```
Class NL: PATH = { (G,5,t) | Graph G has a

path from 5 to t}
           PATHE NL
                 elogspace on any of its branches
        Nondeterministically guess a path starting
from S, that is atmost n ventices
       -> If the path reaches t, accept
          PATH E L ?
             Gnondeterminism helps guess all the paths.
             all paths are explored
             Lit there can be an exponential master of paths
            PATH E NL
            PATHENL-Howd: A <= p B
               log space veduction.
    2) A; ENL ELA (NL=L)
logspace reduction > to be used to show NL- Hardness
          Twe say f is logspace computable iff
                  u \in A \iff f(u) \in B
          PATH E NL-Hard:
             Prof Idea: Suppose A E NL.
                    A Ex PATH, f is logspace computable
   each nodel snapshof a TM ( ) space required for a node is O(S(h)) in SPACE (S(h)) at some step of each node has: Dall tape contents i.e. each node has O(\log n) length computation and each node has O(\log n) length
                    the graph has O(n) nodes.
                 & if (Gn) Cuistant) Cuiaccept) E PATH
                                            NL Complete
                                                             PSPACE=NTSPACE
                  NSPACE = SPACE?
NSPACE = 60 NSPACE?
NSPACE = 60 NSPACE?
NSPACE = 60 NSPACE?
           answer 'no' (NSPACE + WNSPACE) > NSPACE + SPACE?
                     i.e. NSPACE is not
closed under complementation
                 All deterministic complexity classes (decision complexes) are closed under complementation.
                          1mmerman - Szelepcsényi
                            ML = \omega ML
                          NSPALE = CONSPACE
                           Savitch's Theorem
                     NSPACE (f) = SPACE (f2)
                              i.e. PSPACE = NPSPACE
      LCNL = CONL SP SUNP CNP CNP C PSPACE = NPSPACE SEXP
(DTIME(2))P = EXP?

-11 C SPACE(bot) EXPTIME C EXPSPACE!
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L C NL CP C NP C PSPACE CNPSACE SEXP