

Overview

- 1. Stability
- 2. Laplace Transforms
- 3. QUESTIONS

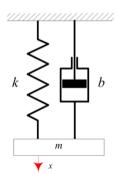
Definition

Stability is a fundamental property of every control system. It also could be generalised to other systems, like chemical, medical or financial. You could study if the solution of the equation you have will diverge or converge.

Mass Spring Damper

Let's find the equation of the following mechanical system!

- 1. What are the equilibrium points for the system?
- 2. Is this system stable?



Mass Spring Damper: Lyapunov Solution

To apply the Lyapunov solution, we simply find a function which have two main properties:

- 1. It is strictly positive unless both state variables are zeros ($x = 0, \dot{x} = 0$).
- 2. The function is monotonically decreasing when the state variables vary according to the initial dynamic equation.

Mass Spring Damper: Lyapunov Solution

To do that easily, find a good Lyapunov function, and check the following:

- 1. $V(x) > 0 : x \neq 0$
- 2. $\dot{V} \leq 0$

Then the system is **Lyapunov** stable, otherwise it is not stable, that mean the solution that start near x_0 stay near x_0 , if all the solutions that start near x_0 end at x_0 then the system is **asymptotically** stable.

Mass Spring Damper: Lambda Solution

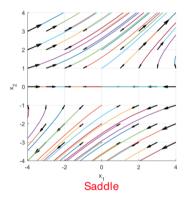
After we solve the equation and find $\lambda = Re + i * Im$ we have three posibilities:

- ightharpoonup Re = 0 Lyapunov stable.
- ► *Re* < 0 **Asymptotically** stable.
- ► Re > 0 Unstable.

Example1:

Study the stability of the following system:

$$\dot{x}_1 = -x_1 + 3x_2
\dot{x}_2 = +2x_2$$
(1)



Example2:

Study the stability of the following system:

$$\ddot{x} + 10\dot{x} + 5x = 0 \tag{2}$$

Definition

If we have the following function f(x) defined in $[0, \infty[$ then the Laplace transform can be defined as:

$$L[f(t)] = \int_0^\infty e^{-st} f(t) dt = F(s)$$
 (3)

Laplace transform properties:

- L[Cf(x)] = CL[f(x)]
- L[f(x) + g(x)] = L[f(x)] + L[g(x)] = F(s) + G(s)

$$L[1] = \frac{1}{S}$$

$$L[c] = \frac{C}{S}$$

$$L[e^{(}ax)] = \frac{1}{s-a}$$

$$L[x^n] = \frac{n!}{s^{n+1}}$$

$$L[sin(ax)] = \frac{a}{s^2+a^2}$$

$$L[cos(ax)] = \frac{s}{s^2+a^2}$$

$$L[sinh(ax)] = \frac{a}{s^2 - a^2}$$

$$L[cosh(ax)] = \frac{s}{s^2 - a^2}$$

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Example:

$$f(x) = 4e^{5x} + 6x^3 - 3\sin(4x) + \cos(2x)$$
 (4)

Example:

$$f(x) = \sin^2(x) \tag{5}$$

Example:

$$f(x) = e^{-2x} \sinh(5x) \tag{6}$$

Example:

$$f(x) = e^{5x}x^2 \tag{7}$$

Example:

$$f(x) = \cos(2x)\cos(3x) \tag{8}$$

QUESTIONS