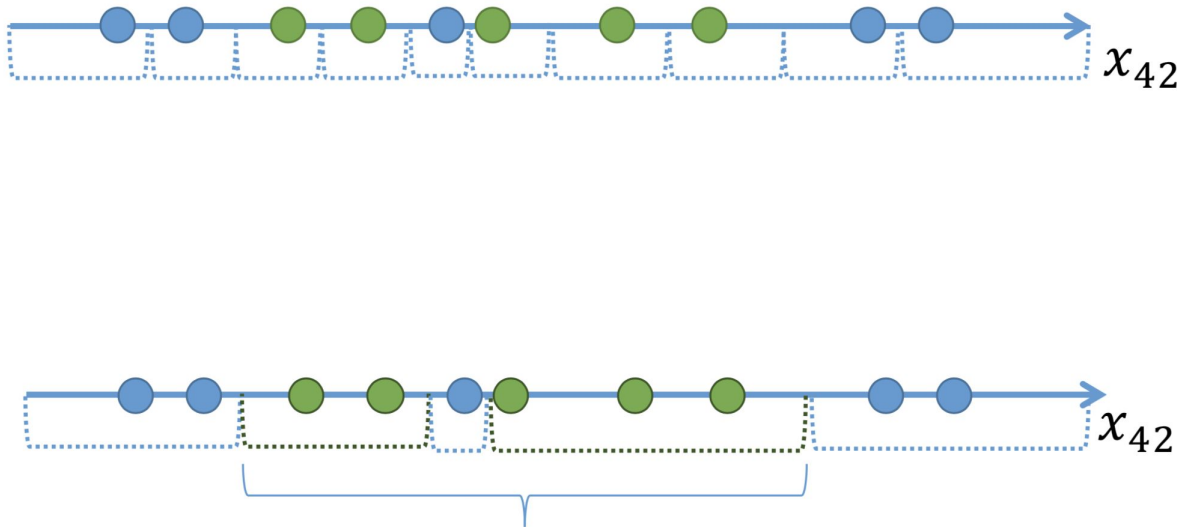
The **default** processing mode **is Min**

[Documentation](#)



Binarization

Idea: instead selecting one threshold define several for one feature.



e.g. [Border count hyperparameter](#) in Catboost (defaults to 254)

Decision Trees as Linear models



Let J be the subspace of the original feature space, corresponding to the leaf of the tree.

Prediction takes form

$$\hat{y} = \sum_j w_j [x \in J_j]$$



Standards

- ID-3
 - Entropy criteria; Stops when no more gain available
- C4.5
 - Normalised entropy criteria; Stops depending on leaf size; Incorporates pruning
- C5.0
 - Some updates on C4.5
- CART
 - Gini criteria; Cost-complexity Pruning; Surrogate predicates for missing data;
- etc.

Hyperparameters

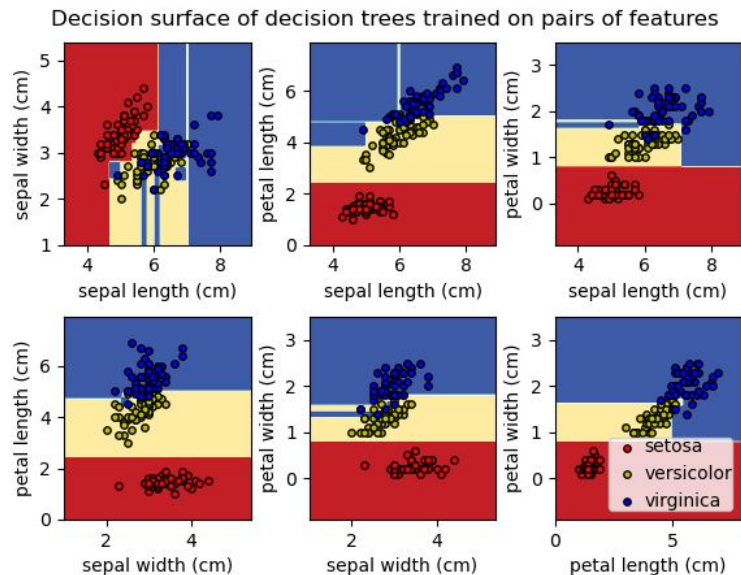


- max_depth: min 1
- min_samples_split: min 2
- min_samples_leaf: min 1
- min_impurity_decrease

Minor

- criterion:
 - gini, entropy, log_loss for classification
 - MSE or MAE for regression
- splitter: best, random
- max_features: sqrt, log2

As of [sklearn implementation](#)



Bootstrap and Bagging

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06



Bootstrap

Consider dataset X containing m objects.

Pick m objects with return from X and repeat in N times to get N datasets.

Error of model trained on X_j : $\varepsilon_j(x) = b_j(x) - y(x), \quad j = 1, \dots, N,$

Then $\mathbb{E}_x(b_j(x) - y(x))^2 = \mathbb{E}_x \varepsilon_j^2(x).$

The mean error of N models: $E_1 = \frac{1}{N} \sum_{j=1}^N \mathbb{E}_x \varepsilon_j^2(x).$

Bootstrap



Consider the errors unbiased and uncorrelated:

$$\mathbb{E}_x \varepsilon_j(x) = 0;$$

$$\mathbb{E}_x \varepsilon_i(x) \varepsilon_j(x) = 0, \quad i \neq j.$$

The final model averages all predictions:

$$a(x) = \frac{1}{N} \sum_{j=1}^N b_j(x).$$

Error decreased by N times!

$$\begin{aligned} E_N &= \mathbb{E}_x \left(\frac{1}{N} \sum_{j=1}^n b_j(x) - y(x) \right)^2 = \\ &= \mathbb{E}_x \left(\frac{1}{N} \sum_{j=1}^N \varepsilon_j(x) \right)^2 = \\ &= \frac{1}{N^2} \mathbb{E}_x \left(\sum_{j=1}^N \varepsilon_j^2(x) + \underbrace{\sum_{i \neq j} \varepsilon_i(x) \varepsilon_j(x)}_{=0} \right) = \\ &= \frac{1}{N} E_1. \end{aligned}$$

Bootstrap



Consider the errors ~~unbiased and uncorrelated~~:

$$\mathbb{E}_x \varepsilon_j(x) = 0;$$

$$\mathbb{E}_x \varepsilon_i(x) \varepsilon_j(x) = 0, \quad i \neq j.$$

This is a lie

The final model averages all predictions:

$$a(x) = \frac{1}{N} \sum_{j=1}^N b_j(x).$$

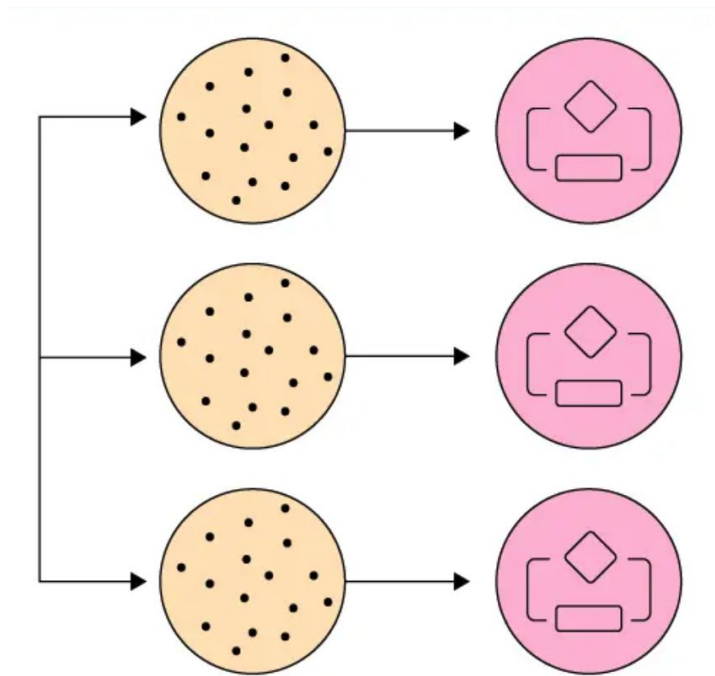
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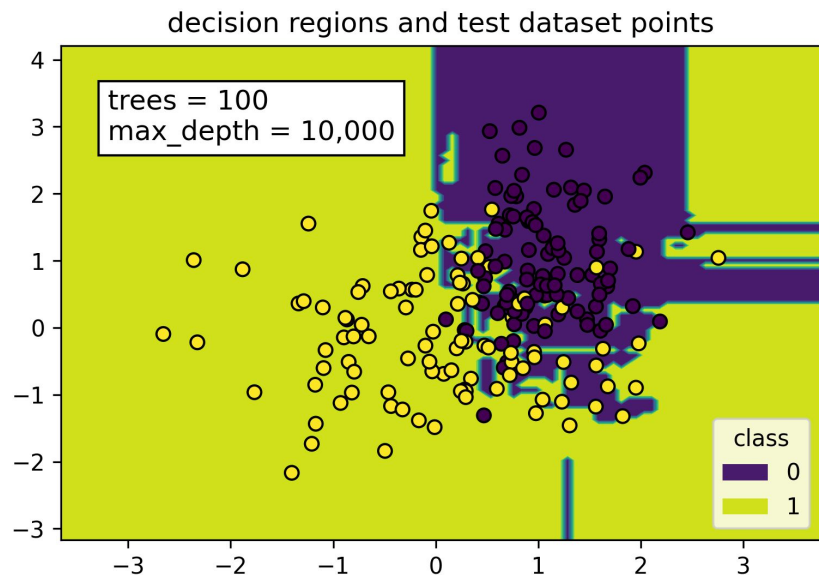
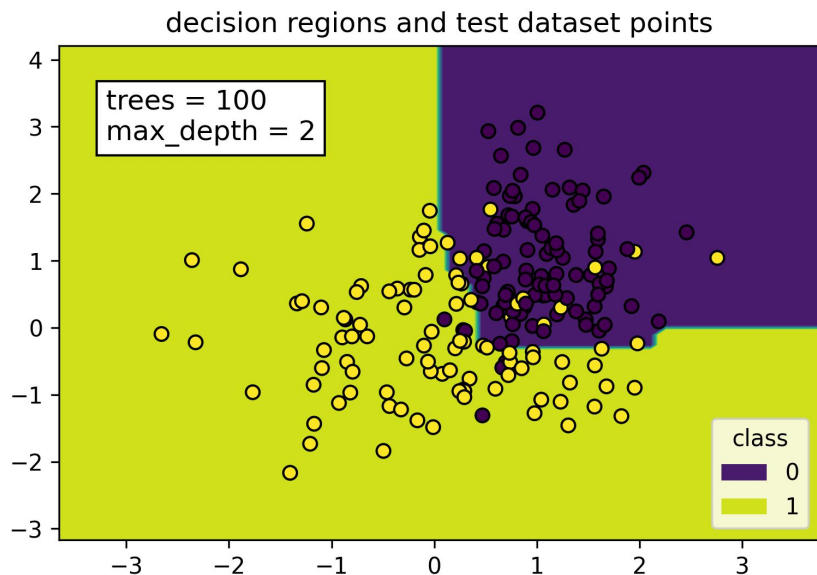
Bagging = Bootstrap aggregating



Decreases the **variance** if the basic algorithms are not correlated



Bagging overfitting



Random Forest

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07

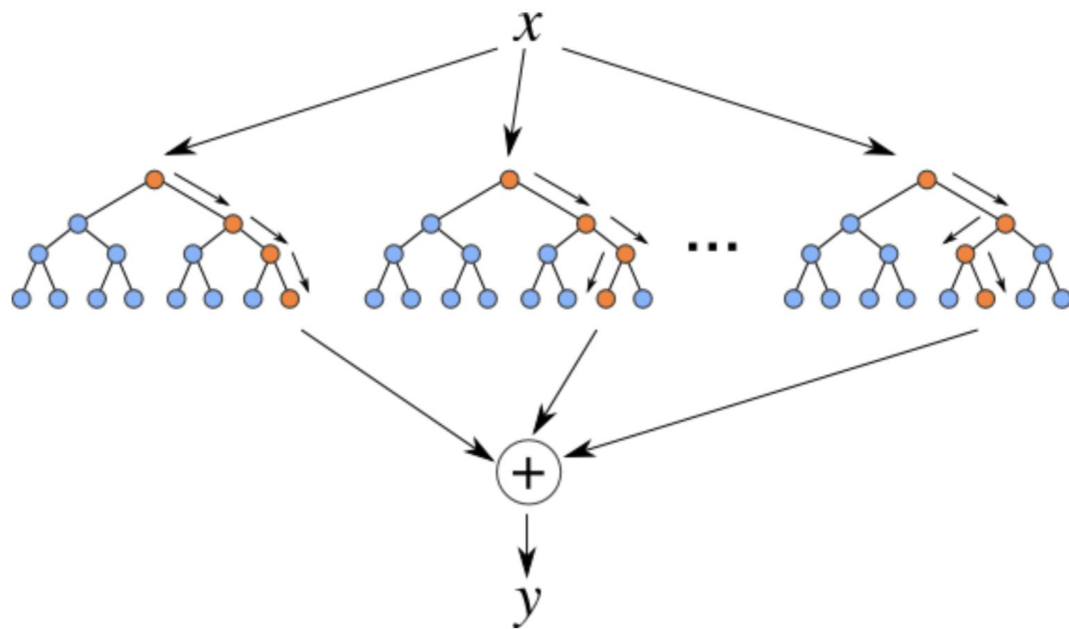
RSM - Random Subspace Method



Same approach, but with features

Random Forest

Bagging + RSM = Random Forest



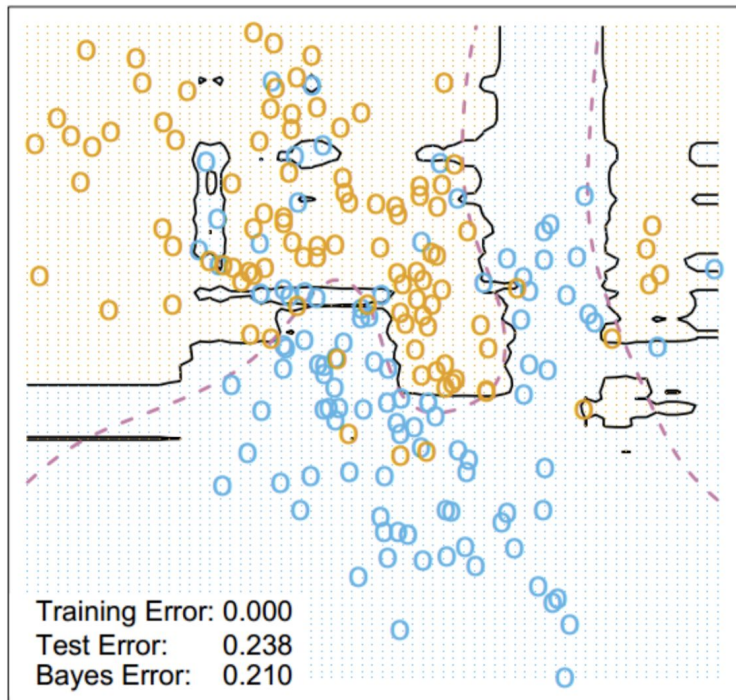
Random Forest



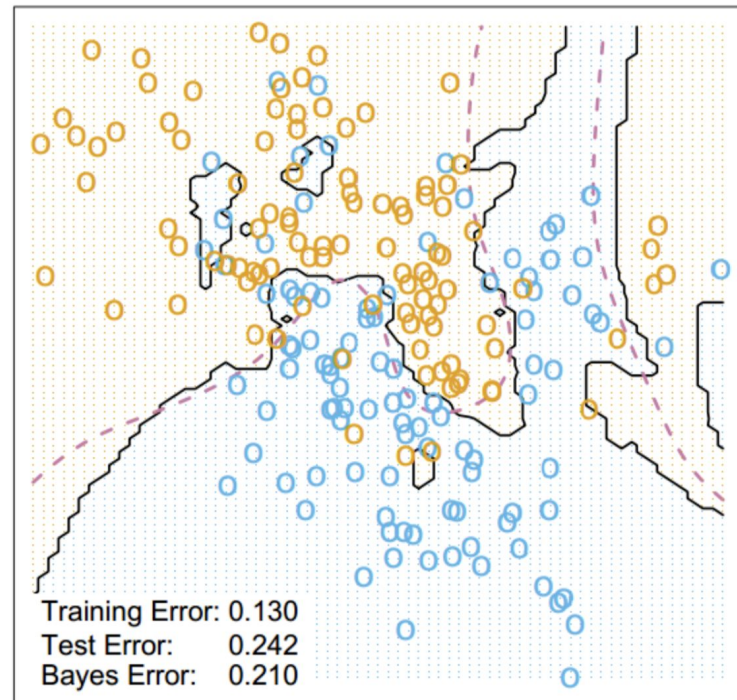
- One of the greatest “universal” models
- There are some modifications: Extremely Randomized Trees, Isolation Forest, etc



Random Forest Classifier



3-Nearest Neighbors



Revise



1. Intuition
2. Construction procedure
3. Information criteria
4. Decision trees special highlights
 - Decision tree as linear model
 - Dealing with missing data
 - Categorical features
5. Bootstrap and Bagging
6. Random Forest

Thanks for attention!

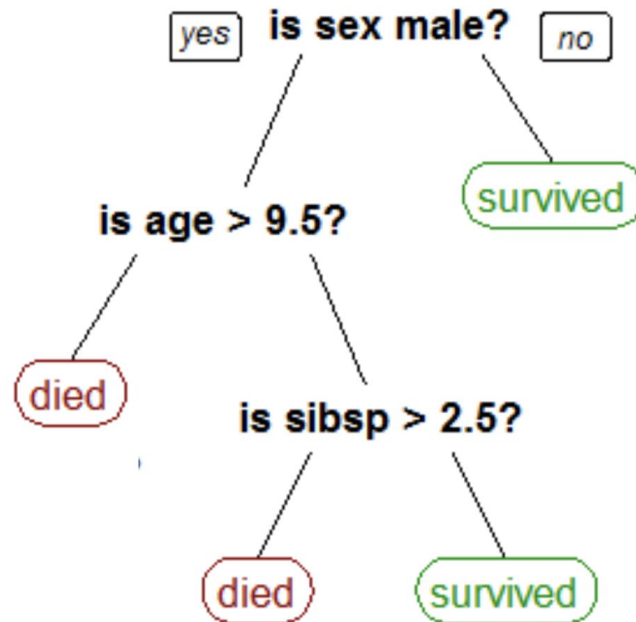
Questions?



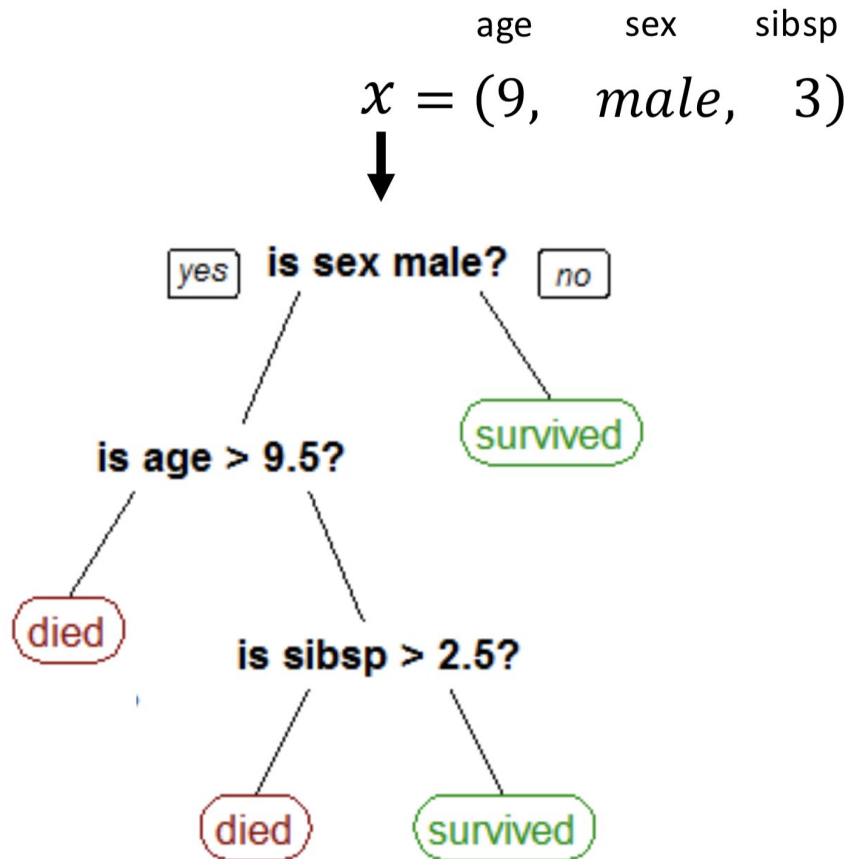
Decision tree



$x = (9, \text{ male}, 3)$



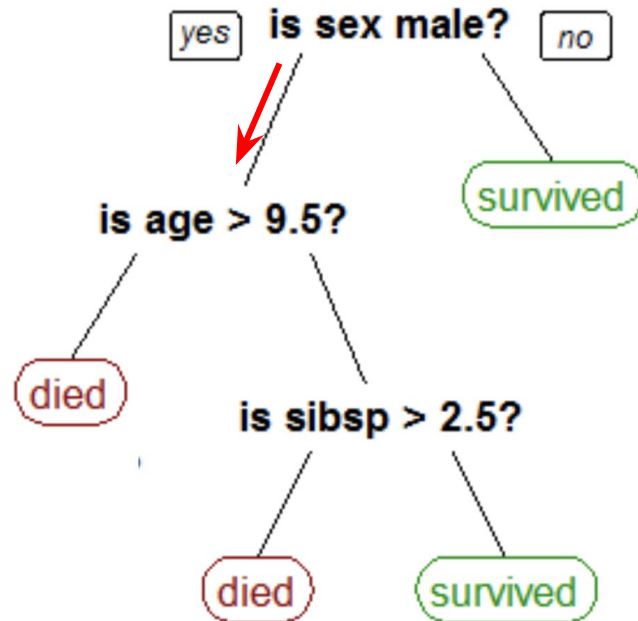
Decision tree



Decision tree



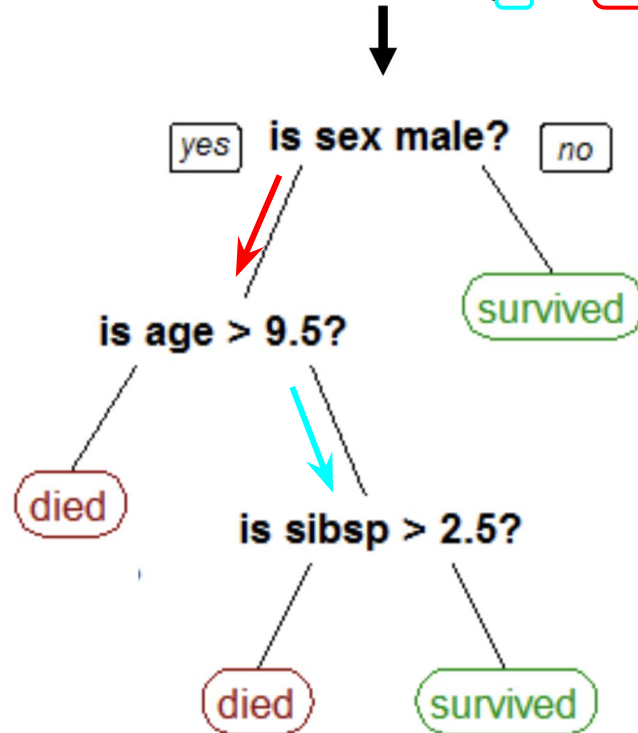
age sex sibsp
 $x = (9, \text{male}, 3)$



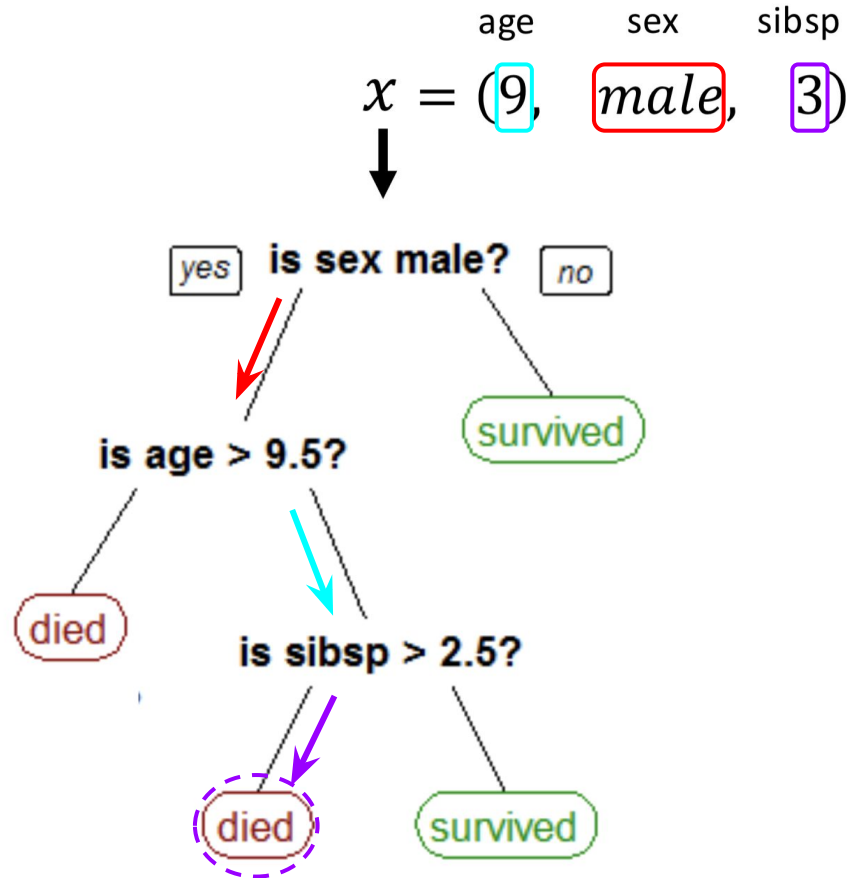
Decision tree



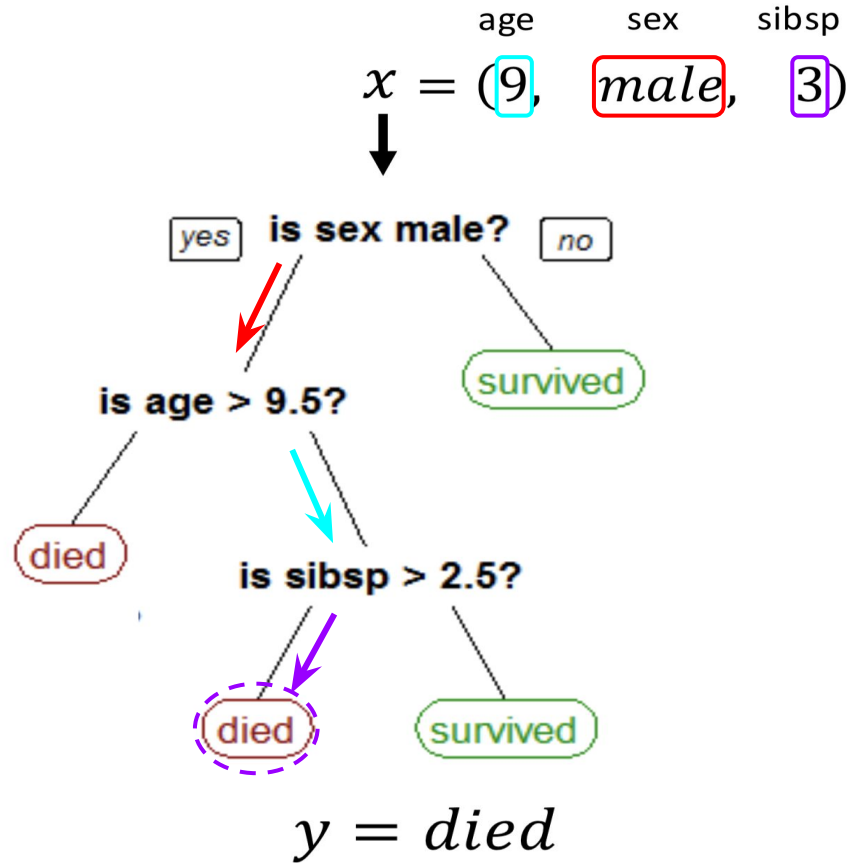
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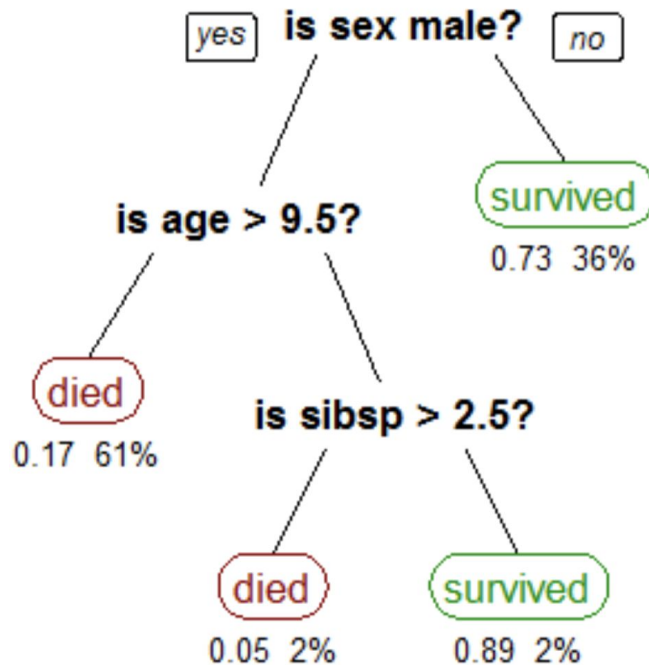
Decision tree



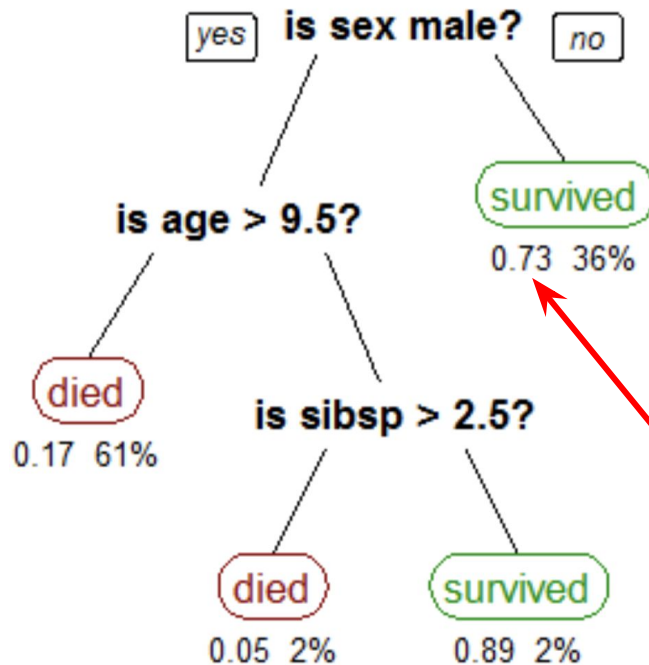
Decision tree



Decision tree in classification

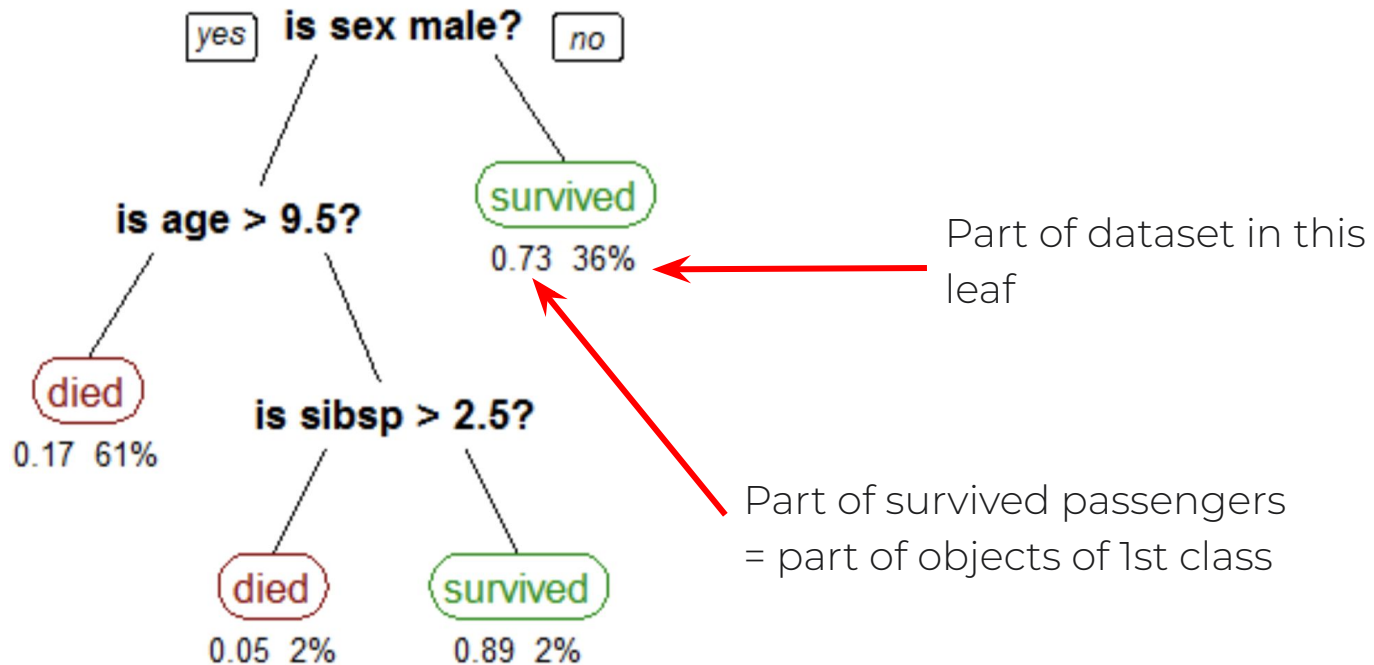


Decision tree in classification

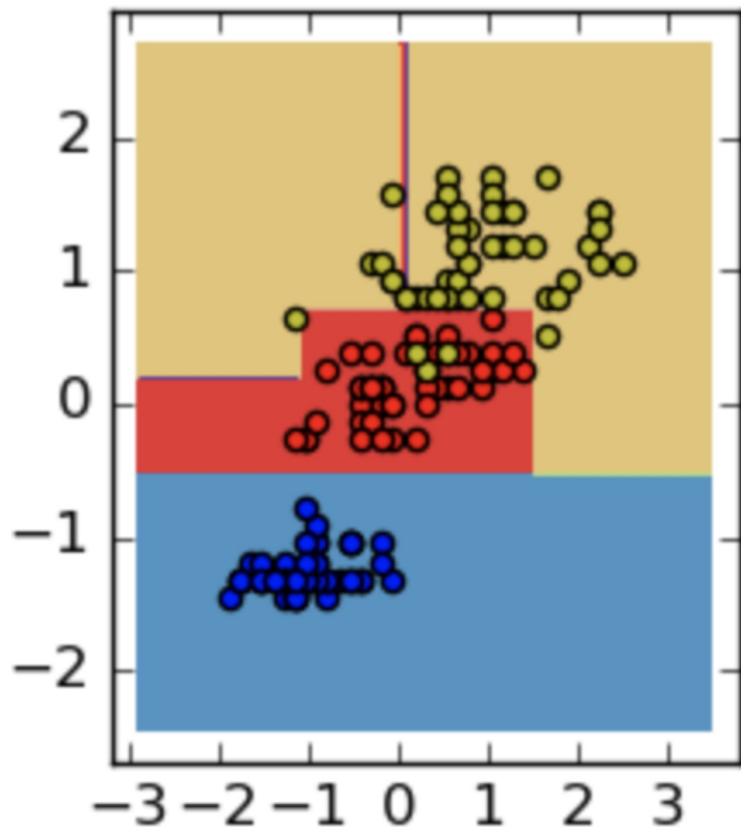


Part of survived passengers
= part of objects of 1st class

Decision tree in classification



Decision tree in classification



Classification problem with 3 classes and 2 features.