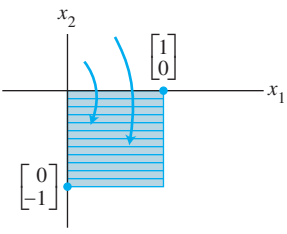
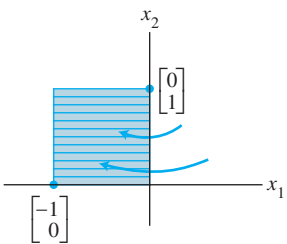
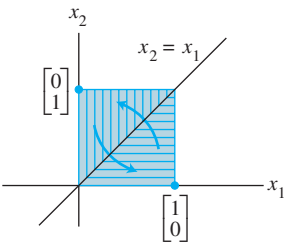
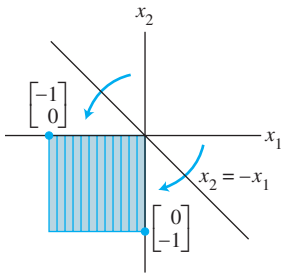
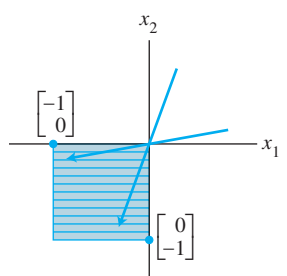
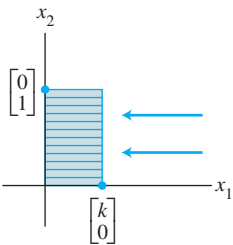
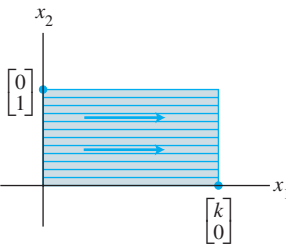
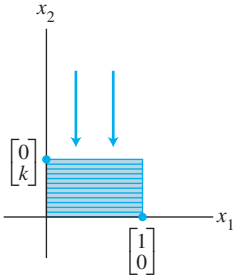
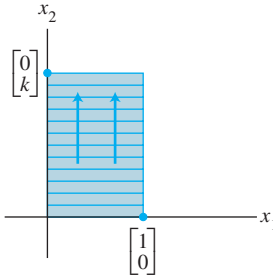


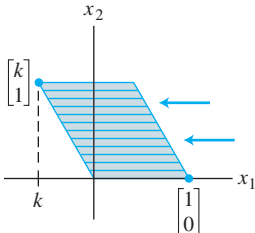
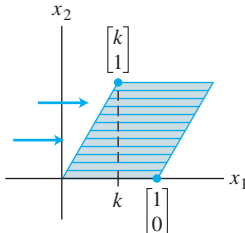
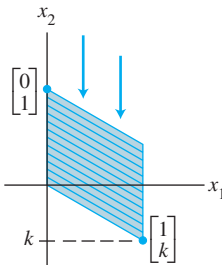
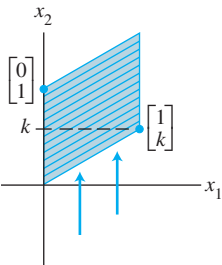
**TABLE 1** Reflections

Transformation	Image of the Unit Square	Standard Matrix
Reflection through the $x_1$ -axis		$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$
Reflection through the $x_2$ -axis		$\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$
Reflection through the line $x_2 = x_1$		$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$
Reflection through the line $x_2 = -x_1$		$\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$
Reflection through the origin		$\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$

**TABLE 2** Contractions and Expansions

Transformation	Image of the Unit Square		Standard Matrix
Horizontal contraction and expansion			$\begin{bmatrix} k & 0 \\ 0 & 1 \end{bmatrix}$
	$0 < k < 1$	$k > 1$	
Vertical contraction and expansion			$\begin{bmatrix} 1 & 0 \\ 0 & k \end{bmatrix}$
	$0 < k < 1$	$k > 1$	

**TABLE 3** Shears

Transformation	Image of the Unit Square		Standard Matrix
Horizontal shear			$\begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$
	$k < 0$	$k > 0$	
Vertical shear			$\begin{bmatrix} 1 & 0 \\ k & 1 \end{bmatrix}$
	$k < 0$	$k > 0$	

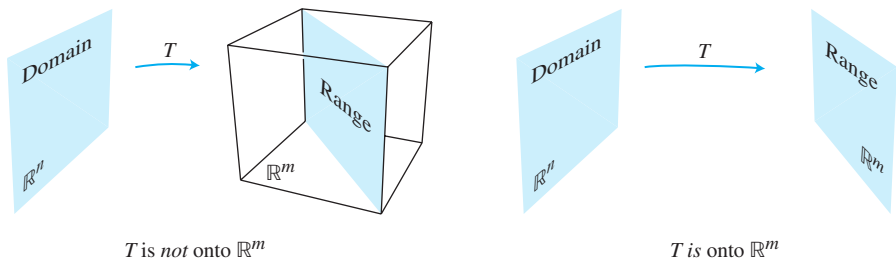
**TABLE 4** Projections

Transformation	Image of the Unit Square	Standard Matrix
Projection onto the $x_1$ -axis		$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$
Projection onto the $x_2$ -axis		$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

**DEFINITION**

A mapping  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is said to be **onto**  $\mathbb{R}^m$  if each  $\mathbf{b}$  in  $\mathbb{R}^m$  is the image of at least one  $\mathbf{x}$  in  $\mathbb{R}^n$ .

Equivalently,  $T$  is onto  $\mathbb{R}^m$  when the range of  $T$  is all of the codomain  $\mathbb{R}^m$ . That is,  $T$  maps  $\mathbb{R}^n$  onto  $\mathbb{R}^m$  if, for each  $\mathbf{b}$  in the codomain  $\mathbb{R}^m$ , there exists at least one solution of  $T(\mathbf{x}) = \mathbf{b}$ . “Does  $T$  map  $\mathbb{R}^n$  onto  $\mathbb{R}^m$ ?” is an existence question. The mapping  $T$  is *not* onto when there is some  $\mathbf{b}$  in  $\mathbb{R}^m$  for which the equation  $T(\mathbf{x}) = \mathbf{b}$  has no solution. See Fig. 3.

**FIGURE 3** Is the range of  $T$  all of  $\mathbb{R}^m$ ?**DEFINITION**

A mapping  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  is said to be **one-to-one** if each  $\mathbf{b}$  in  $\mathbb{R}^m$  is the image of at most one  $\mathbf{x}$  in  $\mathbb{R}^n$ .