

Formalizing Intuition

A UWD is a cospan

$$P_1 + \dots + P_n \rightarrow J \leftarrow P'$$

We compose UWDs by nesting

$$\begin{array}{ccc}
 & & P' \\
 & & \downarrow \\
 & P_1 + \dots + P_n \rightarrow J \\
 & \downarrow & \downarrow \\
 X_{11} + \dots + X_{1m_1} & & \\
 \vdots & & \\
 X_{n1} + \dots + X_{nm_n} & \xrightarrow{\quad} & k_1 + \dots + k_n \rightarrow L
 \end{array}$$

A UWD algebra is a way of assigning data to a UWD in a way that respects nesting.

So UWD Alg is a lax monoidal functor $F : (\text{Cospan}(\text{FinSet}), +) \rightarrow (\text{Set}, \times)$

Given a UWD

$$\Phi : P_1 + \dots + P_n \xrightarrow{i} J \xleftarrow{o} P'$$

$$F(\Phi) : FP_1 \times \dots \times FP_n \rightarrow FP'$$

Laxator gives us

$$FP_1 \times \dots \times FP_n \xrightarrow{\ell} F(P_1 + \dots + P_n) \rightarrow FP'$$

Then use hom map \longrightarrow

• Functoriality means we respect nesting.

For this talk, only care about

$$p_1 + \dots + p_n \xrightarrow{\Phi} J = J$$

So just need

$$F: (\text{FinSet}, +) \rightarrow (\text{Set}, *)$$

Review

$$\text{Opt}: (\text{FinSet}, +) \rightarrow (\text{Set}, *)$$

$$N \mapsto \{f: \mathbb{R}^N \rightarrow \mathbb{R} \mid f \in C^1\}$$

$$(\phi: N \rightarrow M)(f) \mapsto f \circ \phi^*$$

$$\varphi_{N,M}: \text{Opt}(N) \times \text{Opt}(M) \rightarrow \text{Opt}(N+M)$$

$$(f, g) \mapsto f \circ \iota_N^* + g \circ \iota_M^*$$

$$(N \xrightarrow{\iota_N} N+M \xleftarrow{\iota_M} M)^* = (\mathbb{R}^N \xleftarrow[\iota_N^*]{\pi_N^*} \mathbb{R}^N \oplus \mathbb{R}^M \xrightarrow[\iota_M^*]{\pi_M^*} \mathbb{R}^M)$$

$$\text{Dynam}: (\text{FinSet}, +) \rightarrow (\text{Set}, *)$$

$$N \mapsto \{\mathbb{R}^N \rightarrow \mathbb{R}^N\}$$

$$(\phi: N \rightarrow M)(v) \mapsto \phi_* \circ v \circ \phi^*$$

$$\varphi_{N,M}:$$

$$(v, w) \mapsto \iota_{N*} \circ f \circ \iota_N^* + \iota_{M*} \circ g \circ \iota_M^*$$

$$(N \xrightarrow{\iota_N} N+M \xleftarrow{\iota_M} M)_* = (\mathbb{R}^N \xrightarrow{\iota_N} \mathbb{R}^N \oplus \mathbb{R}^M \xleftarrow{\iota_M} \mathbb{R}^M)$$

Gradient flow takes

$$f \in \text{Opt}(\mathcal{N}) \rightarrow -\nabla f \in \text{Dynam}(\mathcal{N})$$

How do we know it respects all our UWD structure?

Answer: NTS a monoidal NT.

flow: $\text{Opt} \Rightarrow \text{Dynam}$

$$\text{flow}_{\mathcal{N}}(f) := -\nabla f$$

Proof:

$$\begin{array}{ccc} \text{Opt}(\mathcal{N}) & \xrightarrow{\text{Opt}(\phi)} & \text{Opt}(\mathcal{M}) \\ \text{flow}_{\mathcal{N}} \downarrow & & \downarrow \text{flow}_{\mathcal{M}} \\ \mathcal{D}(\mathcal{N}) & \xrightarrow{\mathcal{D}(\phi)} & \mathcal{D}(\mathcal{M}) \end{array}$$

Let $f \in \text{Opt}(\mathcal{N})$ & $P = \mathcal{M}(\phi^*)$. chain rule

$$\begin{array}{ccc} f \mapsto f \circ P \mapsto -\nabla(f \circ P) & \stackrel{!}{=} & -\nabla P^T \circ \nabla f \circ P \\ \downarrow & \text{!} & \downarrow \text{!} \\ -\nabla f \mapsto -P^T \circ \nabla f \circ P & \stackrel{!}{=} & P^T \circ \nabla f \circ P \end{array}$$

// z-linearity

Monoidal:

$$\begin{array}{ccc} \text{Opt}(\mathcal{N}) \times \text{Opt}(\mathcal{M}) & \xrightarrow{\text{flow} \times \text{flow}} & \mathcal{D}(\mathcal{N}) \times \mathcal{D}(\mathcal{M}) \\ \eta_{\mathcal{N}, \mathcal{M}} \downarrow & \parallel & \downarrow \eta_{\mathcal{N}, \mathcal{M}} \\ \text{Opt}(\mathcal{N} + \mathcal{M}) & \xrightarrow{\text{flow}} & \mathcal{D}(\mathcal{N} + \mathcal{M}) \end{array}$$

Talk about how this enables message passing semantics.

• Draw a UWD. Illustrate

→ distribute → compute → collect
(in parallel)

• Naturality guarantees distr alg is correct!

What about constraints & min/max?

• They are actually the same thing!

consider:

minimize $f(x)$ \leftarrow convex

subject to $Ax = b$ \leftarrow affine

$$L(x, \lambda) := f(x) + \lambda^T (Ax - b)$$

↑ ↑
convex concave

Uzawa's Alg:

$$\begin{aligned} x_{k+1} &= x_k - \delta \nabla_x L(x_k, \lambda_k) \leftarrow \text{gradient descent in cvx vars} \\ &= x_k - \delta (\nabla f(x) + \lambda^T A) \end{aligned}$$

$$\begin{aligned} \lambda_{k+1} &= \lambda_k + \delta \nabla_\lambda L(x_k, \lambda_k) \leftarrow \text{gd ascent in conc vars.} \\ &= Ax - b \end{aligned}$$

↑ integrate constraint violation

How to keep track of convex vs. concave vars?

Answer: Have you tried slice cuts?

$$\text{Saddle} : (\text{FinSet} /_{\{\downarrow, \uparrow\} \cong 2} , +) \rightarrow (\text{Set}, \times)$$

Review of slice cuts:

$$\text{Obs} : N \xrightarrow{\tau} 2$$

$$\text{Homs} : N \xrightarrow{\phi} M$$

$$\tau_N \downarrow \cong \downarrow \tau_M$$

For $\text{Saddle}(N \xrightarrow{\tau} 2)$, let $N_1 := \tau^{-1}(\downarrow)$ &
 $N_2 := \tau^{-1}(\uparrow)$.

$$\tau \mapsto \{ f : \mathbb{R}^N \cong \mathbb{R}^{N_1} \oplus \mathbb{R}^{N_2} \rightarrow \mathbb{R} \mid f \in C^1 \wedge$$

$$f(\cdot, y) \text{ is convex } \forall y \in \mathbb{R}^{N_2} \wedge$$

$$f(x, \cdot) \text{ is concave } \forall x \in \mathbb{R}^{N_1} \}$$

& same as Opt.

$$\begin{array}{ccc} \text{FinSet}/2 & \xrightarrow{\text{Saddle}} & \text{Set} \\ \downarrow u & \Downarrow & \\ \text{FinSet} & \xrightarrow{\text{Dynam}} & \end{array} \quad \text{flow: Saddle} \Rightarrow \text{Dynam} \circ u.$$

$$\text{Flow}_{N \xrightarrow{\tau} 2}(L)(x) := i \mapsto \begin{cases} -\nabla L(x)(i) & \text{if } \tau(i) = 0 \\ \nabla L(x)(i) & \text{if } \tau(i) = 1 \end{cases}$$

$$\forall i \in N.$$

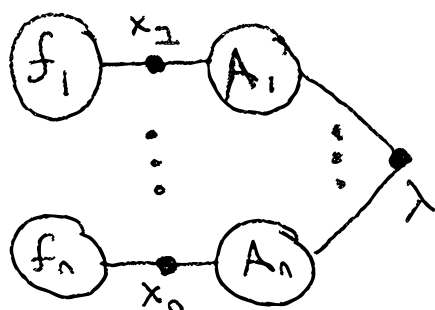
$$\text{Flow}(\tau) : \text{Saddle}(\tau) \rightarrow \text{Dynam}(N)$$

Close w/ nice example:

Many probs of form

$$\text{minimize } f_1(x_1) + \dots + f_n(x_n)$$

$$\text{subject to } A_1 x_1 + \dots + A_n x_n = 0$$



Message Passing Uzawa's!

IG time, talk abt current work.