QIUSHI LYU

Peking University

@ Ivqiushi2015@gmail.com, Ivqiushi@stu.pku.edu.cn ■ 447, Building 45B, Peking University, Beijing, 100871 alfredlyu.github.io

♠ AlfredLyu

EDUCATION

Bachelors of Computer Science and Technology (Turing Class) Peking University

Sept. 2021 - Present

Beijing, China

- GPA 3.92/4.00, Rank 1/121
- Gold medalist at the 2020 China National Olympiad in Informatics (NOI), leading to direct admission into Peking University.
- Entered Peking University for preparatory studies from Mar. 2021 to Aug. 2021.

Visiting Student

Massachusetts Institute of Technology

Mar. 2024 - Aug. 2024

Boston, US

- Advised by Prof. Joshua B. Tenenbaum and Prof. Chuang Gan.
- Specialized in Computer Vision, Multimodal Learning and Embodied Al.

RESEARCH INTERESTS

Computer Vision

Multimodal Learning

Embodied AI and Robotics

Cognitive Al

LANGUAGES

Chinese: Native Speaker English: TOEFL 105(MyBest 106,

Speaking 23), GRE 320

PUBLICATIONS (*DENOTES EQUAL CONTRIBUTION)

Constrained Human-Al Cooperation: An Inclusive Embodied Social Intelligence Challenge [link]

NeurIPS 2024 D & B Track

Authors: Weihua Du*, **Qiushi Lyu***, Jiaming Shan, Zhenting Qi, Hongxin Zhang, Sunli Chen, Andi Peng, Tianmin Shu, Kwonjoon Lee, Behzad Dariush, Chuang Gan

• We created a new benchmark, named CHAIC, to test embodied agents' ability to actively perceive human partners' intents and constraints from egocentric visual observations. We designed new agents with real physical constraints and some long-horizon tasks featuring both indoor and outdoor scenes.

COMBO: Compositional World Models for Embodied Multi-Agent Cooperation [link]

Submit to ICLR 2025

Authors: Hongxin Zhang*, Zeyuan Wang*, Qiushi Lyu*, Zheyuan Zhang, Sunli Chen, Tianmin Shu, Yilun Du, Chuang Gan

- ICLR 2025 average review score 6.67 (8, 6, 6)
- We introduced an embodied multi-agent planning framework that leverages a compositional world model to empower
 the agents to imagine how different actions may affect the world in the long run and used a tree search algorithm to
 plan more cooperatively. The compositional world model can be learned as a video diffusion model by factorizing joint
 actions of agents and compositionally generating the future frames of the world state.

2.5D video-audio generation from single image

In Progress

Authors: Sunli Chen*, Qiushi Lyu*, Haotian Yuan*, Kaizhi Qian, Yang Zhang, Chuang Gan

• We created a pipeline to generate stereo sound from silent videos and used it to generate a high-quality video dataset with stereo sound. We trained a model on this dataset that jointly generates video and stereo sound given an initial frame and text instruction.

MagnifierSketch: A Unified Data Structure for Efficient Aggregate and Per-Flow Latency Quantile Estimation Submit to WWW 2025

Authors: Jiarui Guo*, **Qiushi Lyu***, Yuhan Wu*, Haoyu Li*, Tong Yang, Zhaoqian Yao, Yuqi Dong, Peiqing Chen, Xiaolin Wang

• We proposed MagnifierSketch, an efficient algorithm for per-flow latency quantile estimation, which is unbiased and significantly better than the state-of-the-art algorithms.

SELECTED PRIZES

May 4th Scholarship The best scholarship in Peking University, has equivalent status to National Scholarship	Dec. 2023
POSCO Asia Fellowship Comprehensive Excellent Award sponsored by POSCO	Dec. 2022
International Collegiate Programming Contest (ICPC) Asia-East Continent Final Contest Rank 4, Gold Medal	Jul. 2022
International Collegiate Programming Contest (ICPC) Shenyang Regional Contest Rank 1, Gold Medal, beat the ICPC World Final Champion	Nov. 2021
China National Olympiad in Informatics (NOI) 2020 Rank 45, Gold Medal	Aug. 2020

EXPERIENCES

Research Intern

MIT-IBM Watson AI Lab, Massachusetts Institute of Technology

Aug. 2023 - Present

Boston, US / Remote

- Advised by Prof. Joshua B. Tenenbaum and Prof. Chuang Gan.
- Developed COMBO, an embodied multi-agent planning framework that leverages a compositional world model to empower the agents to imagine future states and plan more cooperatively.
- Also Developed *CHAIC*, a new benchmark to test embodied agents' ability to actively perceive human partners' intents and constraints from egocentric visual observations and cooperate with them more efficiently.
- Another ongoing work aimed to generate a high-quality video dataset with stereo sound and train a model on this dataset that jointly generates video and stereo sound given an initial frame and text instruction.

Research Intern

Peking University

📋 Jan. 2023 - July. 2023

Beijing, China

- · Advised by Prof. Tong Yang.
- Focused on sketch algorithms, introduced MagnifierSketch, an efficient algorithm for per-flow latency quantile estimation.

TEACHING EXPERIENCE

Teaching Assistant: Discrete Mathematics and Structures(I)

Fall 2023

SKILLS & INTERESTS

Programming Languages: proficient in Python, C, C++; experienced in Java, Haskell, MATLAB.

Hobbies: the game of Go (5 Dan), soccer, swimming