Decision trees Bagging

Radoslav Neychev



Outline

- 1. Intuition
- 2. Construction procedure
- 3. Information criteria
- 4. Special highlights
 - Dealing with missing data
 - Binarization
 - Decision tree as linear model
 - Standards
 - Hyperparameters
- 5. Bootstrap and Bagging
- 6. Random Forest



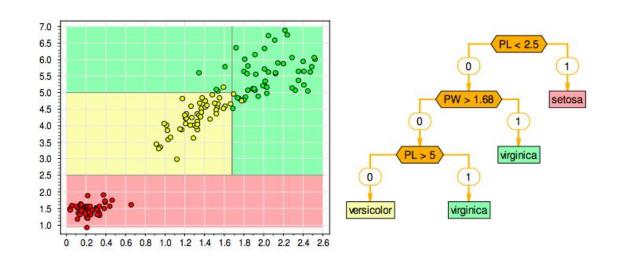
Decision Tree: intuition

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Decision tree for Iris data set

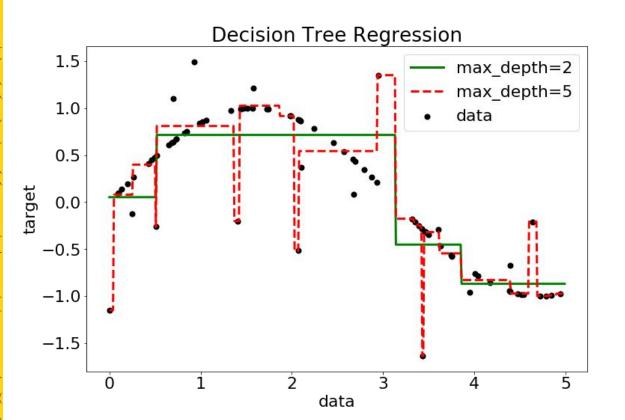




setosa
$$r_1(x) = [PL \leqslant 2.5]$$
virginica $r_2(x) = [PL > 2.5] \land [PW > 1.68]$ virginica $r_3(x) = [PL > 5] \land [PW \leqslant 1.68]$ versicolor $r_4(x) = [PL > 2.5] \land [PL \leqslant 5] \land [PW < 1.68]$

Decision tree in regression





Green - decision tree of depth 2

Red - decision tree of depth 5

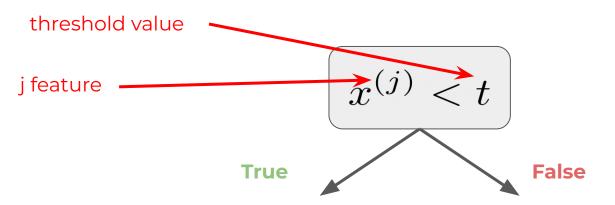
Every leaf corresponds to some constant.

Construction procedure

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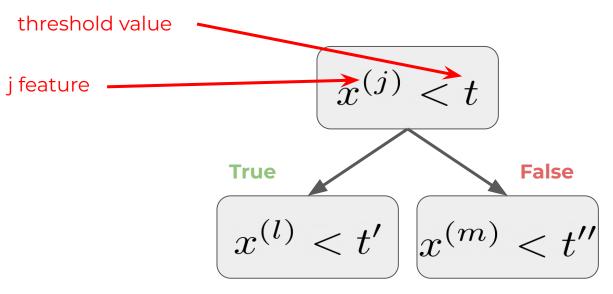






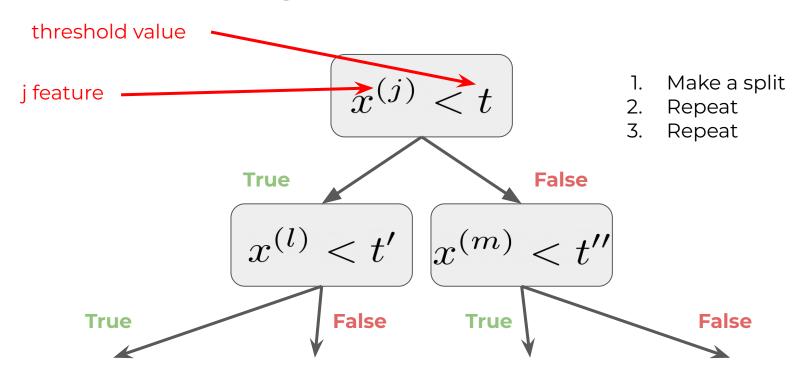
1. Make a split



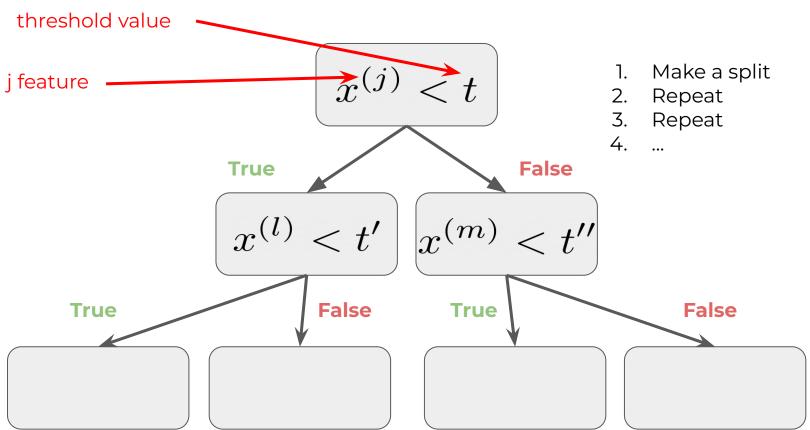


- 1. Make a split
- 2. Repeat











threshold value

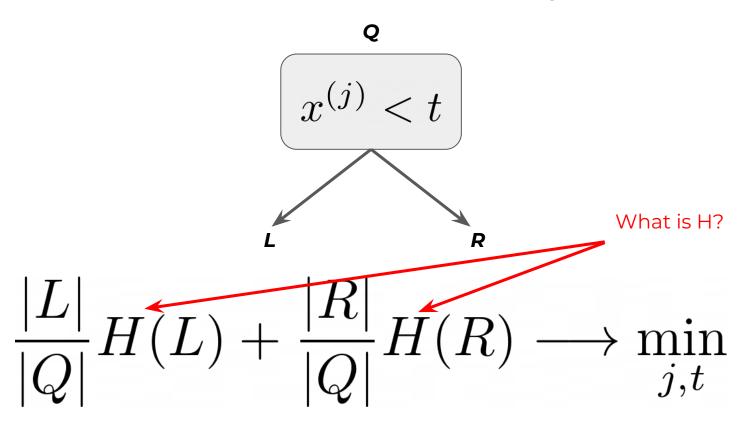
i feature

WHAT IF I TOLD YOU TO TELL ME THAT I SHOULD TELL YOU WHAT IF I TOLD YOU

True

How to split data properly?





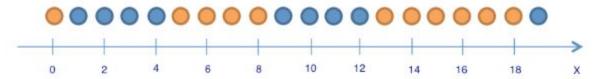
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H(R) is measure of "heterogeneity" of our data.

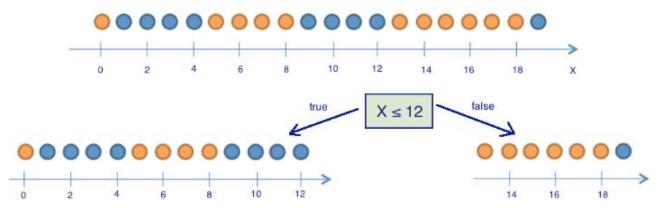
Consider binary classification problem:





H(R) is measure of "heterogeneity" of our data.

Consider binary classification problem:





H(R) is measure of "heterogeneity" of our data.

Consider binary classification problem:

Obvious way:

Misclassification criteria:

$$H(R) = 1 - \max\{p_0, p_1\}$$

1. Entropy criteria:
$$H(R) = -p_0 \log p_0 - p_1 \log p_1$$

2. Gini impurity:
$$H(R) = 1 - p_0^2 - p_1^2 = 1 - 2p_0p_1$$



H(R) is measure of "heterogeneity" of our data.

Consider multiclass classification problem:

Obvious way:

Misclassification criteria:

$$H(R) = 1 - \max_{k} \{p_k\}$$

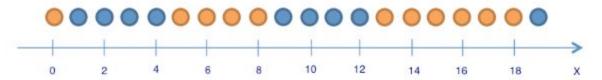
$$H(R) = -\sum_{k=0}^{\infty} p_k \log p_k$$

$$H(R) = 1 - \sum_{k} (p_k)^2$$



H(R) is measure of "heterogeneity" of our data.

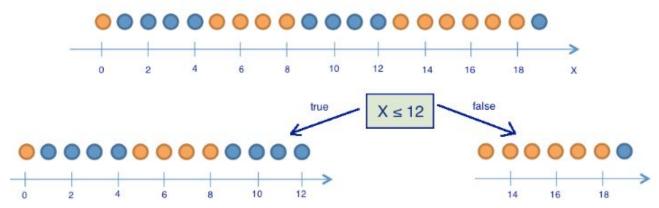
Consider binary classification problem:





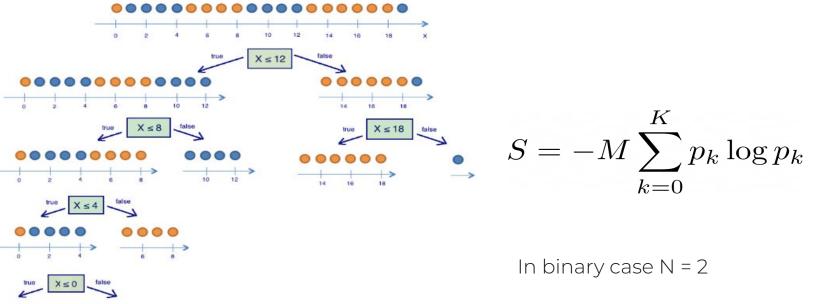
H(R) is measure of "heterogeneity" of our data.

Consider binary classification problem:



Information criteria: Entropy





$$S = -p_{+} \log_{2} p_{+} - p_{-} \log_{2} p_{-} = -p_{+} \log_{2} p_{+} - (1 - p_{+}) \log_{2} (1 - p_{+})$$

Information criteria: Gini impurity



$$G = 1 - \sum_{k} (p_k)^2$$

In binary case N = 2

$$G = 1 - p_+^2 - p_-^2 = 1 - p_+^2 - (1 - p_+)^2 = 2p_+(1 - p_+)$$



H(R) is measure of "heterogeneity" of our data.

Consider multiclass classification problem:

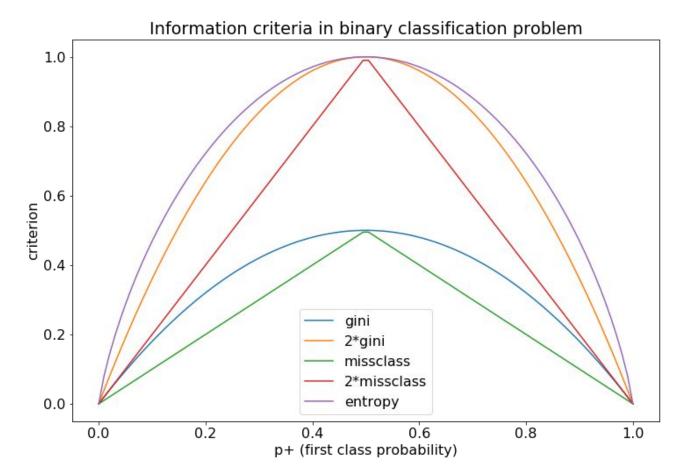
Obvious way: Misclassification criteria:

$$H(R) = 1 - \max_{k} \{p_k\}$$

1. Entropy criteria:
$$H(R) = -\sum_k p_k \log_2 p_k$$

2. Gini impurity:
$$H(R) = 1 - \sum_{k} (p_k)^2$$







H(R) is measure of "heterogeneity" of our data.

Consider regression problem:

1. Mean squared error

$$H(R) = \min_{c} \frac{1}{|R|} \sum_{(x_i, y_i) \in R} (y_i - c)^2$$

What is the constant?

$$c^* = \frac{1}{|R|} \sum_{y_i \in R} y_i$$

Special highlights

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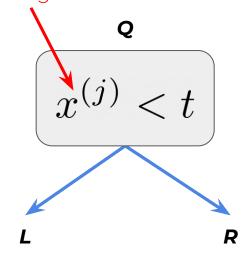
Missing values in Decision Trees



If the value is missing, one might use both sub-trees and average their predictions.

But this will negatively affect model computational performance.

Missing value



$$\hat{y} = \frac{|L|}{|Q|} \hat{y}_L + \frac{|R|}{|Q|} \hat{y}_R$$

Missing values in Catboost



Forbidden: Missing values are not supported, their presence is interpreted as an error

Min: Missing values are processed as the minimum value (less than all other values) for the feature. It is guaranteed that a split that separates missing values from all other values is considered when selecting trees.

Max: Missing values are processed as the maximum value (greater than all other values) for the feature. It is guaranteed that a split that separates missing values from all other values is considered when selecting trees.

The **default** processing mode **is Min**

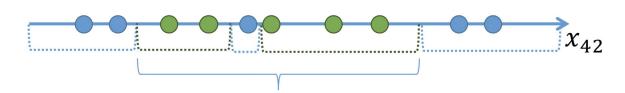
Documentation

Binarization



Idea: instead selecting one threshold define several for one feature.





e.g. <u>Border count hyperparameter</u> in Catboost (defaults to 254)

Decision Trees as Linear models



Let J be the subspace of the original feature space, corresponding to the leaf of the tree.

Prediction takes form

$$\hat{y} = \sum_{j} w_j [x \in J_j]$$

Standards



- ID-3
 - o Entropy criteria; Stops when no more gain available
- C4.5
 - Normalised entropy criteria; Stops depending on leaf size; Incorporates pruning
- C5.0
 - Some updates on C4.5
- CART
 - Gini criteria; Cost-complexity Pruning; Surrogate predicates for missing data;
- etc.

Hyperparameters

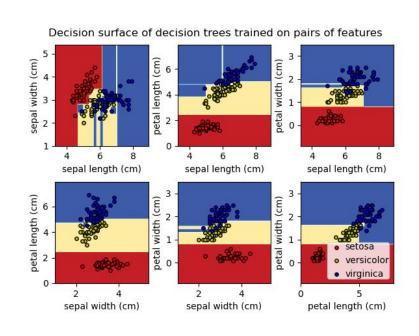


- max_depth: min 1
- min_samples_split: min 2
- min_samples_leaf: min 1
- min_impurity_decrease

Minor

- criterion:
 - o gini, entropy, log_loss for classification
 - MSE or MAE for regression
- splitter: best, random
- max_features: sqrt, log2

As of sklearn implementation



Bootstrap and Bagging

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Bootstrap



Consider dataset X containing m objects.

Pick m objects with return from X and repeat in N times to get N datasets.

Error of model trained on Xj:
$$\varepsilon_j(x) = b_j(x) - y(x), \qquad j = 1, \ldots, N,$$

Then
$$\mathbb{E}_x(b_j(x)-y(x))^2=\mathbb{E}_x\varepsilon_j^2(x)$$
.

The mean error of N models:
$$E_1=rac{1}{N}\sum_{j=1}^N \mathbb{E}_x arepsilon_j^2(x).$$

Bootstrap



Consider the errors unbiased and uncorrelated:

$$\mathbb{E}_x \varepsilon_j(x) = 0;$$

$$\mathbb{E}_x \varepsilon_i(x) \varepsilon_j(x) = 0, \quad i \neq j.$$

$$a(x) = \frac{1}{N} \sum_{i=1}^{N} b_j(x).$$

Error decreased by N times!

$$E_{N} = \mathbb{E}_{x} \left(\frac{1}{N} \sum_{j=1}^{n} b_{j}(x) - y(x) \right)^{2} =$$

$$= \mathbb{E}_{x} \left(\frac{1}{N} \sum_{j=1}^{N} \varepsilon_{j}(x) \right)^{2} =$$

$$= \frac{1}{N^{2}} \mathbb{E}_{x} \left(\sum_{j=1}^{N} \varepsilon_{j}^{2}(x) + \sum_{i \neq j} \varepsilon_{i}(x) \varepsilon_{j}(x) \right) =$$

Bootstrap



Consider the errors unbiased and unc

$$\mathbb{E}_x \varepsilon_j(x) = 0;$$

 $\mathbb{E}_x \varepsilon_i(x) \varepsilon_j(x) = 0, \quad i \neq j.$

This is a lie

$$E_N = \mathbb{E}_x \left(\frac{1}{N} \sum_{j=1}^n b_j(x) - y(x) \right)^2 = 0$$

The final model averages all predictions:

$$a(x) = \frac{1}{N} \sum_{j=1}^{N} b_j(x).$$

Error decreased by N times!

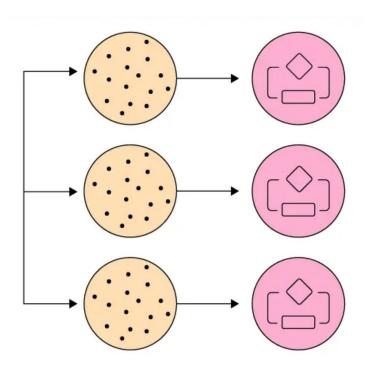
$$= \mathbb{E}_{x} \left(\frac{1}{N} \sum_{j=1}^{N} \varepsilon_{j}(x) \right)^{2} =$$

$$= \frac{1}{N^{2}} \mathbb{E}_{x} \left(\sum_{j=1}^{N} \varepsilon_{j}^{2}(x) + \underbrace{\sum_{i \neq j} \varepsilon_{i}(x) \varepsilon_{j}(x)}_{=0} \right) =$$

Bagging = Bootstrap aggregating

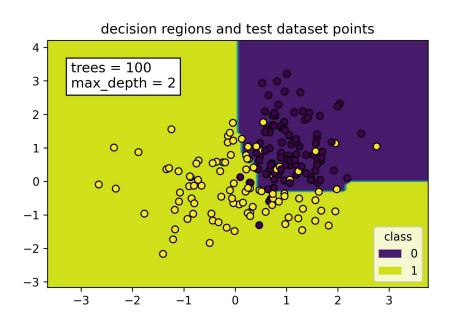


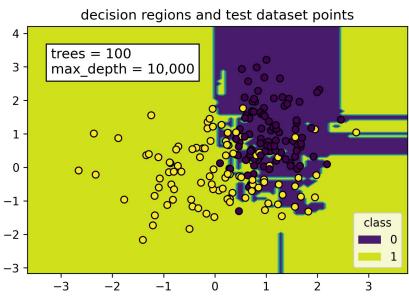
Decreases the variance if the basic algorithms are not correlated



Bagging overfitting







Random Forest

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RSM - Random Subspace Method

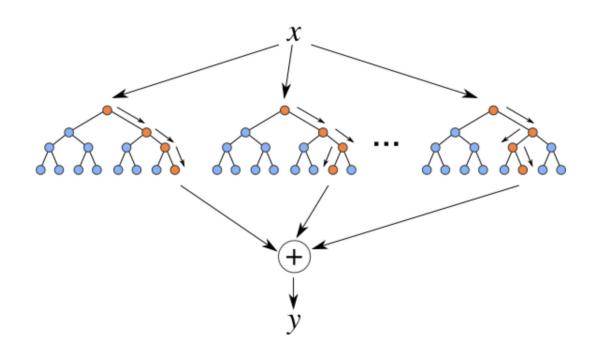


Same approach, but with features

Random Forest



Bagging + RSM = Random Forest



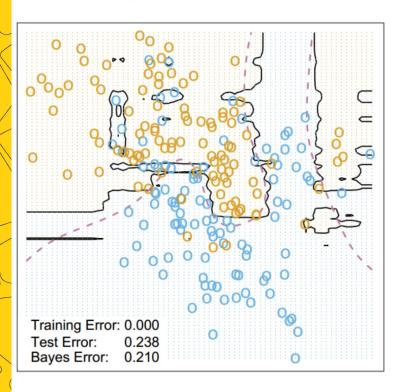
Random Forest



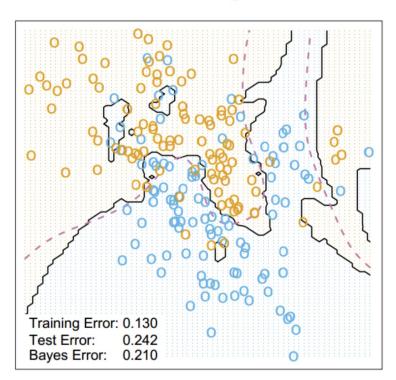
- One of the greatest "universal" models
- There are some modifications: Extremely Randomized Trees, Isolation Forest, etc



Random Forest Classifier



3-Nearest Neighbors



Revise

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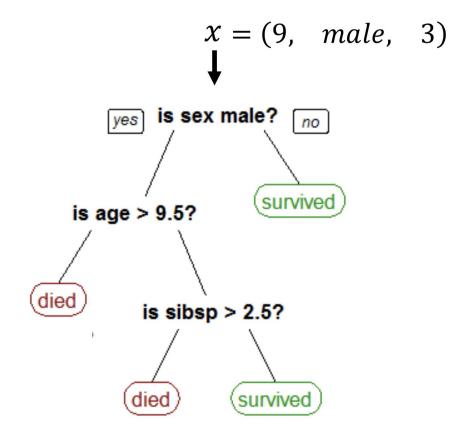
Thanks for attention!

Questions?

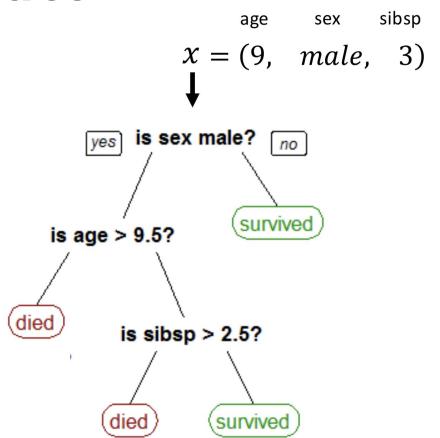




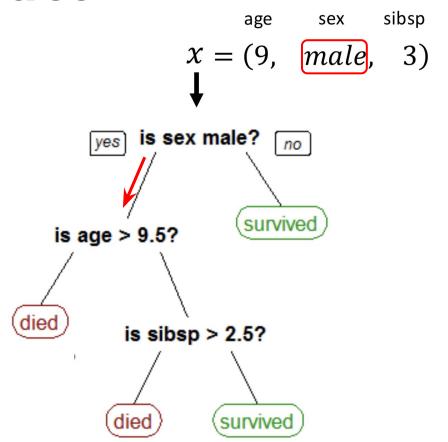




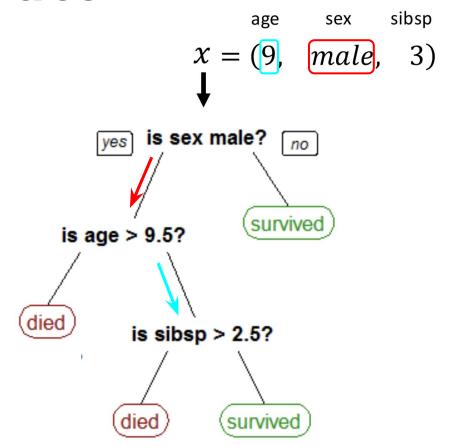




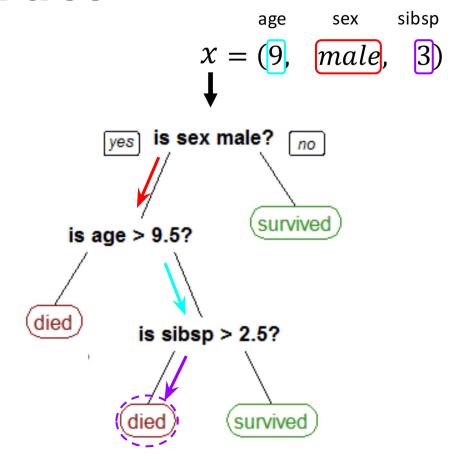




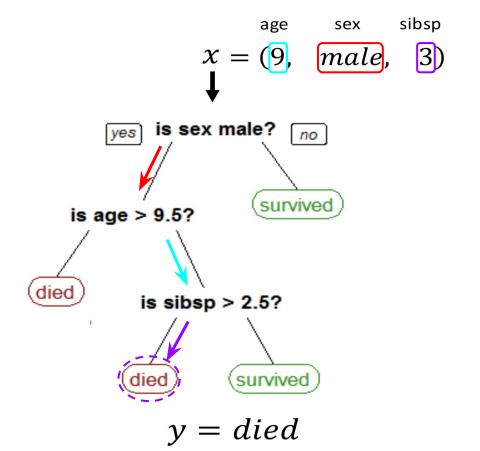




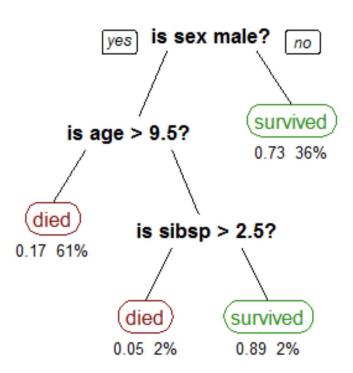




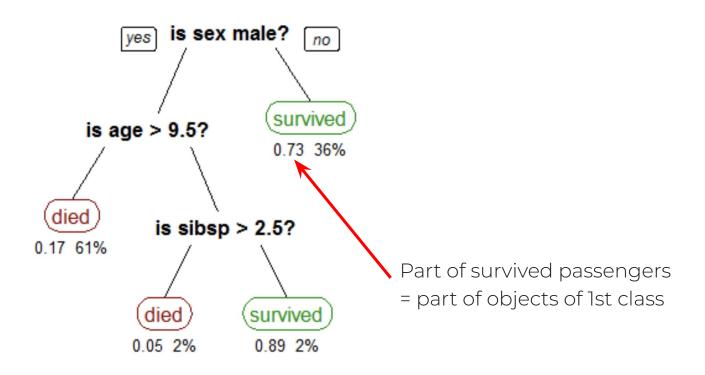




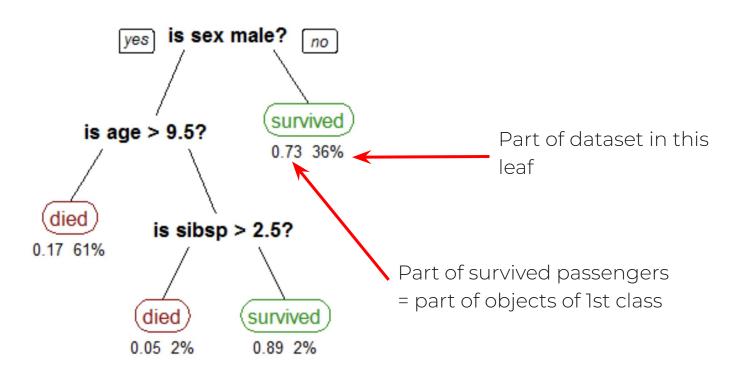




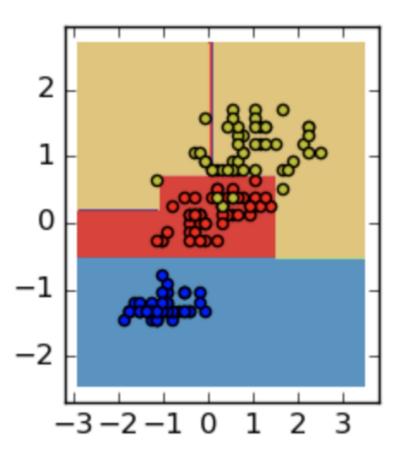












Classification problem with 3 classes and 2 features.