

Linear Algebra – Math 205 Lecture – 6, Exercise Set (SPRING 2023)

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Exercise Set 1.2 Solution

Question 17

For which values of a will the following system have no solutions? Exactly one solution? Infinitely many solutions?

$$x + 2y - 3z = 4$$

 $3x - y + 5z = 2$
 $4x + y + (a^2 - 14)z = a + 2$

Solution:

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 3 & -1 & 5 & 2 \\ 4 & 1 & (a^2 - 14) & a + 2 \end{bmatrix}$$

$$R_2 - 3R_1, R_3 - 4R_1 \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & -7 & (a^2 - 2) & a - 14 \end{bmatrix}$$

$$R_2 - R_3 \begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & 0 & (a^2 - 16) & a - 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & -7 & 14 & -10 \\ 0 & 0 & (a^2 - 16) & a - 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -3 & 4 \\ 0 & 1 & -2 & 10/7 \\ 0 & 0 & (a^2 - 16) & a - 4 \end{bmatrix}$$

The Gauss-Jordan process will reduce this system to the equations

$$x + 2y - 3z = 4$$

 $y - 2z = 10/7$
 $(a^2 - 16) z = a - 4$

If a=4, then the last equation becomes 0=0, and hence there will be infinitely many solutions-for instance,

$$z = t, y = 2t + \frac{10}{7}, x = -2\left(2t + \frac{10}{7}\right) + 3t + 4$$

. If a = -4, then the last equation becomes 0 = -8, and so the system will have no solutions.

Any other value of a will yield a unique solution for z and hence also for y and x.

Exercise Set 1.6 Solution

Question 10

Solution:

The coefficient matrix, augmented by the two **b** matrices, yields

$$\left[\begin{array}{cc|c} 1 & -5 & 1 & -2 \\ 3 & 2 & 4 & 5 \end{array}\right]$$

Applying $R_2 + (-3)R_1$ This reduces to

$$\left[\begin{array}{cc|c}
1 & -5 & 1 & -2 \\
0 & 17 & 1 & 11
\end{array} \right]$$

and then applying $\frac{1}{17}R_2$, $R_1 + (-5)R_2$

$$\left[\begin{array}{cc|c} 1 & 0 & 22/17 & 21/17 \\ 0 & 1 & 1/17 & 11/17 \end{array}\right]$$

Thus the solution to Part (a) is $x_1 = 22/17$, $x_2 = 1/17$, and to Part (b) is $x_1 = 21/17$, $x_2 = 11/17$

Question 16

Find conditions that the b's must satisfy for the system to be consistent.

$$6x_1 - 4x_2 = b_1$$
$$3x_1 - 2x_2 = b_2$$

Solution:

$$\begin{bmatrix} 6 & -4 & b_1 \\ 3 & -2 & b_2 \end{bmatrix} \xrightarrow{R_2 \leftrightharpoons 2R_1} \begin{bmatrix} 3 & -2 & b_2 \\ 6 & -4 & b_1 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 3 & -2 & b_2 \\ 0 & 0 & b_1 - 2b_2 \end{bmatrix}$$

One can see, for consistent second row has to get completely zeros, which deduce $b_1 = 2b_2$.

Question 23

Since Ax = has only x = 0 as a solution, Theorem 1.6.4 guarantees that A is invertible. By Theorem 1.4.8 (b), A^k is also invertible. In fact,

$$\left(A^k\right)^{-1} = \left(A^{-1}\right)^k$$

Since the proof of Theorem 1.4.8 (b) was omitted, we note that

$$\underbrace{A^{-1}A^{-1}\cdots A^{-1}}_{k} \underbrace{AA\cdots A}_{k} = I$$
factors
factors

Because A^k is invertible, Theorem 1.6.4 allows us to conclude that $A^kX = \mathbf{0}$ has only the trivial solution.

Question 24

Let $A\mathbf{x} = \mathbf{0}$ be a homogeneous system of n linear equations in n unknowns, and let Q be an invertible $n \times n$ matrix. Show that $A\mathbf{x} = \mathbf{0}$ has just the trivial solution if and only if $(QA)\mathbf{x} = 0$ has just the trivial solution.

Proof: First let $A\mathbf{x} = \mathbf{0}$ holds. Now we apply Q matrix from L.H.S we will have

$$Q(A\mathbf{x}) = Q\mathbf{0}$$

 $(QA)\mathbf{x} = \mathbf{0}$: Associative property

Now we let $(QA)\mathbf{x} = \mathbf{0}$ and we apply Q^{-1} from L.H.S because Q is invertable we will have

$$Q^{-1}(QA)\mathbf{x} = Q^{-1}\mathbf{0}$$

 $(Q^{-1}Q)A\mathbf{x} = Q^{-1}\mathbf{0}$ \therefore Associative property
 $IA\mathbf{x} = \mathbf{0}$
 $A\mathbf{x} = \mathbf{0}$

Question 25

Suppose that x_1 is a fixed matrix which satisfies the equation $Ax_1 = \mathbf{b}$. Further, let x be any matrix whatsoever which satisfies the equation $Ax = \mathbf{b}$. We must then show that there is a matrix x_0 which satisfies both of the equations $x = x_1 + x_0$ and $Ax_0 = \mathbf{0}$. Clearly, the first equation implies that

$$x_0 = X - X_1$$

This candidate for x_0 will satisfy the second equation because

$$Ax_0 = A(x - x_1) = Ax - Ax_1 = b - b = 0$$

We must also show that if both $Ax_1 = \mathbf{b}$ and $Ax_0 = \mathbf{0}$, then $A(x_1 + x_0) = \mathbf{b}$. But

$$A(x_1 + x_0) = Ax_1 + Ax_0 = \mathbf{b} + \mathbf{0} = \mathbf{b}$$

Question 26:

) If B is a square matrix satisfying BA=I, Then	
prove That if B is a square matrix salisfying $AB=I$, Then $B=A^{-1}$.	3
AB=I> (i) samply pre-multiply (i) with A-1 on both si	des
$\Rightarrow A^{-1}AB = A^{-1}I.$ $\Rightarrow IB = A^{-1}I$	_
\Rightarrow $B = A^{-1}$	_