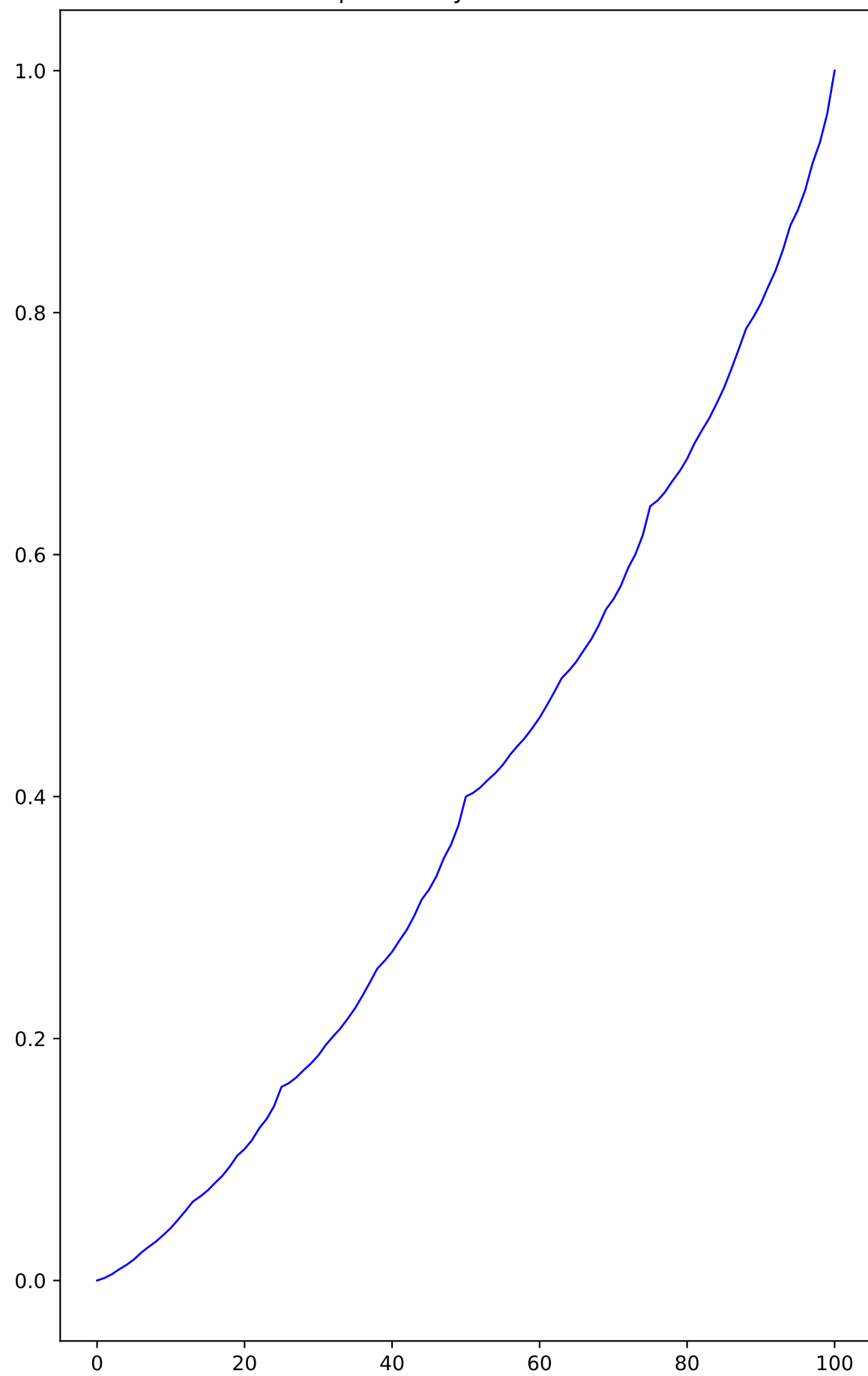


Values of states for probability of head 0.4 for value iteration



Values of states for probability of head 0.4 for policy iteration

