



**HACETTEPE UNIVERSITY
ENGINEERING FACULTY
ELECTRICAL AND ELECTRONICS
ENGINEERING PROGRAM**

2023-2024
SPRING SEMESTER

ELE708
NUMERICAL METHODS IN ELECTRICAL ENGINEERING

HW2

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1) Exercises

1.a) 2.11

2.11 Write out detailed algorithm for solving lower triangular linear systems
- $Lx = b$ by forward substitution.

$$L = \begin{bmatrix} l_{11} & 0 & 0 & 0 \\ l_{21} & l_{22} & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \end{bmatrix}$$

- for $j = 1$ to n
 if $l_{jj} = 0$ then stop
 $x_j = b_j / l_{jj}$
 for $i = j+1$ to n
 $b_i = b_i - l_{ij} \cdot x_j$
 end
end

⇓

- loop over columns
- stop if pivot is zero
- compute x
- subtract found x value from next rows

- for $j = 1$ to n
 if $l_{jj} = 0$, then stop
 for $i = 1$ to j
 $b_i = b_i - x_j \cdot l_{ji}$
 end
 $x_j = b_j / l_{jj}$
end

⇓

- loop over columns
- stop if pivot is zero
- subtract previously found x value from b
- calculate x

2.17. Write out the LU factorization of the following matrix

$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{bmatrix} \xrightarrow{S_1 + S_2} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & -1 & 1 \end{bmatrix} \xrightarrow{S_2 + S_3} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\Downarrow \quad \Downarrow$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

$M_1 \qquad \qquad M_2$

$$L = M_1^{-1} \cdot M_2^{-1} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_L$

2.31. Let A be a symmetric positive matrix.

$$\|x\|_A = (x^T A x)^{1/2}$$

satisfies the three properties of a vector norm.

1. $\|x\| > 0$ if $x \neq 0$
2. $\|yx\| = |y| \cdot \|x\|$ for any scalar y
3. $\|x+y\| \leq \|x\| + \|y\|$

1. A is positive definite so $\Rightarrow x^T A x \geq 0$ ————— So its true
but $x^T A x = 0$ if $x = 0 \rightarrow x^T A x > 0$ if $x \neq 0$

$$\begin{aligned} 2. \|yx\| &= (y^T A y x)^{1/2} = (y^2 \cdot x^T A x)^{1/2} \\ &= |y| \cdot (x^T A x)^{1/2} \\ &= |y| \cdot \|x\| \quad \text{its true} \end{aligned}$$

$$\begin{aligned} 3. \|x+y\|^2 &= (x+y)^T \cdot A \cdot (x+y) \\ &= (x^T A x) + (x^T A y) + (y^T A x) + (y^T A y) \\ &= \|x\|^2 + \|y\|^2 + (x^T A y) + (y^T A x) \\ &= \|x\|^2 + \|y\|^2 + 2 \cdot x^T A y \\ &\leq \|x\|^2 + \|y\|^2 + 2 \cdot (x^T A x) \cdot (y^T A y) \\ &\leq \|x\|^2 + \|y\|^2 + 2 \cdot \|x\| \cdot \|y\| \quad \text{Cauchy-Schwarz} \\ \|x+y\|^2 &\leq (\|x\| + \|y\|)^2 \\ \|x+y\| &\leq \|x\| + \|y\| \end{aligned}$$

$$\begin{aligned} x^T A y &= (x^T A y)^T \\ &= y^T A^T x \\ &= y^T A x \\ \Downarrow \\ x^T A y &= y^T A x \end{aligned}$$

2.32. Show that the following functions of an $m \times n$ matrix A satisfy the matrix norm properties

$$a-) \|A\|_{\max} = \max_{i,j} |a_{ij}|$$

$$b-) \|A\|_F = \left(\sum_{i,j} |a_{ij}|^2 \right)^{1/2}$$

$$1. \|A\| > 0 \text{ if } A \neq 0$$

$$2. \|yA\| = |y| \cdot \|A\|$$

$$3. \|A+B\| \leq \|A\| + \|B\|$$

$$a.1) \text{ if } |a_{ij}| \neq 0, |a_{ij}| > 0 \Rightarrow \text{therefore } \|A\|_{\max} > 0$$

$$a.2) \|y \cdot A\|_{\max} = \max_{j,j} |y \cdot a_{ij}| \Rightarrow \|y \cdot A\|_{\max} = |y| \cdot \|A\|_{\max} = |y| \cdot \max |a_{ij}|$$

$$a.3) \|A+B\|_{\max} = \max_{j,j} |a_{ij} + b_{ij}| \leq \max (|a_{ij}| + |b_{ij}|) \Rightarrow \|A+B\|_{\max} \leq \|A\|_{\max} + \|B\|_{\max} \leq \max |a_{ij}| + \max |b_{ij}|$$

$$b.1) |a_{ij}|^2 > 0 \text{ if } a_{ij} \neq 0 \Rightarrow \|A\|_F > 0$$

Therefore $\left(\sum_{i,j} |a_{ij}|^2 \right) > 0$

$$b.2) \|yA\|_F = \left(\sum |a_{ij} \cdot y|^2 \right)^{1/2} = \left(\sum |y|^2 \cdot |a_{ij}|^2 \right)^{1/2} = |y| \cdot \left(\sum |a_{ij}|^2 \right)^{1/2} > \|yA\| = |y| \cdot \|A\|$$

$$b.3) \|A+B\|^2 = \left(\sum_i |A+B|^2 \right) = \sum_i |A|^2 + 2 \sum_i |A \cdot B| + \sum_i |B|^2$$

$$\leq \sum_i |a_i|^2 + 2 \cdot \left(\sum_i |a_i|^2 \right)^{1/2} \cdot \left(\sum_i |b_i|^2 \right)^{1/2} + \sum_i |b_i|^2$$

$$\leq \left(\left(\sum_i |a_i|^2 \right)^{1/2} + \left(\sum_i |b_i|^2 \right)^{1/2} \right)^2$$

$$\leq (\|A\| + \|B\|)^2$$

$$\|A+B\|^2 \leq \|A\| + \|B\|$$

2) Computer Problems

2.a) 2.3 Resolving the member forces into horizontal and vertical components and defining $\alpha = \frac{v}{2/2}$, we obtain the following system of equations for the member forces f_i :

$$\begin{aligned}\text{Joint 2 : } & \begin{cases} f_2 = f_6 \\ f_3 = 10 \end{cases} \\ \text{Joint 3 : } & \begin{cases} \alpha f_1 = f_4 + \alpha f_5 \\ \alpha f_1 + f_3 + \alpha f_5 = 0 \end{cases} \\ \text{Joint 4 : } & \begin{cases} f_4 = f_8 \\ f_7 = 0 \end{cases} \\ \text{Joint 5 : } & \begin{cases} \alpha f_5 + f_6 = \alpha f_9 + f_{10} \\ \alpha f_5 + f_7 + \alpha f_9 = 15 \end{cases} \\ \text{Joint 6 : } & \begin{cases} f_{10} = f_{13} \\ f_{11} = 20 \end{cases} \\ \text{Joint 7 : } & \begin{cases} f_8 + \alpha f_9 = \alpha f_{12} \\ \alpha f_9 + f_{11} + \alpha f_{12} = 0 \end{cases} \\ \text{Joint 8 : } & \begin{cases} f_{13} + \alpha f_{12} = 0 \end{cases}\end{aligned}$$

Solve the linear system.

When we create the matrix according to the giving equations, and solve. We get following answer.

```
Workspace
>> CP2_3
Force 1: -28.284271
Force 2: 20.000000
Force 3: 10.000000
Force 4: -30.000000
Force 5: 14.142136
Force 6: 20.000000
Force 7: 0.000000
Force 8: -30.000000
Force 9: 7.071068
Force 10: 25.000000
Force 11: 20.000000
Force 12: -35.355339
Force 13: 25.000000
fx >>
```

2.b) 2.4 Write a routine for estimating the condition number of a matrix A. You may use either the 1-norm or the ∞ -norm (or try both and compare the results). You will need to compute $\|A\|$, which is easy, and estimate $\|A^{-1}\|$, which is more challenging. As discussed in Section 2.3.3, one way to estimate $\|A^{-1}\|$ is to choose a vector y such that the ratio $\|z\|/\|y\|$ is large, where z is the solution to $Az = y$. Try two different approaches to choosing y:

Method-a gives better results compared to method-b but calculating b is more practical.

Matrix-2 is more ill-conditioned compared to Matrix-1.

```

Workspace Command Window
>> CP2_4
-----
Matrix 1, 1-norm
Condition estimate, method a: 1.120708e+01
Condition estimate, method b: 7.985759e+00
MATLAB condest function: 1.277419e+01
MATLAB cond function: 1.277419e+01
Actual condition number: 1.277419e+01
-----

Matrix 1, infinity-norm
Condition estimate, method a: 1.457713e+01
Condition estimate, method b: 3.994167e+00
MATLAB condest function: 1.277419e+01
MATLAB cond function: 1.700000e+01
Actual condition number: 1.700000e+01
-----

Matrix 2, 1-norm
Condition estimate, method a: 3.205084e+06
Condition estimate, method b: 2.575753e+06
MATLAB condest function: 4.016285e+06
MATLAB cond function: 4.016285e+06
Actual condition number: 4.016285e+06
-----

Matrix 2, infinity-norm
Condition estimate, method a: 3.536601e+06
Condition estimate, method b: 1.477306e+06
MATLAB condest function: 4.016285e+06
MATLAB cond function: 4.431711e+06
Actual condition number: 4.431711e+06
-----
fx >> |

```

2.c) Codes for 2.3 and 2.4

2.c.i) 2.3

```
Editor - D:\Ders\M.Sc\M.Sc\ELE708 - Numerical Methods in Electrical Engineering\HW2\CP2_3.m
CP2_3.m  CP2_4.m  +
1  A = zeros(13,13);
2  alpha = 1/sqrt(2);
3
4  % Joint 2
5  A(1,2) = 1;
6  A(1,6) = -1;
7  A(2,3) = 1;
8  b(2) = 10;
9
10 % Joint 3
11 A(3,1) = alpha;
12 A(3,4) = -1;
13 A(3,5) = -alpha;
14 A(4,1) = alpha;
15 A(4,3) = 1;
16 A(4,5) = alpha;
17
18 % Joint 4
19 A(5,4) = 1;
20 A(5,8) = -1;
21 A(6,7) = 1;
22
23 % Joint 5
24 A(7,5) = alpha;
25 A(7,6) = 1;
26 A(7,9) = -alpha;
27 A(7,10) = -1;
28 A(8,5) = alpha;
29 A(8,7) = 1;
30 A(8,9) = alpha;
31
32
33 % Joint 6
34 A(9,10) = 1;
35 A(9,13) = -1;
36 A(10,11) = 1;
37
38 % Joint 7
39 A(11,8) = 1;
40 A(11,9) = alpha;
41 A(11,12) = -alpha;
42 A(12,9) = alpha;
43 A(12,11) = 1;
44 A(12,12) = alpha;
45
46 % Joint 8
47 A(13,13) = 1;
48 A(13,12) = alpha;
49
50 b = [0;10;0;0;0;0;0;0;15;0;20;0;0;0;];
51
52 f = A\b;
53
54 fprintf('Force %2d: %f \n', [1:13;f'])
55
```


2.c.ii) 2.4

```

Editor - D:\Ders\M.Sc\M.Sc\ELE708 - Numerical Methods in Electrical Engineering\HW2\CP2_4.m
CP2_3.m CP2_4.m +
1
2   A1 = [10 -7 0;
3         -3 2 6;
4         5 -1 5];
5
6   A2 = [-73 78 24;
7         92 66 25;
8         -80 37 10];
9   fprintf('-----\n');
10  disp('Matrix 1, 1-norm');
11  estcond(A1, 1);
12  disp(' ');
13
14  fprintf('-----\n');
15  disp('Matrix 1, infinity-norm');
16  estcond(A1, inf);
17  disp(' ');
18
19  fprintf('-----\n');
20  disp('Matrix 2, 1-norm');
21  estcond(A2, 1);
22  disp(' ');
23
24  fprintf('-----\n');
25  disp('Matrix 2, infinity-norm');
26  estcond(A2, inf);
27  disp(' ');
28
29  function [c] = estcond(A, p)
30  norm_A = norm(A, p);
31  [L,U,P] = lu(A);
32  n = size(A,1);
33
34  % part (a), transposed triangular solves with special rhs
35  v = zeros(n,1);
36  v(1) = 1/U(1,1);
37  for i=2:n
38      tot = 0;
39      for j=1:i-1
40          tot = tot-U(j,i)*v(j);
41      end
42
43      if tot > 0
44          tot = tot+1;
45      else
46          tot = tot-1;
47      end
48
49      v(i) = tot/U(i,i);
50  end
51
52  for i=n:-1:1
53      tot = v(i);
54      for j=i+1:n
55          tot = tot-L(j,i)*v(j);
56      end
57      v(i) = tot;
58  end
59  y = P*v; z = U\((P*y));
60  fprintf('Condition estimate, method a: %e\n', norm_A*norm(z,p)/norm(y,p));
61
62
63  % part (b), several random choices for y
64  maxratio = 0;
65  for k=1:5
66      y = rand(n,1); z = A\y; t = norm(z,p)/norm(y,p);
67      if t > maxratio, maxratio = t;
68      end
69  end
70
71
72  fprintf('Condition estimate, method b: %e\n', norm_A*maxratio);
73  fprintf('MATLAB condest function: %e\n', condest(A));
74  fprintf('MATLAB cond function: %e\n', cond(A,p));
75  fprintf('Actual condition number: %e\n', norm(A,p)*norm(inv(A),p));
76  fprintf('-----\n');
77  end

```