

GASPI Tutorial

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Goals

- Get an overview over GASPI
- Learn how to
 - Compile a GASPI program
 - Execute a GASPI program
- Get used to the GASPI programming model
 - one-sided communication
 - weak synchronization
 - asynchronous patterns / dataflow implementations



Outline

- Introduction to GASPI
- GASPI API
 - Execution model
 - Memory segments
 - One-sided communication
 - Collectives
 - Passive communication



Outline

- GASPI programming model
 - Dataflow model
 - Fault tolerance

www.gaspi.de

www.gpi-site.com

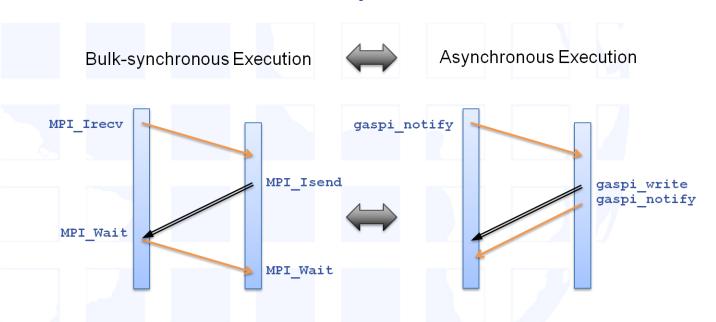


Introduction to GASPI



Motivation

- A PGAS API for SPMD execution
- Take your existing MPI code
- Rethink your communication patterns!
- Reformulate towards an asynchronous data flow model!

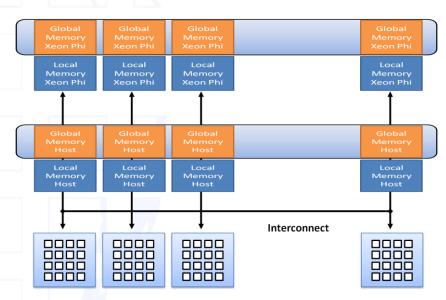




Key Objectives of GASPI

Scalability

- From bulk–synchronous two sided communication patterns to asynchronous onesided communication
- remote completion
- Flexibility and Versatility
 - Multiple Segments,
 - Configurable hardware ressources
 - Support for multiple memory models
- Failure Tolerance
 - Timeouts in non-local operations
 - dynamic node sets.





GASPI history

- GPI
 - originally called Fraunhofer Virtual Machine (FVM)
 - developed since 2005
 - used in many of the industry projects at CC-HPC of Fraunhofer ITWM

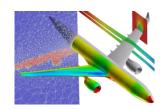


GPI: Winner of the "Joseph von Fraunhofer Preis 2013"

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Scalability

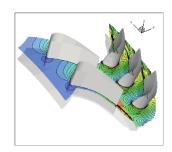


Performance

- One-sided read and writes
- remote completion in PGAS with notifications.
- Asynchronous execution model
 - RDMA queues for one-sided read and write operations, including support for arbitrarily distributed data.
- Threadsafety
 - Multithreaded communication is the default rather than the exception.
- Write, Notify, Write_Notifiy
 - relaxed synchronization with double buffering
 - traditional (asynchronous) handshake mechanisms remain possible.
- No Buffered Communication Zero Copy.



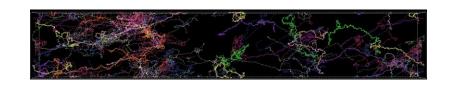
Scalability



Performance

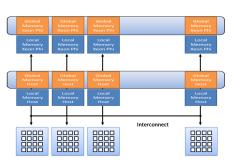
- No polling for outstanding receives/acknowledges for send
 - no communication overhead, true asynchronous RDMA read/write.
- Fast synchronous collectives with time-based blocking and timeouts
 - Support for asynchronous collectives in core API.
- Passive Receives two sided semantics, no Busy-Waiting
 - Allows for distributed updates, non-time critical asynchronous collectives. Passive Active Messages, so to speak ☺.
- Global Atomics for all data in segments
 - FetchAdd
 - cmpSwap.
- Extensive profiling support.





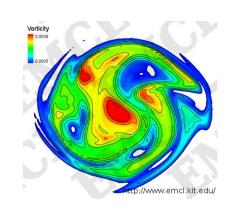
Flexibility and Versatility

- Segments
 - Support for heterogeneous Memory Architectures (NVRAM, GPGPU, Xeon Phi, Flash devices).
 - Tight coupling of Multi-Physics Solvers
 - Runtime evaluation of applications (e.g Ensembles)
- Multiple memory models
 - Symmetric Data Parallel (OpenShmem)
 - Symmetric Stack Based Memory Management
 - Master/Slave
 - Irregular.





Flexibility

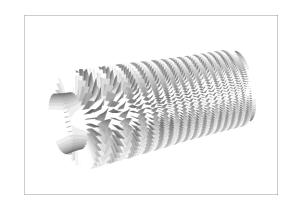


Interoperability and Compatibility

- Compatibility with most Programming Languages.
- Interoperability with MPI.
- Compatibility with the Memory Model of OpenShmem.
- Support for all Threading Models (OpenMP/Pthreads/..)
 - similar to MPI, GASPI is orthogonal to Threads.
- GASPI is a nice match for tile architecture with DMA engines.



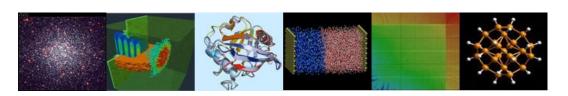




Flexibility

- Allows for shrinking and growing node set.
- User defined global reductions with time based blocking.
- Offset lists for RDMA read/write (write_list, write_list_notify)
- Groups (Communicators)
- Advanced Ressource Handling, configurable setup at startup.
- Explicit connection management.





Failure Tolerance

Failure Tolerance.

- Timeouts in all non-local operations
- Timeouts for Read, Write, Wait, Segment Creation, Passive Communication.
- Dynamic growth and shrinking of node set.
- Fast Checkpoint/Restarts to NVRAM.
- State vectors for GASPI processes.



The GASPI API

- 52 communication functions
- 24 getter/setter functions
- 108 pages
 - ... but in reality:
 - Init/Term
 - Segments
 - Read/Write
 - Passive Communication
 - Global Atomic Operations
 - Groups and collectives

```
GASPI_WRITE_NOTIFY ( segment_id_local , offset_local , rank , segment_id_remote , offset_remote , offset_remote , size , notification_id , notification_value , queue , timeout )
```

Parameter:

- (in) segment id local: the local segment ID to read from
- (in) offset local: the local offset in bytes to read from
- (in) rank: the remote rank to write to
- (in) segment_id_remote: the remote segment to write to
- (in) offset_remote: the remote offset to write to
- (in) size: the size of the data to write
- (in) notification_id: the remote notification ID
- (in) notification value: the value of the notification to write
- (in) queue: the queue to use
- (in) timeout: the timeout

www.gaspi.de







GASPI Exection Model

- SPMD / MPMD execution model
- All procedures have prefix gaspi_

```
gaspi_return_t
gaspi_proc_init ( gaspi_timeout_t const timeout )
```

- All procedures have a return value
- Timeout mechanism for potentially blocking procedures



GASPI Return Values

- Procedure return values:
 - GASPI_SUCCESS
 - designated operation successfully completed
 - GASPI_TIMEOUT
 - designated operation could not be finished in the given period of time
 - not necessarily an error
 - the procedure has to be invoked subsequently in order to fully complete the designated operation
 - GASPI_ERROR
 - designated operation failed -> check error vector
- Advice: Always check return value!

success_or_die.h

```
#ifndef SUCCESS OR DIE H
#define SUCCESS OR DIE H
#include <GASPI.h>
#include <stdlib.h>
#define SUCCESS OR DIE(f...)
do
 const gaspi return t r = f;
 if (r != GASPI SUCCESS)
   gaspi printf ("Error: '%s' [%s:%i]: %i\n", #f, FILE , LINE , r);\
     exit (EXIT FAILURE);
} while (0)
#endif
```



Timeout Mechanism

- Mechanism for potentially blocking procedures
 - procedure is guaranteed to return
- Timeout: gaspi_timeout_t
 - GASPI_TEST (0)
 - procedure completes local operations
 - Procedure does not wait for data from other processes
 - GASPI_BLOCK (-1)
 - wait indefinitely (blocking)
 - Value > 0
 - Maximum time in msec the procedure is going to wait for data from other ranks to make progress
 - != hard execution time



GASPI Process Management

- Initialize / Finalize
 - gaspi_proc_init
 - gaspi_proc_term
- Process identification
 - gaspi_proc_rank
 - gaspi_proc_num
- Process configuration
 - gaspi_config_get
 - gaspi_config_set



GASPI Initialization

gaspi_proc_init

```
gaspi_return_t
gaspi_proc_init ( gaspi_timeout_t const timeout )
```

- initialization of resources
 - set up of communication infrastructure if requested
 - set up of default group GASPI_GROUP_ALL
 - rank assignment
 - position in machinefile ⇔ rank ID
- no default segment creation



GASPI Finalization

gaspi_proc_term

```
gaspi_return_t
gaspi_proc_term ( gaspi_timeout_t timeout )
```

- clean up
 - wait for outstanding communication to be finished
 - release resources
- no collective operation !



GASPI Process Identification

gaspi_proc_rank

```
gaspi_return_t
gaspi_proc_rank ( gaspi_rank_t *rank )
```

gaspi_proc_num

```
gaspi_return_t
gaspi_proc_num ( gaspi_rank_t *proc_num )
```



GASPI Process Configuration

gaspi_config_get

```
gaspi_return_t
gaspi_config_get ( gaspi_config_t *config )
```

gaspi_config_set

```
gaspi_return_t
gaspi_config_set ( gaspi_config_t const config )
```

 Retrieveing and setting the configuration structure has to be done before gaspi_proc_init



GASPI ProcessConfiguration

- Configuring
 - resources
 - sizes
 - max
 - network

```
typedef struct {
 // maximum number of groups
  gaspi_number_t
                     group_max;
  // maximum number of segments
 gaspi_number_t
                     segment_max
 // one-sided comm parameter
  gaspi_number_t
                     queue_num;
  gaspi_number_t
                     queue_size_max;
                     transfer_size_max;
  gaspi_size_t
  // notification parameter
  gaspi_number_t
                     notification_num;
 // passive comm parameter
 gaspi_number_t
                     passive_queue_size_max;
  gaspi_size_t
                     passive_transfer_size_max;
 // collective comm parameter
 gaspi_size_t
                     allreduce_buf_size;
  gaspi_number_t
                     allreduce_elem_max;
 // network selection parameter
  gaspi_network_t
                     network;
 // communication infrastructure build up notification
  gaspi_number_t
                       build_infrastructure;
 void *
                     user_defined;
} gaspi_config_t;
```



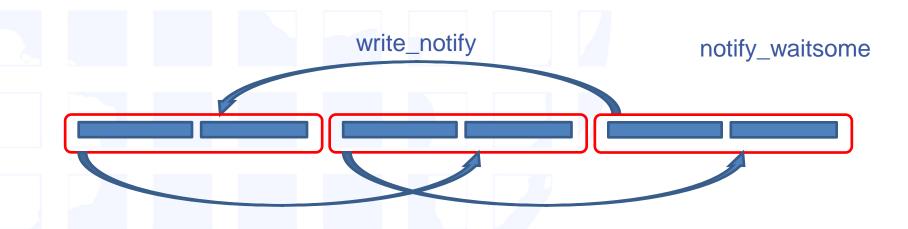
GASPI "hello world"

```
#include "success or die.h"
#include <GASPI.h>
#include <stdlib.h>
int main(int argc, char *argv[])
  SUCCESS OR DIE ( gaspi proc init (GASPI BLOCK) );
 gaspi rank t rank;
 gaspi rank t num;
  SUCCESS OR DIE ( gaspi proc rank (&rank) );
  SUCCESS OR DIE ( gaspi proc num (&num) );
 gaspi printf("Hello world from rank %d of %d\n", rank, num);
  SUCCESS OR DIE ( gaspi proc term (GASPI BLOCK) );
  return EXIT SUCCESS;
```



Communication example

- init local buffer
- write to remote buffer
- wait for data availability
- print



onesided.c (I)

```
// includes
int main(int argc, char *argv[])
 static const int VLEN = 1 << 2;
 SUCCESS OR DIE ( gaspi proc init (GASPI BLOCK) );
 gaspi rank t iProc, nProc;
 SUCCESS OR DIE ( gaspi proc rank (&iProc));
 SUCCESS OR DIE ( gaspi proc num (&nProc));
 gaspi segment id t const segment id = 0;
 SUCCESS OR DIE ( gaspi segment create ( segment id, segment size
                                     , GASPI GROUP ALL, GASPI BLOCK
                                     , GASPI MEM UNINITIALIZED ) );
 gaspi pointer t array;
 SUCCESS OR DIE ( gaspi segment ptr (segment id, &array) );
 double * src array = (double *)(array);
 double * rcv array = src array + VLEN;
 for (int j = 0; j < VLEN; ++j) {
   src array[j] = (double) ( iProc * VLEN + j ); }
```



onesided.c (II)

```
gaspi notification id t data available = 0;
gaspi queue id t queue id = 0;
gaspi offset t loc off = 0;
gaspi offset t rem off = VLEN * sizeof (double);
wait for queue entries for write notify ( &queue id );
SUCCESS OR DIE ( gaspi write notify ( segment id, loc off
                                     , RIGHT (iProc, nProc)
                                     , segment id, rem off
                                     , VLEN * sizeof (double)
                                     , data available, 1 + iProc, queue id
                                     , GASPI BLOCK ) );
wait or die (segment id, data available, 1 + LEFT (iProc, nProc) );
for (int j = 0; j < VLEN; ++j)
{ gaspi printf("rank %d rcv elem %d: %f \n", iProc, j, rcv array[j] );
wait for flush queues();
SUCCESS OR DIE ( gaspi proc term (GASPI BLOCK) );
return EXIT SUCCESS;
```



Memory Segments



Segments

- software abstraction of hardware memory hierarchy
 - NUMA
 - GPU
 - Xeon Phi
- one partition of the PGAS
- contiguous block of virtual memory
 - no pre-defined memory model
 - memory management up to the application
- locally / remotely accessible
 - local access by ordinary memory operations
 - remote access by GASPI communication routines



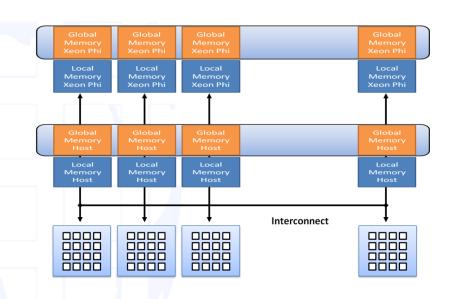
GASPI Segments

- GASPI provides only a few relatively large segments
 - segment allocation is expensive
 - the total number of supported segments is limited by hardware constraints
- GASPI segments have an allocation policy
 - GASPI_MEM_UNINITIALIZED
 - memory is not initialized
 - GASPI_MEM_INITIALIZED
 - memory is initialized (zeroed)



Segment Functions

- Segment creation
 - gaspi_segment_alloc
 - gaspi_segment_register
 - gaspi_segment_create
- Segment deletion
 - gaspi_segment_delete
- Segment utilities
 - gaspi_segment_num
 - gaspi_segment_ptr





GASPI Segment Allocation

gaspi_segment_alloc

- allocate and pin for RDMA
- Locally accessible
- gaspi_segment register

segment accessible by rank



GASPI Segment Creation

gaspi_segment_create

- Collective short cut to
 - gaspi_segment_alloc
 - gaspi_segment_register
- After successful completion, the segment is locally and remotely accessible by all ranks in the group



GASPI Segment Deletion

gaspi_segment_delete

```
gaspi_return_t
gaspi_segment_delete ( gaspi_segment_id_t segment_id )
```

free segment memory



GASPI Segment Utils

gaspi_segment_num

```
gaspi_return_t
gaspi_segment_num ( gaspi_number_t *segment_num )
```

gaspi_segment_list

```
gaspi_return_t
gaspi_segment_list ( gaspi_number_t num
, gaspi_segment_id_t *segment_id_list )
```

gaspi_segment_ptr



One-sided Communication



GASPI One-sided Communication

gaspi_write

 Post a put request into a given queue for transfering data from a local segment into a remote segment



GASPI One-sided Communication

gaspi_read

 Post a get request into a given queue for transfering data from a remote segment into a local segment



GASPI One-sided Communication

gaspi_wait

- wait on local completion of all requests in a given queue
- After successfull completion, all involved local buffers are valid



Queues (I)

- Different queues available to handle the communication requests
- Requests to be submitted to one of the supported queues
- Advantages
 - more scalability
 - channels for different types of requests
 - similar types of requests are queued and synchronized together but independently from other ones
 - separation of concerns



Queues (II)

- Fairness of transfers posted to different queues is guaranteed
 - No queue should see ist communication requests delayed indefinitely
- A queue is identified by its ID
- Synchronization of calls by the queue
- Queue order does not imply message order on the network / remote memory
- A subsequent notify call is guaranteed to be nonovertaking for all previous posts to the same queue and rank



Weak Synchronization

- One sided-communication:
 - Entire communication managed by the local process only
 - Remote process is not involved
 - Advantage: no inherent synchronization between the local and the remote process in every communication request
- Still: At some point the remote process needs knowledge about data availability
 - Managed by weak synchronization primitives



Weak Synchronization

- Several notifications for a given segment
 - Identified by notification ID
 - Logical association of memory location and notification



GASPI Weak Synchronization

gaspi_notify

- posts a notification with a given value to a given queue
- remote visibility guarantees remote data visibility of all previously posted writes in the same queue, the same segment and the same process rank



GASPI Weak Synchronization

gaspi_notify_waitsome

- monitors a contiguous subset of notification id's for a given segment
- returns successfull if at least one of the monitored id's is remotely updated to a value unequal zero



GASPI Weak Synchronization

gaspi_notify_reset

Atomically resets a given notification id and yields
 the old value



Extended One-sided Calls

- gaspi_write_notify
 - gaspi_write + subsequent gaspi_notify
- gaspi_write_list
 - several subsequent gaspi_writes to the same rank
- gaspi_write_list_notify
 - gaspi_write_list + subsequent gaspi_notify
- gaspi_read_list
 - several subsequent gaspi_reads



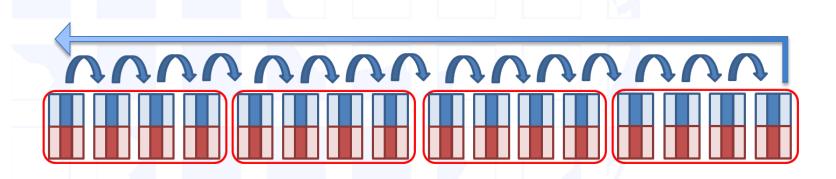
Dataflow model

Hands On Session
The MPI/GASPI Ring Exchange



MPI – MPI_Issend/MPI_Recv

- NITER iterations of Ring Exchange with "nProc" cores
- Shift upper half of vector to the right



Example: 4 Sockets/16 cores – each core holds a vector of length 2*VLEN



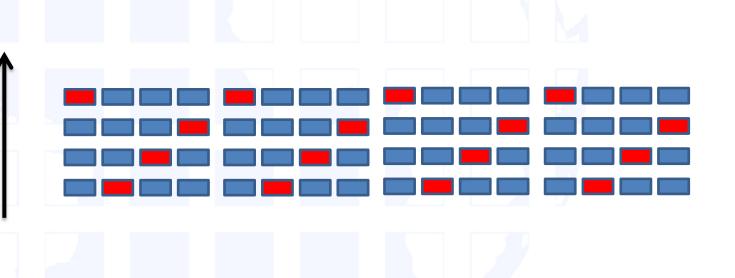
MPI – round_robin_double_buffer.c

```
for (int i = 0; i < nProc; ++i) {
    MPI Request request;
    int left halo = 0;
    int slice id = 1;
    // issue send
    MPI Isend ( &array ELEM right (buffer id, slice id, 0), VLEN,
       MPI DOUBLE, right, i, MPI COMM WORLD, &request);
    // post recv
    MPI Recv ( &array ELEM right (buffer id, left halo, 0), VLEN,
       MPI DOUBLE, left, i, MPI COMM WORLD, MPI STATUS IGNORE);
     // compute data, read from id "buffer id", write to id "1 - buffer id"
    data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
    // wait for Issend
    MPI Wait (&request, MPI STATUS IGNORE);
    // alternate the buffers
    buffer id = 1 - buffer id;
```



MPI - MPI_Issend/MPI_Recv

Synchronous Lockstep Execution





MPI – left_right_double_buffer.c

```
for (int i = 0; i < nProc; ++i) {
    MPI Request send req[2], recv req[2];
    const int left halo = 0; slice id = 1; right halo = 2;
     MPI Irecv ( &array ELEM right (buffer id, left halo, 0), VLEN,
       MPI DOUBLE, left, i, MPI COMM WORLD, &send req[0]);
     MPI Irecv ( &array ELEM left (buffer id, right halo, 0), VLEN,
       MPI DOUBLE, right, i, MPI COMM WORLD, &send reg[1]);
     MPI Isend ( &array ELEM right (buffer id, slice id, 0), VLEN,
       MPI DOUBLE, right, i, MPI COMM WORLD, &recv reg[0]);
     MPI Isend ( &array ELEM left (buffer id, slice id, 0), VLEN,
       MPI DOUBLE, left, i, MPI COMM WORLD, &recv reg[1]);
     MPI Waitall (2, recv req, MPI STATUSES IGNORE);
     data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
     MPI Waitall (2, send req, MPI STATUSES IGNORE);
     buffer id = 1 - buffer id;
```



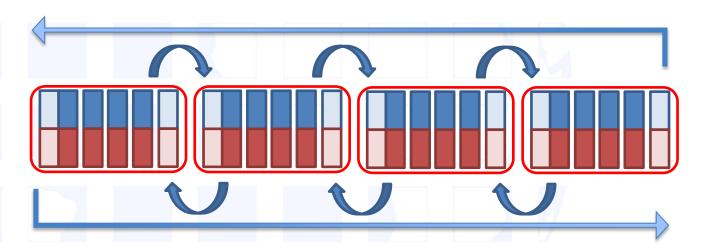
MPI - left_right_double_buffer_req_free.c

```
for (int i = 0; i < nProc; ++i) {
    MPI Request send req[2], recv req[2];
    const int left halo = 0; slice id = 1; right halo = 2;
     MPI Irecv ( &array ELEM right (buffer id, left halo, 0), VLEN,
       MPI DOUBLE, left, i, MPI COMM WORLD, &send req[0]);
     MPI Irecv ( &array ELEM left (buffer id, right halo, 0), VLEN,
       MPI DOUBLE, right, i, MPI COMM WORLD, &send reg[1]);
     MPI Isend ( &array ELEM right (buffer id, slice id, 0), VLEN,
       MPI DOUBLE, right, i, MPI COMM WORLD, &recv reg[0]);
     MPI Isend ( &array ELEM left (buffer id, slice id, 0), VLEN,
       MPI DOUBLE, left, i, MPI COMM WORLD, &recv reg[1]);
    MPI Request free(&send req[0]);
    MPI Request free (&send req[1]);
     MPI Waitall (2, recv req, MPI STATUSES IGNORE);
     data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
     buffer id = 1 - buffer id;
```



MPI – HYBRID MPI/OpenMP

- Shift upper half of the vector to the right
- Shift lower half of the vector to the left



Example: 4 Sockets/16 cores – each core holds a vector of length 2*VLEN



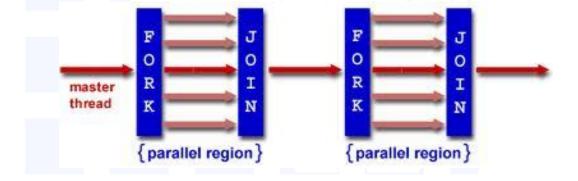
MPI – left_right_double_buffer_funneled.c

```
for ( int i = 0; i < nProc * NTHREADS; ++i ) {
      const int left halo = 0, slice id = tid + 1, right halo = NTHREADS+1;
      if (tid == 0) {
        MPI Request send req[2], recv req[2];
        MPI Irecv ( &array ELEM right (buffer id, left halo, 0), VLEN,
            MPI DOUBLE, left, i, MPI COMM WORLD, &recv req[0]);
        MPI Irecv ( &array ELEM left (buffer id, right halo, 0), VLEN,
            MPI DOUBLE, right, i, MPI COMM WORLD, &recv req[1]);
        MPI Isend ( &array ELEM right (buffer id, slice id, 0), VLEN,
            MPI DOUBLE, right, i, MPI COMM WORLD, &send req[0]);
        MPI Isend ( &array ELEM left (buffer id, slice id, 0), VLEN,
            MPI DOUBLE, left, i, MPI COMM WORLD, &send req[1]);
        MPI Request free(&send req[0]);
        MPI Request free (&send req[1]);
        MPI Waitall (2, recv req, MPI STATUSES IGNORE);
#pragma omp barrier
      data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
#pragma omp barrier
      buffer id = 1 - buffer id; }
```



MPI – left_right_double_buffer_funneled.c

Fork-join model





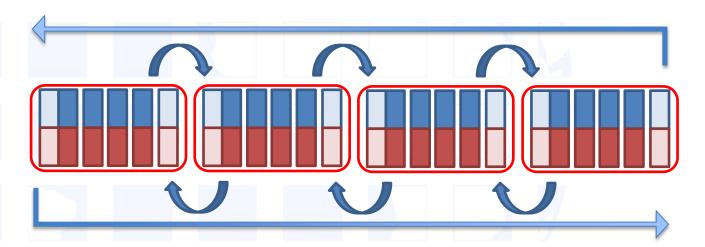
MPI – left_right_double_buffer_multiple.c

```
if (tid == 0) {
      MPI Request request;
      MPI Isend ( &array ELEM left (buffer id, slice id, 0), VLEN,
        MPI DOUBLE, left, i, MPI COMM WORLD, &request);
      MPI Request free(&request);
      MPI Recv ( &array ELEM right (buffer id, left halo, 0), VLEN,
        MPI DOUBLE, left, i, MPI COMM WORLD, MPI STATUS IGNORE);
      data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
} else if (tid < NTHREADS - 1) {</pre>
      data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
    } else {
      MPI Request request;
      MPI Isend ( &array ELEM right (buffer id, slice id, 0), VLEN,
        MPI DOUBLE, right, i, MPI COMM WORLD, &request);
      MPI Request free(&request);
      MPI Recv ( &array ELEM left (buffer id, right halo, 0), VLEN,
        MPI DOUBLE, right, i, MPI COMM WORLD, MPI STATUS IGNORE);
      data compute (NTHREADS, array, 1 - buffer id, buffer id, slice id);
#pragma omp barrier
    buffer id = 1 - buffer id;
```



GASPI – HYBRID GASPI/OpenMP

- Shift upper half of the vector to the right
- Shift lower half of the vector to the left



Example: 4 Sockets/16 cores – each core holds a vector of length 2*VLEN



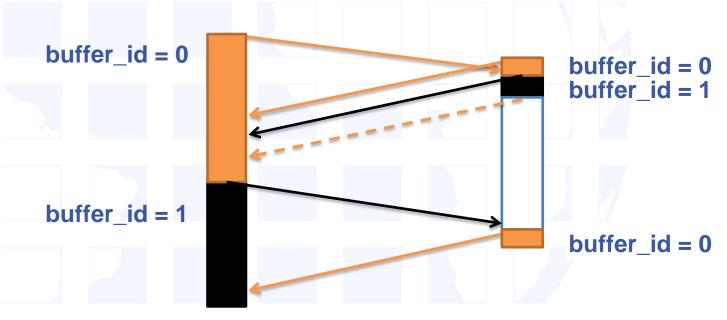
GASPI – left_right_double_buffer_funneled.c

```
if (tid == 0) {
 wait for queue max half (&queue id);
  SUCCESS OR DIE ( gaspi write notify
    ( segment id, array OFFSET left(buffer id, slice id, 0), left,
    segment id, array OFFSET left(buffer id, right halo, 0), VLEN* sizeof(double),
    right data available[buffer id], 1 + i, queue id, GASPI BLOCK));
  wait for queue max half (&queue id);
  SUCCESS OR DIE ( gaspi write notify
    ( segment id, array OFFSET right (buffer id, slice id, 0), right,
    segment id, array OFFSET right(buffer id, left halo, 0), VLEN*sizeof (double),
    left data available[buffer id], 1 + i, queue id, GASPI BLOCK));
  wait or die (segment id, right data available[buffer id], 1 + i);
  wait or die (segment id, left data available[buffer id], 1 + i);
#pragma omp barrier
data compute ( NTHREADS, array, 1 - buffer id, buffer id, slice id);
#pragma omp barrier
buffer id = 1 - buffer id;
```



GASPI – left_right_double_buffer_funneled.c

 Bi-directional halo exchange – implicit synchronization





GASPI – left_right_double_buffer_multiple.c

```
if (tid == 0) {
 wait for queue max half (&queue id);
  SUCCESS OR DIE ( gaspi write notify
   (segment id, array OFFSET left (buffer id, slice id, 0), left,
    segment id, array OFFSET left(buffer id, right halo, 0), VLEN*sizeof(double),
    right data available[buffer id], 1 + i, queue id, GASPI BLOCK));
 wait or die (segment id, left data available[buffer id], 1 + i);
  data compute ( NTHREADS, array, 1 - buffer id, buffer id, slice id);
} else if (tid < NTHREADS - 1) {</pre>
  data compute ( NTHREADS, array, 1 - buffer id, buffer id, slice id);
} else {
  wait for queue max half (&queue id);
  SUCCESS OR DIE ( gaspi write notify
   ( segment id, array OFFSET right (buffer id, slice id, 0), right,
   segment id, array OFFSET right (buffer id, left halo, 0), VLEN*sizeof (double),
  left data available[buffer id], 1 + i, queue id, GASPI BLOCK));
  wait or die (segment id, right data available[buffer id], 1 + i);
   data compute ( NTHREADS, array, 1 - buffer id, buffer id, slice id);
#pragma omp barrier
buffer id = 1 - buffer id;
```



- GASPI left_right_double_buffer_multiple.c
 - One message instead of three (MPI Rendezvouz)
 - No waiting for late MPI_Recv
 - No waiting for acknowledge for MPI_Issend
 - Overlap of communication with computation



GASPI – Dataflow - left_right_dataflow_halo.c

```
#pragma omp parallel default (none) firstprivate (buffer id, queue id)
  shared (array, data available, ssl, stderr)
    slice* sl;
    while (sl = get slice and lock (ssl, NTHREADS, num))
      handle slice(sl, array, data available, segment id, queue id,
        NWAY, NTHREADS, num);
      omp unset lock (&sl->lock);
                    typedef struct slice t
                      omp lock t lock;
                     volatile int stage;
                      int index;
                     enum halo types halo type;
                      struct slice t *left;
                      struct slice t *next;
```

slice;



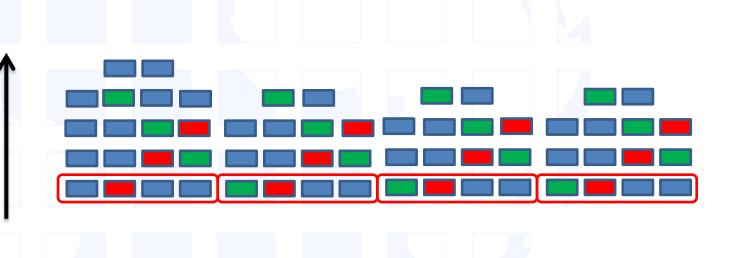
GASPI – Dataflow - slice.c

```
void handle slice ( ...)
 if (sl->halo type == LEFT) {
    if (sl->stage > sl->next->stage) {return;}
    if (! test or die (segment id, left data available[old buffer id], 1))
    { return; }
 } else if (sl->halo type == RIGHT) {
    if (sl->stage > sl->left->stage) { return; }
    if (! test or die (segment id, right data available[old buffer id], 1))
    { return; }
  } else if (sl->halo type == NONE) {
    if (sl->stage > sl->left->stage | | sl->stage > sl->next->stage) {return;}
data compute (NTHREADS, array, new buffer id, old buffer id, sl->index);
  if (sl->halo type == LEFT) {
     SUCCESS OR DIE ( gaspi write notify ...)
  } else if (sl->halo type == RIGHT)
    SUCCESS OR DIE ( gaspi write notify ...)
 ++sl->stage;
```



GASPI - Dataflow

Locally and globally asynchronous dataflow.









Collective Operations (I)

- Collectivity with respect to a definable subset of ranks (groups)
 - Each GASPI process can participate in more than one group
 - Defining a group is a three step procedure
 - gaspi_group_create
 - gaspi_group_add
 - gaspi_group_commit
 - GASPI_GROUP_ALL is a predefined group containing all processes



Collective Operations (II)

- All gaspi processes forming a given group have to invoke the operation
- In case of a timeout (GASPI_TIMEOUT), the operation is continued in the next call of the procedure
- A collective operation may involve several procedure calls until completion
- Completion is indicated by return value GASPI_SUCCESS



Collective Operations (III)

- Collective operations are exclusive per group
 - Only one collective operation of a given type on a given group at a given time
 - Otherwise: undefined behaviour
- Example
 - Two allreduce operations for one group can not run at the same time
 - An allreduce operation and a barrier are allowed to run at the same time



Collective Functions

- Built in:
 - gaspi_barrier
 - gaspi_allreduce
 - GASPI_OP_MIN, GASPI_OP_MAX, GASPI_OP_SUM
 - GASPI_TYPE_INT, GASPI_TYPE_UINT, GASPI_TYPE_LONG, GASPI_TYPE_ULONG, GASPI_TYPE_FLOAT, GASPI_TYPE_DOUBLE
- User defined
 - gaspi_allreduce user



GASPI Collective Function

gaspi_barrier

gaspi_allreduce



Passive communication

Passive Communication Functions (I)

- 2 sided semantics send/recv
 - gaspi_passive_send

time based blocking



Passive Communication Functions (II)

– Gaspi_passive receive

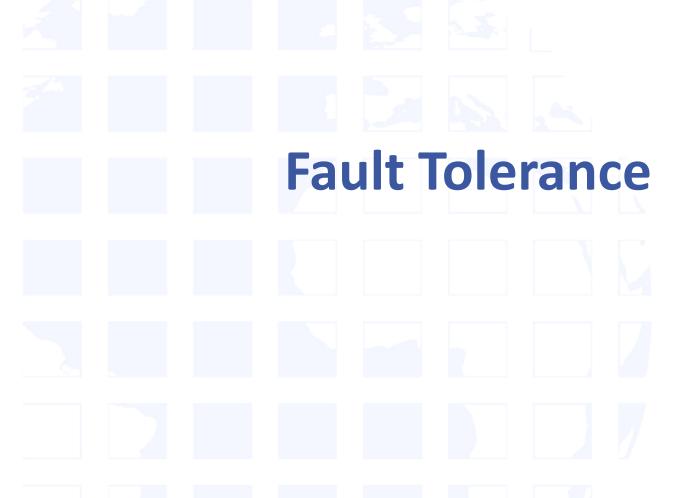
- Time based blocking
- Sends calling thread to sleep
- Wakes up calling thread in case of incoming message or given timeout has been reached



Passive Communication Functions (III)

- Higher latency than one-sided comm.
 - Use cases:
 - Parameter exchange
 - management tasks







Features

- Implementation of fault tolerance is up to the application
- But: well defined and requestable state guaranteed at any time by
 - Timeout mechanism
 - Potentially blocking routines equipped with timeout
 - Error vector
 - contains health state of communication partners
 - Dynamic node set
 - substitution of failed processes



Questions?

Thank you for your attention

www.gaspi.de

www.gpi-site.com