

Anomaly detection in radar data using VAE

PAMI Practice Summer Semester 2025

Prof. Dr. Visvanathan Ramesh

Supervisor: Konrad Wartke

By: Mahmoud Alhag Ali

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Agenda

- 1. Introduction**
- 2. Solution Idea**
- 3. Implementation**
- 4. Result**

Introduction

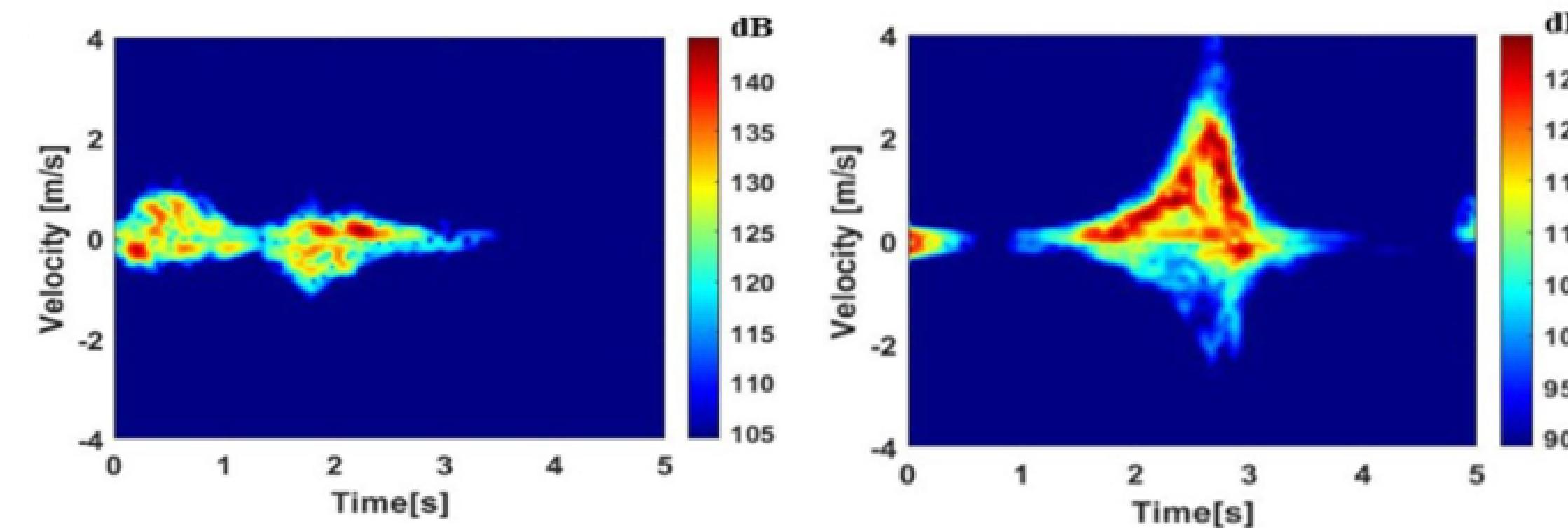
The anomaly detection system can help elderly patients by detecting them falling down. We have a variety of activities captured by radar sensors and we are trying to fall events in processed radar data. Using Variational Auto Encoders we can learn a model of "normal activity" and classify activities as anomalies according to the reconstruction error. The encoder / decoder can use prior knowledge on the expected data structure for better kernel design.

Pipline

- 1.radar**
- 2.pre-processing**
- 3.probabilistic-modeling**
- 4.decision**
- 5.threshold**
- 6.alert**

The Training Data

- Convert the radar data to Images

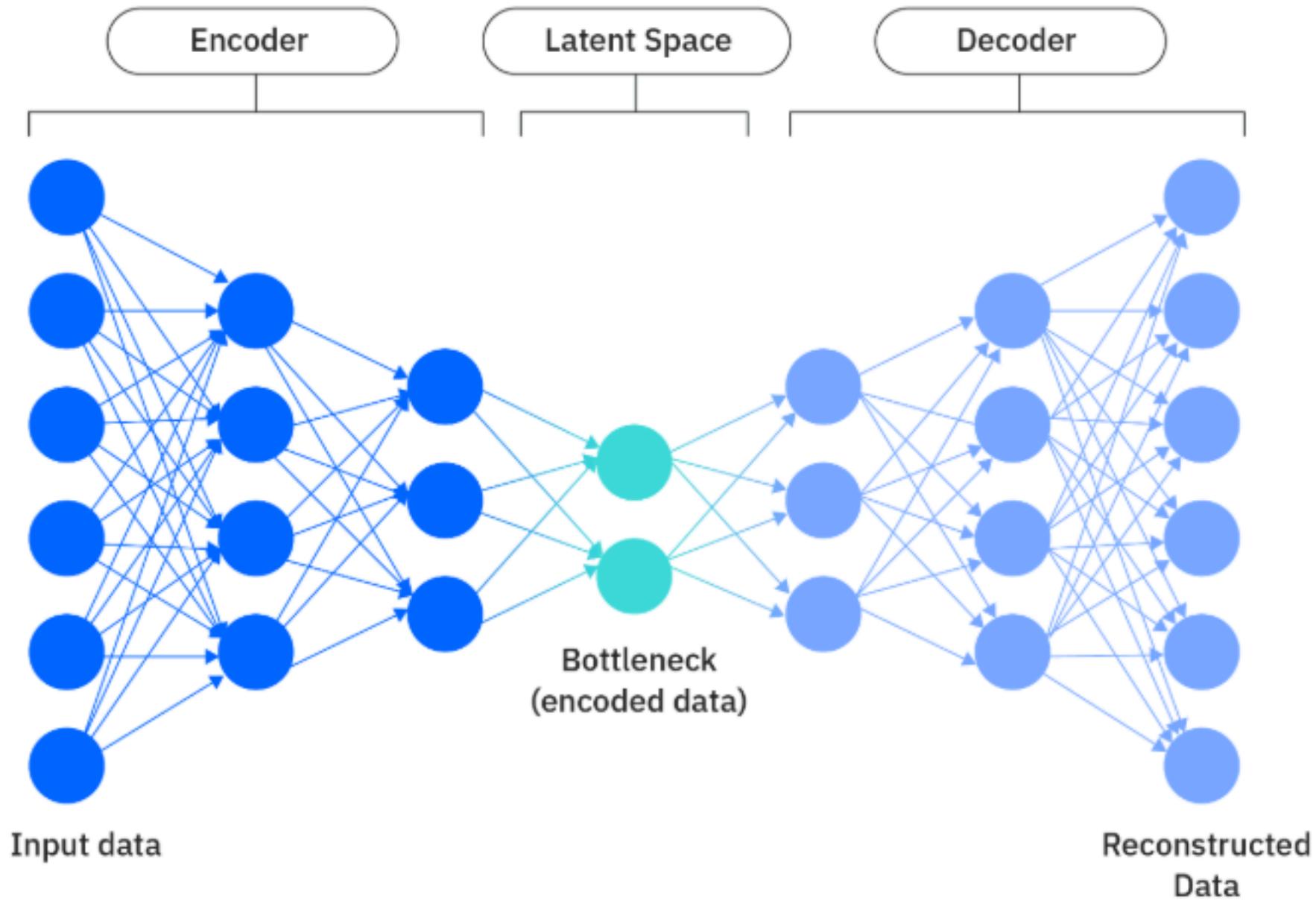


Time-velocity maps showing a single human sitting down (left) and falling (right) (from Li 2023)

Solution Idea

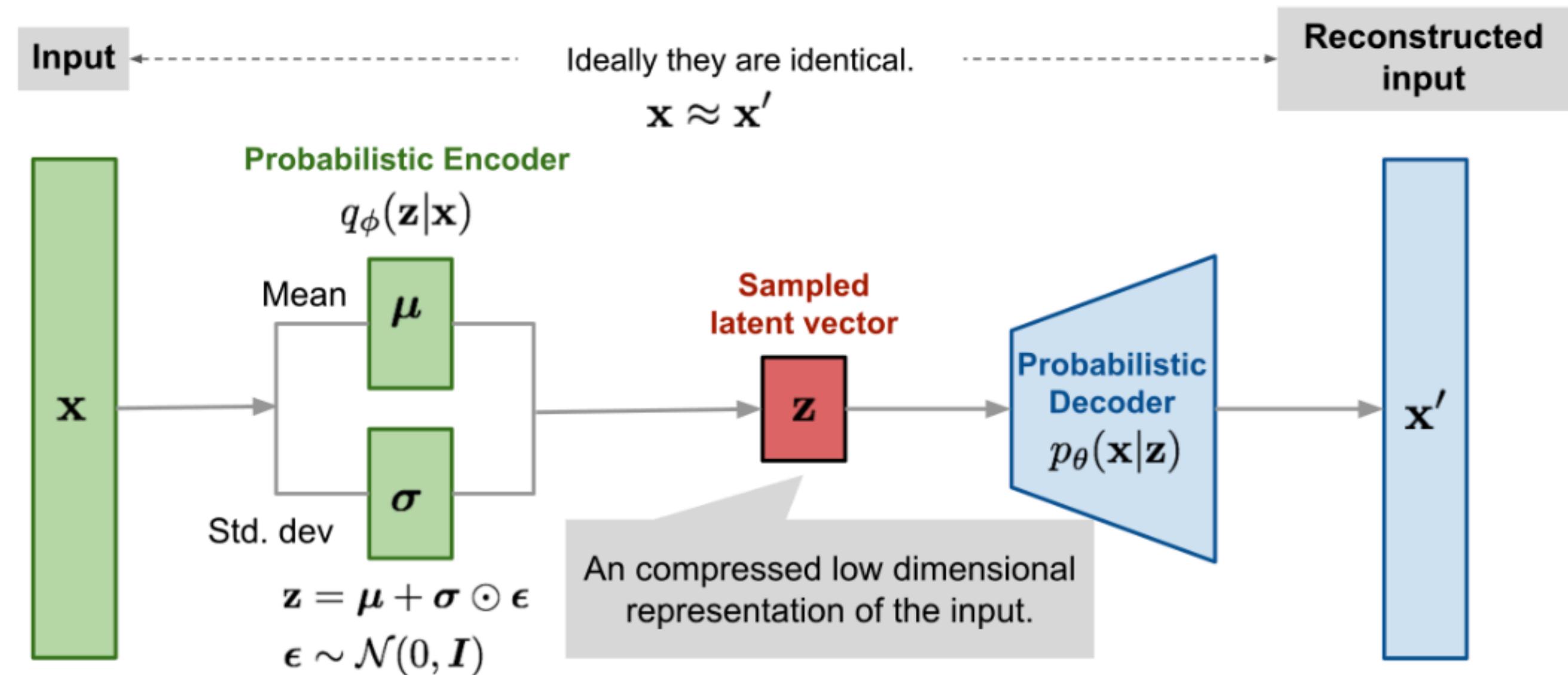
- Convert the radar data to Images
- Use VAE for anomaly detection

Autoencoder



Source: <https://www.ibm.com/think/topics/variational-autoencoder>

Variational Autoencoder



Source:<https://lilianweng.github.io/posts/2018-08-12-vae/>

Implementation

- An, J., & Cho, S. (2015). Variational Autoencoder based Anomaly Detection using Reconstruction Probability.
- Its Implementation from [Michedev](#) (<https://github.com/Michedev>)

Implementation

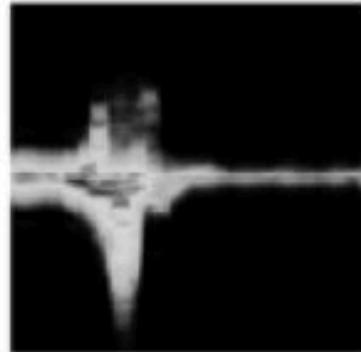
- Frameworks/Libraries: Python: PyTorch, NumPy, Seaborn
- Model architecture: 5 layers for encoder and decoder
- Training dataset: 5844
- Testing dataset: 1125
- Batchsize: 32
- Epoch: 15
- Lernrate: 1e-3

Implementation

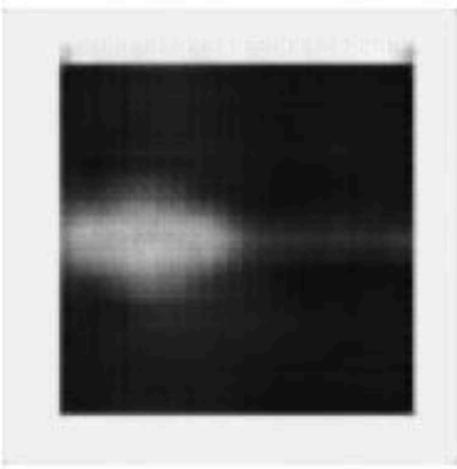
```
def make_encoder(self, input_channels: int, latent_size: int, image_size: int):
    # Convolutional Encoder architecture
    final_spatial_dim = image_size // (2**4) # = 8 for image_size=128
    final_conv_output_channels = 128 # Output channels for the last conv layer before flattening

    return nn.Sequential(
        # Input: (batch_size, input_channels, image_size, image_size) e.g., (B, 1, 128, 128)
        nn.Conv2d(input_channels, 16, kernel_size=4, stride=2, padding=1), # -> (B, 16, 64, 64)
        nn.ReLU(),
        nn.Conv2d(16, 32, kernel_size=4, stride=2, padding=1), # -> (B, 32, 32, 32)
        nn.ReLU(),
        nn.Conv2d(32, 64, kernel_size=4, stride=2, padding=1), # -> (B, 64, 16, 16)
        nn.ReLU(),
        nn.Conv2d(64, final_conv_output_channels, kernel_size=4, stride=2, padding=1), # -> (B, 128, 8, 8)
        nn.ReLU(),
        nn.Flatten(), # -> (B, 128*8*8) = (B, 8192)
        nn.Linear(final_conv_output_channels * final_spatial_dim * final_spatial_dim, latent_size * 2) # -> (B, Latent_size * 2)
    )
```

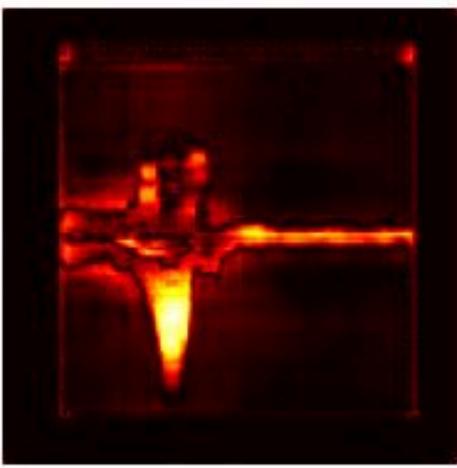
Original (Anomalie)
Batch 69, Sample 12



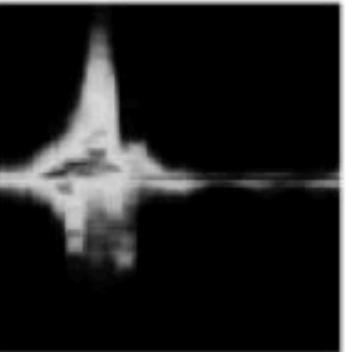
Rekonstruktion
Prob: 12.309555



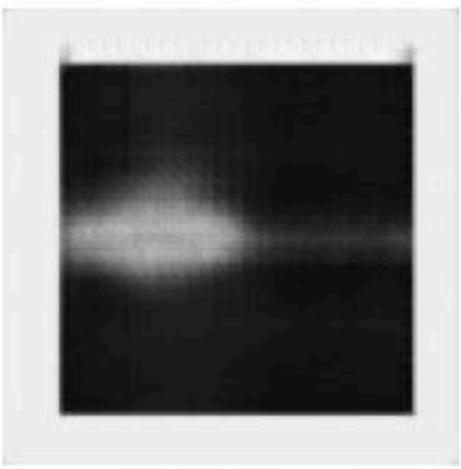
Fehler (|Original - Rekon|)
Mean: 0.087180



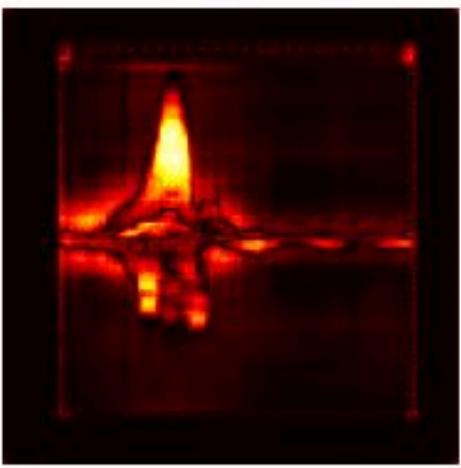
Original (Anomalie)
Batch 69, Sample 13



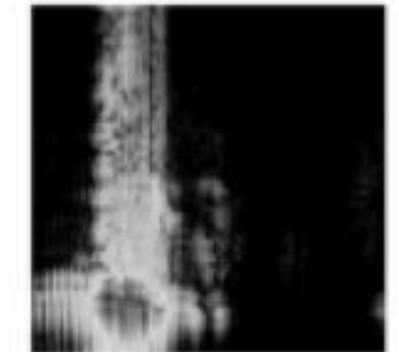
Rekonstruktion
Prob: 12.250659



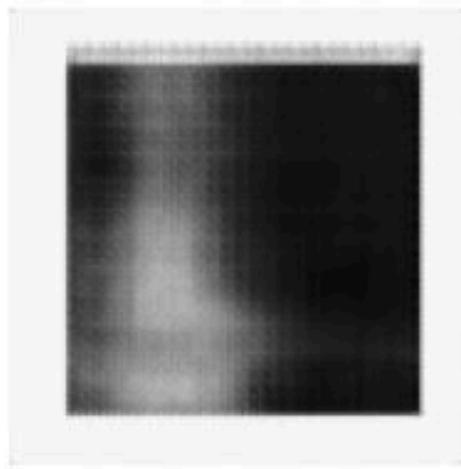
Fehler (|Original - Rekon|)
Mean: 0.085880



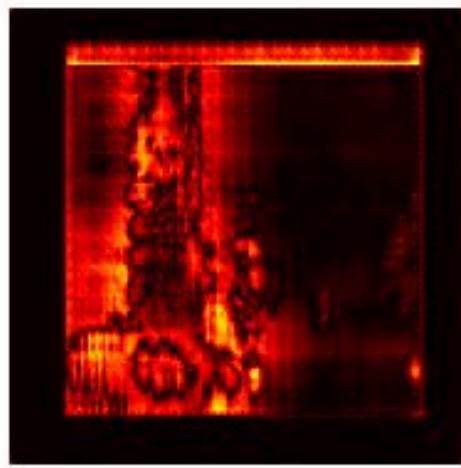
Original (Anomalie)
Batch 69, Sample 14



Rekonstruktion
Prob: 11.355322

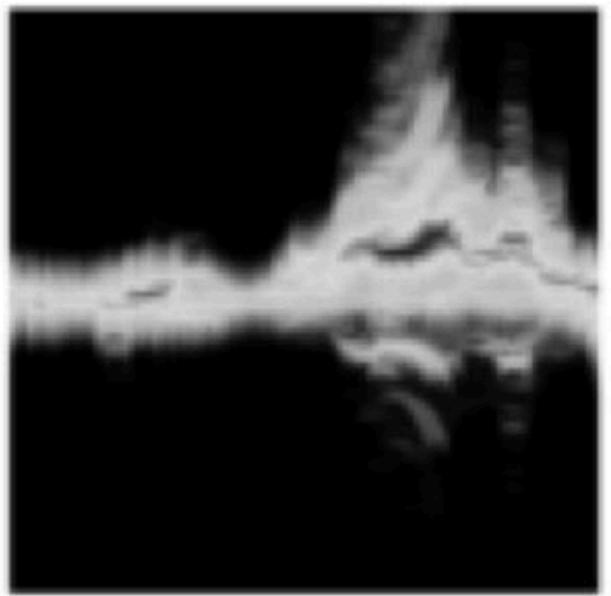


Fehler (|Original - Rekon|)
Mean: 0.121943

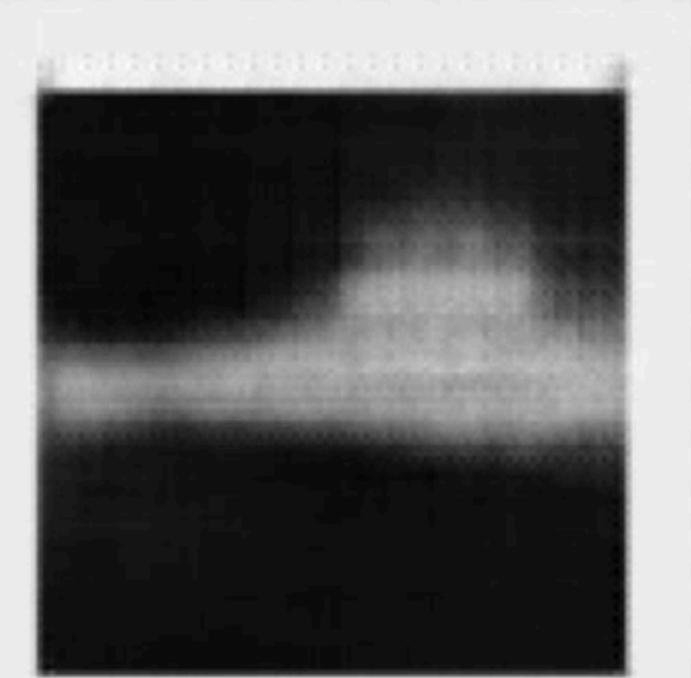


VAE Anomaly Detection: Normal vs Anomaly Comparison

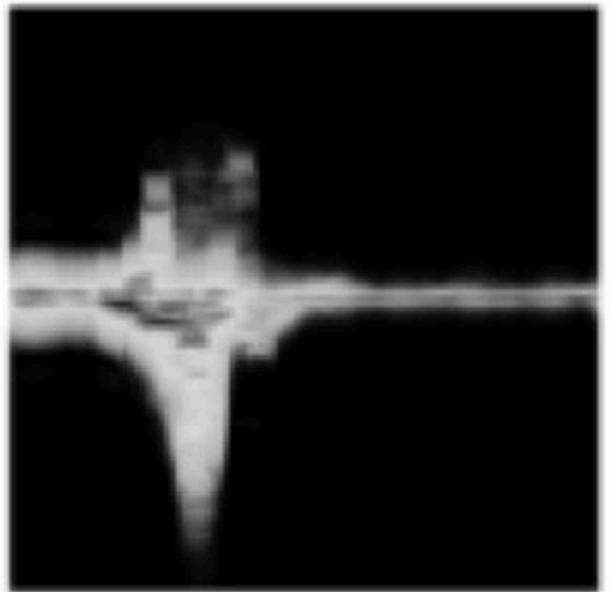
Normal Activity
(Original)



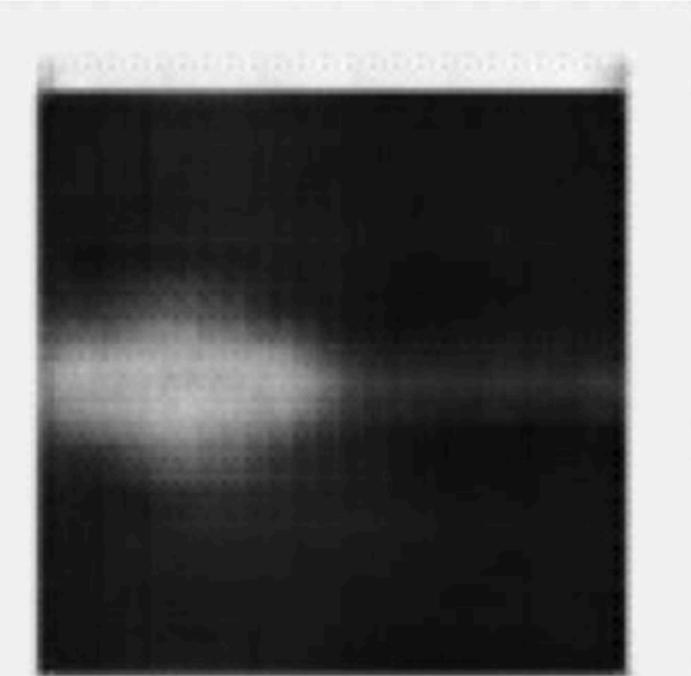
Normal Activity
(Reconstruction)



Fall Activity
(Original)



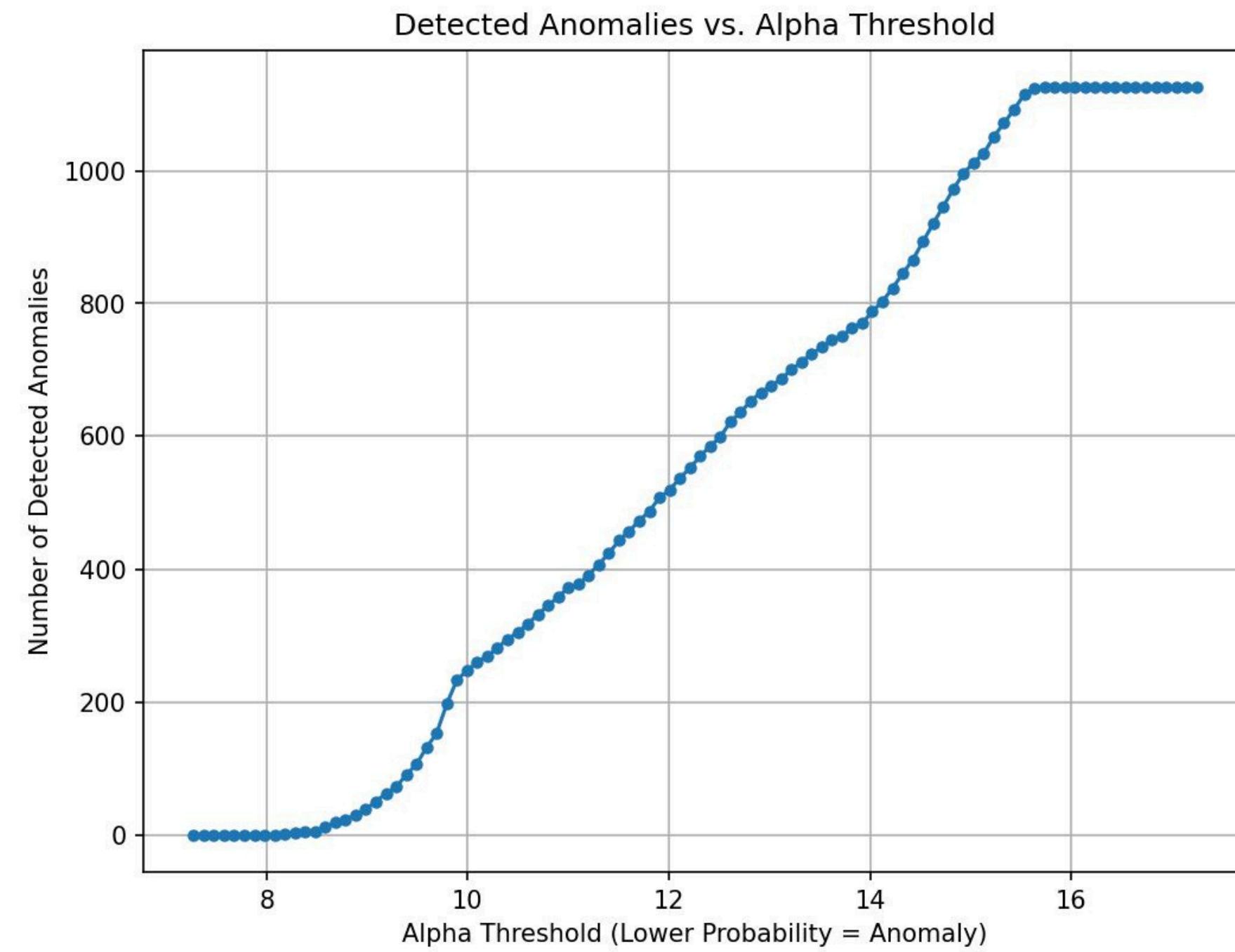
Fall Activity
(Reconstruction)



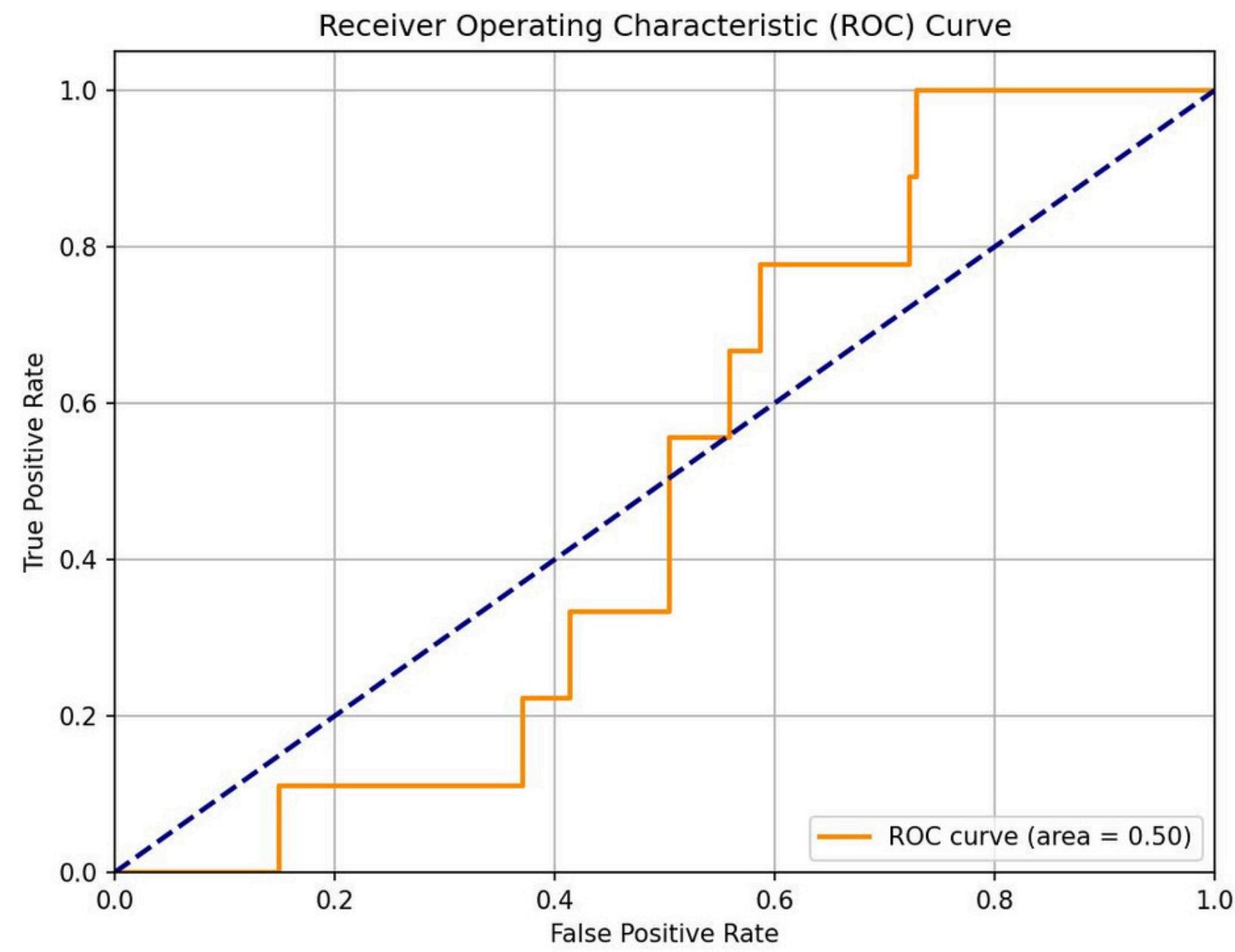
Normal Error: 0.1

Anomaly Error: 0.1

Results

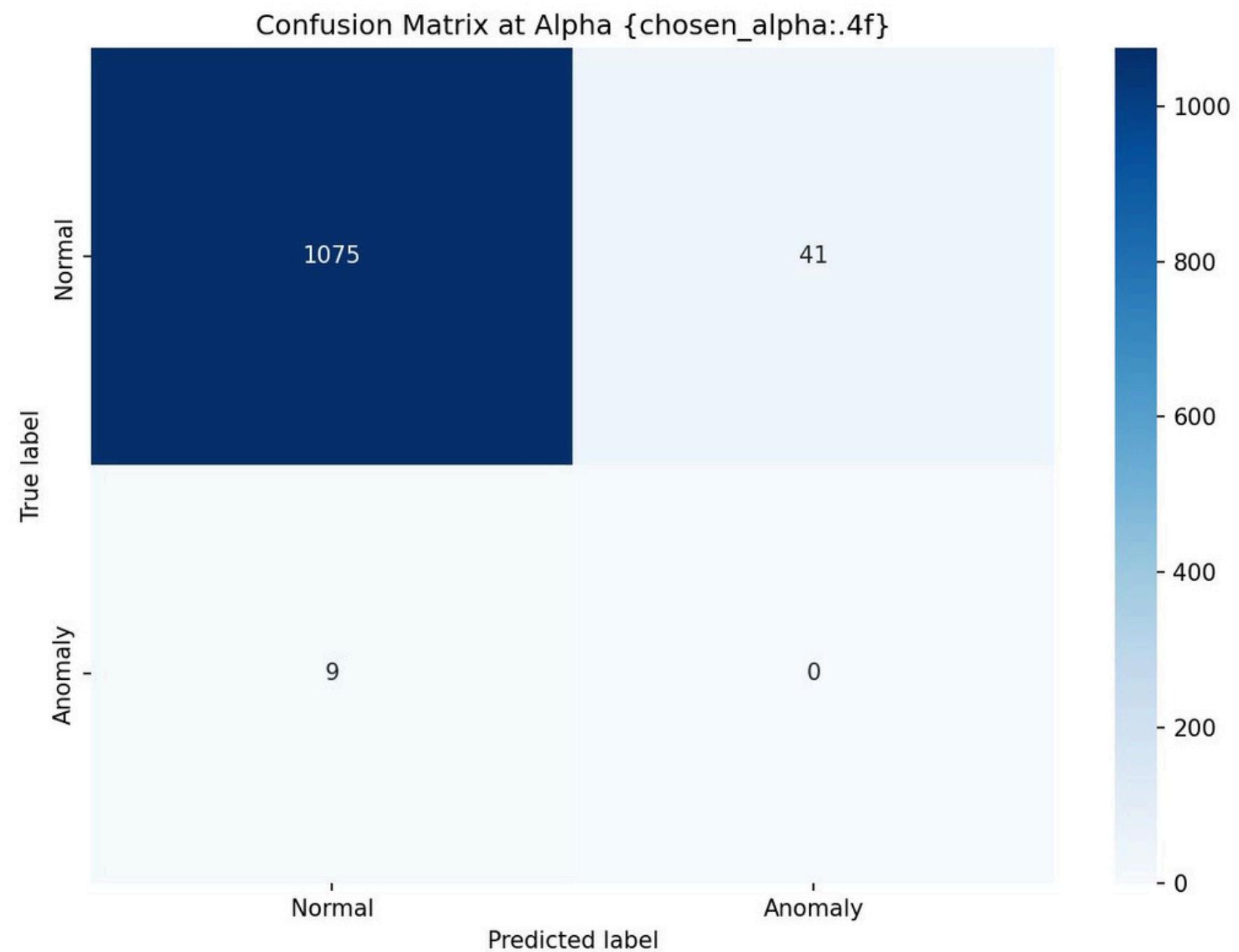


Results

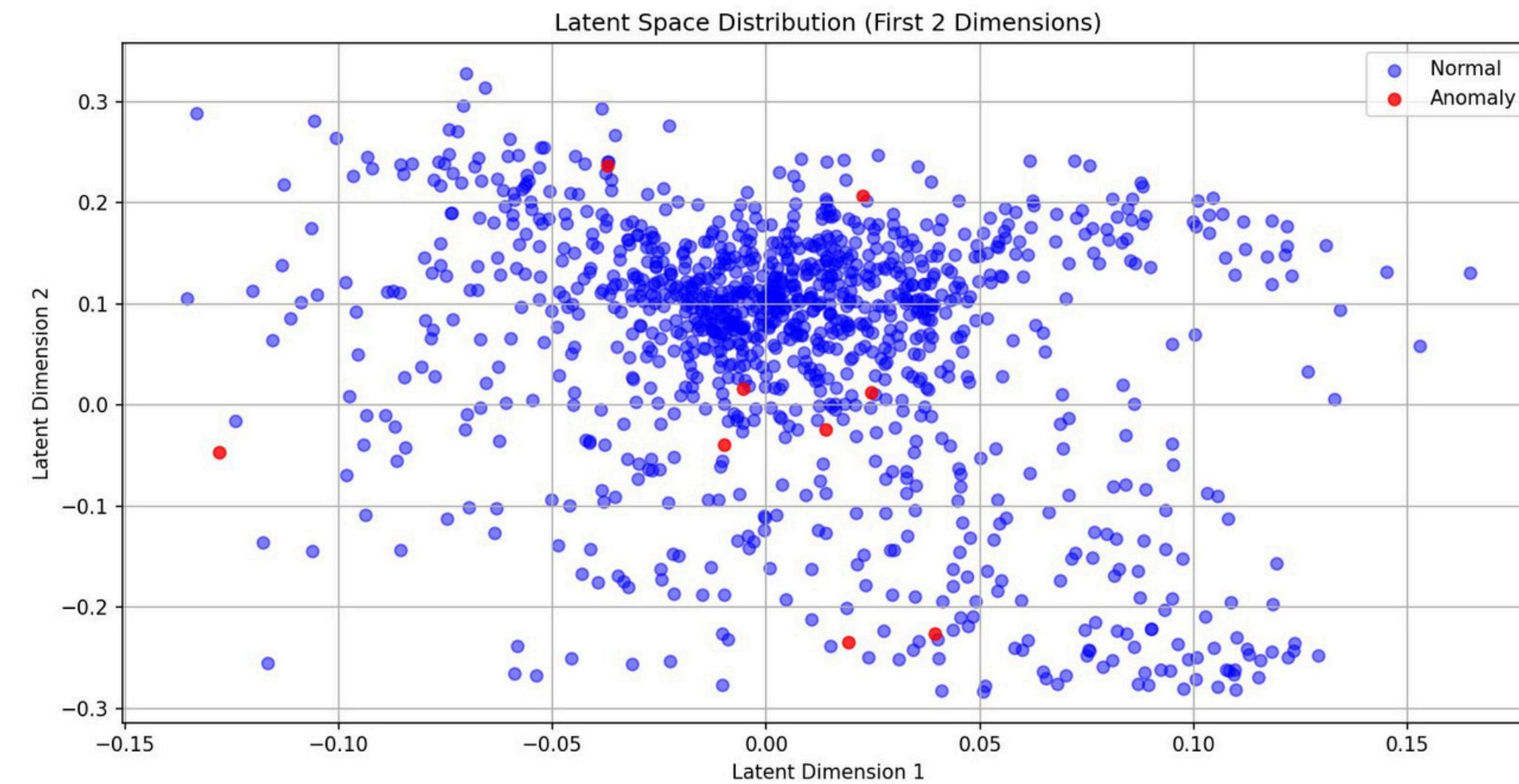


Results

Alpha (Threshold) = 9.0



Results



Results

Classification Report:				
	precision	recall	f1-score	support
Normal	0.99	0.96	0.98	1116
Anomaly	0.00	0.00	0.00	9
accuracy			0.96	1125
macro avg	0.50	0.48	0.49	1125
weighted avg	0.98	0.96	0.97	1125

**Thank
You**