

*with( plottools )*

[annulus, arc, arrow, circle, cone, cuboid, curve, cutin, cutout, cylinder, disk, dodecahedron, ellipse, ellipticArc, exportplot, extrude, getdata, hemisphere, hexahedron, homothety, hyperbola, icosahedron, importplot, line, octahedron, parallelepiped, pieslice, point, polygon, polygonbyname, prism, project, rectangle, reflect, rotate, scale, sector, semitorus, sphere, stellate, tetrahedron, torus, transform, translate, triangulate]

(1)

*with( plots )*

[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d, conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d, densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d, inequal, interactive, interactiveparams, intersectplot, listcontplot, listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra\_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, shadebetween, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]

(2)

*with( DifferentialGeometry )*

[&algmult, &minus, &mult, &plus, &tensor, &wedge, Annihilator, ApplyTransformation, ChangeFrame, ComplementaryBasis, ComposeTransformations, DGIm, DGImageSpace, DGNullSpace, DGRe, DGbasis, DGconjugate, DGsetup, DGsolve, DGzip, DeRhamHomotopy, DualBasis, ExteriorDerivative, ExteriorDifferentialSystems, Flow, FrameData, GetComponents, GroupActions, Hook, InfinitesimalTransformation, IntegrateForm, IntersectSubspaces, InverseTransformation, JetCalculus, Library, LieAlgebras, LieBracket, LieDerivative, Preferences, Pullback, PullbackVector, Pushforward, RemoveFrame, Tensor, Tools, Transformation, evalDG]

(3)

*with( VectorCalculus )*

[&x, `\*`, `+`, `-`, `.`; <, >, <|>, About, AddCoordinates, ArcLength, BasisFormat, Binormal, ConvertVector, CrossProduct, Curl, Curvature, D, Del, DirectionalDiff, Divergence, DotProduct, Flux, GetCoordinateParameters, GetCoordinates, GetNames, GetPVDDescription, GetRootPoint, GetSpace, Gradient, Hessian, IsPositionVector, IsRootedVector, IsVectorField, Jacobian, Laplacian, LineInt, MapToBasis,  $\nabla$ , Norm, Normalize, PathInt, PlotPositionVector, PlotVector, PositionVector, PrincipalNormal, RadiusOfCurvature, RootedVector, ScalarPotential, SetCoordinateParameters, SetCoordinates, SpaceCurve, SurfaceInt, TNBFrame, TangentLine, TangentPlane, TangentVector, Torsion, Vector, VectorField, VectorPotential, VectorSpace, Wronskian, diff, eval, evalVF, int, limit, series]

(4)

## Define dual, reverse dual and 'to point' functions

**ext43\_dual := proc( ext43 )**

**local** S1, comps;

S1 := DifferentialGeometry:-evalDG( [DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dx, dy), dz), DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dx, dy), dw), DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dx, dz), dw),

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DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dy, dz), dw) ]]);
comps := DifferentialGeometry:-GetComponents(ext43, S1);
return _DG([["form", M, 1], [[1], comps[4]], [[2], -comps[3]], [[3], comps[2]], [[4],
-comps[1]]]])
end proc
ext43_dual := proc(ext43)
local S1, comps;
S1 := DifferentialGeometry:-evalDG([DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dy), dz), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dy), dw), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dz), dw), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dy, dz), dw) ]]);
comps := DifferentialGeometry:-GetComponents(ext43, S1);
return _DG([["form", M, 1], [[1], comps[4]], [[2], VectorCalculus:-`(comps[3])],
[[3], comps[2]], [[4], VectorCalculus:-`(comps[1])]]])
end proc

ext43_reverse_dual := proc(ext43)
local S1, comps;
S1 := DifferentialGeometry:-evalDG([DifferentialGeometry:-&wedge(DifferentialGeometry:-
&wedge(dx, dy), dz), DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dx, dy), dw),
DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dx, dz), dw),
DifferentialGeometry:-&wedge(DifferentialGeometry:-&wedge(dy, dz), dw) ]]);
comps := DifferentialGeometry:-GetComponents(ext43, S1);
return _DG([["form", M, 1], [[1], -comps[4]], [[2], comps[3]], [[3], -comps[2]], [[4],
comps[1]]]])
end proc
ext43_reverse_dual := proc(ext43)
local S1, comps;
S1 := DifferentialGeometry:-evalDG([DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dy), dz), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dy), dw), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dx, dz), dw), DifferentialGeometry:-
&wedge(DifferentialGeometry:-&wedge(dy, dz), dw) ]]);
comps := DifferentialGeometry:-GetComponents(ext43, S1);
return _DG([["form", M, 1], [[1], VectorCalculus:-`(comps[4])], [[2], comps[3]],
[[3], VectorCalculus:-`(comps[2])], [[4], comps[1]]]])
end proc

ext41_to_point := proc(ext41)
local S1, comps;
S1 := DifferentialGeometry:-evalDG([dx, dy, dz, dw]);
comps := DifferentialGeometry:-GetComponents(ext41, S1);
return [VectorCalculus:-`*(comps[1], comps[4]^VectorCalculus:-`(1)), VectorCalculus:-
`*(comps[2], comps[4]^VectorCalculus:-`(1)), VectorCalculus:-`*(comps[3], comps[4]
^VectorCalculus:-`(1))]

```

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(6)

**end proc**

*ext41\_to\_point* := **proc**(*ext41*)

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**local** *S1*, *comps*;

*S1* := *DifferentialGeometry:-evalDG*( [*dx*, *dy*, *dz*, *dw*] );

*comps* := *DifferentialGeometry:-GetComponents*(*ext41*, *S1*);

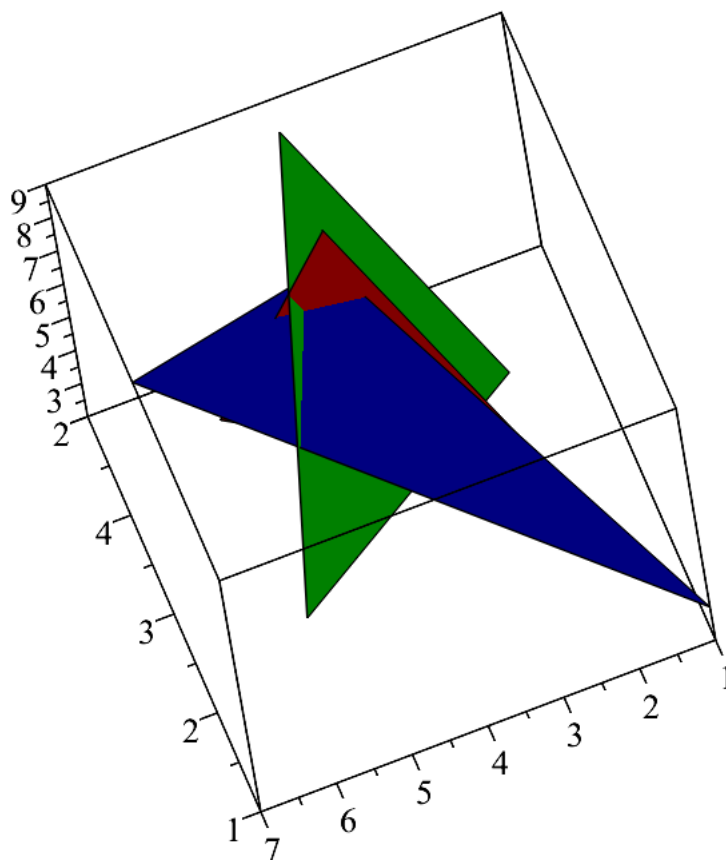
**return** [*VectorCalculus:-`\*`*(*comps*[1], *comps*[4]^*VectorCalculus:-`-`*(1)),

*VectorCalculus:-`\*`*(*comps*[2], *comps*[4]^*VectorCalculus:-`-`*(1)), *VectorCalculus:-`\*`*(*comps*[3], *comps*[4]^*VectorCalculus:-`-`*(1))]

**end proc**

**Plot the three triangles to be intersected**

*display*( {*polygonplot3d*( [ [1, 3, 1], [4, 7, 4], [7, 9, 3] ], *color* = *blue*), *polygonplot3d*( [ [2, 2, 3], [6, 7, 3], [4, 8, 4] ], *color* = *red*), *polygonplot3d*( [ [2, 2, 4], [6, 7, 1], [4, 8, 5] ], *color* = *green*) } )



*DGsetup*( [*x*, *y*, *z*, *w*], *M*, *verbose*)

*The following coordinates have been protected:*

[*x*, *y*, *z*, *w*]

*The following vector fields have been defined and protected:*

[*D\_x*, *D\_y*, *D\_z*, *D\_w*]

The following differential 1-forms have been defined and protected:

$$[dx, dy, dz, dw]$$

$$\text{frame name: } M$$

(8)

Define functions for the three triangle points

$$a := e1\_0 \cdot dx + e1\_1 \cdot dy + e1\_2 \cdot dz + e1\_3 \cdot dw$$

$$a := e1\_0 dx + e1\_1 dy + e1\_2 dz + e1\_3 dw$$

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$$b := e2\_0 \cdot dx + e2\_1 \cdot dy + e2\_2 \cdot dz + e2\_3 \cdot dw$$

$$b := e2\_0 dx + e2\_1 dy + e2\_2 dz + e2\_3 dw$$

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$$c := e3\_0 \cdot dx + e3\_1 \cdot dy + e3\_2 \cdot dz + e3\_3 \cdot dw$$

$$c := e3\_0 dx + e3\_1 dy + e3\_2 dz + e3\_3 dw$$

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Use the wedge product to join the three points to yield an ext4\_3 for a triangle.

$$t\_ext3 := (a \wedge b) \wedge c$$

$$\begin{aligned} t\_ext3 := & (e1\_0 e2\_1 e3\_2 - e1\_0 e2\_2 e3\_1 - e1\_1 e2\_0 e3\_2 + e1\_1 e2\_2 e3\_0 \\ & + e1\_2 e2\_0 e3\_1 - e1\_2 e2\_1 e3\_0) dx \wedge dy \wedge dz + (e1\_0 e2\_1 e3\_3 - e1\_0 e2\_3 e3\_1 \\ & - e1\_1 e2\_0 e3\_3 + e1\_1 e2\_3 e3\_0 + e1\_3 e2\_0 e3\_1 - e1\_3 e2\_1 e3\_0) dx \wedge dy \wedge dw \\ & + (e1\_0 e2\_2 e3\_3 - e1\_0 e2\_3 e3\_2 - e1\_2 e2\_0 e3\_3 + e1\_2 e2\_3 e3\_0 \\ & + e1\_3 e2\_0 e3\_2 - e1\_3 e2\_2 e3\_0) dx \wedge dz \wedge dw + (e1\_1 e2\_2 e3\_3 - e1\_1 e2\_3 e3\_2 \\ & - e1\_2 e2\_1 e3\_3 + e1\_2 e2\_3 e3\_1 + e1\_3 e2\_1 e3\_2 - e1\_3 e2\_2 e3\_1) dy \wedge dz \wedge dw \end{aligned}$$

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Get specific ext4\_3s for each of the three triangles.

$$t1\_ext3 := \text{subs}(\{e1\_0=1, e1\_1=3, e1\_2=1, e1\_3=1, e2\_0=4, e2\_1=7, e2\_2=4, e2\_3=1, e3\_0=7, e3\_1=9, e3\_2=3, e3\_3=1\}, t\_ext3)$$

$$t1\_ext3 := 20 dx \wedge dy \wedge dz - 6 dx \wedge dy \wedge dw - 12 dx \wedge dz \wedge dw - 10 dy \wedge dz \wedge dw$$

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$$t2\_ext3 := \text{subs}(\{e1\_0=2, e1\_1=2, e1\_2=3, e1\_3=1, e2\_0=6, e2\_1=7, e2\_2=3, e2\_3=1, e3\_0=4, e3\_1=8, e3\_2=4, e3\_3=1\}, t\_ext3)$$

$$t2\_ext3 := 44 dx \wedge dy \wedge dz + 14 dx \wedge dy \wedge dw + 4 dx \wedge dz \wedge dw + 5 dy \wedge dz \wedge dw$$

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$$t3\_ext3 := \text{subs}(\{e1\_0=2, e1\_1=2, e1\_2=4, e1\_3=1, e2\_0=6, e2\_1=7, e2\_2=1, e2\_3=1, e3\_0=4, e3\_1=8, e3\_2=5, e3\_3=1\}, t\_ext3)$$

$$t3\_ext3 := 82 dx \wedge dy \wedge dz + 14 dx \wedge dy \wedge dw + 10 dx \wedge dz \wedge dw + 23 dy \wedge dz \wedge dw$$

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Compute the point of intersection for all three triangles. This is a combination of wedges and duals. Convert the ext4\_1 to a point.

$$\text{intersection} := \text{ext41\_to\_point}(\text{ext43\_reverse\_dual}(\text{ext43\_dual}(t1\_ext3) \wedge \text{ext43\_dual}(t2\_ext3)) \wedge \text{ext43\_dual}(t3\_ext3)))$$

$$\text{intersection} := \left[ \frac{104}{23}, \frac{499}{69}, \frac{248}{69} \right]$$

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Plot the triangles again but with the intersection point highlighted.

```
display( {polygonplot3d( [ [1, 3, 1], [4, 7, 4], [7, 9, 3] ], color = blue), polygonplot3d([ [2, 2, 3], [6, 7, 3], [4, 8, 4]], color = red), polygonplot3d([ [2, 2, 4], [6, 7, 1], [4, 8, 5]], color = green), sphere(intersection, 0.1, color = white, style = patchnogrid) } )
```

