



MARKING SCHEME

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INSTRUCTOR:

LINEAR ALGEBRA, MIDTERM [Total Marks: 100]

(SPRING 2022)

Question 1: [10 Marks]

Prove that for an invertible matrix A , its inverse is unique. [6 MARKS]

Let B and C be two inverses of A .

$\therefore B$ is an inverse, $BA = I \quad \textcircled{1}$

Multiplying both sides of $\textcircled{1}$ on right by C :

$$(BA)C = IC = C \quad \textcircled{2}$$

$$\text{But } (BA)C = B(AC) = BI = B \quad \textcircled{3} (\because AC = I)$$

From $\textcircled{2}$ and $\textcircled{3}$, $B = C$

Inverse of A is unique

For a matrix C , if we know that $\det(C) > 0$, then show that $(C^{-1})^T = (C^T)^{-1}$. [4 MARKS]

$$(C^{-1})^T C^T = (CC^{-1})^T$$

$$= I^T$$

$$= I$$

$$\therefore (C^{-1})^T = (C^T)^{-1}$$



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Question 2: [10 Marks]

Let Y and Z be $n \times n$ matrices.

- (a) Prove that if $I_n = YZ$ then $Z = Y^{-1}$. [5 MARKS]

$$\begin{aligned} \det(YZ) &= \det(I) = 1 \\ \Rightarrow \det(Y) \det(Z) &= 1 \quad \left. \begin{array}{l} Y^{-1}, Z^{-1} \\ \text{exist} \end{array} \right\} \\ \Rightarrow \det(Y) &\neq 0 \text{ and } \det(Z) \neq 0 \end{aligned}$$

(3)

$$\begin{aligned} Y^{-1}YZ &= Y^{-1}I \\ IZ &= Y^{-1} \quad (2) \\ Z &= Y^{-1} \end{aligned}$$

- (b) Prove that if $I_n = ZY$ then $Z = Y^{-1}$. [5 MARKS]

Since Y^{-1} exists (proved in (a)):

$$I = ZY$$

$$IY^{-1} = ZYY^{-1}$$

$$Y^{-1} = ZI$$

$$Y^{-1} = Z \quad (\text{Proved})$$



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Question 3 [10 MARKS]

If B is an $m \times m$ square matrix, and the homogenous system $B\mathbf{x} = \mathbf{0}$ has only the trivial solution, then show that the reduced row echelon form of B is the identity matrix I_m . [7 MARKS]

Th. 1.5.3 (b) \Rightarrow (c)

Let $B\mathbf{x} = \mathbf{0}$ be $m \times m$ system of eq. with only trivial sol. The sys. corresponding to RREF of the augmented matrix is:

$$\textcircled{1} \rightarrow \begin{array}{l} x_1 = 0 \\ x_2 = 0 \\ \vdots \\ x_m = 0 \end{array} \Rightarrow \left[\begin{array}{cccc|c} a_{11} & a_{12} & \cdots & a_{1m} & 0 \\ a_{21} & a_{22} & \cdots & a_{2m} & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mm} & 0 \end{array} \right] \textcircled{2}$$

\textcircled{1} Can be reduced to the aug.-matrix for \textcircled{1} in form $\begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}$ through EROs

Ignoring the last column of 0's in each of the matrices, we can conclude that RREF of B is identity matrix I_m .

Give two different row Echelon forms for the matrix $\begin{bmatrix} 1 & 3 \\ 2 & 7 \end{bmatrix}$. [3 MARKS]

\textcircled{1} $R_2 \rightarrow R_2 - 2R_1$ $\begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}$

\textcircled{2} $R_1 \rightarrow R_1 - 3R_2$ $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

(other correct answers possible)



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Question 4 [10 MARKS]

Let $A\underline{x} = \underline{b}$ be any consistent system of linear equations and let \underline{x}_1 be a fixed solution. Show that every solution to the system can be written in the form $\underline{x} = \underline{x}_1 + \underline{x}_0$ where \underline{x}_0 is a solution of the homogenous linear system $A\underline{x} = \underline{0}$. Show also that every matrix of this form is a solution.

Let \underline{x}^* be any solution to $A\underline{x} = \underline{b}$. Then:

$A\underline{x}^* = \underline{b}$. We also know that $A\underline{x}_1 = \underline{b}$

$$\therefore A\underline{x}^* - A\underline{x}_1 = \underline{b} - \underline{b} = \underline{0} = A(\underline{x}^* - \underline{x}_1) \quad [4]$$

$\therefore (\underline{x}^* - \underline{x}_1)$ is a solution to the homo.
system $A\underline{x} = \underline{0} \Rightarrow \underline{x}^* = \underline{x}_1 + (\underline{x}^* - \underline{x}_1) \xrightarrow{\text{required form}} \underline{x} \quad [3]$

For a matrix of the form $\underline{x} = \underline{x}_1 + \underline{x}_0$,

$$\Rightarrow A\underline{x} = A\underline{x}_1 + A\underline{x}_0 = \underline{b} + \underline{0} = \underline{b} \quad [3]$$

$\therefore \underline{x}$ is a solution (with form $\underline{x}_1 + \underline{x}_0$)

Question 5 [10 MARKS]

If \underline{u} and \underline{v} are vectors in \mathbb{R}^n then prove that $\|\underline{u} + \underline{v}\| \leq \|\underline{u}\| + \|\underline{v}\|$. [5 MARKS]

$$\begin{aligned}
 \|\underline{u} + \underline{v}\|^2 &= (\underline{u} + \underline{v}) \cdot (\underline{u} + \underline{v}) = \underline{u} \cdot \underline{u} + 2(\underline{u} \cdot \underline{v}) + \underline{v} \cdot \underline{v} \\
 &= \|\underline{u}\|^2 + 2(\underline{u} \cdot \underline{v}) + \|\underline{v}\|^2 \\
 &\leq \|\underline{u}\|^2 + 2|\underline{u} \cdot \underline{v}| + \|\underline{v}\|^2 \quad (\text{absolute value property}) \\
 &\leq \|\underline{u}\|^2 + 2\|\underline{u}\|\|\underline{v}\| + \|\underline{v}\|^2 \quad (\text{CS inequality}) \\
 &= (\|\underline{u}\| + \|\underline{v}\|)^2
 \end{aligned}$$

Take $\sqrt{\quad}$ throughout: $\|\underline{u} + \underline{v}\| \leq \|\underline{u}\| + \|\underline{v}\|$



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If \underline{u} , \underline{v} , and \underline{w} are vectors in \mathbb{R}^n then show that $d(\underline{u}, \underline{v}) \leq d(\underline{u}, \underline{w}) + d(\underline{w}, \underline{v})$. [5 MARKS]

$$\begin{aligned}
 d(\underline{u}, \underline{v}) &= \|\underline{u} - \underline{v}\| \\
 &= \|\underline{u} - \underline{w} + (\underline{w} - \underline{v})\| \\
 &\leq \|\underline{u} - \underline{w}\| + \|\underline{w} - \underline{v}\| \quad (\text{using part a}) \\
 &= d(\underline{u}, \underline{w}) + d(\underline{w}, \underline{v})
 \end{aligned}$$

Question 6 [10 MARKS]

Prove or disprove the following claim: "It is possible for a vector space to contain only two distinct elements." [5 MARKS]

Not possible! Every vector space must contain the $\underline{0}$ vector. For any other non-zero vector, it must contain all its scalar multiples as well. So, FALSE
 Distinct scalar multiples of non-zero vector must be unequal $\Rightarrow k_1 \neq k_2 \Rightarrow k_1 - k_2 \neq 0 \Rightarrow (k_1 - k_2)\underline{v} \neq 0$

[4]

[i] +

Let S be the set of all real numbers in $(0, \infty)$. If S is a vector space under the operations $\underline{u} + \underline{v} = \underline{u} \underline{v}$ AND $k\underline{u} = \underline{u}^k$, then identify the zero element of S and show that it truly is the zero element. [5 MARKS]

$\underline{k}_1 \neq \underline{k}_2 \underline{v}$

$\forall \underline{v} \neq 0$

$$\begin{aligned}
 \underline{0} &= 1 & [2] \\
 \underline{u} + \underline{0} &= \underline{0} + \underline{u} \Rightarrow \text{for any real no. } \underline{u} = \underline{u} \\
 \underline{x} + 1 &= \underline{x}(1) = \underline{x} \\
 \therefore \underline{0} &= 1 \text{ fulfills conditions of zero vector}
 \end{aligned}$$



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Question 7 [10 MARKS]

Prove that for any vectors \underline{a} , \underline{b} , and \underline{c} , the vectors $(\underline{a} - \underline{b})$, $(\underline{b} - \underline{c})$ and $(\underline{c} - \underline{a})$ form a linearly dependent set. [5 MARKS]

For all real k , we have (show this with ANY $k \neq 0$)

$$k(\underline{a} - \underline{b}) + k(\underline{b} - \underline{c}) + k(\underline{c} - \underline{a}) = \underline{0}$$

\therefore the vectors are linearly dependent
(k must be non-zero scalar)

Prove that if $\{\underline{a}, \underline{b}\}$ is a linearly independent set, and $\underline{c} \notin \text{span}\{\underline{a}, \underline{b}\}$, then $\{\underline{a}, \underline{b}, \underline{c}\}$ is also linearly independent. [5 MARKS]

Using +/- theorem, $\{\underline{a}, \underline{b}\} \cup \{\underline{c}\}$ is also linearly independent.

Hence, $\{\underline{a}, \underline{b}, \underline{c}\}$ is also linearly independent

OR

Proof by Contradiction: Use definitional equation of linear independence.

If \underline{c} had non-zero coefficient k ,

then $k_c = k_1\underline{a} + k_2\underline{b}$ and hence,
 $\underline{c} \in \text{span}\{\underline{a}, \underline{b}\} \Rightarrow$ not possible



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Question 8 [10 MARKS]

Given a set S with two or more vectors, prove that if S is linearly independent then no vector in S is expressible as a linear combination of other vectors in S . [5 MARKS]

Let $S = \{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\}$. Assume $\exists \underline{v}_i \in S$ st. it equals a linear combination of the others i.e. \exists scalars k_1, k_2, \dots, k_n s.t. $\underline{v}_i = k_1 \underline{v}_1 + \dots + k_n \underline{v}_n$

Then, $\underline{v}_i + k_1 \underline{v}_1 + \dots + k_n \underline{v}_n = \underline{0}$

This is clearly non-trivial, since the coefficient for $\underline{v}_i = 1 \neq 0 \Rightarrow$ Contradiction
so, such a vector \underline{v}_i doesn't exist.

Given a set S with two or more vectors, prove that if no vector in S is expressible as a linear combination of other vectors in S , then S is linearly independent. [5 MARKS]

Suppose the set $S = \{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_n\}$ is linearly dependent. Then \exists some non-zero k_i s.t. $k_1 \underline{v}_1 + k_2 \underline{v}_2 + \dots + k_i \underline{v}_i + \dots + k_n \underline{v}_n = \underline{0}$.

$\Rightarrow k_i \underline{v}_i = k_1 \underline{v}_1 + \dots + k_n \underline{v}_n$

This gives a contradiction, since now, \underline{v}_i is a linear combination of the others.
So, S must be linearly independent.



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Question 9 [10 MARKS]

Let S be a finite set of vectors in a *finite dimensional* vector space V . Then prove that if $\text{span}(S) = V$ but S is linearly dependent, then S contains a proper subset B (i.e. $B \subset S$) such that B is a basis for V .

Theorem 5.4.6.(a)

\therefore linearly dependent, $\exists v \in S$ that is expressible as a linear combination of other vectors in S . Using +/- theorem, we can remove v from S , giving S' that still spans V . [4]

- o If S' linearly indep, S' is a basis for $V \Rightarrow$ Proof complete
- o If S' linearly dependent, then remove some appropriate vector from S' to produce "that still spans V ". Continue this till you arrive at set of vectors in S that's lin. indep. & spans V .

This subset $B \subseteq S$ is a basis for V .

Question 10 [10 MARKS]

Show that the set of all polynomials in P_n that have a horizontal tangent at $x = 1$ is a subspace of P_n .

Horizontal tangent means derivative is zero. [2]

For closure under vector addition: [4]

$$\frac{d(p_1 + p_2)}{dx}(1) = \frac{dp_1}{dx}(1) + \frac{dp_2}{dx}(1)$$

For closure under scalar multiplication [4]

$$\frac{d(kp)}{dx}(1) = k \frac{dp}{dx}(1)$$