Muhammad Ali

Contact • Email 37alirisalpur@gmail.com

• **Phone** +92 311 5112586

• Address Marghuz, Swabi, KPK, Pakistan

Attachments

• Self-introduction video https://bit.ly/3jG8TkP

• Portfolio https://mmali.netlify.app/

• Sample research project https://youtu.be/aDtnSoSor4E

• Sample research proposal https://bit.ly/3FdWZpk

• Sample practical work https://youtu.be/NtWT8aEdATg

• Supporting documents https://bit.ly/3v62nqc

Education

• Pakistan Institute of Engineering and Applied Sciences (PIEAS)

BS Electronics Engineering
 Sep 2018 - June 2022

CGPA: 3.74 / 4.00
 Distinction with 2nd position

• Fazaia Degree College, MRF, Kamra

School: Matriculation
 April 2013 – March 2015

Percentage: 95 %
 Distinction with 1st position

• Fazaia Degree College, Risalpur

Date: 22-08-2022 --- Present

College: FSC Pre-engineering
 June 2015 – May 2017

Percentage: 83%
 Distinction with 4th position

Work Experience

Cloud Core Network Engineer at Huawei, OEC tower, Isb

• Group Leader: 03-10-2022 --- Present

• Robotics Engineer at Natinal Institue of Electronics, Sector H-9, Isb

• Date: 02-08-2021 --- 24-09-2021

Made two-wheel self-balancing robot

• Vice-president IEEE Robotics PIEAS Student Branch

Date: 20-Sep-2021 --- 16-May-2022

Responsibilities: Organizing seminars and workshops on Robotics

Huawei's Projects

• 5G Core Deployment (AMF)

Cloud Edge (MME)

Network function virtualization (FusionSphere OpenStack)

Research Experience

• Implementation of deep learning control for a Quadcopter

Made digital twin of Quadcopter in gazebo environment (in Ubuntu OS)

Trained the model through Proximal Policy Optimization, a reinforcement learning algorithm

Replaced the PID algorithm of betaflight with our trained model

Compiled the modified betaflight to create a hex file

Assembled the Quadcopter (used STM32F722 microcontroller which runs up to 216 MHz)

Flashed the hex file to quadcopter using betaflight configurator

• Video: https://youtu.be/aDtnSoSor4E



Technical Projects

- Maze Solver Robot
- Line follower robot
- Controlling Servo from Web browser wirelessly using ESP32
- Controlling Servo using Potentiometer and ESP32
- 15,000 mAh Laptop Power Bank
- Android P2P messaging App
- Trained Reinforcement Learning agent for autonomous driving
- Reinforcement Learning for Atari Breakout Game
- Trained Neural Network for Image prediction
- Training CartPole to balance itself
- Tic-tac-toe game using a C++ programming language
- Detection of cracks in Ceramic Tiles using Digital Image Processing
- Designed a 1kVA UPS powered by a single-phase 220V/50Hz AC.
- Designed 8-bit SAR ADC
- Designed and implemented a stepper motor controller
- 35% Duty Cycle Rectangular Waveform using Astable Multivibrator (555 Timer)
- · Designed a filter
 - that removes cross-over distortion from class B push-pull amplifier
 - that minimizes noise coming from a tape recorder.
 - for a car alternator.

Skills

• Programming Languages

C++, Python, C, and Java

• Integrated Development Environments (IDEs)

MATLAB/Simulink, Arduino IDE, Xilinx ISE, Keil, LTspice, MobotSim, ModelSim, Visual Studio, Android Studio, Gazebo simulator, GymFC, Autodesk Inventor, Creo Parametric, Virtual box(Linux/Ubuntu), Microsoft Word, PowerPoint, Excel

• Electronics Boards

ESP32 MCU, Spartan 3 SoC FPGA, Arduino Due, and Arduino Mega, Uno, Nano

• Sensors/ Actuators etc

6-axis IMU; quadrature encoder; GPS, ultrasonic, IR, barometer, temperature sensors; 3S 12V 25A BMS; Radio transceiver; servo, stepper, DC, brushless motors

• Practical Work

PCB Designing, Veroboard usage/Soldering, Metalworks (lathe Machine, Wielding, etc.), Wood Works

Web Development

React, CSS, Tailwind CSS, HTML, JavaScript

Media

Graphics Designing; Animation; Video, Photo, and Voice Editing

Soft Skills

Quick Learning Ability, self-management, adaptability, responsibility, time- management, teamwork, leadership

Other

Blog writing, Thoughts illustration, MS Office

Leadership/ Volunteer Experience	 Head Design Team at PIEAS Literary Society Head Videography at NGO Muaawin Co-director Videography PIEAS Media Club Inquiry Team Member at NGO Muaawin-e-rozgaar Head videography at IEEE's ISYWSC event Head videography PIEAS National Olympiad Organizing member at International Workshop on 2D and Quantum Effect Devices 				Jan 2021 – May 2021 Jan 2021 – Jun 2021 Nov 2020 – Apr 2021 Dec 2020 – July 2021 Nov 2021 – Dec 2021 Dec 2021 – Jan 2022 Nov 2018 – Nov 2018
Awards	 Graduation with 2nd distinction 2nd position in maze-solver robotics competition 2nd position in line-follower robotics competition PKR 15,000 for 2nd position in 2nd semester 				
Languages	• Urdu	• English	• Pushto	• Punjabi	• Hindi
References	• Dr. Naeem Iqba Dean Research, naeem@pieas.e	PIEAS	• Dr. Muhammad Abid Professor PIEAS mabid@pieas.edu.pk	 Dr. Haroon-ur-Rashid Director Academics, PIEAS haroon@pieas.edu.pk 	



MUHAMMAD ALI

• Sample research project:

Education

• Pakistan Institute of Engineering and Applied Sciences (PIEAS)

BS Electronics Engineering

• Sep 2018 - June 2022

CGPA: 3.72 / 4.00

Distinction with 2nd position

• Fazaia Degree College, MRF, Kamra

School: Matriculation

April 2013 – March 2015

■ Percentage: 95 %

Distinction with 1st position

• Fazaia Degree College, Risalpur

College: FSC Pre-engineering

■ June 2015 - May 2017

• Percentage: 83%

Distinction with 4th position

Research Experience

• Implementation of deep learning control for Quadcopter

Made digital twin of Quadcopter in gazebo environment (in Ubuntu OS)

• Trained the model through PPO, a reinforcement learning algorithm

Replaced the PID algo of traditional betaflight with our trained model

Compiled the modified betaflight to create a hex file

 Assembled the Quadcopter (using STM32F722 MCU-based Mateksys FC F722-STD, ESC, Brushless motors, PDM, Radio transceiver etc)

Flashed the hex file to quadcopter using betaflight configurator

Video: https://youtu.be/aDtnSoSor4E

Work Experience

Cloud Core Network Engineer at <u>Huawei</u>, OEC tower, Isb

■ Date: 22-08-2022 --- Present

• Group Leader: 03-10-2022 --- Present

Robotics Engineer at <u>National Institute of Electronics</u>, Sector H-9, Isb

■ Date: 02-08-2021 --- 24-09-2021

Made two-wheel self-balancing robot

Video: https://youtu.be/XZjVsQ4YW9w

• Certificate: https://bit.ly/3IcEiBP

• Vice-president <u>IEEE</u> Robotics PIEAS Student Branch

■ Date: 20-Sep-2021 --- 16-May-2022

• Responsibilities: Organizing seminars and workshops on Robotics

• Certificate: https://bit.ly/3i150ms

Huawei's Projects

• 5G Core Deployment (AMF) Cloud Edge (MME)

Network function virtualization (FusionSphere OpenStack)

Awards

• Graduation with 2nd distinction

• 2nd position in maze-solver robotics competition

• 2nd position in line-follower robotics competition

PKR 15,000 for 2nd position in 2nd semester



Contact

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November 30th, 1998

(ii) linkedin.com/in/m--ali

Documents: bit.ly/3v62ngc

https://bit.ly/3t5Pb4a

Marghuz, Swabi, KPK, Pakistan

Leadership/Volunteer Experience

Head Design Team at PIEAS Literary Society

Date: 18-01-2021 ---- 26-05-2021 Certificate: https://bit.ly/3i1ArwW

Head Videography at NGO Muaawin

Date: 28-01-2021 ---- 29-06-2021 Certificate: https://bit.ly/36gOE6r

Co-head Videography PIEAS Media Club

Date: 24-11-2020 ---- 13-04-2021 Certificate: https://bit.ly/3J92gPX

Inquiry Team Member at NGO Muaawin-e-Rozgaar

Date: 21-12-2020 ---- 26-07-2021 Certificate: https://bit.ly/3leALmU

Head videography at IEEE's ISYWSC event

Date: 24-11-2021 ---- 15-12-2021 Certificate: https://bit.ly/3bTD2cR

Head videography PIEAS National Olympiad

Date: 12-12-2021 ---- 03-01-2022 Certificate: https://bit.ly/3w3fUjR

 Organizing member at International Workshop on 2D and Quantum Effect Devices

Date: 12-11-2018 ---- 14-11-2018 Certificate: https://bit.ly/37sk0b1

Languages

1- Urdu

2- English

3- Pushto

4- Hindi

5- Punjabi

Technical Projects

Maze Solver Robot

Date: 19-11-2019 ---- 20-12-2019 Video: https://youtu.be/NtWT8aEdATg

• Line follower robot

Date: 19-11-2019 ---- 20-12-2019 Certificate: https://bit.ly/350vHZg

Controlling Servo from Web browser wirelessly using ESP32

Date: 17-03-2021 ---- 18-03-2021 Video: https://bit.ly/3AkcgDW

Controlling Servo using Potentiometer and ESP32

Date: 17-03-2021 ---- 18-03-2021 Video: https://bit.ly/3bRPzNX

• 15,000 mAh Laptop Power Bank

Date: 19-07-2022 ---- 28-07-2022 Video: https://youtu.be/zX1eYh3Lx2A

Android P2P messaging App

Date: 07-12-2020 ---- 14-01-2021 Video: https://youtu.be/wOFHmuyRXFY Report: https://bit.ly/3KHV5yi

• Trained Reinforcement Learning agent for

 Trained Reinforcement Learning agent to autonomous driving

Date: 15-05-2022 ---- 17-05-2022

Code: https://bit.ly/38nxtln

Reinforcement Learning for Atari Breakout Game

Date: 17-05-2022 ---- 18-05-2022 Code: https://bit.ly/3wgR8Zz

• Trained Neural Network for Image prediction

Date: 28-04-2022 ---- 30-04-2022 Video: https://bit.ly/3lek8P8

Training CartPole to balance itself

Date: 11-05-2022 ---- 14-05-2022 Code: https://bit.ly/3sAKyyG

• Tic-tac-toe game using a C++ programming language

Date: 06-12-2018 ---- 16-12-2018
Report: https://bit.ly/3i1Hw0m

Designed and implemented a stepper motor controller

Date: 13-12-2019 ---- 14-01-2021 Report: https://bit.ly/3hZQoUu

Designed a 1kVA UPS powered by a single-phase 220V/50Hz AC

Date: 18-06-2021 ---- 27-06-2021
Report: https://bit.ly/3MNBlv0

Designed 8-bit SAR ADC

Date: 31-12-2020 ---- 30-12-2019
Report: https://bit.ly/36cbv3a

 35% Duty Cycle Rectangular Waveform using Astable Multivibrator (555 Timer)

Date: 23-12-2019 ---- 30-12-2019
Report: https://bit.ly/3tglw8N

 Detection of cracks in Ceramic Tiles using Digital Image Processing

Date: 30-12-2021 ---- 06-01-2022

Report: https://bit.ly/3tSHDRx

 Designed a filter (i) that removes cross-over distortion from class B push-pull amplifier (ii) that minimizes noise coming from a tape recorder (iii) for a car alternator.

Date: 02-01-2020 ---- 09-01-2020 Report: https://bit.ly/3KCyHXh

Skills

• Programming Languages: C++, Python, C, and Java

 IDEs: MATLAB/Simulink, Arduino IDE, Xilinx ISE, Keil, LTspice, MobotSim, ModelSim, Visual Studio, Android Studio, Gazebo simulator, GymFC, Autodesk Inventor, Creo Parametric, Virtual box (Linux/Ubuntu),

• Electronics Boards: ESP32 MCU, Spartan 3 SoC FPGA, Arduino Due, and Arduino Mega, Uno, Nano

• Sensors/ Actuators etc: 6-axis IMU; quadrature encoder; GPS, ultrasonic, IR, barometer, temperature sensors; 3S 12V 25A BMS; Radio transceiver; servo, stepper, DC, brushless motors

• Practical Work: PCB Designing, Veroboard usage/Soldering

• Web Development: React, CSS, Tailwind CSS, HTML, JavaScript

• Media: Graphics Designing; Animation; Video, Photo, and Voice Editing

• **Soft Skills:** Quick Learning Ability, self-management, adaptability, responsibility, time- management, teamwork, leadership

• Other: Blog writing, Thoughts illustration, MS Office

Online Courses

• TensorFlow 2.0 Complete Course - Python

Neural Networks freecodecamp.org

Python full Course for Beginners

freecodecamp.org

• C++ full Course for Beginners

freecodecamp.org

• 9 Axis Inertial Measurement Units with Arduino

Paul McWhorter

• PID Control systems with Arduino

Paul McWhorter

Reinforcement Learning Using Python

Edureka

Java Programming

Great Learning Academy

• Android Development Tutorial

CodeWithHarry

Gazebo Simulator Course

Robotogeddon

Neural networks

3Blue1Brown

References

• Dr Naeem Iqbal

Dean Research / Professor, PIEAS E-mail: naeem@pieas.edu.pk

• Dr. Haroon-ur-Rashid

Director Academics / Professor, PIEAS E-mail: haroon@pieas.edu.pk

• Dr Muhammad Abid

Professor, PIEAS

Email: mabid@pieas.edu.pk