

Politecnico di Torino

schivaTO

OBSTACLE AVOIDANCE SYSTEM

ELECTRONIC SYSTEMS ENGINEERING

PROF: PASERO EROS

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PROJECT SPECIFICATIONS

Design a small, low power and precise obstacle avoidance system for various applications.

The system is in charge of detecting obstacles in range of a predefined sensing distance. Collected data are then sent via Bluetooth Low Energy to an external application.

Use-case scenarios

Work with extreme precision.





Avoid obstacles. Avoid house-works.

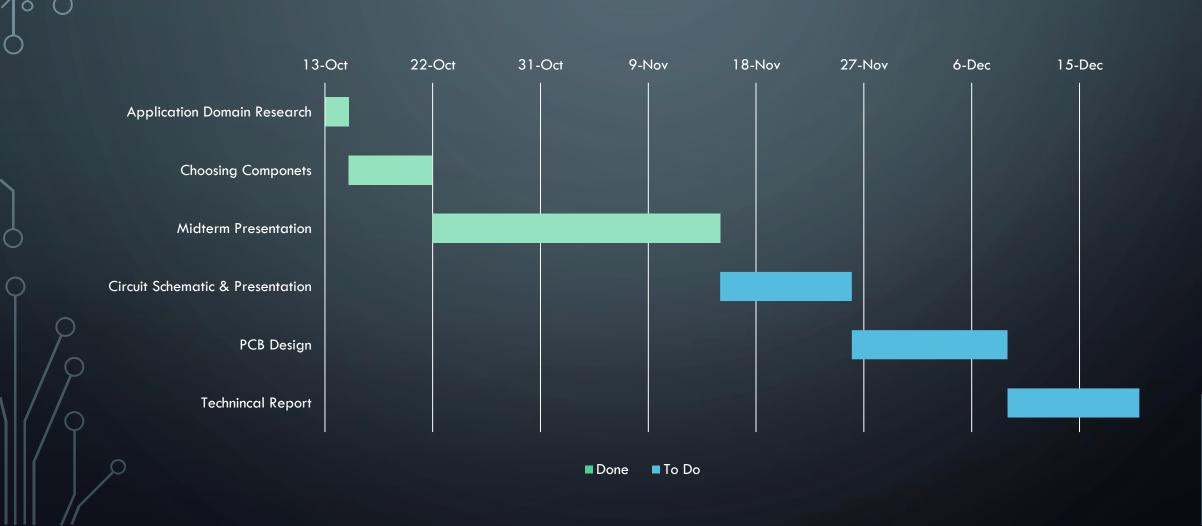
Avoid cars too.



DEVICE SPECIFICATIONS

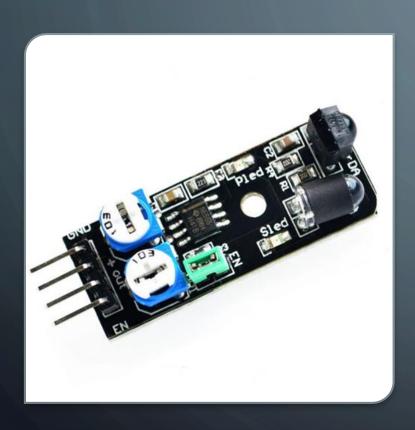
- Low cost device
- Low power consumption
- Self-contained power source
- Small to medium distance detection (range between 2cm and 40cm)

GANTT DIAGRAM



ELECTRONIC COMPONENTS

IR KY-032 OBSTACLE AVOIDANCE SENSOR



• Working voltage: 3.3V – 5V DC

• Working current: ≥ 20mA

• Working temperature : -10°C - 50°C

• **Detection distance:** 2cm - 40cm [0.79in - 15.75in]

• **IO** interface: 4-wire interface (-/+/S/EN)

• Adjustment method: multi-turn resistance adjustment

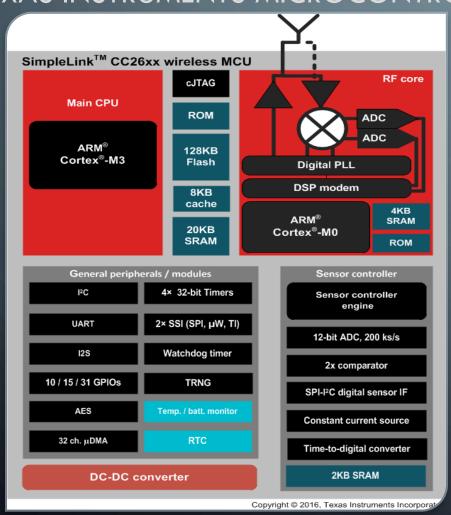
• IR pulse frequency: 38kHz

• Effective angle: 35°

• Board Size: 1.6cm x 4cm

• Weight: 9g

ELECTRONIC COMPONENTS TEXAS INSTRUMENTS MICROCONTROLLER CC2640F128RSMT



Number of Pins: 32

• Clock Frequency: 48 MHz

Interfaces: I2C, SPI, UART

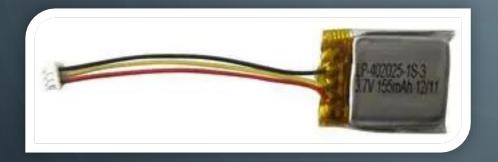
• Operating Temperature Range : -40°C - 85 °C

Max Supply Voltage: 1.7 V - 3.8 V

• Number of GPIOs: 10

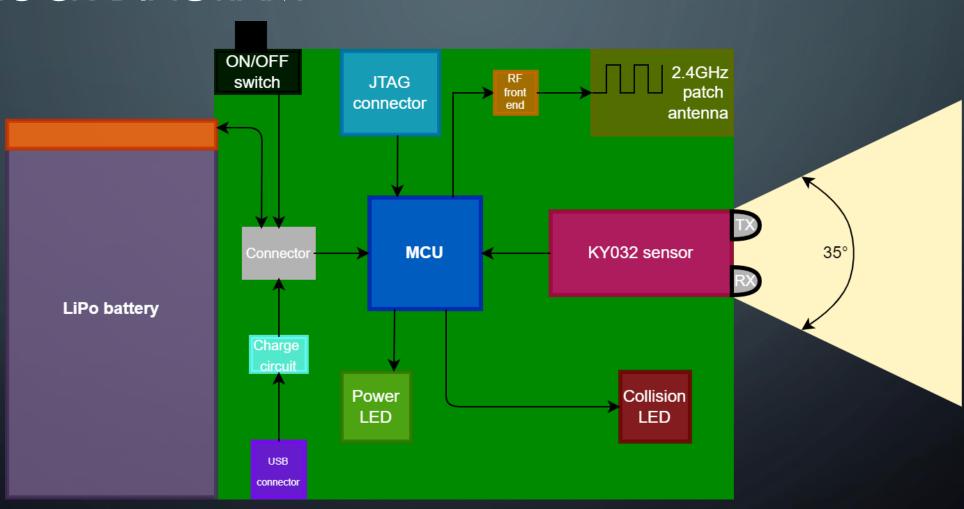
• Dimensions: 4mm x 4mm x 1mm

ELECTRONIC COMPONENTS LIPO BATTERY LP-402025-IS-3



- Nominal Capacity(0.2C): 165 mAh (typical)
- **Nominal Voltage:** 3.7 V (0.2C discharge)
- Charging Voltage: 4.2 V
- Maximum Charging Current: 155 mA
- Maximum Continuous Discharge Current: 310 mA
- Dimensions: 20 mm x 26 mm x 3.8 mm
- **Weight**: 4 g

BLOCK DIAGRAM



CHOSEN APPROACH

- The module is thought to work both powered by the LiPo battery or from an external power source. So that, the battery can be unplugged in favor of the external power lines.
- The ON/OFF switch has been added in order to reduce the power consumption during idle periods.
- Power & Collision LEDs have been introduced to notify the status of the system.
- The KY-032 sensor can be reproduced directly onto the PCB thus removing the additional costs introduced by buying an external module (see Market Analysis).

POWER CONSUMPTION ESTIMATION

The estimations rely upon the datasheets of each component.

- Texas Instruments MCU: Supposing 30% idle mode and 70% active mode power consumption is given by: $0.3*550 \,\mu\text{A} + 0.7*(1.45 \,\text{mA} + 48 \,\text{MHz} * 31 \,\mu\text{A}/\text{MHz}) = 2.2 \,\text{mA}$
- Obstacle Sensor: Value taken from the datasheet reports minimum supply current >= 20 mA

As a result, the total supply current required is around 22.2 mA. Given that the current requirements are particularly low, we can choose a small capacity LiPo battery in order to have a duration of around 4.5 hours.

MARKET ANALYSIS (COTS)

Analysis done with KY-032 sensor as a component off the shelf.

COSTS ESTIMATION FOR 1000 SchivaTO pieces:

IR KY-032 OBSTACLE AVOIDANCE SENSOR	2000 €
Charge controller MAX1555	1250 €
 Regulating charge pump MAX1759 	3600 €
TEXAS INSTRUMENTS MICROCONTROLLER CC2640F128RSMT	2170 €
• LiPo battery LP-402025-IS-3	8900 €
Total (1000 pieces)	17,920 €
Total (1 piece)	17.92 €

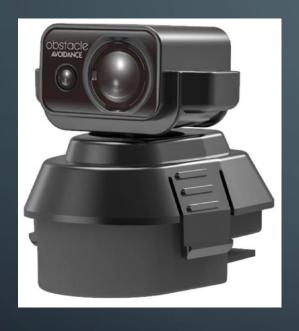
MARKET ANALYSIS (NO COTS)

Analysis done with KY-032 sensor directly reproduced on the PCB.

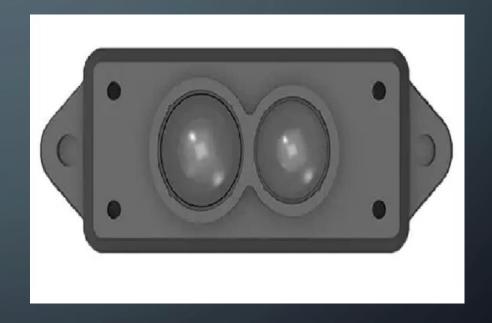
COSTS ESTIMATION FOR 1000 SchivaTO pieces:

Total (1 piece)		17.55 €
Total (1000 pieces)		17,551 €
• LiPo battery LP-4020	D25-IS-3	8900 €
TEXAS INSTRUMENTS	S MICROCONTROLLER CC2640F128RSMT	2170€
Regulating charge p	ump MAX1 <i>75</i> 9	3600€
• Charge controller M	AX1555	1250€
• IR333-A - IR Diod	e transmitter	58€
• S0038B3VM – IR Red	ceiver	545 €
• NE555 Timer		198€
 Resistive Trimmer (5kg) 	Ω and $10 \mathrm{k}\Omega$)	780 €

MARKET COMPARISON



ZLL SG906 Laser Obstacle Avoider 36,11€



Tfmini LiDAR Module Obstacle Avoider 49,15€

Our device guarantees a profit margin of at least 15€