

mechanics chapter 4

Ali Abdallah

June 2022

1 Chapter 4 : Work Power Energy

Differential :

$$du = \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial y} dy + \frac{\partial u}{\partial z} dz$$

Gradients :

In Cartesian Coordinates :

$$\vec{grad} = \vec{\nabla} = \frac{\partial}{\partial x} \vec{i} + \frac{\partial}{\partial y} \vec{j} + \frac{\partial}{\partial z} \vec{k}$$

In Cylindrical Coordinates :

$$\vec{grad} = \vec{\nabla} = \frac{\partial}{\partial \rho} \vec{\rho} + \frac{1}{\rho} \frac{\partial}{\partial \phi} \vec{\phi} + \frac{\partial}{\partial z} \vec{k}$$

In Spherical Coordinates :

$$\vec{grad} = \vec{\nabla} = \frac{\partial}{\partial r} \vec{r} + \frac{1}{r} \frac{\partial}{\partial \theta} \vec{\theta} + \frac{1}{r \sin(\theta)} \frac{\partial}{\partial \phi} \vec{\phi}$$

Divergence of a vector :

In Cartesian Coordinates :

$$\text{div } \vec{u} = \vec{\nabla} \cdot \vec{u} = \frac{\partial}{\partial x} u_x + \frac{\partial}{\partial y} u_y + \frac{\partial}{\partial z} u_z$$

In Cylindrical Coordinates :

$$\text{div } \vec{u} = \frac{\partial}{\partial \rho} u_\rho + \frac{1}{\rho} \frac{\partial}{\partial \phi} u_\phi + \frac{\partial}{\partial z} u_z$$

In Spherical Coordinates :

$$\text{div } \vec{u} = \frac{\partial}{\partial r} u_r + \frac{1}{r} \frac{\partial}{\partial \theta} u_\theta + \frac{1}{r \sin(\theta)} \frac{\partial}{\partial \phi} u_\phi$$

Rotation of a Vector :

$$\vec{Rot} \vec{A} = \vec{\nabla} \wedge \vec{A} = \frac{1}{h_1 h_2 h_3} \begin{vmatrix} h_1 \vec{e}_1 & h_2 \vec{e}_2 & h_3 \vec{e}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ h_1 A_1 & h_2 A_2 & h_3 A_3 \end{vmatrix}$$

In Cartesian Coordinates :

$$h_1 = h_2 = h_3 = 1$$

$$\vec{e}_1 = \vec{e}_x \quad \vec{e}_2 = \vec{e}_y \quad \vec{e}_3 = \vec{e}_z$$

In Cylindrical Coordinates :

$$h_1 = 1 \quad h_2 = \rho \quad h_3 = 1$$

$$\vec{e}_1 = \vec{e}_\rho \quad \vec{e}_2 = \vec{e}_\phi \quad \vec{e}_3 = \vec{e}_z$$

In Spherical Coordinates :

$$h_1 = 1 \quad h_2 = r \quad h_3 = r \sin(\theta)$$

$$\vec{e}_1 = \vec{e}_r \quad \vec{e}_2 = \vec{e}_\theta \quad \vec{e}_3 = \vec{e}_\phi$$

Circulation of a Vector Field :

$$dC = \vec{u} d\vec{M}$$

(Where dC is elementary element of circulation)

$$C = \int_c \vec{u} d\vec{M}$$

In Cartesian Coordinates :

$$C = \int_{(c)} u_x dx + u_y dy + u_z dz$$

In Cylindrical Coordinates :

$$C = \int_{(c)} u_\rho d\rho + \rho u_\phi d\phi + u_z dz$$

In Spherical Coordinates :

$$C = \int_{(c)} u_r dr + r u_\theta d\theta + r \sin(\theta) u_\phi d\phi$$

Circulation of a Conservative Field :

\vec{A} is said to be conservative if it is path independent

$$\int_{(c)} \vec{A} d\vec{M}$$

has same value for any path taken

$$\Rightarrow \vec{A} = -g \vec{\text{grad}} u$$

$$C = \int_{(c)} \vec{A} d\vec{M} = \int_{(c)} -g \vec{\text{grad}} u d\vec{M} = - \int_p^q du = u_p - u_q$$

Conclusion : $\vec{A} = -g \vec{\text{grad}} u \iff \vec{A}$ is Conservative

Characteristics of a Conservative Field \vec{A}

$$\vec{\text{Rot}} \vec{A} = \vec{0} \iff \vec{A} \text{ is Conservative} \iff \vec{A} = -g \vec{\text{grad}} u$$

The Circulation of a conservative field along closed curve is zero

$$\text{If } \vec{A} = A(q) \vec{e}_q \Rightarrow \vec{\text{Rot}} \vec{A} = \vec{0} \text{ and } A \text{ is Conservative}$$

Work :

$$W = C = \int_{(c)} \vec{F} d\vec{M}$$

$$\vec{F} = \vec{F}_\tau + \vec{F}_n$$

$$W = \int \vec{F}_\tau d\vec{M} + \int \vec{F}_n d\vec{M}$$

Remark :

For a Conservative Vector Field \vec{A} :

$$\vec{A} = -g \vec{\text{grad}} u$$

For a Conservative Field of Force \vec{F} :

$$\vec{F} = -g \vec{\text{grad}} EP$$

Power :

$$dw = \vec{F} d\vec{M} = \vec{F} \frac{d\vec{M}}{dt} dt = \vec{F} \vec{V} dt$$

$$p = \frac{dw}{dt} = \vec{F} \vec{V}$$

Theorem of Kinetic Energy :

$$\vec{F} = \frac{d\vec{P}}{dt} = m \frac{d\vec{V}}{dt}$$

$$dw = \vec{F} d\vec{M} = \vec{F} \frac{dM}{dt} dt = \vec{F} \vec{V} dt = m \frac{d\vec{V}}{dt} \vec{V} dt = m \vec{V} d\vec{V}$$

$$W = \int_A^B dw = \int_{V_i}^{V_f} m \vec{V} d\vec{V} = \frac{1}{2} m V^2 \Big|_{V_i}^{V_f}$$

$$\Rightarrow w = \Delta KE = \frac{1}{2} m (V_f^2 - V_i^2)$$