

Integration

We often need to compute:

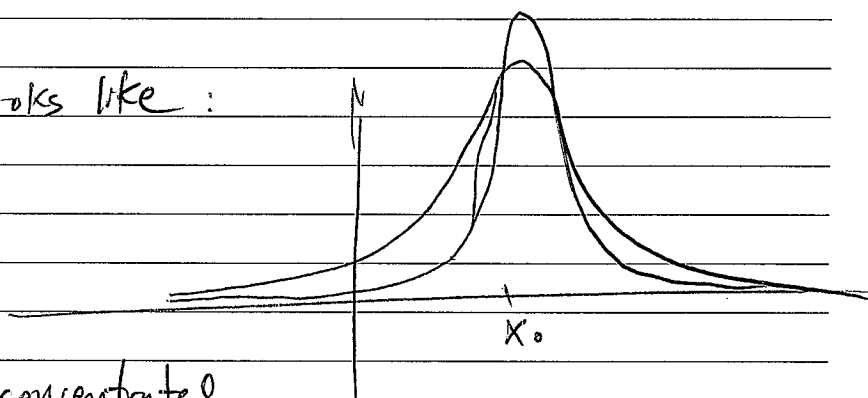
- ① $E_f g(X)$ — expectations / moments
- ② $\int p(x|\theta) dx$ — normalizing constants for densities.

\Rightarrow In general this can be very hard, but there are many special cases.

Suppose we want to calculate:

$$\int g(x) dx \quad \text{and } g \in L^2$$

Suppose g looks like:



So g is highly concentrated about x_0 .

Then we could say (?)

$$\int g(x) dx \stackrel{?}{=} g(x_0) \epsilon$$

$$\int_{x_0}^{x_0 + \epsilon} g(x) dx =$$

Suppose ~~g~~ h achieves its max at x_0

Suppose we want

$$\int_a^b g(x) dx = \int_a^b e^{h(x)} dx \quad [h(x) = \log g(x)]$$

$$\equiv \int_a^b \exp\left(h(x_0) + \underbrace{h'(x_0)(x-x_0)}_{=0} + \frac{h''(x_0)(x-x_0)^2}{2}\right) dx$$

$$= \int_a^b \exp\left(h(x_0) + \frac{h''(x_0)(x-x_0)^2}{2}\right) dx$$

$$= \exp(h(x_0)) \int_a^b \exp\left(\frac{h''(x_0)(x-x_0)^2}{2}\right) dx$$

$$= \exp(h(x_0)) \int_a^b \exp\left(-\frac{1}{2} \frac{(x-x_0)^2}{-h''(x_0)^{-1}}\right) dx$$

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$N(x_0, -h''(x_0)^{-1})$ density

$$= \underbrace{\exp(h(x_0))}_{=g(x_0)} \left[\frac{\sqrt{2\pi}}{-h''(x_0)^{1/2}} \right] \left[\Phi\left(b|x_0, -h''(x_0)^{-1}\right) - \Phi\left(a|x_0, -h''(x_0)^{-1}\right) \right]$$

$$= 1 \text{ if } \begin{matrix} b = \infty \\ a = -\infty \end{matrix}$$

$$\equiv g(x_0) \int_a^b \exp\left(-\frac{1}{2} \frac{(x-x_0)^2}{-h''(x_0)^{-1}}\right) dx$$

$$h''(x_0) = \left(\frac{g'}{g}\right)'$$

$$\frac{g g'' - (g')^2}{g^2}$$

$$g \frac{\frac{g''}{g} - \frac{g'}{g} \frac{g'}{g}}{\frac{g''}{g} - \frac{g'}{g} \frac{g'}{g}}$$

$$E[\theta] = \frac{\int \theta f(y|\theta) \pi(\theta) d\theta}{\int f(y|\theta) \pi(\theta) d\theta}$$

$$E[\theta] = \int \theta p(\theta|y) d\theta$$

$$= \frac{\int \theta f(y|\theta) \pi(\theta) d\theta}{\int f(y|\theta) \pi(\theta) d\theta}$$

$$= \frac{\int \theta \exp(\log f(y|\theta) \pi(\theta))}{\int \exp(\log f(y|\theta) \pi(\theta))} d\theta$$

$h(\theta|y)$

Need θ

$$= \frac{\int \theta \exp(h(\hat{\theta}|y) + h''(\hat{\theta}|y)(\theta - \hat{\theta})^2/2) d\theta}{\int \exp(h(\hat{\theta}|y) + h''(\hat{\theta}|y)(\theta - \hat{\theta})^2/2) d\theta}$$

$$= \frac{\int \theta \exp(h''(\hat{\theta}|y)(\theta - \hat{\theta})^2/2) d\theta}{\int \exp(h''(\hat{\theta}|y)(\theta - \hat{\theta})^2/2) d\theta}$$

$$= \frac{\int \theta \frac{\sqrt{2\pi}}{h''(\hat{\theta})^{1/2}} \mathcal{Q}(\theta|\hat{\theta}, -h''(\hat{\theta})^{-1}) d\theta}{\int \frac{\sqrt{2\pi}}{h''(\hat{\theta})^{1/2}} \mathcal{Q}(\theta|\hat{\theta}, -h''(\hat{\theta})^{-1}) d\theta}$$

$$\hat{\theta}$$

$$= \hat{\theta}$$

Laplace approx to
posterior mean
is the
posterior mode!

See Lange Chap 4.6 for Laplace Approx.

Monte Carlo

Suppose we want to compute \mathbb{E}_f for $h: \mathbb{R}^K \rightarrow \mathbb{R}$

$$\mathbb{E}_f[h(X)] = \int h(x) f(x) dx$$

If we can simulate $X_1, \dots, X_n \stackrel{iid}{\sim} f$, then by the LLN,

$$\underbrace{\frac{1}{n} \sum_{i=1}^n h(x_i)}_{\text{sum}} \longrightarrow \underbrace{\mathbb{E}_f[h(X)]}_{\text{integral}}$$

Furthermore, $\text{Var} \left[\frac{1}{n} \sum_{i=1}^n h(x_i) \right] = \frac{1}{n^2} \sum_{i=1}^n \text{Var}(h(x_i))$

~~$$\text{Var} \left[\frac{1}{n} \sum_{i=1}^n h(x_i) \right] = \frac{1}{n^2} \sum_{i=1}^n \text{Var}(h(x_i))$$~~

Notice that the variance doesn't depend on dimension of X . That is, $\text{Var} \sim \frac{1}{n}$. This is very important, both good and bad,

Applications

- ① Monte Carlo / Simulation studies. We have a method that estimates a parameter $h(x) = \hat{\beta}$ and we want to explore performance of $\hat{\beta}$.
- ② $\mathbb{E}_f h(x)$ might be a posterior mean (f is post.-dis)
- ③ Might want $\int h(x) dx = \int \frac{h(x)}{f(x)} f(x) dx$
 $\approx \frac{1}{n} \sum \frac{h(x_i)}{f(x_i)}, X_1, \dots, X_n \sim f$

We need to be able to simulate numbers, i.e. from some dist. f

Random Number Generation

Most popular (and simplest) are linear congruential generators.

Let X_0 be some starting value, called the "seed".
Then generate a sequence (for $n=0, 1, 2, \dots$)

$$X_{n+1} = (aX_n + b) \bmod m$$

a = multiplier

b = increment

m = modulus

For uniform RN, just let $U_{n+1} = \frac{X_{n+1}}{m}$

Ideally, X_1, X_2, \dots will hit every number from 0 to $m-1$ before repeating.

of steps until repeat is "period".

A "maximal period generator" has period m .

Setting a, b , and m is a very tricky business.

For example, this is bad

$$X_{n+1} = (2X_n + 0) \bmod 2^{32}$$

One good set is

$$a = 106, \quad b = 1283, \quad m = 6075$$

There are quadratic and cubic PRNGs, but they require more work and not much better, i.e.

$$X_{n+1} = (aX_n^2 + bX_n + c) \bmod m$$

LCG are not useful for things like cryptography. Any polynomial generator can be broken.

RNG are critical for stream ciphers which ~~generate~~

Use linear feedback shift registers (LFSR)
"bread + butter"

All PRNGs produce deterministic sequences that "look" random

One can check "randomness" of sequence with a test for uniformity

- Kolmogorov-Smirnov test
- Chi-square test

Marsaglia has "die hard" tests

Also, many PRNGs generate good 1-D sequences but do not look random in > 1 dimension

It may be stuck on a hyperplane.

exponential(1)

$$f(x) = e^{-x}$$

$$F(x) = 1 - e^{-x}$$

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$$F^{-1}(u) = -\log(1-u)$$

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Uniforms are good but we need values from some density f . First, assume you can simulate $\text{Unif}(0,1)$

* Integral transform / rescaling

$$(1) u \sim \text{Unif}(0,1)$$

$$(2) X \sim F^{-1}(u), \text{ where } F(x) = \int_{-\infty}^x f(x) dx \text{ cdf.}$$

* Transformation

$$(1) Z_1 = \sqrt{-2\log u_1} \cos(2\pi u_2) \quad \text{i.i.d.} \\ \sim N(0,1)$$

$$Z_2 = \sqrt{-2\log u_1} \sin(2\pi u_2)$$

$$(2) \text{Beta}(\alpha, \beta) = \frac{X}{X+Y} \sim \text{Beta}(\alpha, \beta)$$

$$\text{where } X \sim \text{gamma}(\alpha, 1) \\ Y \sim \text{gamma}(\beta, 1)$$

$$(3) \mu \sim \text{gamma}(\alpha, \beta) \\ Y/\mu \sim \text{Poisson}(\mu)$$

$$Y \sim \text{neg. binomial}$$

Most standard dist. are implemented in R.

$$p(y) = \int_0^{\infty} \underbrace{p(y|\mu)}_{\text{Poisson}} \underbrace{p(\mu)}_{\text{gamma}} d\mu$$

Multivariate Normal

Want $X \sim N(\mu, \Sigma)$

Let $\Sigma = L^T L$ (cholesky decomp)

① Simulate $Z \sim N(0, I)$

② $X = \mu + L Z \sim N(\mu, \Sigma)$

Sequential sampling

Rejection sampling

A way of generating samples/obs. from f by thinning out obs/samples from a candidate density g . ("Random thinning")

Suppose f is our target density and we can evaluate it.

Let g be our candidate density that we can simulate from.

Let X_f be the support of f and X_g be support of g and assume $X_f \subset X_g$

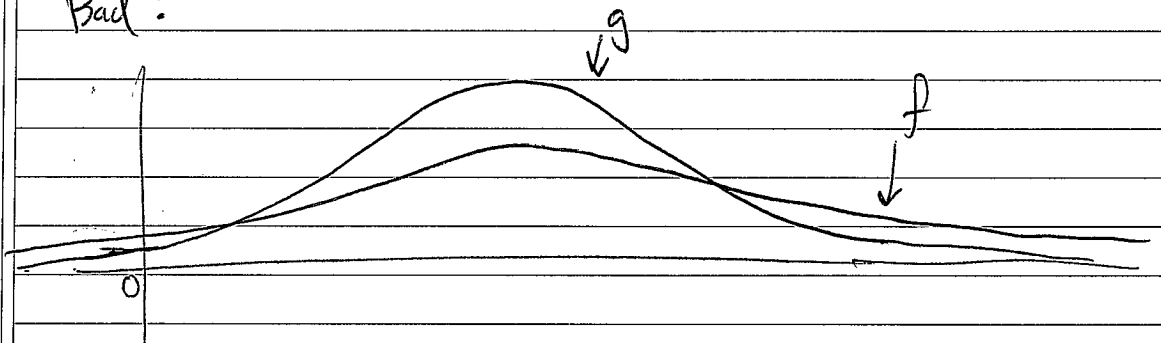
Assume $C = \sup_{x \in X_f} \frac{f(x)}{g(x)} < \infty$

and that we can calculate C

④ The higher the dimension of f, g the more inefficient rejection sampling will be.

⑤ Whether $C = \infty$ depends (usually) on the tails of the candidate, which must be heavier than the target

Bad:



As $x \rightarrow \infty$, $g(x) \downarrow 0$ faster than $f(x) \downarrow 0$.
 $\Rightarrow f(x)/g(x) \uparrow \infty$.

\Rightarrow What if we cannot calculate $C = \sup \frac{f(x)}{g(x)}$?

Can we estimate C ? Yes!

Empirical sup rejection sampling (calto '02)

① Guess $\hat{C} \geq 1$

② Generate $U \sim \text{uniform}(0,1)$, $X \sim g$

③ Accept X if $U \leq \frac{f(X)}{\hat{C}g(X)}$

④ Update $\hat{C}^* = \max \left\{ \hat{C}, \frac{f(X)}{g(X)} \right\}$ \longleftrightarrow sup estimator

⑤ Goto step ②, set $\hat{C} = \hat{C}^*$

$$h(x) = \frac{f(x)}{g(x)}$$

$$h(x_n), h(x_{n+1})$$

$$x_{n+1} = x_n - \alpha h(x_n)$$

Rejection Sampling

- ① simulate $u \sim \text{uniform}(0,1)$
- ② Simulate $X \sim g(X)$
- ③ IF $u \leq \frac{f(X)}{cg(X)}$, "accept" X
 otherwise, ~~go to~~ discard X
 go back to ①.

let $X_1, X_2, \dots \stackrel{\text{iid}}{\sim} g$

$X_1 \quad X_2 \quad X_3 \quad X_4 \quad X_5 \quad X_6 \quad X_7 \quad \dots$

0 0 1 0 1 0 0 ...
 reject reject accept accept
 geometric(p)

iid coin flips

sample size of 2.

of flips until acceptance is geometric w/
 success probability $1/c$.

pf: $P(X \text{ accepted}) = P(u \leq \frac{f(x)}{cg(x)})$

$$= \int P(u \leq \frac{f(x)}{cg(x)} | X=x) g(x) dx$$

$$= \int \frac{f(x)}{cg(x)} g(x) dx$$

$$= 1/c$$

The dist. of accepted values is f .

$$P(X \leq t | X \text{ accepted})$$

$$= \frac{P(X \leq t, X \text{ accepted})}{P(X \text{ accepted})}$$

$$= \frac{E_g[1\{X \leq t\} 1\{X \text{ accepted}\}]}{1/c}$$

$$= c E_g E_g[1\{X \leq t\} 1\{u \leq \frac{f(x)}{cg(x)}\} | X]$$

$$= c E_g[1\{X \leq t\} \frac{f(x)}{cg(x)}]$$

$$= c \int 1\{x \leq t\} \frac{f(x)}{cg(x)} g(x) dx$$

$$= \int_{-\infty}^t f(x) dx = F(t)$$

Notes:

- ① Only need to know f or g up to a constant of proportionality
- ② Any number $c' > c$ will work, but will be less efficient.
- ③ Operations can (and should) be performed on log scale

ESUP

Extra assumption is need for ~~ESUP~~.

$$c = \frac{f(x_c)}{g(x_c)} \text{ for some } x_c \in \mathcal{X}_f$$

& (sup is achievable)

This is satisfied if g has heavier tails than f .

~~Call to prove that~~
~~if f is discrete~~

let x_1, x_2, x_3, \dots i.i.d g

$x_1 \quad x_2 \quad x_3 \quad x_4 \quad x_5 \quad x_6 \quad \dots$

True C

\tilde{y}_i 0 0 1 0 1 0
 accept accept

 \hat{c}

y_i 1 0 1 0 0 0
 accept accept accept ~~reject~~
 error error

Call to showed that

① ~~$P(Y_i \neq \tilde{Y}_i \text{ i.o.}) = 0$~~ if f is discrete

~~By assumption 3~~, $\exists x_c \in \mathcal{X}_f$ s.t. $c = \frac{f(x_c)}{g(x_c)}$.

Let $\gamma = \min_i \{X_i = x_c\}$ where $X_i \sim g$.

Then $\gamma \sim \text{geometric}(g(x_c))$. Once $\hat{c} = c$, algorithms are the same.

Coupling lemma \Rightarrow

$$P(Y_i \neq \tilde{Y}_i) \leq P(\gamma \geq i) = (1 - g(x_c))^{i-1}$$

$$\Rightarrow \sum_{i=1}^{\infty} P(Y_i \neq \tilde{Y}_i) < \infty$$

② For continuous f , it's trickier. In general,

$$P(Y_i \neq \tilde{Y}_i) = O(i^{-1})$$

But if $\log(f/g)$ is smooth (twice differentiable) and unimodal (w/mode at x_c), then

$$P(Y_i \neq \tilde{Y}_i) = O(i^{-2})$$

Suggests a "burn-in", ~~of~~ discard first several variables.

More on burn-in with MCMC

~~Can~~ Often we want to simulate from

$$p(\theta|y) \propto \underbrace{f(y|\theta)}_{\text{likelihood}} \underbrace{\pi(\theta)}_{\text{prior}}$$

\Rightarrow use π as the candidate dist:

$$C = \sup_{\theta} \frac{p(\theta|y)}{\pi(\theta)} = \sup_{\theta} f(y|\theta) = \underbrace{f(y|\hat{\theta})}_{\substack{\text{MLE} \\ \text{potential mode}}}$$

Rejection sampling is

- ① Simulate $U \sim \text{uniform}(0,1)$
- ② Simulate $\theta \sim \pi$
- ③ Accept θ if $U \leq \frac{p(\theta|y)}{C\pi(\theta)} = \frac{f(y|\theta)}{f(y|\hat{\theta})}$

$$\sum_{n=1}^{\infty} \frac{1}{n^2}$$

$$= \int_1^{\infty} x^{-2}$$

$$= \frac{1}{x} \Big|_1^{\infty}$$

$$= 1 - 0 = 1$$

Ex: $Y_i \rightarrow Y_n \overset{i.i.d}{\sim} N(\mu, \sigma^2)$

Prior $= \pi(\mu) = N(0, B) \xrightarrow{\text{BIG}}$

$$\pi(\sigma^2) = \text{IG}(\alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} 2^{-\alpha-1} e^{-\beta/2} = \beta(\alpha)$$

MLE: $\hat{\mu} = \bar{Y}, \hat{\sigma}^2 = S^2 = \frac{1}{n} \sum (Y_i - \bar{Y})^2$

$$C = f(Y|\hat{\mu}, \hat{\sigma}^2) = \frac{1}{(\sqrt{2\pi})^n \hat{\sigma}^2} e^{-\frac{1}{2\hat{\sigma}^2} \sum (Y_i - \hat{\mu})^2}$$

$$= \left(\frac{1}{\sqrt{2\pi}} \right)^n \left(\frac{\sum (Y_i - \bar{Y})^2}{n} \right)^{-n/2} e^{-\frac{n}{2}}$$

① Simulate $U \sim \text{unif}(0,1)$

② Simulate $\mu \sim N(0, B), \frac{1}{\sigma^2} \sim \text{gamma}(\alpha, \beta)$

③ Accept (μ, σ^2) if

$$U \leq \frac{f(Y|\mu, \sigma^2)}{f(Y|\hat{\mu}, \hat{\sigma}^2)} = \left(\frac{\sum (Y_i - \bar{Y})^2}{n \sigma^2} \right)^{n/2} \exp\left(-\frac{1}{2\sigma^2} \sum (Y_i - \mu)^2 + \frac{n}{2}\right)$$

Given a sample from $p(\theta|y)$ we can compute confidence/posterior intervals, mean, variance, etc.

What does ESUP do? It searches for MLE by random search.