

EP3260: Machine Learning Over Networks

Homework Assignment 2

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Problem 2.1

Consider Human Activity Recognition Using Smartphones dataset $\{(\mathbf{x}_i, y_i)\}_{i \in [N]}$, with inputs defined as the accelerometer and gyroscope sensors, and outputs defined as moving (e.g., walking, running, dancing) or not (sitting or standing). Consider the logistic ridge regression loss function

minimize
$$f(\mathbf{w}) = \frac{1}{N} \sum_{i \in [N]} f_i(\mathbf{w}) + \lambda ||\mathbf{w}||_2^2,$$

where $f_i(\mathbf{w}) = \log (1 + \exp\{-y_i \mathbf{w}^T \mathbf{x}_i\}).$

Then, address the following questions:

- (a) Is f Lipschitz continuous? If so, find a small B?
- (b) Is f_i smooth? If so, find a small L for f_i ? What about f?
- (c) Is f strongly convex? If so, find a high μ ?

Problem 2.2

Let us assume that there exist scalars $c_0 \ge c > 0$ such that for all $k \in \mathbb{N}$

$$\nabla f(\mathbf{w}_k)^T \mathbb{E}_{\zeta_k} \left[g(\mathbf{w}_k; \zeta_k) \right] \ge c \|\nabla f(\mathbf{w}_k)\|_2^2, \tag{1a}$$

$$\|\mathbb{E}_{\zeta_k} \left[g(\mathbf{w}_k; \zeta_k) \right] \|_2 \le c_0 \|\nabla f(\mathbf{w}_k)\|_2. \tag{1b}$$

Furthermore, let us assume that there exist scalars $M \geq 0$ and $M_V \geq 0$ such that for all $k \in \mathbb{N}$

$$\operatorname{Var}_{\zeta_k}\left[g(\mathbf{w}_k;\zeta_k)\right] \le M + M_V \|\nabla f(\mathbf{w}_k)\|_2^2. \tag{2}$$

For the convergence proof of SGD with an L-smooth convex objective function (see slides), prove that

$$\mathbb{E}_{\zeta_k} \left[\|g(\mathbf{w}_k; \zeta_k)\|_2^2 \right] \le \alpha + \beta \|\nabla f(\mathbf{w}_k)\|_2^2.$$

Problem 2.3

For the SGD with non-convex objective function, prove that with square summable but not summable step-size, we have for any $K \in \mathbb{N}$

$$\mathbb{E}\left[\sum_{k\in[K]}\alpha_k\|\nabla f(\mathbf{w}_k)\|_2^2\right] < \infty \tag{3}$$

and therefore

$$\mathbb{E}\left[\frac{1}{\sum_{k \in [K]} a_k} \sum_{k \in [K]} \alpha_k \|\nabla f(\mathbf{w}_k)\|_2^2\right] \xrightarrow{K \to \infty} 0 \tag{4}$$