

New board modifications

Actuators part :

Add 2 stepper motor (total 6 stepper)

Remove 1 servo (total 2 servo)

Locks part:

Add 2 lock (total 3 locks)

Power supply part:

Make input 24v 30A

Add step down to 5V 3A

Add step down to 12V

Isolation of sensors part:

Modify the opto coupler to handle some issues

Screen part

Add another header to second screen with same pins

Weight system part:

Replace the holder of module with header and make the module external

Leds part:

Add header 3 pins