

view_frames Result

Recorded at time: 1653669017.304

pan_tilt_pitch_link

base_link

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

pan_tilt_surface

pan_tilt_base_link

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

camera_mount

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

camera_body

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

camera_base

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1653669017.304 sec old)

Buffer length: 0.000 sec

camera_visor