# Advanced Techniques for Combinatorial Algorithms: Approximation Algorithms

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# **NPO**

### Optimization problem

- ullet Infinite set  ${\mathcal I}$  of instances. The set  ${\mathcal I}$  is recognizable in polynomial time
- For each instance  $I \in \mathcal{I}$ , the set F(I) of feasible solutions. Each set F(I) is recognizable in polynomial time. The set of all feasible solutions is  $\mathcal{F}$
- An objective function  $w: \mathcal{I} \times \mathcal{F} \mapsto \mathbb{Q}^+$ . w is a partial function w(i, x) can be undefined if  $x \notin F(i)$ . w is computable in polynomial time
- Goal: to minimize or to maximize

### Approximation factor

$$\frac{APX}{OPT}$$

APX: value of (approximate) feasible solution, OPT: value of best feasible solution

# Min Vertex Cover

#### Instance

Undirected graph  $G = \langle V, E \rangle$ 

#### Feasible solutions

A set  $C \subset V$  such that for each edge  $e \in E$  at least one endpoint of e belongs to C





# Objective function

|C|

# Max Clique

#### Instance

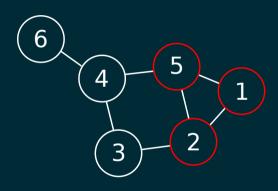
Undirected graph  $G = \langle V, E \rangle$ 

#### Feasible solution

Find a set  $C \subset V$  such that all pairs of vertices in C are connected by an edge

### Objective function

|C|



# Max Independent Set

#### Instance

Undirected graph  $G = \langle V, E \rangle$ 

#### Feasible solution

Find a set  $I \subset V$  such that no two vertices in K are connected by an edge





#### Objective function

|K|

# Max Cut

#### Instance

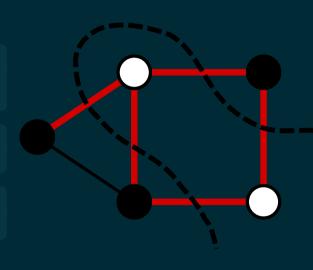
A weighted undirected graph  $G = \langle V, E \rangle$ ,  $w : E \mapsto \mathbb{Q}^+$ 

#### Feasible solution

a bipartition  $(V_1, V_2)$  of V

### Objective function

 $\sum_{v_1 \in V_1, v_2 \in V_2} w(v_1, v_2)$ 



# Min Traveling Salesperson (TSP)

#### Instance

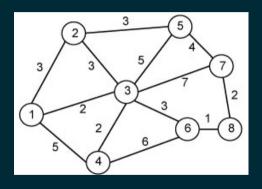
A weighted undirected graph  $G = \langle V, E \rangle$ ,  $w : E \mapsto \mathbb{Q}^+$ 

#### Feasible solution

Find a cycle C that visits each vertex  $v \in V$  exactly once.

### Objective function

 $\sum_{e \in C} w(e)$ 



# **Approximation Goal**

### Complexity classes

- NPO: Optimization problems in NP
- FPTAS: Fully polynomial-time approximation scheme. Guaranteed error ratio  $(1+\epsilon)$  or  $(1-\epsilon)$ , for any  $\epsilon>0$ . Time complexity polynomial in n and  $\frac{1}{\epsilon}$
- PTAS: Polynomial-time approximation scheme. Guaranteed error ratio  $(1+\epsilon)$  or  $(1-\epsilon)$ , for any  $\epsilon>0$ . Time complexity polynomial in n — can be exponential in  $\frac{1}{\epsilon}$ , e.g.  $O(n^{1/\epsilon})$
- $\bullet$  APX: O(1) approximation ratio, polytime
- MAX SNP: Definition based on logic and L-reduction. MAX SNP is included in APX

# Min Set Cover

#### Instance

Universe set U, collection

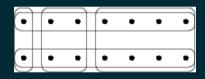
$$\mathcal{S} = \{S_1, \dots, S_n\}$$
 of subsets of  $U$ . Weight  $w : \mathcal{S} \mapsto \mathbb{O}^+$ 

#### Feasible solutions

A cover, that is a subcollection C of S that covers all elements of U

# Objective function

$$\sum_{C \in \mathcal{C}} w(C)$$



# Min Set Cover

#### **Algorithm 1:** greedy-set-cover

- 1  $C, D \leftarrow \emptyset$ ;
- 2 while  $C \neq U$  do
- 3  $X \leftarrow \text{the set in } S \text{ minimizing } w(X)/|X \setminus C|$ ;
- 4  $\alpha = \frac{w(X)}{|X \setminus C|}$ ;
- 5 Add *X* to *D*;
- For each  $e \in C \setminus X$ ,  $p(e) \leftarrow \alpha$ ;
- 7  $C \leftarrow C \cup X$
- 8 Output D

#### Lemma

$$p(e_k) \leq \frac{OPT}{n-k+1}$$

### Corollary

Approximation factor is

$$1+\frac{1}{2}+\frac{1}{3}+\cdots+\frac{1}{n}\leq O(\log n)$$

# Min Metric Steiner Tree

#### Instance

A weighted undirected graph  $G = \langle V, E \rangle$ ,  $w : E \mapsto \mathbb{Q}^+$ , w with triangle inequality. V partition into R (required) and S (steiner)

#### Feasible solution

A subtree T of G that includes all required vertices.

### Objective function

 $\sum_{e\in\mathcal{T}}w(e)$ 

# Approximation

Spanning tree T of G

# 2-approximation

Euler tour of optimal solution  $T^*$ 

# Min Metric Traveling Salesperson (TSP)

#### Instance

A weighted undirected graph  $G = \langle V, E \rangle$ ,  $w : E \mapsto \mathbb{Q}^+$ , w with triangle inequality.

#### Feasible solution

Find a cycle C that visits each vertex  $v \in V$  exactly once.

# Objective function

$$\sum_{e\in C}w(e)$$

# 2-approximation

Euler tour

 $\frac{3}{2}$ -approximation

Matching on odd-degree vertices of a spanning tree  $\mathcal{T}$ 

# **Shortest Superstring**

#### Instance

 $s_1, \ldots, s_m$ : strings of length n.

#### Feasible solution

A superstring T, that is each  $s_i$  is a substring of T

### Objective function

|T|

# **Shortest Superstring**

# Prefix graph

Arc  $s_i, s_j$  with weight  $pref(s_i, s_j)$ 

# Length of superstring

Cycle of prefix graph + overlap last and first string

### Assignment problem = cycle cover

From  $G = \langle V, E \rangle$  to  $G_2$  with two copies U, W of V. For each edge  $(v_i, v_j) \in E$ , add two edges  $(u_i, w_i)$ ,  $(w_i, u_i)$  to  $G_2$ 

### Algorithm

- Concatenate all cycle covers
- 4-approximation

# Knapsack

#### Instance

Universe set U, size  $s:U\mapsto\mathbb{Z}^+$ , profit  $p:U\mapsto\mathbb{Z}^+$ , capacity  $B\in\mathbb{Z}^+$ 

#### Feasible solutions

A subset  $K \subseteq U$ , such that  $\sum_{k \in K} s(k) \leq B$ 

### Objective function

 $\sum_{k \in K} p(k)$ , to maximize

# Knapsack

### Algorithm

- Dynamic programming
- NP-hard
- K(i, b): uses only  $\{u_1, \ldots, u_i\}$ , total size b
- pseudo-polynomial time
- Transform it into an approximation algorithm
- Scale down profits  $p_1(u) = \lfloor p(u) \frac{n}{\epsilon \max\{p(u)\}} \rfloor$ , move to dual problem
- Approximation factor  $1 \epsilon$ ,  $\forall \epsilon > 0$
- Time polynomial in n and  $\cdot$
- FPTAS

# **Linear Programming**

#### Basic facts

- The primal has finite optimum iff the dual has finite optimum
- Let x, y be two feasible solution of the primal and dual. Then x are y re both optimal if:

# Min Vertex Cover

# Integral version

$$\min \sum x_{v}$$
 subject to  $x_{v} + x_{w} \geq 1 \quad \forall (v, w) \in E$   $x_{v} \in \{0, 1\} \quad \forall v \in V$   $(1)$ 

# Fractional version

$$\min \sum x_{
u}$$
 subject to  $x_{
u} + x_{
u} \geq 1 \quad orall (
u, w) \in E$   $0 \leq x_{
u} \leq 1 \quad orall v \in V$ 

(2)

# Integrality ratio

$$sup_{I} \frac{OPT(I)}{OPT_{f}(I)} \tag{3}$$

over all instances I, where OPT is the integral optimum,  $OPT_{\ell}$  is the fractional optimum

#### Lemma

An LP-based approach cannot outperform the integrality ratio

# Half Integrality of Vertex Cover

#### Fractional version

min 
$$\sum x_{v}$$
 subject to
$$x_{v} + x_{w} \quad \forall (v, w) \in E$$

$$x_{v} \geq 0 \quad \forall v \in V$$

$$(4)$$

#### Lemma

There exists an optimal solution with  $x_{\nu} \in \{0, 1, \frac{1}{2}\}$ 

# Half Integrality of Vertex Cover

#### Lemma

There exists an optimal solution with  $x_v \in \{0, 1, \frac{1}{2}\}$ 

$$y_{v} = x_{v} + \epsilon, \frac{1}{2} < x_{v} < 1 x_{v} - \epsilon, 0 < x_{v} < \frac{1}{2}$$
 (5) 
$$z_{v} = x_{v} - \epsilon, \frac{1}{2} < x_{v} < 1 x_{v} + \epsilon, 0 < x_{v} < \frac{1}{2}$$
 (6)

### Proof

 $x=\frac{1}{2}(y+z)$ . Choose  $\epsilon$  sufficiently small, then y and z are both feasible

# **Dual Fitting for Greedy Set Cover**

```
1 C, D \leftarrow \emptyset;

2 while C \neq U do

3 X \leftarrow \text{set in } S \text{ with min } w(X)/|X \setminus C|;

4 \alpha = \frac{w(X)}{|X \setminus C|};

5 Add X to D;

6 For each e \in C \setminus X, p(e) \leftarrow \alpha;

7 C \leftarrow C \cup X

8 Output D
```

```
ILP \min \sum_{S \in \mathcal{S}} w(S) subject to \sum_{S: e \in \mathcal{S}} x_S \geq 1 \quad \forall e \in U \quad (7) x_S \in \{0,1\} \quad \forall S \in \mathcal{S}
```

# **Dual Fitting for Greedy Set Cover**

### Primal

$$\min \sum_{S \in \mathcal{S}} w(S)$$
 subject to  $\sum_{S: e \in S} x_S \geq 1 \quad orall e \in U$  (8)  $x_S \geq 0 \quad orall S \in \mathcal{S}$ 

#### Dual

$$\max \sum_{e \in U} y_e$$
 subject to  $\sum_{e:e \in S} y_e \leq c(S) \quad orall S \in \mathcal{S}$   $y_e \geq 0 \quad orall S \in \mathcal{S}$ 

### Algorithm — ILP

$$p(e) = y_e$$

Not dual feasible

# **Dual Fitting for Greedy Set Cover**

# Fitting

$$y_e = rac{p(e)}{H_n}$$
,  $H_n = \sum_{i=1}^n \frac{1}{n}$ 

#### Lemma

x. v are both feasible

#### Proof

Let  $S \in \mathcal{S}$ , |S| = k. Let  $e_1, \ldots, e_k \in S$ , same order as the algorithm. When inserting  $e_i$ , there are least k-i+1 uncovered elements of S. By choice of S.  $p(e_i) \le c(S)/(k-i+1)$ , hence  $y_e = \frac{p(e_i)}{H} \le \frac{c(S)/(k-i+1)}{H}$ . Checking the constraint:

$$\sum_{i=1}^{k} y_{e_i} \le \frac{c(S)}{H} \sum_{i=1}^{k} \frac{1}{i} = c(S)$$

# Max Cut

### Integral version

$$\max rac{1}{2} \sum_{i,j} w_{i,j} d_{i,j}$$
 subject to  $d_{i,j} \leq x_i + x_j \quad orall (v_i, v_j) \in E$   $d_{i,j} \leq 2 - (x_i + x_j) \quad orall (v_i, v_j) \in E$   $x_{v}, d_{i,j} \in \{0, 1\}$ 

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# Max Cut

#### Second version

#### Fractional version

$$\max rac{1}{2} \sum_{i,j} w_{i,j} (1-x_i x_j)$$
 subject to  $x_{v}^2 = 1 \quad orall v \in V \ -1 \leq x_{v} \leq 1 \quad orall v \in V \ (12$ 

# **Semidefinite programming**

### Vector version

$$\max rac{1}{2} \sum_{i,j} w_{i,j} (1-x_i \cdot x_j)$$
 subject to  $x_v \cdot x_v = 1 \quad orall v \in V$ 

### How to solve?

Can be solved approximately (additive error  $\epsilon$ ) via interior point

#### Problem

From vector (fractional) solution to bipartition

(13)

# Semidefinite programming

#### Solution

- Random hyperplane
- Contribution of vertices  $x_i$ ,  $x_j$  is  $\frac{w_{i,j}}{2}(1-\cos\theta_{i,j})$ , where  $\theta_{i,j}$  is the angle between the two vectors  $x_i$ ,  $x_j$
- Probability of separation:  $\frac{\theta_i}{\pi}$

### Approximation Factor

$$\alpha = \frac{2}{\pi} \min_{\theta} \frac{\theta}{1 - \cos \theta} > 0.878 \tag{14}$$

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# Max Sat

#### Instance

A set of boolean clauses

over variables  $X = \langle x_1, \dots, x_n \rangle$  A weight

 $w: C \mapsto \mathbb{O}^+$  of each clause.

#### **Feasible** solution

A truth assignment Y to the variables in X

### Objective function

 $\sum_{c \in D} w(c)$ , where D is the set of clauses of C that are made true by Y

### Example

$$c_2 = \neg x_1 \lor \neg x_2$$

$$c_3 = x_4$$

# Probabilistic Approach for Max Sat

### Random assignment

- Each variable  $x_i$  is true is probability 1/2
- $E[w(c)] = w(c) \cdot Pr[c \text{ is satisfied}]$
- Depends on  $size(c) = k_c$
- $E[w(c)] = w(c) (1 2^{-k_c}) = \alpha_k w_c$ , for  $\alpha_k = (1 2^{-k_c})$
- Since  $\alpha_k \geq \frac{1}{2}$ , then  $\frac{1}{2}$  approximation (expected)

# **Conditional expectation**

#### Derandomize

- $E[Y] = \sum_{c \in C} \alpha_k w_c$
- ② Pick the best between  $E[Y|x_1 = T]$  and  $E[Y|x_1 = F]$

# LP Approach for Max Sat

#### **ILP** for Max Sat

$$\max_{c \in C} w_c z_c \quad \text{subject to}$$

$$\sum_{i \in S_c^+} y_i + \sum_{i \in S_c^-} (1 - y_i) \ge z_c \quad \forall c \in C$$

$$y_i \in \{0, 1\} \quad \forall i$$

$$z_c \in \{0, 1\} \quad \forall c \in C$$

$$(15)$$

 $S_c^+$ : boolean variables non-negated in  $c_i$ ,  $S_c^-$ : boolean variables negated in  $c_i$ 

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# LP Approach for Max Sat

#### ILP relaxation

$$\max_{c \in C} w_c z_c$$
 subject to

$$\sum_{i \in S_c^+} y_i + \sum_{i \in S_c^-} (1 - y_i) \ge z_c \quad \forall c \in C$$

$$0 < z_c < 1 \quad \forall c \in C$$

 $\forall c \in \mathcal{C}$  (16)

 $y^*, z^*$ : fractional optimum

# Algorithm

 $x_i \leftarrow T$  with probability  $y_i^*$ 

#### Lemma

$$E[W] \geq eta_k w_c z_c^*$$
, with  $eta_k = 1 - \left(1 - rac{1}{k}\right)^k$ 

### Proof

- $\bullet$   $c_i$  satisfied if at least a variable is T
- $egin{aligned} & E[W_c] = 1 \prod_{i=1}^k (1-y_i) \geq \ & 1 \left(rac{\sum_{i=1}^k (1-y_i)}{k}
  ight)^k \geq 1 \left(1 rac{z_c^*}{k}
  ight)^k \end{aligned}$
- $1-\left(1-rac{z_c^*}{k}\right)^{\kappa}\geq eta_k$  for  $0\leq z_c^*\leq 1$

# LP Approach for Max Sat

### **Approximation**

$$eta_k = 1 - \left(1 - rac{1}{k}
ight)^k \geq 1 - rac{1}{6}$$

#### Notice

 $\beta_k$  monotone increasing

# Better approximation for Max Sat

### Algorithm

Pick the better of the solutions of the two algorithms

### Approximation Factor

- $E[W_c] = \alpha_k w_c + \beta_k w_c z_c^*$
- $z_c^* \leq 1$ , hence  $E[W_c] = \alpha_k w_c z_c^* + \beta_k w_c z_c^* = (\alpha_k + \beta_k) w_c z_c^*$
- <sup>3</sup>/<sub>4</sub>-approximation

# Max multicommodity flow

#### Instance

Undirected graph  $G = \langle V, E \rangle$ . Capacity  $c_e$  for each edge E. A set  $\{(s_1, t_1), \dots, (s_k, t_k)\}\$  of source-sink pairs (commodity)

#### Feasible solution

A flow that respects the maximum capacity and satisfies flow conservation.

### Objective function

 $\sum_{(s_i,t_i)}$  flow from  $s_1$  to  $t_i$ 

# Max multicommodity flow

# Primal

### Dual

$$\min \sum_{e \in E} c_e d_e$$
 subject to  $\sum_{e \in p} d_e \geq 1 \quad orall p \in P$   $(18)$   $d_e \geq 0 \quad orall e \in E$ 

 $d_e$ 

distance between vertices.

- Flow-cut duality
- Pick a multicut D

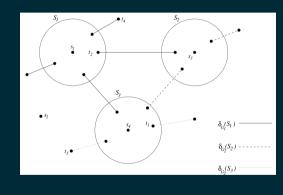
# **Growing regions**

#### Goal

- No region contains a source-sink pair
- region centered on a source
- $c(R) \le \epsilon wt(R)$ , where c(R) is the capacity of the cut

#### Lemma

Radius  $\leq rac{1}{2}$ , the ball has no source-sink pair



# **Growing regions**

### Weight distribution

- $wt(s) = \frac{F}{k}$ , with s source, F fractional optimum
- $q_e$ : fraction of edge e in the region
- $q_e = \frac{r dist(s, u)}{dist(s, v) dist(s, u)}$  for each edge e = (u, v) in the cut
- $wt(R) = wt(s) + \sum_{e \in X} c_e d_e q_e$ , with X the set of edges with at least an endpoint in R
- Larger region R, easier  $c(R) \leq \epsilon wt(R)$
- ullet  $\epsilon \leftarrow 2 \ln(k+1) \Rightarrow \mathsf{radius} \leq \frac{1}{2}$
- $ullet rac{dwt(s(r))}{dr} \geq \sum_e c_e d_e rac{dq_e}{dr} \geq c(S(r))$

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# **Smooth polynomial programming**

# Program

$$\max p(x_1,\ldots,x_n)$$
 subject to 
$$\sum l_i \leq p(x_1,\ldots,x_n) \leq g_i \qquad (19)$$
  $x_i \in \{0,1\} \quad \forall x_i$ 

#### **Smoothness**

For each degree-d polynomial, each coefficient of each degree i monomial is  $\leq cn^{d-i}$ 

# Compute a (random) solution with

- Additive error  $\epsilon n^d$
- ullet degree-f constraints satisfied with additive error  $\epsilon n^f$
- linear constraints satisfied with additive error  $O(\epsilon \sqrt{n \log n})$
- time complexity  $O\left(\left(dKn^d\right)^t\right)$ , with  $t=4\frac{c^2e^2d^2}{\epsilon^2}$  and K the number of constraints

# Max Cut

#### Instance

A weighted undirected graph  $G = \langle V, E \rangle$ ,  $W : E \hookrightarrow \mathbb{O}^+$ 

### Feasible solution

a bipartition  $(V_1, V_2)$  of V

### Objective function

$$\sum_{v_1 \in V_1, v_2 \in V_2} w(v_1, v_2)$$

# Program

$$\max_{(i,j)\in E} w(i,j) (x_i(1-x_j)) + (x_i(1-x_j))$$
(20)

# Dense-*k*-subgraph

#### Instance

An undirected graph  $G = \langle V, E \rangle$ 

### Feasible solution

A subset S of k vertices of G

### Objective function

 $|E \cap S \times S|$ 

#### **Denseness**

Average degree  $\delta$ 

# Random algorithm

Has  $\alpha^2 \delta^2 n^2/2$  edges.

# Dense-*k*-subgraph

#### Instance

An undirected graph  $G = \langle V, E \rangle$ 

### Feasible solution

A subset S of k vertices of G

### Objective function

 $|E \cap S \times S|$ 

# Program

$$\max_{(i,j)\in E} x_i x_j$$
 subject to  $\sum_{x_i = k} x_i = k$   $(21)$   $x_i \in \{0,1\}$   $orall x_i$ 

#### Linear constraint

Move  $O(\sqrt{n \log n})$  vertices in/out the set S, at most  $O(n\sqrt{n \log n}) = o(n^2)$  edges affected

# **Attribution**

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