MATLAB Cheat Sheet

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note: MATLAB® code is sensitive to casing, and insensitive to blank spaces except when defining arrays.

```
# Clear screen
clc
                              # Clear x variable
clear x
                              # Clear all variables
clear
help elfun
                              # Show elementary functions
sin(), cos(), tan(), cot()
exp(), abs()
factorial()
A = [12345]
                              # Create a row matrix
B = [10; 20; 30]
                              # Create a column matrix
X = [15800; 96207; 24501]
N = [935; 724; 142]
A(end)
                              # Shows last element of matrix (array)
A(:)
                              # Shows all elements in a column
A(9) = 1
                              # Change 9th element in A(:)
                              # Range with specified distance
N = 2:7
K = 10:7:70
A(1:2:end)
                              # Shows odd elements
A(2:2:end)
                              # Shows even elements
a = 5, b = 7
                              # Matrix multiply (for array multiply use .*)
a * b
a / b, a \ b
                              # Matrix divide (for array divide use./or.\)
a + b, a - b
```

 $a \wedge b$

```
sum(1:10)
prod(1:10)
M = [123; 456; 789]
M(2,:)
                              # Get second column
M(:,2)
                              # Get second row
M(2,3)
                              # Get element in 2th row and in 3th column
M(1,:) = []
                              # Delete first column
M(:,3) = []
                              # Delete third row
M(:,[2,5]) = []
                              # Delete a few rows
A = [123]
B = [456]
C = [A B]
                              # Row concatenation of two matrices
D = [A; B]
                              # Column concatenation of two matrices
length(X)
                              # Length of vector (it is equivalent to MAX(SIZE(X)))
                              # Number of rows in an array (is equivalent to SIZE(X, 1))
height(X)
size(X)
                              # Size of array
ndims(X)
                              # Number of dimensions
nnz(X)
                              # Number of non zeros elements
numel(X)
                              # Number of elements
sum(sum(x))
                              # Sum of all elements
Χ'
                              # Transform a matrix
sort(X)
sort(X,1), sort(X,2)
                              # Sort for columns or rows
sort(X, 'descend'), sort(X, 'ascend')
sortrows(A,2)
                              # Sort second row of a matrix
min(X), max(X)
mean(X)
                              # Shows Mean of each column as one row
max(max(X))
                              # Max of elements
tril(X)
                              # Lower triangular matrix
triu(X)
                              # Upper triangular matrix
diag(X)
                              # Main diameter
sum(diag(X))
                              # Sum of the main diameter reservoirs
fliplr(X)
                              # Flip array in left/right direction
flipud(X)
                              # Flip array in up/down direction
```

```
rot90(X)
                               # Rotate array 90 degrees
rot90(X,K)
                               # Rotate array K*90 degrees
ones(m,n)
zeros(m,n)
eye(m,n)
det(B)
                              # Determinant of a square matrix
inv(B)
                              # Inverse of a square matrix
X = inv(A) * B
                               \# AX = B \longrightarrow X = A \wedge -1 * B
magic(n)
pascal(n)
eig(N)
                              # Eigenvalues and eigenvectors
<, >, <=, >=
                        # Less than, Greater than, Less than or equal, Greater than or equal
                              # Equal, Not equal
==, ~=
                              # Logical or, Logical and
&, |
r = X>0
X(r)
                              # Shows elements greater than 0 in X
r = X > 5 & X < 20
X(r)
rem(-13,2)
                               # Remainder after division
mod(-13,2)
                               # Modulus after division
r = rem(X,2) \sim 0
                               # Find elements by condition
r = rem(X,2) == 0 \& X > 5
r = rem(X,2) \sim = 0 \mid X > 8
X(r) = X(r) + 100
                               # Change the specified elements
find(X>0)
                               # Index of the elements that apply to the condition
all(X>0)
                               # columns whose all elements are valid in the condition
any(X>0)
                               # columns where at least one element applies to the condition
rand(m,n)
                              # Uniformly distributed pseudorandom numbers
randn(m,n)
                              # Normally distributed pseudorandom numbers
r = a + (b-a) .* rand();
                               # Random number in range (a,b)
randi(100, 1, 5)
                               # Random integer in 1:100
linspace(1,5,100)
                               # Linearly spaced vector
```

```
M = 0:0.25:1
                               # Both included
repmat(X, 2, 5)
                               # Replicate and tile an array
reshape(1:20,4,5)
                               # Reshape array by rearranging existing elements
T = 0:.01:2*pi
plot(T, Sin(T))
plot(x, y, 'color style marker')
                               # Grid lines
grid on
grid off
                               # Control axis scaling and appearance
axis on
axis off
axis([XMIN XMAX YMIN YMAX])
figure
                               # Create figure window
                               # Hold current graph for next plot
hold on
hold off
subplot(m, n, k)
                        # Create axes in tiled positions (m rows, n columns, k=current window)
clf
                               # Clears Figure
                               # close all figures
close
xlabel("text")
ylabel("text")
zlabel("text")
title("text")
text(x, y, "text")
                               # Add text descriptions to data points
gtext("text")
                               # Place text with mouse
legend('Label 1', 'Label 2')
                               # Create legend
gtext('\int_0^5 x.^2 dx')
                               # Mathematical symbols
\sum_{n=0}^{\sin y}
\infty
x^{y+1}
```

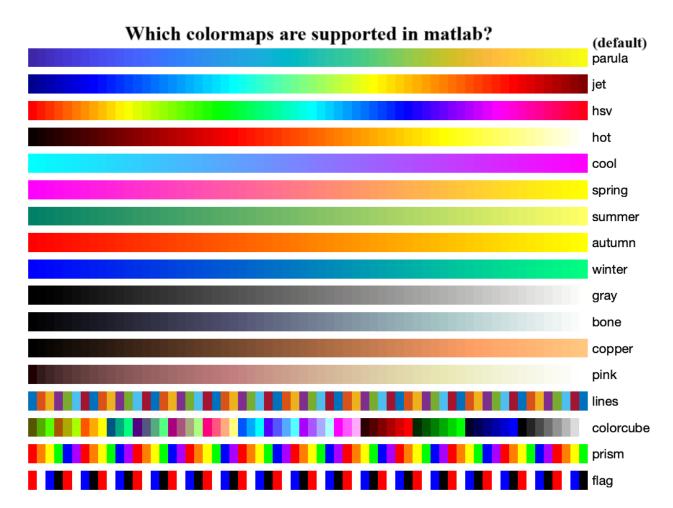
\sin

Character Sequence	Symbol	Character Sequence	Symbol	Character Sequence	Symbol
\alpha	α	\upsilon	U	\sim	~
\angle	4	\phi	ф	\leq	≤
\ast	*	\chi	х	\infty	00
\beta	β	\psi	Ψ	\clubsuit	•
\gamma	γ	\omega	ω	\diamondsuit	•
\delta	δ	\Gamma	Г	\heartsuit	•
\epsilon	ε	\Delta	Δ	\spadesuit	•
\zeta	ζ	\Theta	Θ	\leftrightarrow	↔
\eta	η	\Lambda	٨	\leftarrow	-
\theta	8	\Xi	≡	\Leftarrow	=
\vartheta	э	\Pi	п	\uparrow	1
\iota	1	\Sigma	Σ	\rightarrow	→
\kappa	К	\Upsilon	Υ	\Rightarrow	⇒
\lambda	λ	\Phi	Φ	\downarrow	1
\mu	и	\Psi	Ψ	\circ	•
\nu	v	\Omega	Ω	\pm	±
\xi	ξ	\forall	¥	\geq	2
\pi	π	\exists	3	\propto	œ
\rho	ρ	\ni	9	\partial	a
\sigma	σ	\cong	≅	\bullet	
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```
Line(x, y, z)
                               # Create line
rectangle('position',[1256], 'curvature',1) # Create rectangle, rounded-rectangle, or ellipse
triplot(TRI, x, y)
                               # Plots a 2D triangulation
r = rectangle('position', [0 0 11]) # Create and customize a rectangle
r.FaceColor = [0.5.5];
r.EdgeColor = 'b';
r.LineWidth = 3;
x = [123]; y = [232]; TRI = [123];
triplot(TRI, x, y)
axis([0 5 0 5])
plot3(x, y, z, 'color style marker')
                               # Adds a box to the current axes
box on
box off
                               # Removes the box from the current axes
comet3(x, y, z)
                               # 3-D comet-like trajectories
[X, Y] = meshgrid(x, y)
                               # Cartesian rectangular grid in 2-D or 3-D
surf(X, Y, Z)
                               #3-D colored surface
mesh(X, Y, Z)
                               #3-D mesh surface
```

Sets the Colormap property of a figure

colormap(hot)



colormap('default') colormap([111])

RGB (between 0 and 1)

shading flat shading interp shading faceted # Sets the shading of the current graph to flat

Sets the shading to interpolated

Sets the shading to faceted, which is the default

sphere(N)

Graph the sphere as a SURFACE and do not return anything

[X,Y,Z] = sphere(N)

Generates three (N+1)by(N+1) matrices

surf(X,Y,Z)

Produces a unit sphere

axis equal axis square # equal tick mark increments on the x-,y- and z-axis are equal in size

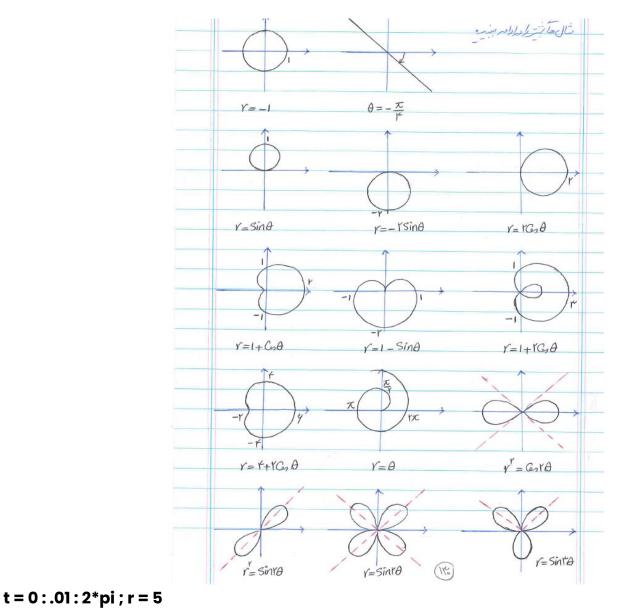
makes the current axis box square in size

cylinder(R,N) # forms the unit cylinder based on the generator curve in the vector R. The cylinder has N points around the circumference.

[X,Y,Z] = cylinder(R)

Default to N = 20, you can graph it with MESH or SURF

polar(THETA, RHO) # makes a plot using polar coordinates of the angle THETA, in radians, versus the radius RHO.



```
x = R * cos(t)
y = R * sin(t)
plot(x, y)
                              # Draws a circle with radius R
polar(t, R + zeros(size(t))
                              # Draws a circle with radius R
pos = [0 0 R R];
rectangle('position', pos, 'curvature', [11]) # Draws a circle with radius R
axis equal
ezplot('sin(x)')
                              # (NOT RECOMMENDED) Easy to use function plotter
ezplot3('\sin(x)', '\cos(x)', 'x', [0, 2.* pi], 'animate')
# (NOT RECOMMENDED) Easy to use 3-d parametric curve plotter
                              # (NOT RECOMMENDED) Easy to use 3-D mesh plotter
ezmesh(tan(x))
ezsurf(tanh(x))
                              # (NOT RECOMMENDED) Easy to use 3-D colored surface plotter
```

Easy to use polar coordinate plotter

ezpolar('1+cos(t)')

```
fill(x, y, color)
                              # Filled 2-D polygons
x = 0:.01:2*pi;
y = \sin(x)
t = x(end:-1:1)
                              # The same as t = fliplr(x)
u = cos(t)
a = [x t]; b = [y u]
fill(a, b, 'g')
                              # Coloring the area between sine and cosine
p=[30-5]
                              # p(x)=3x^2-5
x = roots(p)
                              # Find polynomial roots
poly(x)
                              # Convert roots to polynomial
conv(A, B)
                              # Convolution and polynomial multiplication
[X, R] = deconv(Y, H)
                              # Least-squares deconvolution and polynomial division
Y = polyval(P, X)
                              # Evaluate polynomial
polyder(P)
                              # Differentiate polynomial
polyint(P)
                              # Integrate polynomial analytically
F = polyfit(X, Y, N)
                              # Fit polynomial to data
hold on
```

plot(X, polyval(F, X), 'b')