Case Study 6 Report:

Particle Prediction Classifier

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Abstract

The team has been provided with a large complex dataset from a group of scientists to create a dense neural network and classifier to predict the existence of a new particle. The data is binary with 0 representing no detection and 1 representing detection. The goal is to provide a high level accuracy for the algorithm.

1. Introduction

1.1 Business Understanding

The objective for this study is to create a dense neural network classifier to predict the existence of a new particle. The scientific community is interested because the high energy produced when a new particle is made can only be observed by the features that it leaves behind due to it disappearing so quickly.

1.2 Data Meaning Type

To engineer an algorithm that predicts the existence of a new particle, scientists provided a large complex dataset from the Higgs Boson Research. The dataset comprises 6,999,999 and 29 features described in Figure 1.2a.

<pre><class 'pandas.core.frame.dataframe'=""></class></pre>					
RangeIndex: 7000000 entries, 0 to 6999999					
Data columns (total 29 columns):					
#	Column	Dtype			
0	detection	int64			
1	f0	float64			
2	f1	float64	16	f15	float64
3	f2	float64	17	f16	float64
4	f3	float64	18	f17	float64
5	f4	float64	19	f18	float64
6	f5	float64	20	f19	float64
7	f6	float64	21	f20	float64
8	f7	float64	22	f21	float64
9	f8	float64	23	f22	float64
10	f9	float64	24	f23	float64
11	f10	float64	25	f24	float64
12	f11	float64	26	f25	float64
13	f12	float64	27	f26	float64
14	f13	float64	28	mass	float64
15	f14	float64	dtyp	es: float64	4(28), int64(1)

Figure 1.2a- Feature Descriptions

2. Methods

2.1 Data Preprocessing

The dataset originally consisted of a single dataset with almost 7 million records. To ensure the data was ready for processing, the "# label" column was changed to "detection". Next, the "detection" variables were transformed from 0.0 and 1.0 float64 to 0 and 1 int64. Then, the dataset was checked for null values and none were found. From the team's observations, the dataset did not require much preprocessing prior to the exploratory data analysis.

2.2 Exploratory Data Analysis

Conducting an exploratory data analysis, the team saw that the new particles detected (1) versus the not detected (0) were fairly. Depicted in 2.2a and 2.2b, the data shows 3,500,879 new particles detected and 3,499,121 new particles not detected.

35008793499121

Name: detection, dtype: int64



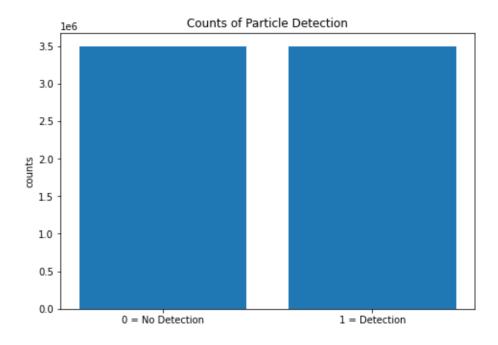


Figure 2.2b- Detection Bar Graph

Next, the team split our dataset into data/target train and test subsets using the train_test_split function from the sklearn model_selection package. Then, the data was rescaled to the default normalization using MinMaxScaler to scale variables into the range 0 to 1. After the aforementioned procedures were conducted,

the model was ready to run.

2.3 Dense Neural Network Models

2.3.1 Model 1

For the first model, the team used a very basic selection of layers. The team defined the shape of the data, then proceeded to add the first dense layer. The activation relu was used as the team believed it would be well suited to the data and a good starting point for experimentation. For the same reason, the team decided to set the neurons to 50. Then, the team compiled the function. The team decided to use the optimizer "Adam" as the adaptive nature and low memory requirements are well suited for large data. Now addressing the fit, the team decided on a relatively low number of epochs in order to conserve resources and the same will apply to following models. The same logic applies to our batch size.

2.3.2 Model 2

For the second model, the same fit and compile methods have been applied as they have served well and the team have continued the study with layering the models. With the second model, the team tried various parameters before deciding that this combination was most optimal. The team has added a layer with 25 neurons and the activation sigmoid. The sigmoid function was chosen as it was deemed a good compliment to our previous layer according to a broad net of research. This did in fact bolster our results in a very distinctive manner and as such this model was chosen to continue our experimentation.

2.3.3 Model 3

The last model is the direct successor to model 2 and the team have once again decided to add a layer. For this layer, the team examined the results gained from the previous model and decided not to use a more involved activation and simply assigned the linear activation to our newest layer and to provide further variation we utilized the neuron scheme of 64, 32, and 16. The results from this were not ideal and as such the team decided to re-examine the activation structure. After a few rounds of slightly more empirical alterations, the team decided upon the final model of activation tanh, relu, and linear. The results gained were slightly above the given accuracy range, however the team believes this is the result of true methods and a data leak is unlikely. Therefore, this is also the team's best model.

3. Results

3.1 Dense Neural Network

3.1.1 Model 3

As stated in the previous section, the accuracy has gone slightly beyond the defined range but the team has decided that the results are trustworthy. Thus, the team is very satisfied with both our loss and accuracy metrics. The team used the cross validation method to judge the model in terms of new data and as shown in Figure 3.1.1.a and Figure 3.1.1.b below there are variations with the validation set but overall it does follow the training set well.

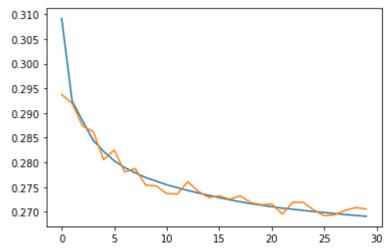


Figure 3.1.1.a-The loss attributed to our training (blue) and validation (orange) sets

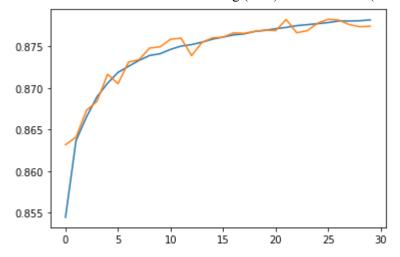


Figure 3.1.1.b-The accuracy attributed to our training (blue) and validation (orange) sets

4. Conclusion

The team was able to classify particles as new or not by utilizing the given records and processing them through a wide variety of neural network models. The last model reached a maximum accuracy of 87.83% and the loss reached a low of 26.92%. Thus, the team believes that as of now this is the best method for an automated particle classifier. At this time, the team does not believe

that it can further improve the model with more time.

5. Citation

5.1. Baldi, P., P. Sadowski, and D. Whiteson. "Searching for Exotic Particles in High-energy Physics with Deep Learning." Nature Communications 5 (July 2, 2014).

6. Code

```
In [ ]:
         #import libraries
         from __future__ import print_function
         import pandas as pd
         import numpy as np
         import os
         import tensorflow as tf
         import cv2
         from tensorflow.python import keras
         from tensorflow.python.keras.utils.np_utils import to_categorical
         from PIL import Image
         import matplotlib.pyplot as plt
         import datetime
         import keras
         from keras.models import Sequential
         from tensorflow.keras import layers
         from keras.layers import Dense, Dropout, Activation, Flatten
         from keras.layers import Conv2D, MaxPooling2D
         from keras import backend as K
In [ ]:
         #Mount drive
         from google.colab import drive
         drive.mount('/content/drive/')
In [ ]:
         #Unzip file and store in csv
         import gzip
         with gzip.open('/content/drive/MyDrive/Colab Notebooks/CS6/all_train.csv.gz',
             csv data = csv file.read()
             with open('/content/drive/MyDrive/Colab Notebooks/CS6/all train.csv', 'wt')
                  out file.write(csv data)
In [ ]:
         #Load up data and show.
          df = pd.read csv('/content/drive/MyDrive/Colab Notebooks/CS6/all train.csv')
          df.head()
In [ ]:
         #Rename Labels column
         df2=df
         df2.rename(columns = {'# label':'detection'}, inplace = True)
         df2.head()
In [ ]:
         #Display a summary of variables
         df2.info()
In [ ]:
         #Summary of Attributes in the dataframe
         df2.describe()
```

```
#Replace all '0.0' with '0' and '1.0' with '1' in the "# labels" column.
         df2['detection'] = df2['detection'].map({0.0: 0, 1.0: 1})
         df2.head()
In [ ]:
         df2.info()
In [ ]:
         #see if there are nulls
         df2.isnull().sum()
In [ ]:
         #Count values in label
         df2['detection'].value_counts()
In [ ]:
         fig = plt.figure()
         ax = fig.add axes([0,0,1,1])
         labels = ["0 = No Detection", "1 = Detection"]
         ax.bar(labels,df2["detection"].value_counts())
         plt.ylabel("counts")
         plt.title('Counts of Particle Detection')
         plt.show()
In [ ]:
         #Examine the mean of the Numerical Values by detection
         df2.groupby(['detection']).mean()
In [ ]:
         #Examine the mean of the numerical values by mass
         df2.groupby('mass')['detection'].value_counts()
In [ ]:
         import seaborn as sns
In [ ]:
         #Create a Violinplot of Detection and Mass
         import seaborn as sns
         sns.set_palette("pastel")
         sns.violinplot(x='detection',y='mass', data = df2)
         plt.title('Detection by Mass')
         plt.show()
In [ ]:
         #Potential attribute with all factors
         sns.pairplot(df2, kind="scatter", hue = "detection", markers = ["o", "s"], pale
         plt.show()
In [ ]:
         now = datetime.datetime.now
         batch size = 128
         num classes = 10
         epochs = 30
         # number of convolutional filters to use
         filters = 32
```

```
# size of pooling area for max pooling
         pool size = 2
         # convolution kernel size
         kernel_size = 3
In [ ]:
         x = df2.loc[:,df2.columns !='detection']
         y = df2['detection']
In [ ]:
         # Range of 0,1 is important for well trained neural networks
         from sklearn.preprocessing import MinMaxScaler
         scaler = MinMaxScaler(feature range=(0, 1))
         scaled train = scaler.fit transform(x)
         # Print out the adjustment that the scaler applied to the total earnings column
         print("Note: median values were scaled by multiplying by {:.10f} and adding {:.
         multiplied by = scaler.scale [27]
         added = scaler.min [27]
         scaled train df = pd.DataFrame(scaled train, columns=x.columns.values)
In [ ]:
         %matplotlib inline
         for i in scaled train df:
             scaled_train_df[i].hist()
             plt.title(i)
             plt.show()
In [ ]:
         # Split into test/train
         from sklearn.model selection import train test split
         X_train, X_test, y_train, y_test = train_test_split(scaled_train_df, y, test_si
In [ ]:
         # Create the model and build layers
         model = tf.keras.Sequential()
         model.add(tf.keras.Input(shape=(28,)))
         model.add(layers.Dense(50,activation='relu'))
In [ ]:
         model.compile(optimizer='Adam',
                       loss=tf.keras.losses.SparseCategoricalCrossentropy(from logits=Tr
                       metrics=['mean squared error', 'accuracy'])
In [ ]:
         model.fit(X train, y train, epochs=30, validation data=(X test,y test), batch s
In [ ]:
         #Plot loss
         train_loss = model.history.history['loss']
         val_loss = model.history.history['val_loss']
         plt.plot(train loss)
         plt.plot(val loss)
         plt.show()
```

```
In [ ]:
         #Plot Accuacy
         train acc = model.history.history['accuracy']
         val acc = model.history.history['val accuracy']
         plt.plot(train_acc)
         plt.plot(val acc)
         plt.show()
In [ ]:
         # Create the model and build layers
         model = tf.keras.Sequential()
         model.add(tf.keras.Input(shape=(28,)))
         model.add(layers.Dense(50,activation='relu'))
         model.add(layers.Dense(25, activation='sigmoid'))
In [ ]:
         model.compile(optimizer='Adam',
                       loss=tf.keras.losses.SparseCategoricalCrossentropy(from logits=Tr
                       metrics=['mean squared error', 'accuracy'])
In [ ]:
         model.fit(X train, y train, epochs=30, validation data=(X test,y test), batch s
In [ ]:
         #PLot Loss
         train loss = model.history.history['loss']
         val loss = model.history.history['val loss']
         plt.plot(train loss)
         plt.plot(val loss)
         plt.show()
In [ ]:
         #Plot Accuacy
         train acc = model.history.history['accuracy']
         val acc = model.history.history['val accuracy']
         plt.plot(train acc)
         plt.plot(val acc)
         plt.show()
In [ ]:
         # Create the model and build layers
         model = tf.keras.Sequential()
         model.add(tf.keras.Input(shape=(28,)))
         model.add(layers.Dense(64,activation='tanh'))
         model.add(layers.Dense(32, activation='relu'))
         model.add(layers.Dense(16, activation='linear'))
In [ ]:
         model.compile(optimizer='Adam',
                       loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=Tr
                       metrics=['mean squared error', 'accuracy'])
In [ ]:
         model.fit(X_train, y_train, epochs=30, validation_data=(X_test,y_test), batch_s
```

```
#PLOT LOSS
train_loss = model.history.history['loss']
val_loss = model.history.history['val_loss']
plt.plot(train_loss)
plt.plot(val_loss)
plt.show()

In []:

#PLot Accuacy
train_acc = model.history.history['accuracy']
val_acc = model.history.history['val_accuracy']
plt.plot(train_acc)
plt.plot(val_acc)
plt.show()
```