Complex Networks

Project 2

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1 Introduction

The Kuramoto model is a mathematical model used to describe the collective behavior of N coupled oscillators. Each oscillator is represented by a phase angle θ_i , which evolves over time according to the following equation¹:

$$\frac{d}{dt}\theta_i(t) = \omega_i + \frac{K}{N} \sum_{i} \sin(\theta_j(t) - \theta_i(t))$$
 (1)

with i = 1, ..., N, the frequencies ω_i are i.i.d random variables and K the coupling constant.

If the coupling K is small each oscillator rotates with its natural frequency ω_i , whereas for large coupling K almost all angles θ_i will be entrained by the mean field and the oscillators synchronize. This model emphasises a phase transition, such that it will exist a critical value of the coupling K_c where for $K > K_c$ the system is synchronized $(\dot{\theta_i} = \dot{\theta})$, while for $K < K_c$ no such state exists.

In this project we study first a simple case where the natural frequencies of the rotators are known and in the second part, when they are sampled from a probability distribution $g(\omega)$.

2 Theory: Kuramoto model

2.1 Lyapunov Function

In this first half we concentrate on phase locking state and exhibit a Lyapunov function. One can define the arithmetical² mean frequency to be:

$$\bar{\omega} := \frac{1}{N} \sum_{i=1}^{N} \omega_i \tag{2}$$

and intuitively think that it is the common frequency of the phase locked component. In fact,

$$\frac{d}{dt} \left(\frac{1}{N} \sum_{i=1}^{N} \theta_i(t) \right) = \left(\frac{1}{N} \sum_{i=1}^{N} \frac{d}{dt} \theta_i(t) \right)$$

from equation ??:

$$= \left(\frac{1}{N}\sum_{i}\omega_{i}\right) + \frac{K}{N^{2}}\sum_{i,j}\sin(\theta_{j}(t) - \theta_{i}(t))$$

Since i, j = 1, ..., N, in the calculations one encounters the terms $\theta_i - \theta_j$ as well $\theta_j - \theta_i$ and since the sum is and odd function:

$$\sin(\theta_i - \theta_i) = -\sin(\theta_i - \theta_i)$$

hence the term i, j and j, i cancels out. More precisely, we can separate the initial sum:

$$\sum_{i>j} \sin(\theta_j - \theta_i) + \sum_{i< j} \sin(\theta_j - \theta_i)$$

exchanging i with j in the second one we get $\sum_{j < i} \sin(\theta_i - \theta_j) = -\sum_{j < i} \sin(\theta_j - \theta_i)$ which is exactly equal to the first term in the sum. we then are left with:

$$\frac{d}{dt}\left(\frac{1}{N}\sum_{i=1}^{N}\theta_i(t)\right) = \frac{1}{N}\sum_{i=1}^{N}\omega_i = \bar{\omega}$$
 (3)

Now one can consider the new variables ϕ_i in the reference frame rotating with $\omega = \bar{\omega}$:

$$\phi_i(t) = \theta_i(t) - om\bar{e}gat$$

so that the Kuramoto model becomes:

$$\frac{d\phi_i}{dt}(t) = (\omega_i - \bar{\omega}) + \frac{K}{N} \sum_{j=1}^{N} \sin(\phi_j(t) - \phi_i(t))$$
 (4)

At this point we can introduce the Lyapunov function to study the nature of stable points (if they exists):

$$\mathcal{H} := -\frac{K}{2N} \sum_{i,j} \cos(\phi_i - \phi_j) - \sum_{i=1}^{N} (\omega_i - \bar{\omega}) \phi_i.$$
 (5)

To be a good guess for a Lyapunov Function must satisfy:

$$\dot{\mathcal{H}} = \sum_{l=1}^{N} \frac{\partial \mathcal{H}}{\partial \phi_l} \frac{d\phi_l}{dt} \le 0, \tag{6}$$

for any solution ϕ_i .

The term $\frac{d\phi_l}{dt}$ is given by eq. (??), while the term $\frac{\partial \mathcal{H}}{\partial \phi_l}$ is:

$$\frac{\partial \mathcal{H}}{\partial \phi_l} = +\frac{K}{2N} \sum_{i,j} \sin(\phi_i - \phi_j) \, \delta_{i,l}$$
$$-\sum_{i=1}^{N} (\omega_i - \bar{\omega}) \, \delta_{i,l}$$
$$= -\frac{K}{2N} \sum_{j} \sin(\phi_j - \phi_l) - (\omega_l - \bar{\omega})$$

one can notice that this term is equal to eq. ?? except for a global minus sign³. Therefore:

$$\dot{\mathcal{H}} = -\sum_{l=1}^{N} \left(\frac{\partial \mathcal{H}}{\partial \phi_l} \right)^2$$

which is non positive.

Moreover we can write down the equation for the extreme points, and check their nature:

$$\nabla \mathcal{H} = 0 = \frac{K}{2N} \sum_{i} \sin(\phi_j - \phi_l) + (\omega_l - \bar{\omega})$$

¹The original Kuramoto model was developed with the sin function. Nonetheless Kuramoto showed that for any system of weakly coupled, nearly limit-cycle oscillators, long term dynamics are given by phase equations where the sin term is replaced by a generic function $\Gamma_{ij}(\theta_j - \theta_i)$, generalysing the model

 $^{^2 \}text{This}$ is an aritmetical mean, however as $N \to \infty$ the quantity $\bar{\omega})$ is a nonrandom number and equals the mean $\int d\mu(\omega)\omega$ by the strong law of large numbers.

³This means that $\phi_i = -\nabla \mathcal{H}$ we can represent the dynamics of the system thought the Lyapunov function which now can be considered as a potential