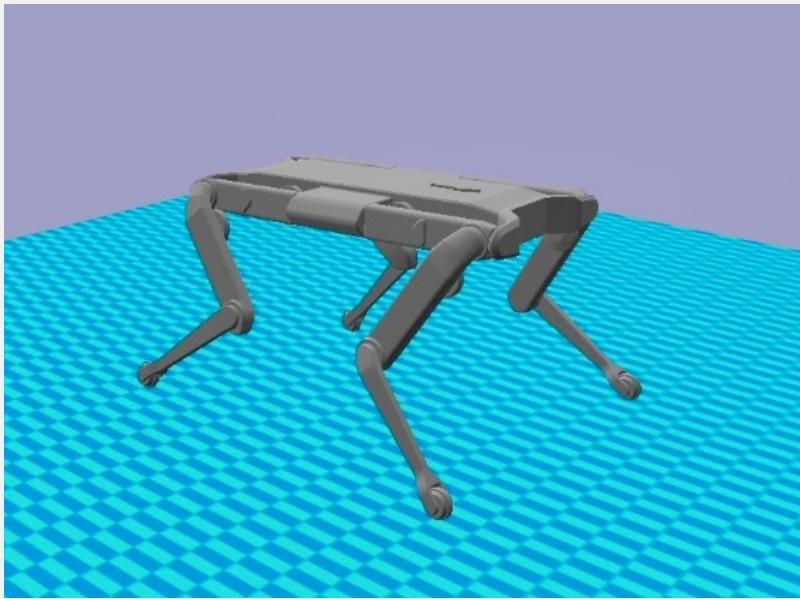
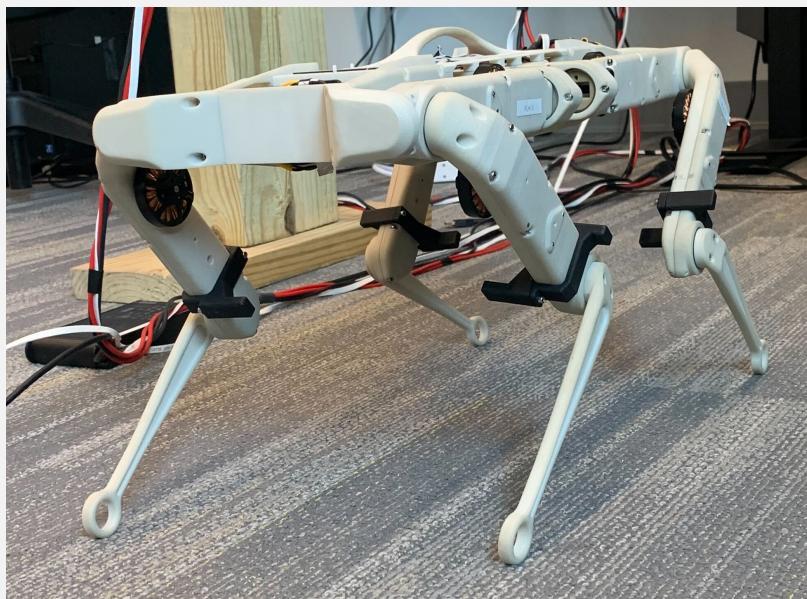


Simulation



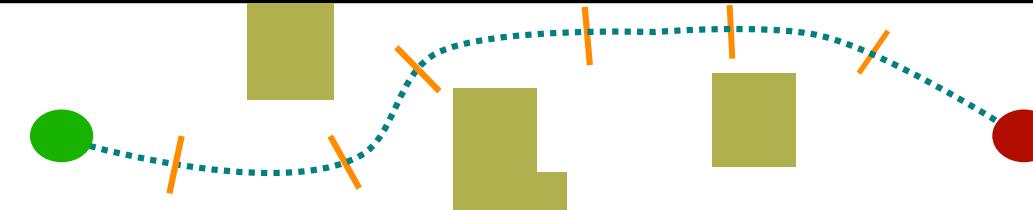
Real



Commands

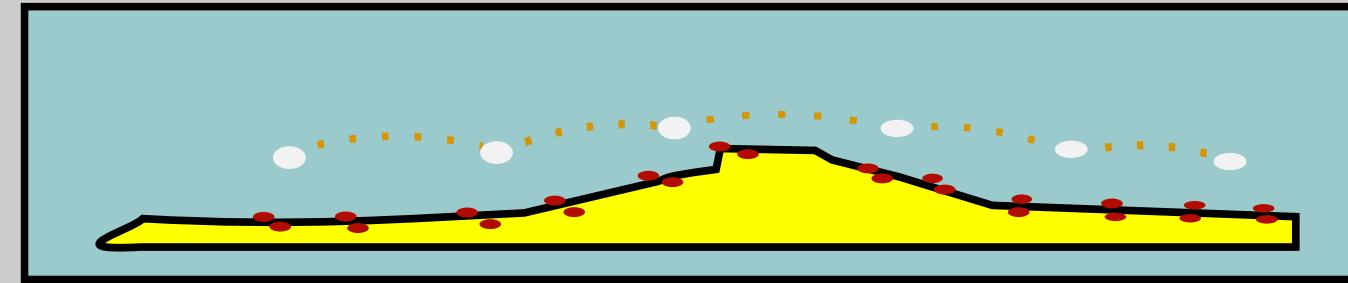
Sensor Data

Global Planner



Start + Goal CoM States

Local Planner



States + Endeffector Trajectory

Controller

Inverse Kinematics

q

Torque Controller

\dot{q}

Joint Angles + Joint Velocities + Torques

Robot Interface

Setup

Communication