

# Texture Representation and Analysis

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# Overview

What's a texture

Examples of textured images

Texture representation

Texture analysis

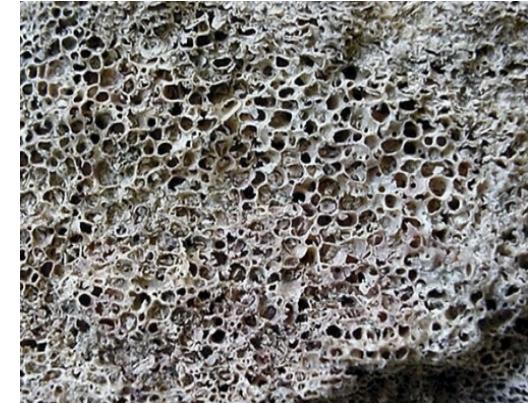
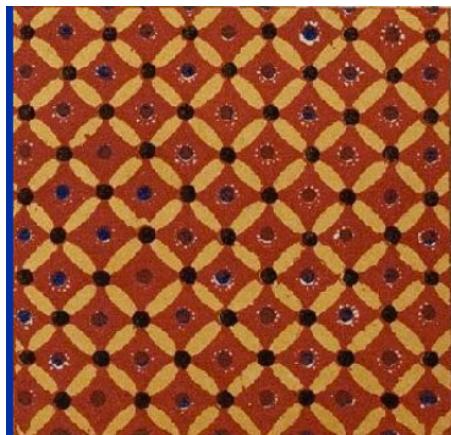
# What's a texture

- Definition not sharp
- Image of stationary statistics
- Pattern repeated in an image
- Whenever I see, too many
- Extreme variability
- How to describe them?

# What's a texture



It could be homogeneous and regular, stochastic, non regular/non homogenous, strong reflectance variation&warping, stochastic scale variation and stoch. scale, shape and reflectance variation



...and more



flower

food

water

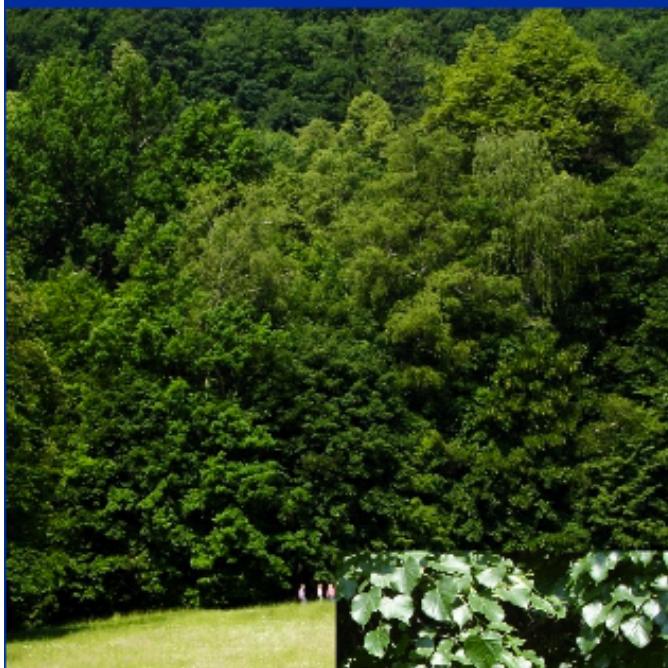


quito

machu

crowd

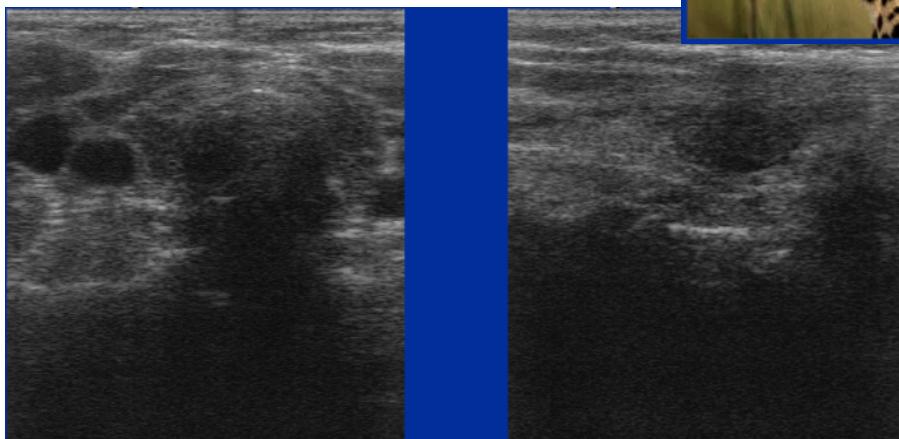
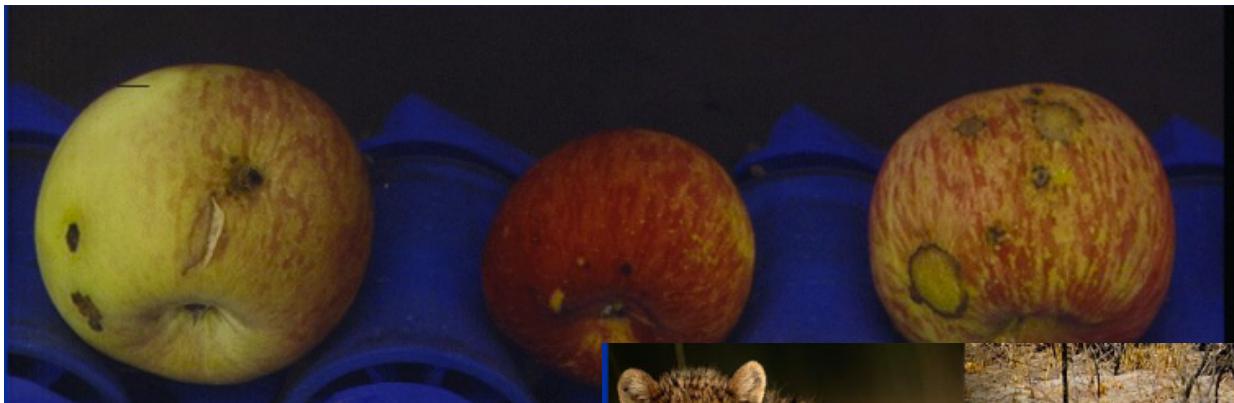
# Texture and structure



# Application

- Assessment quality of :
- Food
- Matérials
- Healtheness

# Application

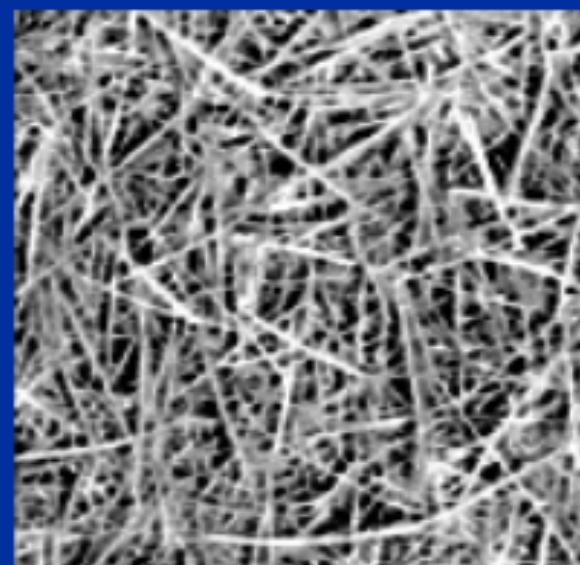
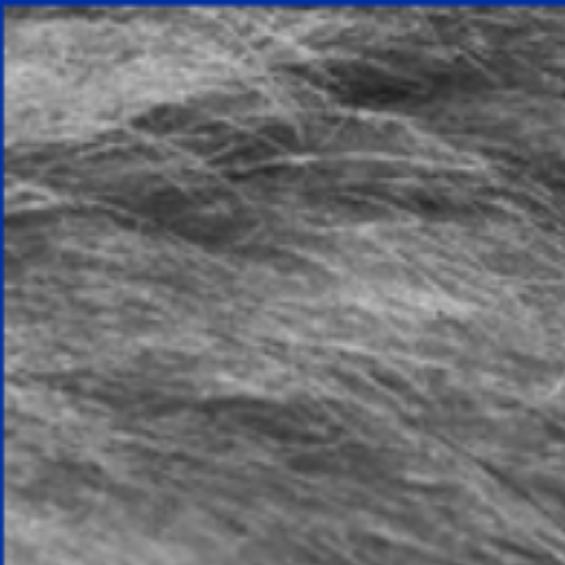


# So a texture is

- ❖ Patterns of structure from
  - changes in surface albedo (eg printed cloth)
  - changes in surface shape (eg bark)
  - many small surface patches (eg leaves on a bush)
- ❖ Hard to define; but texture tells us
  - what a surface is like
  - (sometimes) object identity
  - (sometimes) surface shape

# Description

- **primitives (texels)**
- spatial structure → statistical properties



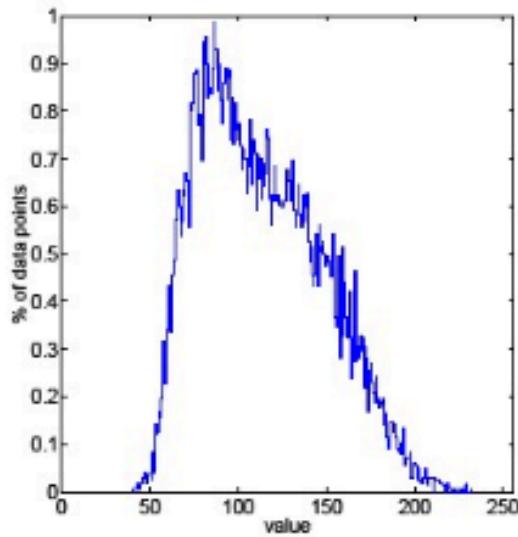
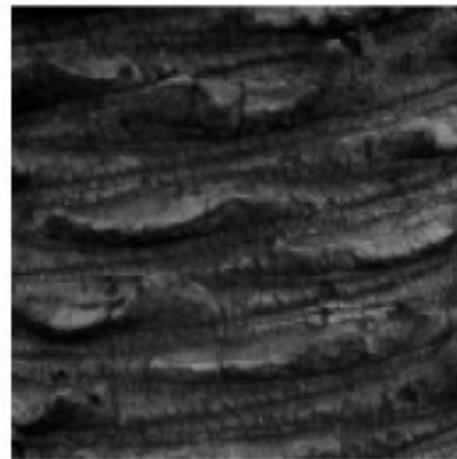
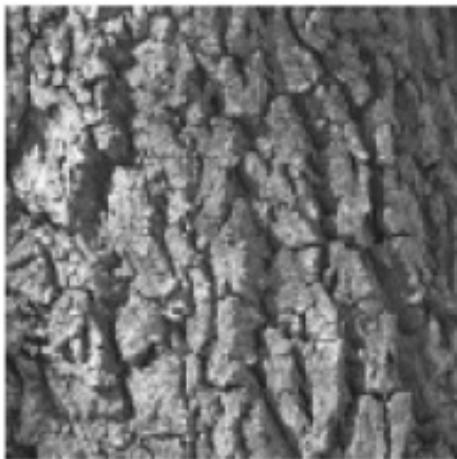
# Texture representation

- Usually depends in regards to the task
- Recognition methods tend to use simple and more robust features. Aim at discriminability (Intra-class vs. Inter-class variability)
- Synthesis methods sometimes sample from the source image itself, thus arguably overfitting

# Texture recognition

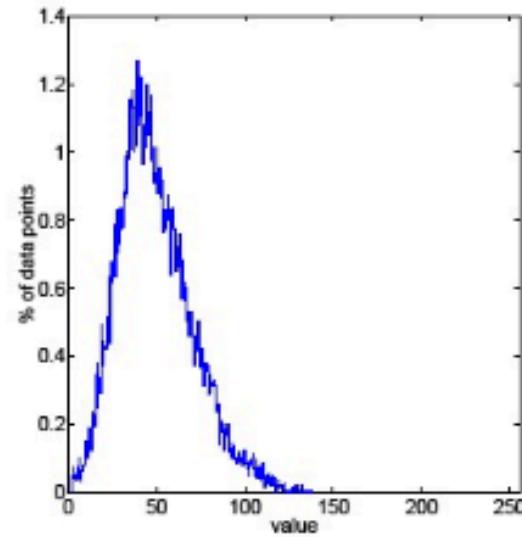
- Marginal statistics of filter responses (Review: Randen & Hussey, PAMI 1999)
- Joint statistics of filter responses (Leung & Malik, ICCV'99)
- Filter, cluster, make histogram, compare using chi-sq (Leung & Malik, Varma & Zisserman, Forsyth 2004, ..)
- Extract affine-covariant regions, SPIN/SIFT, cluster, compare using EMD (Lazebnik, Schmid, Ponce)

# Texture sample



$$E(I) = 113.2$$

$$\text{std}(I) = 46.3$$

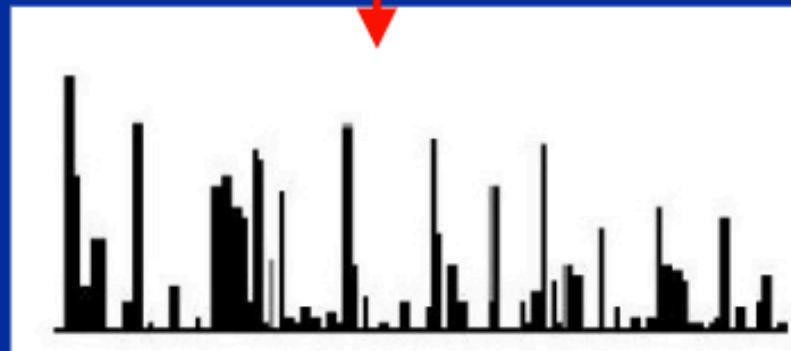
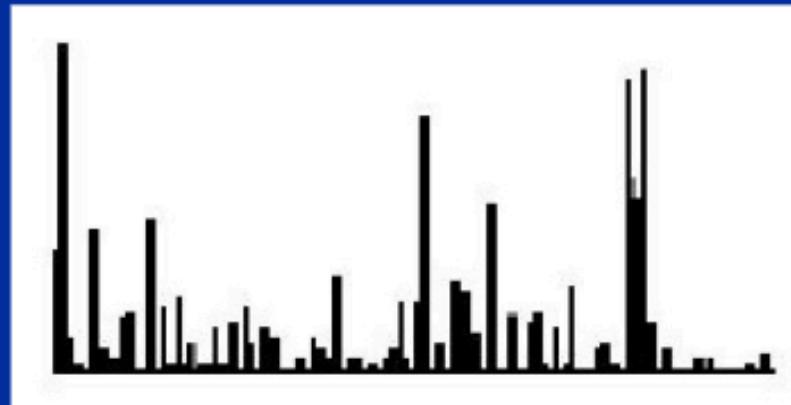


$$E(I) = 49.4$$

$$\text{std}(I) = 25.0$$

# Histogram comparison

$$\chi^2 = \sum_i \frac{(R_i - S_i)^2}{R_i + S_i}$$



# Some fields of application

## Inspection :

Defect detection in images of textiles, automated inspection of carpet wear and automobile paints



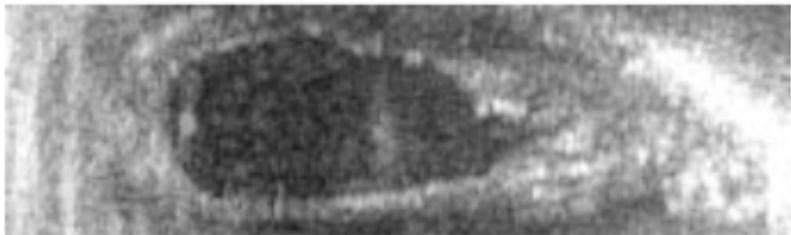
What is wrong in this image

# Some fields of application

## Medical images analysis :

Distinguish normal from abnormal tissues

(a)



Differentiate types of white blood

(b)



Analyse ultrasons images of the heart

(c)



Analyse X-rays images of some lesions

- (a) Utrason image of the left ventricle hart
- (b) Textures fractal representation
- (c) Segmentation (blood in white)

# Some fields of application

## Document processing

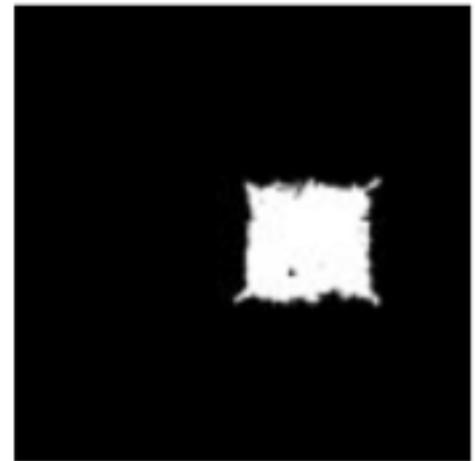
Document analysis



Character recognition

Postal address recognition

Barcode inspection



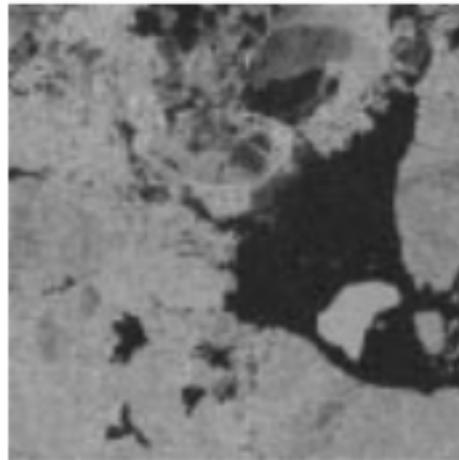
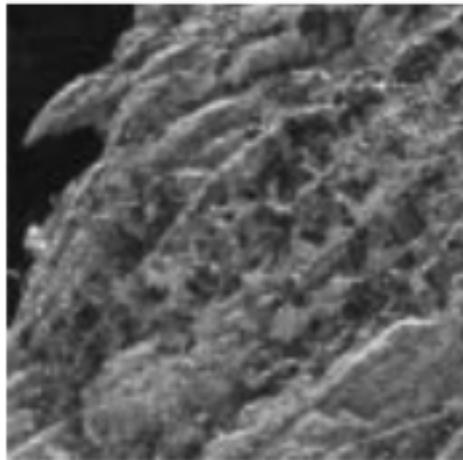
Barcode localization by textures,  
features segmentation

# Some fields of application

## Remote sensing

Classify different types of terrains

Segmentation of SAR images



Aerial SAR images

# Some fields of application

**In sum, there are a number of intuitive properties of texture :**

- Texture is a property of areas; the texture of a point is undefined. So, texture is a contextual property and its definition must involve gray values in a spatial neighborhood. The size of this neighborhood depends upon the texture type, or the size of the primitives defining the texture.
- Texture involves the spatial distribution of gray levels. Thus, two-dimensional histograms or co-occurrence matrices are reasonable texture analysis tools.
- Texture in an image can be perceived at different scales or levels of resolution [10]. For example, consider the texture represented in a brick wall. At a coarse resolution, the texture is perceived as formed by the individual bricks in the wall; the interior details in the brick are lost. At a higher resolution, when only a few bricks are in the field of view, the perceived texture shows the details in the brick.
- A region is perceived to have texture when the number of primitive objects in the region is large. If only a few primitive objects are present, then a group of countable objects is perceived instead of a textured image. In other words, a texture is perceived when significant individual “forms” are not present.

# Textures representation

There are different methods to represent and analyse a texture

- Statistical methods
- Geometrical methods
- Model based methods
- Signal processing methods

# Textures representation

## Statistical methods

### First order statistics :

- histogram, average variance, skewness, Kurtosis, SNR, std...

### Second order statistics :

- Co-occurrence matrix : energy, entropy, contrast, homogeneity, correlation
- Auto-correlation

# Textures representation

## Statistical methods

First order statistics : histogram, average variance, skewness, Kurtosis, SNRstd...

Given

$$P(I) = \frac{\text{number of pixels with gray level } I}{\text{total number of pixels in the region}}$$

We define the first order statistics by :

$$m_1 = E[I^1] = \sum_{I=0}^{N_g-1} I^1 P(I) \quad \text{Is the mean}$$

$$\mu_k = E[(I - E[I])^k] = \sum_{I=0}^{N_g-1} (I - m_1)^k P(I),$$

$$k = 2, 3, 4$$

**K=2** : the variance measuring the deviation of the graylevels from the mean

**K=3**: the skewness measuring the histogram assymetrie arround the mean

**K=4** the Kurtosis measuring the histogram Sharpness

# Textures representation

## First order Statistical methods

$$m_1 = E[I^1] = \sum_{I=0}^{N_g-1} I^1 P(I)$$

$$\mu_k = E[(I - E[I])^k] = \sum_{I=0}^{N_g-1} (I - m_1)^k P(I),$$

$$k = 2, 3, 4$$

$m_1$  is the mean

$\mu_2$  is the variance measuring the deviation of the graylevels from the mean

$\mu_3$  is the skewness measuring the histogram assymetrie arround the mean

$\mu_4$  is the Kurtosis measering the histogram Sharpness

# Textures representation

## Statistical methods : second order statistical methods

**Co-occurrence matrix** : the most used texture feature introduced by Haralick

We use  $\{I(x,y), 0 \leq x \leq N-1, 0 \leq y \leq N-1\}$  to denote an NxN image of G gray levels

$P_d$  is a GxG gray level matrix called a co-occurrence matrix defined as :

$$P_d(i,j) = \left| \left\{ ((r,s), (t,v)) : I(r,s) = i, I(t,v) = j \right\} \right|$$

- (i,j) is the gray levels entry at a distance  $d = (dx, dy)$
- It gives the number of co-occurrence of the pair of gray levels i and j separated by a distance d
- The Co-occurrence matrix may give an idea about the pattern of the texture

# Textures representation

## Statistical methods : second order statistical methods

Co-occurrence matrix : example

$$P_d(i, j) = \left| \left\{ (r, s), (t, v) : I(r, s) = i, I(t, v) = j \right\} \right|$$

- Give a co-occurrence matrix of the following patch at a distance  $d=(1,0)$  and then for  $d=(1,1)$

<b>2</b>	<b>1</b>	<b>0</b>	<b>4</b>
0	2	1	0
0	4	0	4
3	4	0	0

# Textures representation

## Statistical methods :: second order statistical methods

Co-occurrence matrix :

Other strongly useful statistics with  $\mu_x, \mu_y$  the means and  $\sigma_x, \sigma_y$  the std of  $P_d(x)$ ,  $P_d(y)$

Texture Feature	Formula
Energy	$\sum_i \sum_j P_d(i, j)^2$
Entropy	$-\sum_i \sum_j P_d(i, j) \log P_d(i, j)$
Contrast	$\sum_i \sum_j (i - j)^2 P_d(i, j)$
Homogeneity	$\sum_i \sum_j \frac{P_d(i, j)}{1 +  i - j }$
Correlation	$\frac{\sum_i \sum_j (i - \mu_x)(j - \mu_y) P_d(i, j)}{\sigma_x \sigma_y}$

$$P_d(x) = \sum_j P_d(x, j)$$

$$P_d(y) = \sum_i P_d(i, y)$$

# Textures representation

## Statistical methods

Co-occurrence matrix : example

After computing the co-occurrence matrix of the patch at a distance  $d=(1,0)$ , Compute for the same matrix  $P(1,0)$  the second order statistics.

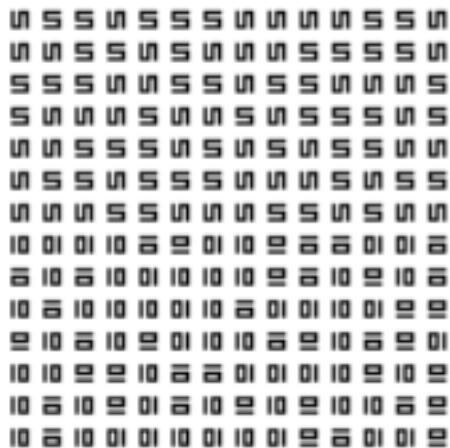
<b>2</b>	<b>1</b>	<b>0</b>	<b>4</b>
0	2	1	0
0	4	0	4
3	4	0	0

# Textures representation

## Statistical methods

Co-occurrence matrix :

- The co-occurrence matrix has some difficulties, there is no well established method for selecting the displacement vector  $d$
- The following two images have the same second statistics order



- Feature selection method is necessary to select the most relevant features (and directions)

# Textures representation

## Statistical methods

Autocorrelation features:

- Used to assess the amount of regularity , the finess or coarsness of the texture.
- The autocorrelation function of an image  $I(x,y)$  is defined as :

$$\rho(x, y) = \frac{\sum_{u=0}^N \sum_{v=0}^N I(u, v)I(u + x, v + y)}{\sum_{u=0}^N \sum_{v=0}^N I^2(u, v)}$$

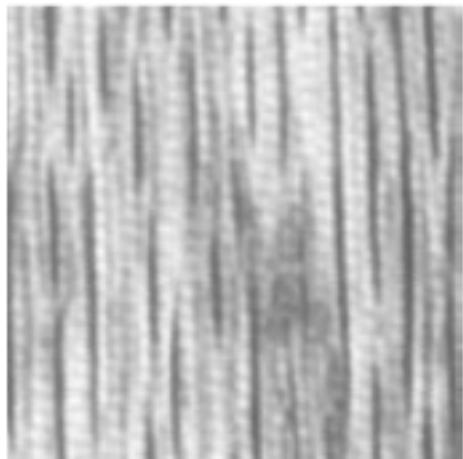
- The autocorreclation function is related to the finess of the texture
- If the texture is coarse, the function will drop of slowly, otherwise, it will dropp of rapidly
- For regular textures, the autocorrelation function exhibits pics and valleys

# Textures representation

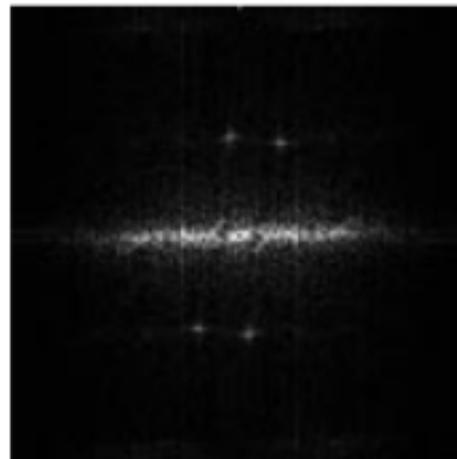
## Statistical methods

Autocorrelation features::

- The autocorrelation function is related to the power spectrum of the Fourier transform (PSF)
- The following image shows the effects of the directionality of the texture on the distribution of energy of the PSF



(a)



(b)

(a) Textured image  
(b) Its PSF

# Textures representation

## Statistical methods

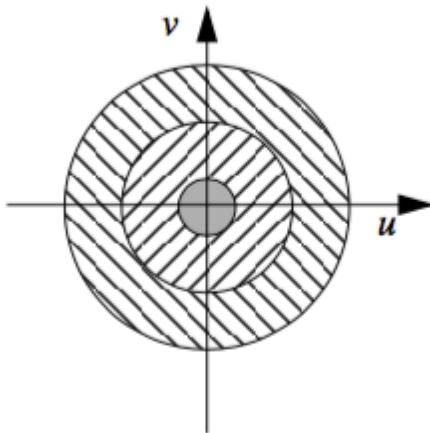
Autocorrelation features:.

- To get the textures feature, the PSF image is devided into regions,
- The following image shows the effects of the directionality of the texture on the distribution of energy of the PSF
- The energy function is deveded into rings (for frequency content) and wedges (for orientation contents)

# Textures representation

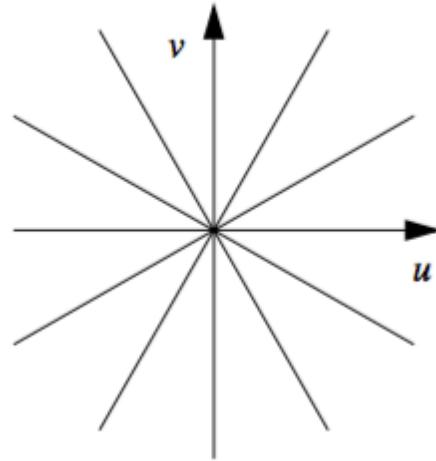
## Statistical methods

Autocorrelation features::



$$f_{r_1, r_2} = \iint_{0, r_2}^{2\pi r_1} |F(u, v)|^2 dr d\theta$$

$$r = \sqrt{u^2 + v^2} \quad \theta = \text{atan}(v/u)$$



$$f_{\theta_1, \theta_2} = \iint_{\theta_1, 0}^{\theta_2, \infty} |F(u, v)|^2 dr d\theta$$

$$r = \sqrt{u^2 + v^2} \quad \theta = \text{atan}(v/u)$$

(a)

(b)

Texture features computed from the PSF image

- a) The energy computed in each shaded bound is a feature indicating coarseness/fitness
- b) The energy computed in each wedge is a feature indicating the directionality

# Textures representation

## ➤ Geometrical methods :

- Veronoi tessellation features
- Structural methods

# Textures representation

## ➤ Model based methods:

- Random field models
- Fractals

# Textures representation

## ➤ Signal processing methods:

- Spatial domain filtering
- Fourier domain filtering
- Gabor and wavelets models

# Textures Analysis problems

- Texture segmentation
- Texture analysis
- Texture synthesis
- Shape from textures

# References

- Texture Analysis, team 5, A. Belgaru et al
- Medical image analysis, Chapter 2.1, M. Tuceyran and A. K. Jain