

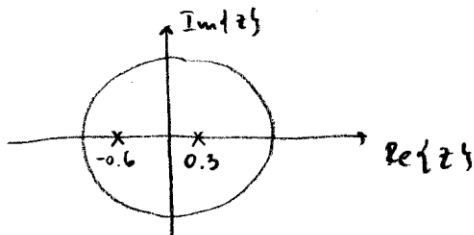
# Midterm 1: Solutions

1. (30 points) The z-transform of a sequence  $x[n]$  is given by:

$$X(z) = \frac{3z^2 + 0.1z + 0.87}{(z + 0.6)(z - 0.3)}$$

Specify all possible regions of convergence, and find the respective inverse z-transforms.

poles at:  $-0.6, 0.3$



$$ROC_x^{(1)} : |z| > 0.6$$

$$ROC_x^{(2)} : 0.3 < |z| < 0.6$$

$$ROC_x^{(3)} : |z| < 0.3$$

$$ROC_x^{(4)} = \emptyset$$

$$\begin{aligned} X(z) &= 3 + \frac{-0.8z + 1.41}{(z + 0.6)(z - 0.3)} = 3 - \frac{2.1}{z + 0.6} + \frac{1.3}{z - 0.3} \\ &= 3 - 2.1z^{-1} \cdot \frac{z}{z + 0.6} + 1.3z^{-1} \cdot \frac{z}{z - 0.3} \end{aligned}$$

$$h^{(1)}[n] = 3\delta[n] - 2.1(-0.6)^{n-1}u[n-1] + 1.3 \cdot (0.3)^{n-1}u[n-1]$$

$$h^{(2)}[n] = 3\delta[n] + 2.1(-0.6)^{n-1}u[-n] + 1.3(0.3)^{n-1}u[n-1]$$

$$h^{(3)}[n] = 3\delta[n] + 2.1(-0.6)^{n-1}u[-n] - 1.3 \cdot (0.3)^{n-1}u[-n]$$

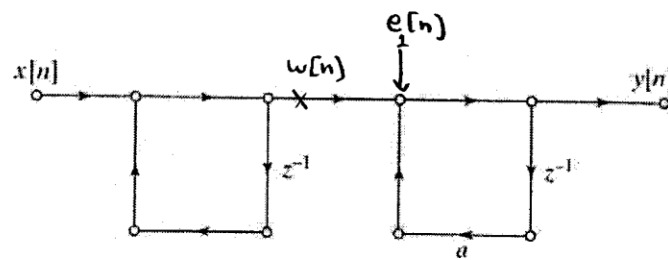
$$h^{(4)}[n] \rightarrow \text{does not exist}$$

2. The parameter  $a$  in the flow diagrams below is a real number in the interval  $(0, 1)$ .

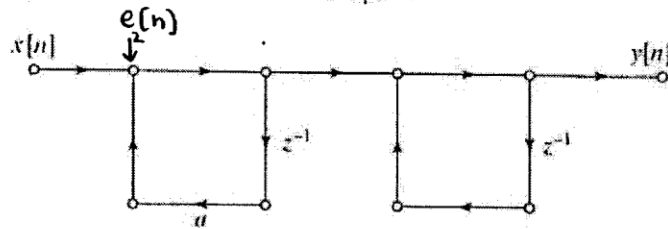
a) (10 points) Calculate the transfer function implemented by these flow diagrams and determine its BIBO stability.

b) (10 points) What condition must the input sequence  $x[n]$  satisfy so that the output  $y[n]$  remains bounded.

c) (10 points) Assuming that these systems are implemented with two's complement fixed point arithmetic with  $B$  magnitude bits, calculate the output noise variance for the Flow Graph #1. Which of the two flow graphs would have a larger output noise variance?



Flow Graph #1



Flow Graph #2

a)

$$\begin{aligned} \text{Flow graph \#1: } w[n] &= x[n] + w[n-1] \Rightarrow W(z)(1-z^{-1}) = X(z) \\ y[n] &= w[n] + ay[n-1] \Rightarrow Y(z)(1-az^{-1}) = W(z) \\ \Rightarrow Y(z)(1-az^{-1})(1-z^{-1}) &= X(z) \\ H_1(z) &= \frac{Y(z)}{X(z)} = \frac{1}{(1-az^{-1})(1-z^{-1})} \end{aligned}$$

Similarly for the Flow graph #2 :  $H_2(z) = \frac{1}{(1-az^{-1})(1-z^{-1})}$

$$H_1(z) = H_2(z)$$

Since both systems are causal, and  $a \in (0, 1)$

$\Rightarrow \text{ROC}_{H_1} = \text{ROC}_{H_2} : |z| > 1 \Rightarrow H_1, H_2 \text{ are } \underline{\text{not stable}}$

b)  $H_1(z) = H_2(z) = \frac{1}{(1-az^{-1})(1-z^{-1})}$

$$Y(z) = H_1(z) \cdot X(z)$$

In this system instability comes from the integrator

block :  $\frac{1}{1-z^{-1}}$ . Hence, any summable  $x[n]$  would work

i.e.  $\sum_n x[n] < \infty$ . To see this, observe a system :

$$\begin{aligned} w[n] \xrightarrow{\left| \frac{1}{1-z^{-1}} \right|} y[n] \quad & y[n] = w[n] + y[n-1] \\ & = w[n] + w[n-1] + y[n-2] \\ & = w[n] + w[n-1] + w[n-2] + y[n-3] \\ & = w[n] + w[n-1] + w[n-2] + w[n-3] + \dots \end{aligned}$$

Hence,  $y[n]$  is bounded as long as  $\sum_n w[n] < \infty$ .

$$c) \quad \sigma_e^2 = \frac{2^{-2B}}{12}$$

$$e_1[n] \rightarrow \boxed{H_{e1}(z)} \rightarrow y[n]$$

$$H_{e1}(z) = \frac{1}{1 - az^{-1}} \Rightarrow h_{e1}[n] = a^n u[n]$$

$$\begin{aligned} \sigma_{f_1}^2 &= \sigma_e^2 \cdot \frac{1}{2\pi} \int_{-\pi}^{\pi} |H_{e1}(e^{j\omega})|^2 d\omega = \frac{2^{-2B}}{12} \sum_{n=0}^{\infty} |h_{e1}[n]|^2 \\ &= \frac{2^{-2B}}{12} \cdot \sum_{n=0}^{\infty} |a|^{2n} = \frac{2^{-2B}}{12} \cdot \frac{1}{1 - |a|^2} \end{aligned}$$

$$e_2[n] \rightarrow \boxed{H_{e2}(z)} \rightarrow y[n]$$

$$H_{e2}(z) = \frac{1}{(1 - az^{-1})(1 - z^{-1})}$$

Flow graph #2 has larger output noise variance because  $H_{e2}(z)$  is a cascade of two systems:

$H_{e2}(z)$  and  $H_{e2}'(z) = \frac{1}{1 - z^{-1}}$ .  $H_{e2}'(z)$  introduces infinite output noise power to the system

since  $h_{e2}'[n] = u[n]$  and  $\sum_{n=-\infty}^{\infty} |h_{e2}'[n]|^2 \rightarrow \infty$

3. The following values from the 8-point DFT of a length-8 real sequence  $x[n]$  are known:

$$X[0] = 3, X[2] = 0.5 - 4.5j, X[4] = 5, X[5] = 3.5 + 3.5j, X[7] = -2.5 - 7j.$$

a) (10 points) Evaluate  $x[0]$  and  $x[4]$ .

b) (10 points) Find the 8-point DFT of the circular convolution:

$$x[n] \otimes \delta[n - 1]$$

where  $\delta[n]$  is the unit impulse.

c) (10 points) Find the 4-point DFT of the length-4 sequence  $w[n]$  given by:

$$w[n] = x[n] + x[n + 4] \quad n = 0, 1, 2, 3.$$

d) (10 points) Find the 8-point DCT2 coefficients  $X^{c2}[0]$ ,  $X^{c2}[2]$ ,  $X^{c2}[4]$ ,  $X^{c2}[6]$ .

$$a) \quad x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] W_N^{-nk}$$

$$x[0] = \frac{1}{8} \cdot \sum_{k=0}^7 X[k] = \frac{11}{8}$$

$$x[n] \text{ is real, hence } X[k] = X^*[-k]_8$$

$$\Rightarrow X[1] = X^*[7] = -2.5 + 7j$$

$$X[3] = X^*[5] = 3.5 - 3.5j$$

$$X[6] = X^*[2] = 0.5 + 4.5j$$

$$b) y[n] = x[n] \otimes \delta[n-1]$$

$$\Rightarrow Y[k] = X[k] \cdot W_8^k$$

$$Y[0] = 3, \quad Y[1] = (-2.5 + 7j) \cdot W_8, \quad Y[2] = 4.5 + 0.5j$$

$$Y[3] = (3.5 - 3.5j) W_8^3, \quad Y[4] = -5, \quad Y[5] = (3.5 + 3.5j) W_8^5$$

$$Y[6] = 4.5 - 0.5j, \quad Y[7] = (-2.5 - 7j) W_8^7;$$

$$c) w[n] = x[n] + x[n+4], \quad n=0, 1, 2, 3$$

$$\Rightarrow W[k] = X[2k], \quad k=0, 1, 2, 3 \quad (\text{sampling in freq. domain is causing aliasing in time domain}).$$

$$W[0] = 3, \quad W[1] = 0.5 - 4.5j, \quad W[2] = 5, \quad W[3] = 0.5 + 4.5j.$$

$$d) \quad X^{C_2}[k] = 2 \cdot \text{Re} \left\{ \underset{\substack{\downarrow \\ 8 \text{ pt}}}{\tilde{X}[k]} \cdot e^{-j \cdot \frac{\pi k}{2N}} \right\}, \quad N=8$$

$\downarrow$   
 16 pt

$$\tilde{X}[k] \text{ is DFT transform of } \tilde{x}[n] = \begin{cases} x[n], & n=0, \dots, N-1 \\ 0, & \text{otherwise} \end{cases}$$

$$\tilde{X}[k] = \sum_{n=0}^7 x[n] \cdot W_{16}^{nk} = \sum_{n=0}^7 x[n] W_8^{nk/2} = \begin{cases} X[\frac{k}{2}], & k \text{ even} \\ ?, & k \text{ odd} \end{cases}$$

$$X^{C_2}[0] = 2 \cdot \text{Re} \{ \tilde{X}[0] \} = 2 \text{Re} \{ X[0] \} = 6$$

$$X^{C_2}[2] = 2 \text{Re} \{ \tilde{X}[2] \cdot e^{-j \cdot \frac{2\pi}{16}} \} = 2 \text{Re} \{ X[1] e^{-j \cdot \frac{\pi}{8}} \} = 0.7382$$

$$X^{C_2}[4] = 2 \text{Re} \{ \tilde{X}[4] e^{-j \cdot \frac{4\pi}{16}} \} = 2 \text{Re} \{ X[2] e^{-j \cdot \frac{\pi}{4}} \} = -5.6569$$

$$X^{C_2}[6] = 2 \text{Re} \{ \tilde{X}[3] e^{-j \cdot \frac{6\pi}{16}} \} = 2 \text{Re} \{ X[3] \cdot e^{-j \cdot \frac{3\pi}{8}} \} = -3.7884$$