Bayesian Generative Adversarial Networks

March 30, 2017

Abstract

Generative Adversarial Networks (GANs) belong to the class of generative models and have received a lot of attention recently. GANs are interesting because they learn to implicitly represent the likelihood function of training data. This is known to work exceptionally well for image data. A trained GAN is able to generate samples that look almost realistic. However, the restriction to an implicit representation means that a GA can only produce samples from the likelihood function. A GAN cannot estimate the likelihood directly. It remains intractable.

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In this Meetup we will take a look at the situation in which a prior distribution is placed over the weights and biases of the GAN. This is called a Bayesian GAN in the literature. Bayesian GANs allow for the modelling of parameter uncertainty. Inferring th posterior distribution for Bayesian GANs poses new challenges due to the absence of a tractable likelihood. We will discuss a recent preprint article by Tran et al. (arXiv:1702.08896), in which an inference method is proposed that is based on variationa inference. The method finds a posterior by fitting the latent variables of a family of distributions. Since the variational family is implicit, the inferred posterior will be implicit as well.

Bayesian Generative Adversarial Networks Outline

- 1. What is a model?
- 2. What is a GAN?
- 3. What is a Bayesian GAN?
- 4. What is a deep implicit model?
- 5. Inference for deep implicit models
- 6. A toy model in Edward

What Is A Model?

Abstract mathematical description of an aspect of the world.

Only valid in a certain regime, and typically under simplifying assumptions.

Essentially, all models are wrong, but some are useful.

George E.P. Box

What Is A GAN?

Basic setup of a Generative Adversarial Network (GAN) is a game between two players:

The generator creates samples from the same distribution as the training data.

The discriminator classifies samples and determines whether they are real or fake.

Training:

The discriminator learns using supervised learning techniques.

The **generator** learns the distribution of the training data and is trained to fool the discriminator.

What Is A GAN?

The players are represented by differentiable functions:

The **discriminator** is a function $d(\mathbf{x}; \theta)$ of samples \mathbf{x} .

The **generator** is a function $g(\varepsilon;\beta)$ taking random $\varepsilon\sim s(\cdot)$ and turning them into fake samples ${\bf x}$.

There are two cost functions:

The **discriminator** must minimize $\mathcal{D}(\theta, \beta)$ while only varying θ .

The **generator** must minimize $\mathcal{G}(\theta, \beta)$ while only varying β .

The solution is a Nash equilibrium $(heta^*,eta^*)$, a tuple where

 ${\mathcal D}$ has a local minimum with respect to ${ heta}.$

 ${\mathcal G}$ has a local minimum with respect to ${\mathcal B}$.

What Is A Bayesian GAN?

In a **GAN**, the generator function g with

$$\mathbf{x}_n = g(arepsilon_n | eta), \quad arepsilon_n \sim s(\cdot), \quad n = 1, \dots, N,$$

is an **implicit** representation of a **likelihood** $p(\mathbf{x}_n|\beta)$ for the observation \mathbf{x}_n :

$$\mathbf{x}_n \sim p(\cdot|eta)$$
.

In a **Bayesian GAN**, we put a **prior** p(eta) on the parameters eta:

$$\beta \sim p(\cdot)$$
.

This allows for explicit modelling of uncertainties in eta.

Bayesian GAN:

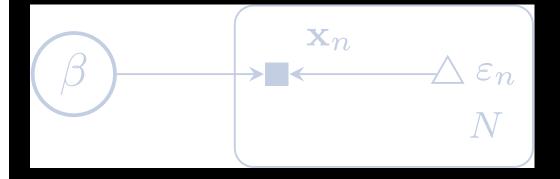
$$\mathbf{x}_n = g(arepsilon_n | eta), \quad arepsilon_n \sim s(\cdot), \quad n = 1, \dots, N.$$

Deep **implicit** model with L+1 layers:

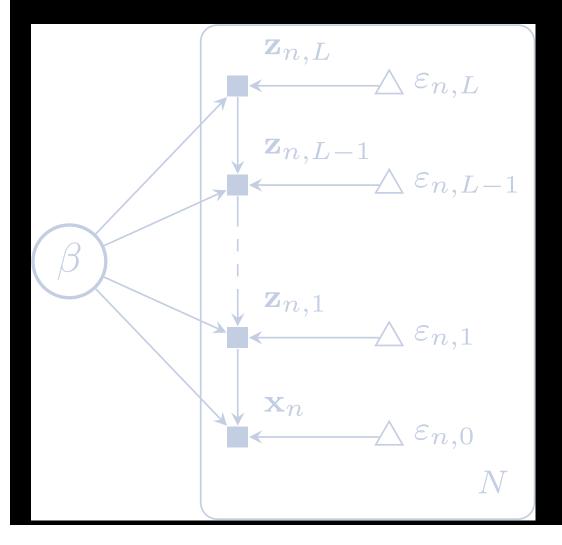
$$egin{aligned} \mathbf{x}_n &= g_0(arepsilon_{n,0}|\mathbf{z}_{n,1},eta), \quad arepsilon_{n,0} \sim s(\cdot), \ \mathbf{z}_{n,1} &= g_1(arepsilon_{n,1}|\mathbf{z}_{n,2},eta), \quad arepsilon_{n,1} \sim s(\cdot), \ &drawpsilon_{n,L-1} &= g_{L-1}(arepsilon_{n,L-1}|\mathbf{z}_{n,L},eta), \quad arepsilon_{n,L-1} \sim s(\cdot), \ \mathbf{z}_{n,L} &= g_L(arepsilon_{n,L}|eta), \quad arepsilon_{n,L} \sim s(\cdot). \end{aligned}$$

This defines the likelihoods $p(\mathbf{x}_n|\mathbf{z}_n,eta)$ and $p(\mathbf{z}_n|eta)$ implicitly.

Bayesian GAN:



Deep ${\color{red}\mathsf{implicit}}$ model with L+1 layers:





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Together with the prior for β , a deep **implicit** model defines a hierarchical Bayesian model,

$$p(\mathbf{X},\mathbf{Z},eta) = p(eta) \prod_{n=1}^N p(\mathbf{x}_n|\mathbf{z}_n,eta) \, p(\mathbf{z}_n|eta).$$

Remainder of the talk: Inference or how do we get the **intractable** posterior $p(\mathbf{Z}, \beta | \mathbf{X})$?

Inference For Deep Implicit Models

Instead of intractable model posterior $p(\mathbf{Z}, \beta | \mathbf{X})$ use variational approximation $q(\beta, \mathbf{Z} | \mathbf{X}; \lambda, \phi)$ with

$$q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi)=q(eta|\mathbf{X};\lambda)\prod_{n=1}^{N}q(\mathbf{z}_{n}|\mathbf{x}_{n},eta;\phi).$$

Minimize the Kullback-Leibler divergence from q to p,

$$\mathrm{KL}\left(q(\beta,\mathbf{Z}|\mathbf{X};\lambda,\phi)||p(\mathbf{Z},\beta|\mathbf{X})\right) \equiv$$

$$\mathbb{E}_{q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi)}igg[\lograc{q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi)}{p(\mathbf{Z},eta|\mathbf{X})}igg]$$

with respect to λ , ϕ since it measures closeness between p and q.

The Evidence Lower Bound

Minimization of $\mathrm{KL}\left(q(\beta,\mathbf{Z}|\mathbf{X};\lambda,\phi)||p(\mathbf{Z},\beta|\mathbf{X})\right)$ with respect to λ and ϕ is not possible, though, because both densities are **intractable**.

Maximize the Evidence Lower BOund (ELBO) instead,

$$egin{aligned} \mathcal{L}(\lambda,\phi) & riangleq \log p(\mathbf{X}) - \mathrm{KL}\left(q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi) \| p(\mathbf{Z},eta|\mathbf{X})
ight) \ & = \mathbb{E}_{q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi)}[\log p(\mathbf{X},\mathbf{Z},eta) - \log q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi)] \,. \end{aligned}$$

The Evidence Lower Bound

$$\mathcal{L}(\lambda, \phi) = \mathbb{E}_{q(eta, \mathbf{Z} | \mathbf{X}; \lambda, \phi)}[\log p(\mathbf{X}, \mathbf{Z}, eta) - \log q(eta, \mathbf{Z} | \mathbf{X}; \lambda, \phi)]$$

Substitute:

$$p(\mathbf{X},\mathbf{Z},eta) = p(eta) \prod_{n=1}^N p(\mathbf{x}_n|\mathbf{z}_n,eta) \, p(\mathbf{z}_n|eta), \ q(eta,\mathbf{Z}|\mathbf{X};\lambda,\phi) = q(eta|\mathbf{X};\lambda) \prod_{n=1}^N \, q(\mathbf{z}_n|\mathbf{x}_n,eta;\phi).$$

Get (dependence on λ , ϕ omitted):

$$egin{aligned} \mathcal{L} &= \mathbb{E}_{q(eta, \mathbf{Z} | \mathbf{X})}[\log p(eta) - \log q(eta | \mathbf{X})] \ &+ \sum_{n=1}^{N} \mathbb{E}_{q(eta, \mathbf{z}_n | \mathbf{X})}[\log p(\mathbf{x}_n, \mathbf{z}_n | eta) - \log q(\mathbf{z}_n | \mathbf{x}_n, eta)] \end{aligned}$$

Ratio Estimation

Subtract the constant **empirical distribution** on the observations \mathbf{X} , $\log q(\mathbf{X}) = \sum_{n=1}^N \log q(\mathbf{x}_n)$, from the latter term:

$$\sum_{n=1}^N \left\{ \mathbb{E}_{q(eta,\mathbf{z}_n|\mathbf{X})}[\log p(\mathbf{x}_n,\mathbf{z}_n|eta) - \log q(\mathbf{z}_n|\mathbf{x}_n,eta)] - \log q(\mathbf{x}_n)
ight\}.$$

Substitute $q(\mathbf{x}_n, \mathbf{z}_n | \beta) \equiv q(\mathbf{x}_n) \, q(\mathbf{z}_n | \mathbf{x}_n, \beta)$ and $q(\beta, \mathbf{z}_n | \mathbf{X}) = q(\beta | \mathbf{X}) \, q(\mathbf{z}_n | \mathbf{x}_n, \beta)$:

$$\sum_{n=1}^{N} \mathbb{E}_{q(eta|\mathbf{X})\,q(\mathbf{z}_n|\mathbf{x}_n,eta)} igg[\log rac{p(\mathbf{x}_n,\mathbf{z}_n|eta)}{q(\mathbf{x}_n,\mathbf{z}_n|eta)} igg] \,.$$

We are going to estimate the log-ratio $\log(p(\cdot|eta)/q(\cdot|eta))$.

The New Evidence Lower Bound

Once we have an estimate of the log-ratio, $r(\mathbf{x}_n,\mathbf{z}_n,\beta)\simeq \log(p(\cdot|\beta)/q(\cdot|\beta))$, we can maximize the new ELBO:

$$egin{aligned} \mathcal{L} & \propto \mathbb{E}_{q(eta, \mathbf{Z} | \mathbf{X})}[\log p(eta) - \log q(eta | \mathbf{X})] \ & + \sum_{n=1}^{N} \mathbb{E}_{q(eta | \mathbf{X}) \, q(\mathbf{z}_n | \mathbf{x}_n, eta)}[r(\mathbf{x}_n, \mathbf{z}_n, eta)] \,. \end{aligned}$$

But we are not there yet.

Back to Ratio Estimation

that it is in (0,1).

Use a GAN-style algorithm:

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Given a sample from p(\cdot) ("fake") or q(\cdot) ("real"), we seek to estimate the probability that it was drawn from p(\cdot) ("fake"):

High probability: "fake" (from p).

Low probability: "real" (from q).

Model this using \sigma(r(\cdot;\theta)), where:

r is a GAN-like discrepancy function.

\theta are the parameters of r.

\sigma(r)=(1+\mathrm{e}^{-r})^{-1} is the logistic function that transforms the output of r such
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Negative Loss Function

Train estimator $r(\cdot; heta)$ by maximizing a negative loss function,

$$egin{aligned} \mathcal{D} &= \mathbb{E}_{p(\mathbf{x}_n, \mathbf{z}_n | eta)}[l_{ ext{fake}}(r(\mathbf{x}_n, \mathbf{z}_n, eta; heta))] \ &+ \mathbb{E}_{q(\mathbf{x}_n, \mathbf{z}_n | eta)}[l_{ ext{real}}(r(\mathbf{x}_n, \mathbf{z}_n, eta; heta))] \end{aligned}$$

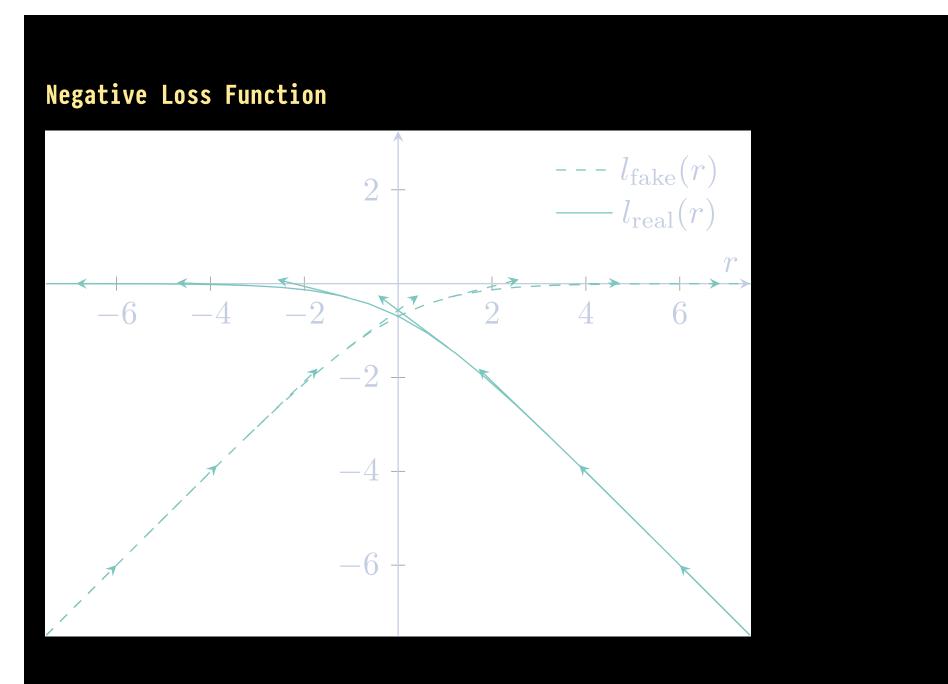
with

$$egin{aligned} l_{ ext{fake}}(r) &= \log \sigma(r) = -\log(1 + \mathrm{e}^{-r}) \equiv \mathrm{softminus}(r), \ l_{ ext{real}}(r) &= \log(1 - \sigma(r)) = -\log(1 + \mathrm{e}^{r}) \equiv -\mathrm{softplus}(r). \end{aligned}$$

Thus:

r is encouraged to be **large** when sample is "fake" (from p).

r is encouraged to be ${\sf small}$ when sample is "real" (from q).



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r is encouraged to be large when sample is "fake" (from p).
r is encouraged to be small when sample is "real" (from q).
```

Why Does This Work?

Why does maximizing $\mathcal D$ with respect to r give us an estimator for the log-ratio $\log(p(\cdot|\beta)/q(\cdot|\beta))$? Consider:

$$\mathcal{D}[r] = \mathbb{E}_{x \sim p}[\operatorname{softminus}(r(x))] - \mathbb{E}_{x \sim q}[\operatorname{softplus}(r(x))]$$
 .

Pretend we can solve the maximization problem in function space:

$$egin{aligned} 0 &= rac{\delta}{\delta r(x)} \mathcal{D} = p(x) \left[rac{\mathrm{d}}{\mathrm{d}s} \mathrm{softminus}(s)
ight]_{s=r(x)} \ &- q(x) \left[rac{\mathrm{d}}{\mathrm{d}s} \mathrm{softplus}(s)
ight]_{s=r(x)} \ &= rac{1}{1+\mathrm{e}^{r(x)}} \left\{p(x) - q(x)\,\mathrm{e}^{r(x)}
ight\} \end{aligned}$$

Why Does This Work?

What's the optimal function? It's the solution of

$$0=p(x)-q(x)\operatorname{e}^{r(x)},$$

that is: $r^*(x) = \log(p(x)/q(x))$ for q(x) > 0 or

$$r^*(\mathbf{x}_n,\mathbf{z}_n,eta;\lambda,\phi)) = \lograc{p(\mathbf{x}_n,\mathbf{z}_n|eta)}{q(\mathbf{x}_n,\mathbf{z}_n|eta;\lambda,\phi)}.$$

Thus we can use our estimate $r(\cdot; \theta)$ as a proxy to the log-ratio!

This is possible as long as the family $r(\cdot;\theta)$ is expressive enough to come close to the optimal function $r^*(\mathbf{x}_n,\mathbf{z}_n,\beta;\lambda,\phi)$.

Gradient of ${\mathcal D}$ with Respect to heta

$$egin{aligned} oldsymbol{
abla}_{ heta} \mathcal{D}(heta) &= \mathbb{E}_{p(\mathbf{x}_n, \mathbf{z}_n | eta)} [oldsymbol{
abla}_{ heta} \, l_{ ext{fake}}(r(\mathbf{x}_n, \mathbf{z}_n, eta; heta))] \ &+ \mathbb{E}_{q(\mathbf{x}_n, \mathbf{z}_n | eta)} [oldsymbol{
abla}_{ heta} \, l_{ ext{real}}(r(\mathbf{x}_n, \mathbf{z}_n, eta; heta))] \end{aligned}$$

Maximizing The ELBO

$$egin{aligned} \mathcal{L}(\phi,\lambda, heta) &\propto \mathbb{E}_{q(eta,\mathbf{Z}|\mathbf{X};\lambda)}[\log p(eta) - \log q(eta|\mathbf{X};\lambda)] \ &+ \sum_{n=1}^N \mathbb{E}_{q(eta|\mathbf{X};\lambda)\,q(\mathbf{z}_n|\mathbf{x}_n,eta;\phi)}[r(\mathbf{x}_n,\mathbf{z}_n,eta; heta)]\,. \end{aligned}$$

Needed gradients for SGA: $\nabla_{\phi}\mathcal{L}$, $\nabla_{\lambda}\mathcal{L}$.

Problem: ϕ and λ are appearing in the **probability measures** $q(\cdot)$ of the expectation value $\mathbb{E}_{q(\cdot)}$.

Solution: Use a differentiable transformation T to move ϕ and λ out of these measures.

Maximizing The ELBO

$$egin{aligned} \mathcal{L}(\phi,\lambda, heta) &\propto \mathbb{E}_{q(eta,\mathbf{Z}|\mathbf{X};\lambda)}[\log p(eta) - \log q(eta|\mathbf{X};\lambda)] \ &+ \sum_{n=1}^N \mathbb{E}_{q(eta|\mathbf{X};\lambda)\,q(\mathbf{z}_n|\mathbf{x}_n,eta;\phi)}[r(\mathbf{x}_n,\mathbf{z}_n,eta; heta)]\,. \end{aligned}$$

Global and local transformations:

1.
$$\mathbb{E}_{q(eta|\mathbf{X};\lambda)}[f(eta)] o \mathbb{E}_{\delta_{\mathrm{global}}\sim s(\cdot)}[f\left(\mathbf{T}_{\mathrm{global}}(\delta_{\mathrm{global}};\lambda)
ight)]$$
 ,

2.
$$\mathbb{E}_{q(\mathbf{z}_n|\mathbf{x}_n,eta;\phi)}[h(\mathbf{z}_n)] o \mathbb{E}_{\delta_{\mathrm{local}}\sim s(\cdot)}[h\left(\mathbf{T}_{\mathrm{local}}(\delta_{\mathrm{local}},\mathbf{x}_n;\phi)
ight)]$$
 .

Example: $s(\cdot)$ is, say, a standard multivariate normal distribution. ${\bf T}$ can then be used map this to a multivariate normal distribution with location μ and covariance ${\bf \Sigma}$.

Gradient of ${\cal L}$ with Respect to ϕ And λ

$$oldsymbol{
abla}_{\phi} \mathcal{L} = \sum_{n=1}^{N} \mathbb{E}_{q(eta | \mathbf{X}; \lambda)} ig[\mathbb{E}_{\delta_{ ext{local}} \sim s(\cdot)} ig[oldsymbol{
abla}_{\phi} \, r(\mathbf{x}_n, \mathbf{z}_n, eta; heta) ig] ig],$$

$$egin{aligned} oldsymbol{
abla}_{\lambda} \mathcal{L} &= \mathbb{E}_{\delta_{ ext{global}} \sim s(\cdot)} [oldsymbol{
abla}_{\lambda} \left(\log p(eta) - \log q(eta | \mathbf{X}; \lambda)
ight)] \ &+ \sum_{n=1}^{N} \mathbb{E}_{\delta_{ ext{global}} \sim s(\cdot)} ig[\mathbb{E}_{q(\mathbf{z}_n | \mathbf{x}_n, eta; \phi)} [oldsymbol{
abla}_{\lambda} r(\mathbf{x}_n, \mathbf{z}_n, eta; heta)] ig] \,. \end{aligned}$$

The Finished Algorithm

Input:

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Model: implicit likelihood p(\mathbf{X},\mathbf{Z}|\beta), tractable prior p(\beta). Variational approximation family: implicit likelihood q(\mathbf{z}_n|\mathbf{x}_n,\beta;\phi), tractable prior q(\beta|\mathbf{X};\lambda). Ratio estimate: r(\cdot;\theta).
```

Output: Variational parameters ϕ and λ .

Algorithm:

```
Initialize \phi, \lambda, and \theta randomly. While not converged do: Compute unbiased estimates of \nabla_{\theta}\mathcal{D}(\theta), \nabla_{\phi}\mathcal{L}, and \nabla_{\lambda}\mathcal{L}. Update \phi, \lambda, and \theta using SGA. End.
```





Can I Use This?

Bayesian GANs and GAN-style inference are available in Edward.

Where Can I Read More About This?

Tran et al., Deep and Hierarchical Implicit Models, arXiv: 1702.08896

Tran et al., Deep Probabilistic Programming, arXiv:1701.03757

Mescheder et al., Adversarial Variational Bayes: Unifying Variational Autoencoders and Generative Adversarial Networks, arXiv:1701.04722

F. Huszár, Variational Inference using Implicit Distributions, arXiv:1702.08235

Goodfellow et al., Generative Adversarial Nets, arXiv:1406.2661

I. Goodfellow, Generative Adversarial Networks, arXiv:1701.00160, NIPS 2016 Tutorial

Blei et al., Variational Inference: Foundations and Modern Methods, NIPS 2016 Tutorial

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