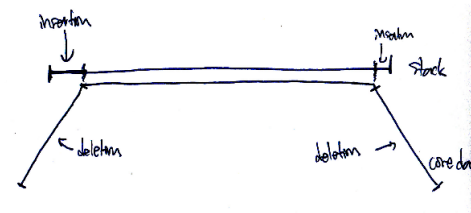
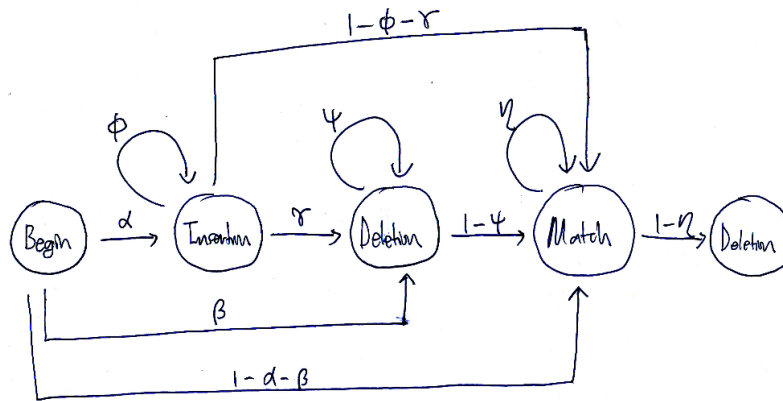


Supplementary Note: Detailed Computations

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- K : number of cores
- T : number of discretized age indices in the stack
- N_i : number of discretized depth indices in the core i
- $\{A_t\}_{t=1}^T$: ages assigned to age indices in the stack
- $\{\mu_t\}_{t=1}^T$: means of $\delta^{18}\text{O}$ concentrations assigned to age indices in the stack
- $\{\sigma_t\}_{t=1}^T$: standard deviations of $\delta^{18}\text{O}$ concentrations assigned to age indices in the stack
- τ_i : shifts of $\delta^{18}\text{O}$ concentrations assigned to the core i
- $\{d_n^{(i)}\}_{n=1}^{N_i}$: depths assigned to depth indices in the core i
- $\{v_n^{(i)}\}_{n=1}^{N_i}$: $\delta^{18}\text{O}$ assigned to depth indices in the core i
- $\{(a_n^{(i)}, b_n^{(i)})\}_{n=1}^{N_i}$: confidence intervals of ages inferred by radiocarbon data assigned to depth indices in the core i
- $\{C_n^{(i)}\}_{n=1}^{N_i}$: (hidden) ages assigned to depth indices in the core i
- R_i : average sedimentation rate in the core i
- $\alpha_i, \beta_i, \gamma_i, \phi_i, \psi_i, \eta_i, \delta_i$: transition parameters for the core i , where



1. Forward Algorithm:

1.1. Initialization:

1.1.1. For each $s \in \{1, 2, \dots, T\}$,

$$\begin{aligned}
\mathbf{F}_i(\mathbf{2}, \mathbf{1}, s) &\triangleq p\left(v_{1:2}^{(i)}, C_1^{(i)} = A_1, C_2^{(i)} = A_s, 1 \text{ was not skipped} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\
&= p(v_2^{(i)} | C_2^{(i)} = A_s) p(C_2^{(i)} = A_s | C_1^{(i)} = A_1, d_1^{(i)}, d_2^{(i)}, a_2^{(i)}, b_2^{(i)}) p(v_1^{(i)} | C_1^{(i)} = A_1) p(C_1^{(i)} = A_1 | a_1^{(i)}, b_1^{(i)}) p(1 \text{ was not skipped}) \\
&= \begin{cases} \mathbf{N}(v_2^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{N}(v_1^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{1}_{\{A_s \in (a_2^{(i)}, b_2^{(i)})\}} \cdot \mathbf{1}_{\{A_1 \in (a_1^{(i)}, b_1^{(i)})\}} \cdot \mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_1}{R_i(d_2^{(i)} - d_1^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_s - A_1}{R_i(d_2^{(i)} - d_1^{(i)})}\right) \cdot (1 - \alpha_i - \beta_i), & s > 1 \\ \mathbf{N}(v_2^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{N}(v_1^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{1}_{\{A_1 \in (a_2^{(i)}, b_2^{(i)})\}} \cdot \mathbf{1}_{\{A_1 \in (a_1^{(i)}, b_1^{(i)})\}} \cdot \mathbf{1}_{\{0.125 \leq R_i(d_2^{(i)} - d_1^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_2^{(i)} - d_1^{(i)})}\right) \cdot (1 - \alpha_i - \beta_i), & s = 1 \end{cases}
\end{aligned}$$

1.1.2. For each $n \in \{3, 4, \dots, N_i\}$ and $s \in \{1, 2, \dots, T\}$,

$$\begin{aligned}
\mathbf{F}_i(\mathbf{n}, \mathbf{1}, s) &\triangleq p\left(v_{1:n}^{(i)}, C_{n-1}^{(i)} = A_1, C_n^{(i)} = A_s, 1:(n-2) \text{ were not aligned} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\
&= p(v_n^{(i)} | C_n^{(i)} = A_s) p(C_n^{(i)} = A_s | C_{n-1}^{(i)} = A_1, d_{n-1}^{(i)}, d_n^{(i)}, a_n^{(i)}, b_n^{(i)}) p(v_{n-1}^{(i)} | C_{n-1}^{(i)} = A_1) p(C_{n-1}^{(i)} = A_1 | a_{n-1}^{(i)}, b_{n-1}^{(i)}) p(1:(n-2) \text{ were not aligned}) \\
&= \begin{cases} \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{N}(v_{n-1}^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{1}_{\{A_s \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\{A_1 \in (a_{n-1}^{(i)}, b_{n-1}^{(i)})\}} \cdot \mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_1}{R_i(d_n^{(i)} - d_{n-1}^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_s - A_1}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot \beta_i \psi_i^{n-2} \delta_i^{n-2} \cdot (1 - \psi_i), & s > 1 \\ \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{N}(v_{n-1}^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_1, \boldsymbol{\sigma}_1) \cdot \mathbf{1}_{\{A_1 \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\{A_1 \in (a_{n-1}^{(i)}, b_{n-1}^{(i)})\}} \cdot \mathbf{1}_{\{0.125 \leq R_i(d_n^{(i)} - d_{n-1}^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot \beta_i \psi_i^{n-2} \delta_i^{n-2} \cdot (1 - \psi_i), & s = 1 \end{cases}
\end{aligned}$$

1.1.3. For each $t, s \in \{2, 3, \dots, T\}$,

$$\begin{aligned}
\mathbf{F}_i(\mathbf{2}, \mathbf{t}, s) &\triangleq p\left(v_{1:2}^{(i)}, C_1^{(i)} = A_t, C_2^{(i)} = A_s, 1:(t-1) \text{ were skipped}, t \text{ was not skipped} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\
&= p(v_2^{(i)} | C_2^{(i)} = A_s) p(C_2^{(i)} = A_s | C_1^{(i)} = A_t, d_1^{(i)}, d_2^{(i)}, a_2^{(i)}, b_2^{(i)}) p(v_1^{(i)} | C_1^{(i)} = A_t) p(C_1^{(i)} = A_t | a_1^{(i)}, b_1^{(i)}) p(1:(t-1) \text{ were skipped}, t \text{ was not skipped})
\end{aligned}$$

$$= \begin{cases} \mathbf{N}\left(v_2^{(i)} \middle| \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s\right) \cdot \mathbf{N}\left(v_1^{(i)} \middle| \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_t, \boldsymbol{\sigma}_t\right) \cdot \mathbf{1}_{\{A_s \in (a_2^{(i)}, b_2^{(i)})\}} \cdot \mathbf{1}_{\{A_t \in (a_1^{(i)}, b_1^{(i)})\}} \cdot \mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_t}{R_i(d_2^{(i)} - d_1^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_s - A_t}{R_i(d_2^{(i)} - d_1^{(i)})}\right) \cdot \alpha_i \phi_i^{t-1} \cdot (1 - \phi_i - \gamma_i) \cdot (1 - \phi_i), & s > t \\ \mathbf{N}\left(v_2^{(i)} \middle| \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s\right) \cdot \mathbf{N}\left(v_1^{(i)} \middle| \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s\right) \cdot \mathbf{1}_{\{A_s \in (a_2^{(i)}, b_2^{(i)})\}} \cdot \mathbf{1}_{\{A_s \in (a_1^{(i)}, b_1^{(i)})\}} \cdot \mathbf{1}_{\{0.125 \leq R_i(d_2^{(i)} - d_1^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_2^{(i)} - d_1^{(i)})}\right) \cdot \alpha_i \phi_i^{s-1} \cdot (1 - \phi_i - \gamma_i) \cdot (1 - \phi_i), & s = t \end{cases}$$

1.2. Iterations: for each $n \in \{3, 4, \dots, N_i\}$ and $t, s \in \{2, 3, \dots, T\}$,

$$\begin{aligned} & \mathbf{F}_i(\mathbf{n}, \mathbf{t}, \mathbf{s}) \triangleq p\left(v_{1:n}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= p\left(v_{1:n}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s, \text{staying in the match state} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) + p\left(v_{1:n}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s, 1: (n-2) \text{ were not aligned} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ & \quad p\left(v_{1:n}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s, \text{staying in the match state} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= \sum_{u=1}^T p(v_n^{(i)} | C_n^{(i)} = A_s) p(C_n^{(i)} = A_s | C_{n-2}^{(i)} = A_u, C_{n-1}^{(i)} = A_t, d_{n-2}^{(i)}, d_{n-1}^{(i)}, a_n^{(i)}, b_n^{(i)}) p\left(v_{1:n-1}, C_{n-2}^{(i)} = A_u, C_{n-1}^{(i)} = A_t \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) p(\text{staying in the match state}) \\ &= \begin{cases} \eta_i \cdot \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{1}_{\{A_s \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_t}{R_i(d_n^{(i)} - d_{n-1}^{(i)})} \leq 4\right\}} \left[\mathbf{1}_{\{0.125 \leq R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})}, \frac{A_s - A_t}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot F_i(n-1, t, t) + \sum_{u \neq t} \left(\mathbf{1}_{\left\{0.25 \leq \frac{A_t - A_u}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_t - A_u}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})}, \frac{A_s - A_t}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot F_i(n-1, u, t) \right) \right], & s > t \\ \eta_i \cdot \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{1}_{\{A_s \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\{0.125 \leq R_i(d_n^{(i)} - d_{n-1}^{(i)}) \leq 2\}} \left[\mathbf{1}_{\{0.125 \leq R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})}, \frac{0.5}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot F_i(n-1, s, s) + \sum_{u \neq s} \left(\mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_u}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_s - A_u}{R_i(d_{n-1}^{(i)} - d_{n-2}^{(i)})}, \frac{0.5}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot F_i(n-1, u, s) \right) \right], & s = t \end{cases} \\ & \quad p\left(v_{1:n}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s, 1: (n-2) \text{ were not aligned} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= p(v_n^{(i)} | C_n^{(i)} = A_s) p(C_n^{(i)} = A_s | C_{n-1}^{(i)} = A_t, d_{n-1}^{(i)}, d_n^{(i)}, a_n^{(i)}, b_n^{(i)}) p(v_{n-1}^{(i)} | C_{n-1}^{(i)} = A_t) p(C_{n-1}^{(i)} = A_t | a_{n-1}^{(i)}, b_{n-1}^{(i)}) p(1: (n-2) \text{ were not aligned}) \\ &= \begin{cases} \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{N}(v_{n-1}^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_t, \boldsymbol{\sigma}_t) \cdot \mathbf{1}_{\{A_s \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\{A_t \in (a_{n-1}^{(i)}, b_{n-1}^{(i)})\}} \cdot \mathbf{1}_{\left\{0.25 \leq \frac{A_s - A_t}{R_i(d_n^{(i)} - d_{n-1}^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_s - A_t}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot \alpha_i \phi_i^{t-1} \cdot \gamma_i \psi_i^{n-2} \delta_i^{n-2} \cdot (1 - \psi_i), & s > t \\ \mathbf{N}(v_n^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{N}(v_{n-1}^{(i)} | \boldsymbol{\tau}^{(i)} + \boldsymbol{\mu}_s, \boldsymbol{\sigma}_s) \cdot \mathbf{1}_{\{A_s \in (a_n^{(i)}, b_n^{(i)})\}} \cdot \mathbf{1}_{\{A_s \in (a_{n-1}^{(i)}, b_{n-1}^{(i)})\}} \cdot \mathbf{1}_{\{0.125 \leq R_i(d_n^{(i)} - d_{n-1}^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_n^{(i)} - d_{n-1}^{(i)})}\right) \cdot \alpha_i \phi_i^{t-1} \cdot \gamma_i \psi_i^{n-2} \delta_i^{n-2} \cdot (1 - \psi_i), & s = t \end{cases} \end{aligned}$$

1.3. Termination:

1.3.1. for each $n \in \{2, 3, \dots, N_i - 1\}$ and $t, s \in \{1, 2, \dots, T\}$,

$$\begin{aligned} \mathbf{E}_i(\mathbf{n}, \mathbf{t}, \mathbf{s}) &\triangleq p\left(v_{1:N_i}^{(i)}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s, (n+1):N_i \text{ were not aligned} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= p\left(v_{n+1:N_i}^{(i)}, (n+1):N_i \text{ were not aligned}\right) p\left(v_{1:n}^{(i)}, C_{n-1}^{(i)} = A_t, C_n^{(i)} = A_s \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) = (\mathbf{1} - \boldsymbol{\eta}_i) \cdot \boldsymbol{\delta}_i^{N_i - n} \cdot \mathbf{F}_i(\mathbf{n}, \mathbf{t}, \mathbf{s}) \end{aligned}$$

1.3.2. for each $t, s \in \{1, 2, \dots, T\}$,

$$\mathbf{E}_i(\mathbf{N}_i, \mathbf{t}, \mathbf{s}) \triangleq p\left(v_{1:N_i}^{(i)}, C_{N_i-1}^{(i)} = A_t, C_{N_i}^{(i)} = A_s \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) = \mathbf{F}_i(\mathbf{N}_i, \mathbf{t}, \mathbf{s})$$

2. Backward Sampling:

2.1. Initialization: for each $m \in \{2, 3, \dots, N_i\}$ and $t_{m-1}^{(i),(l)}, t_m^{(i),(l)} \in \{1, 2, 3, \dots, T\}$,

$$\begin{aligned} &\mathbb{P}\left(\mathbf{C}_{m-1}^{(i),(l)} = \mathbf{A}_{t_{m-1}^{(i),(l)}}, \mathbf{C}_m^{(i),(l)} = \mathbf{A}_{t_m^{(i),(l)}} \middle| v_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}, d_{1:N_i}^{(i)}\right) \\ &\propto p\left(v_{1:N_i}^{(i)}, C_{m-1}^{(i),(l)} = A_{t_{m-1}^{(i),(l)}}, C_m^{(i),(l)} = A_{t_m^{(i),(l)}}, (m+1):N_i \text{ were not aligned} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= \mathbf{E}_i(\mathbf{m}, \mathbf{t}_{m-1}^{(i),(l)}, \mathbf{t}_m^{(i),(l)}) \end{aligned}$$

2.2. Iterations: for each $n \in \{m-2, m-3, \dots, 1\}$ and $t_n^{(i),(l)} \in \{1, 2, 3, \dots, T\}$,

$$\begin{aligned} &\mathbb{P}\left(\mathbf{C}_n^{(i),(l)} = \mathbf{A}_{t_n^{(i),(l)}} \middle| \mathbf{C}_{n+1}^{(i),(l)} = \mathbf{A}_{t_{n+1}^{(i),(l)}}, \mathbf{C}_{n+2}^{(i),(l)} = \mathbf{A}_{t_{n+2}^{(i),(l)}}, v_{1:n+2}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}, d_{1:N_i}^{(i)}\right) \\ &\propto \mathbb{P}\left(C_n^{(i),(l)} = A_{t_n^{(i),(l)}}, C_{n+1}^{(i),(l)} = A_{t_{n+1}^{(i),(l)}}, C_{n+2}^{(i),(l)} = A_{t_{n+2}^{(i),(l)}}, v_{1:n+2}^{(i)} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \\ &= p\left(v_{n+2}^{(i)} \middle| C_{n+2}^{(i),(l)} = A_{t_{n+2}^{(i),(l)}}\right) p\left(C_{n+2}^{(i),(l)} = A_{t_{n+2}^{(i),(l)}} \middle| C_n^{(i),(l)} = A_{t_n^{(i),(l)}}, C_{n+1}^{(i),(l)} = A_{t_{n+1}^{(i),(l)}}, d_n^{(i)}, d_{n+1}^{(i)}, d_{n+2}^{(i)}, a_{n+2}^{(i)}, b_{n+2}^{(i)}\right) p\left(C_n^{(i),(l)} = A_{t_n^{(i),(l)}}, C_{n+1}^{(i),(l)} = A_{t_{n+1}^{(i),(l)}}, v_{1:n+1}^{(i)} \middle| d_{1:N_i}^{(i)}, a_{1:N_i}^{(i)}, b_{1:N_i}^{(i)}\right) \end{aligned}$$

$$= N\left(v_{n+2}^{(i)} \middle| \tau^i + \mu_{t_{n+2}^{(i),(l)}}, \sigma_{t_{n+2}^{(i),(l)}}\right) 1_{\left\{A_{t_{n+2}^{(i),(l)}} \in (a_{n+2}^{(i)}, b_{n+2}^{(i)})\right\}} \rho\left(\frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{A_{t_{n+2}^{(i),(l)}} - A_{t_{n+1}^{(i),(l)}}}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) F_i(n+1, t_n^{(i),(l)}, t_{n+1}^{(i),(l)})$$

2.2.1. $t_{n+1}^{(i),(l)} < t_{n+2}^{(i),(l)}$:

$$= \begin{cases} N\left(v_{n+2}^{(i)} \middle| \tau^i + \mu_{t_{n+2}^{(i),(l)}}, \sigma_{t_{n+2}^{(i),(l)}}\right) \cdot 1_{\left\{A_{t_{n+2}^{(i),(l)}} \in (a_{n+2}^{(i)}, b_{n+2}^{(i)})\right\}} \cdot 1_{\left\{0.25 \leq \frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{A_{t_{n+2}^{(i),(l)}} - A_{t_{n+1}^{(i),(l)}}}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) \cdot F_i(n+1, t_n^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} < t_{n+1}^{(i),(l)} \\ N\left(v_{n+2}^{(i)} \middle| \tau^i + \mu_{t_{n+2}^{(i),(l)}}, \sigma_{t_{n+2}^{(i),(l)}}\right) \cdot 1_{\left\{A_{t_{n+2}^{(i),(l)}} \in (a_{n+2}^{(i)}, b_{n+2}^{(i)})\right\}} \cdot 1_{\{0.125 \leq R_i(d_{n+1}^{(i)} - d_n^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{A_{t_{n+2}^{(i),(l)}} - A_{t_{n+1}^{(i),(l)}}}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) F_i(n+1, t_{n+1}^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} = t_{n+1}^{(i),(l)} \end{cases}$$

$$\propto \begin{cases} 1_{\left\{0.25 \leq \frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{A_{t_{n+2}^{(i),(l)}} - A_{t_{n+1}^{(i),(l)}}}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) \cdot F_i(n+1, t_n^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} < t_{n+1}^{(i),(l)} \\ 1_{\{0.125 \leq R_i(d_{n+1}^{(i)} - d_n^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{A_{t_{n+2}^{(i),(l)}} - A_{t_{n+1}^{(i),(l)}}}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) F_i(n+1, t_{n+1}^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} = t_{n+1}^{(i),(l)} \end{cases}$$

2.2.2. $t_{n+1}^{(i),(l)} = t_{n+2}^{(i),(l)}$:

$$= \begin{cases} N\left(v_{n+2}^{(i)} \middle| \tau^i + \mu_{t_{n+2}^{(i),(l)}}, \sigma_{t_{n+2}^{(i),(l)}}\right) \cdot 1_{\left\{A_{t_{n+2}^{(i),(l)}} \in (a_{n+2}^{(i)}, b_{n+2}^{(i)})\right\}} \cdot 1_{\left\{0.25 \leq \frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{0.5}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) \cdot F_i(n+1, t_n^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} < t_{n+1}^{(i),(l)} \\ N\left(v_{n+2}^{(i)} \middle| \tau^i + \mu_{t_{n+2}^{(i),(l)}}, \sigma_{t_{n+2}^{(i),(l)}}\right) \cdot 1_{\left\{A_{t_{n+2}^{(i),(l)}} \in (a_{n+2}^{(i)}, b_{n+2}^{(i)})\right\}} \cdot 1_{\{0.125 \leq R_i(d_{n+1}^{(i)} - d_n^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{0.5}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) F_i(n+1, t_{n+1}^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} = t_{n+1}^{(i),(l)} \end{cases}$$

$$\propto \begin{cases} 1_{\left\{0.25 \leq \frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})} \leq 4\right\}} \cdot \rho\left(\frac{A_{t_{n+1}^{(i),(l)}} - A_{t_n^{(i),(l)}}}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{0.5}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) \cdot F_i(n+1, t_n^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} < t_{n+1}^{(i),(l)} \\ 1_{\{0.125 \leq R_i(d_{n+1}^{(i)} - d_n^{(i)}) \leq 2\}} \cdot \rho\left(\frac{0.5}{R_i(d_{n+1}^{(i)} - d_n^{(i)})}, \frac{0.5}{R_i(d_{n+2}^{(i)} - d_{n+1}^{(i)})}\right) F_i(n+1, t_{n+1}^{(i),(l)}, t_{n+1}^{(i),(l)}), & t_n^{(i),(l)} = t_{n+1}^{(i),(l)} \end{cases}$$

2.3. Termination: iterate the above sampling steps to get $t_m^{(i),(l)}, t_{m-1}^{(i),(l)}, \dots, t_k^{(i),(l)}$ recursively until possible.

a. If $t_{k-1}^{(i),(l)}$ was not sampled because $A_{t_k^{(i),(l)}} - 0.25R_i(d_k^{(i)} - d_{k-1}^{(i)}) < A_1$ and $1_{\{0.125 \leq R_i(d_k^{(i)} - d_{k-1}^{(i)}) \leq 2\}} = 0$, keep the samples in the form of:

$$\{(\tilde{t}_1^{(i),(l)}, \tilde{n}_1^{(i),(l)}), (\tilde{t}_2^{(i),(l)}, \tilde{n}_2^{(i),(l)}), \dots, (\tilde{t}_{m-k+1}^{(i),(l)}, \tilde{n}_{m-k+1}^{(i),(l)})\} \triangleq \{(t_k^{(i),(l)}, k), (t_{k+1}^{(i),(l)}, k+1), \dots, (t_m^{(i),(l)}, m)\}$$

b. Otherwise, discard them and go back to 2.1 for starting the sampling procedure again.

3. Updating transition parameters by ML estimators:

Suppose that we get $L^{(i)}$ samples for the core i by running the above backward sampling algorithm.

Let:

$\lambda_{i,l} \triangleq$ length of the sample l for the core i

$A \triangleq$ # of samples where $\tilde{t}_1^{(i),(l)} > 1$ and $\tilde{n}_1^{(i),(l)} > 1$

$B \triangleq$ # of samples where $\tilde{t}_1^{(i),(l)} > 1$ and $\tilde{n}_1^{(i),(l)} = 1$

$C \triangleq$ # of samples where $\tilde{t}_1^{(i),(l)} = 1$ and $\tilde{n}_1^{(i),(l)} > 1$

$D \triangleq$ # of samples where $\tilde{n}_{\lambda_{i,l}}^{(i),(l)} < N_i$

Then,

$$\begin{aligned} \hat{\alpha}_i &\triangleq \frac{A+B}{L^{(i)}}, & \hat{\beta}_i &\triangleq \frac{C}{L^{(i)}}, & \hat{\gamma}_i &\triangleq \frac{A}{A+B+\sum_{l=1}^{L^{(i)}} \tilde{t}_1^{(i),(l)} - L^{(i)}} \\ \hat{\phi}_i &\triangleq \frac{\sum_{l=1}^{L^{(i)}} \tilde{t}_1^{(i),(l)} - L^{(i)}}{A+B+\sum_{l=1}^{L^{(i)}} \tilde{t}_1^{(i),(l)} - L^{(i)}}, & \hat{\psi}_i &\triangleq \frac{\sum_{l=1}^{L^{(i)}} \tilde{n}_1^{(i),(l)} - \sum_{l=1}^{L^{(i)}} \tilde{n}_{\lambda_{i,l}}^{(i),(l)} + L^{(i)}(N_i - 1)}{(A+C) + \sum_{l=1}^{L^{(i)}} \tilde{n}_1^{(i),(l)} - \sum_{l=1}^{L^{(i)}} \tilde{n}_{\lambda_{i,l}}^{(i),(l)} + L^{(i)}(N_i - 1)}, & \hat{\eta}_i &\triangleq \frac{\sum_{l=1}^{L^{(i)}} \lambda_{i,l} - L^{(i)}}{D + \sum_{l=1}^{L^{(i)}} \lambda_{i,l} - L^{(i)}} \\ \hat{R}_i &\triangleq \frac{1}{L^{(i)}} \sum_{l=1}^{L^{(i)}} \frac{A_{\tilde{t}_{\lambda_{i,l}}^{(i),(l)}} - A_{\tilde{t}_1^{(i),(l)}}}{d_{\tilde{n}_{\lambda_{i,l}}^{(i),(l)}} - d_{\tilde{n}_1^{(i),(l)}}} \end{aligned}$$

Of course, it is possible to do above in the Bayesian style with appropriate priors. For example, if we use beta priors on α_i , the hyperparameters act like pseudo-counts, like the estimates in the next part. Priors usually contribute the stability of inferred parameters, which prevent some extreme estimations (e.g. $\pm\infty$) caused by the lack of data and reflect our strong/weak beliefs on the parameters from our past experiences.

3.1. About δ_i : its ML estimator is always 1, which is not proper to our purpose of maximizing the length of aligned data, so...

Suppose that we give a prior on $\delta_i \sim \text{Beta}(z, w)$ for some hyperparameters z and w , then

$$\hat{\delta}_i \triangleq \frac{\sum_{l=1}^{L^{(i)}} \tilde{n}_1^{(i),(l)} - \sum_{l=1}^{L^{(i)}} \tilde{n}_{\lambda_{i,l}}^{(i),(l)} + \mathbf{NL}^{(i)} - \mathbf{L}^{(i)} + \mathbf{z} - \mathbf{1}}{\sum_{l=1}^{L^{(i)}} \tilde{n}_1^{(i),(l)} - \sum_{l=1}^{L^{(i)}} \tilde{n}_{\lambda_{i,l}}^{(i),(l)} + \mathbf{NL}^{(i)} - \mathbf{L}^{(i)} + \mathbf{z} + \mathbf{w} - \mathbf{2}}$$

To make this algorithm “meaningful”, it is recommended to set $1 \approx z \ll w$, which makes $\hat{\delta}_i$ stay in the range of low values near to 0.

4. Updating stack parameters by ML estimators:

If we are only interested in aligning each core to the stack, it is just needed to learn shift parameters τ_i 's for the cores. If we are interested in constructing the new stack from the data as well, it is also required to learn means and standard deviations $\{\mu_t\}_{t=1}^T$ and $\{\sigma_t\}_{t=1}^T$. An EM algorithm can learn both the alignments and stack parameters simultaneously: to be specific, it first aligns each core to the stack by generating samples, and then updates the stack parameters by using samples.

$$\begin{aligned} \hat{\tau}_i &\triangleq \frac{\sum_{l=1}^{L^{(i)}} \sum_{s=1}^{\lambda_{i,l}} \left(v_{\tilde{n}_s^{(i),(l)}}^{(i)} - \tilde{\mu}_{\tilde{\tau}_s^{(i),(l)}} \right)}{\sum_{l=1}^{L^{(i)}} \lambda_{i,l}} \\ \hat{\mu}_t &\triangleq \frac{\sum_{i=1}^K \sum_{l=1}^{L^{(i)}} \sum_{s=1}^{\lambda_{i,l}} \left(v_{\tilde{n}_s^{(i),(l)}}^{(i)} - \hat{\tau}_i \right) \mathbf{1}_{\{\tilde{\tau}_s^{(i),(l)}=t\}}}{\sum_{i=1}^K \sum_{l=1}^{L^{(i)}} \sum_{s=1}^{\lambda_{i,l}} \mathbf{1}_{\{\tilde{\tau}_s^{(i),(l)}=t\}}} \\ \hat{\sigma}_t &\triangleq \frac{\sum_{i=1}^K \sum_{l=1}^{L^{(i)}} \sum_{s=1}^{\lambda_{i,l}} \left(v_{\tilde{n}_s^{(i),(l)}}^{(i)} - \hat{\tau}_i - \hat{\mu}_t \right)^2 \mathbf{1}_{\{\tilde{\tau}_s^{(i),(l)}=t\}}}{\sum_{i=1}^K \sum_{l=1}^{L^{(i)}} \sum_{s=1}^{\lambda_{i,l}} \mathbf{1}_{\{\tilde{\tau}_s^{(i),(l)}=t\}}} \end{aligned}$$

, where $\{\tilde{\mu}_t\}_{t=1}^T$ are the updated means in the previous iteration.

Note that EM algorithms are quite sensitive to the initial conditions, which means that it is, in general, not possible to see good inference if we do not use “proper” initializations. One suggestion to deal with this defect is initializing stack parameters by using any existing stacks (for example, LR04). Then, EM algorithms will “refine” our initial guesses on the parameters iteratively by using data.