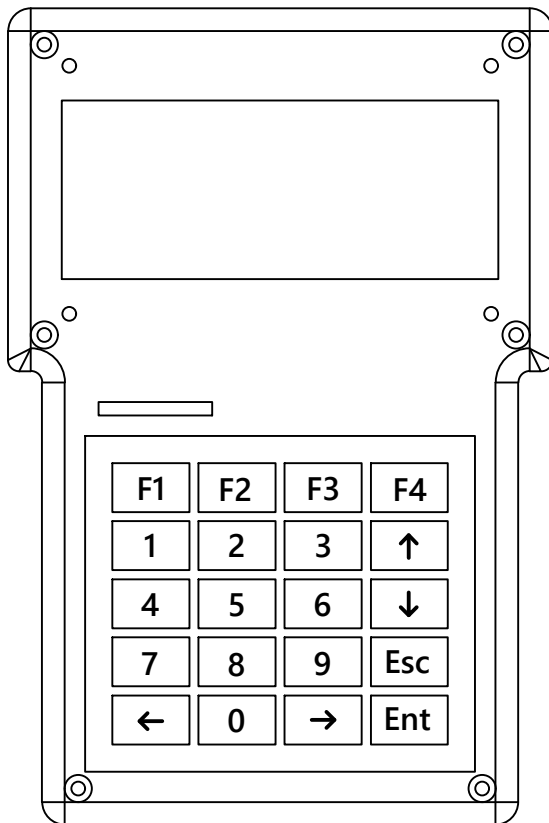


# PENDANT INTERFACE GUIDANCE

## PENDANT INTERFACE



## MAPPING RUNNING MENU

KEY	FUNCTION	VALUE
F1	Change mapping menu	-
F2	Set control mode	Position ctrl Angle Control
F3	Move cursor	-
F4	Set change value mode	Continues mode Distance mode Step mode
↑	Increase move value	-
↓	Decrease move value	-
←	Next point	-
→	Previous point	-
Esc	Back to home menu	-
Ent	Save pattern	-

## HOME MENU

KEY	FUNCTION	VALUE
F1	Auto home	-
F2	Set control mode	Position ctrl Angle Control
F3	Move cursor	-
F4	Set change value mode	Continues mode Distance mode Step mode
Num	Set distance value	-
↑	Increase move value	-
↓	Decrease move value	-
←	Delete	-
→	OK	-
Esc	Insert coma	-
Ent	Move to preparation menu	-

## PREPARATION MENU

KEY	FUNCTION	VALUE
F1	Change running mode	Welding, Mapping, Preview
F2	Change running speed	LOW, MED, HIGH
↑	Increase preview point	-
↓	Decrease preview point	-
Esc	Back to home menu	-
Ent	Start running	-

## WELDING RUNNING MENU

KEY	FUNCTION	VALUE
F1	Pause	-
F2	Hold lcd information	-
←	Previous running menu	-
→	Next running menu	-
Esc	Stop	-
Ent	Continue	-

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HALAMAN : 1/3 TANGGAL : 12 Juli 2024

PERANCANGAN INTERFACE PENDANT  
UNTUK WELDING ARM MANIPULATOR 6 DOF

STR - TEKNIK LISTRIK INDUSTRI  
SEKOLAH VOKASI UNIVERSITAS DIPONEGORO  
SEMARANG

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