

$$a) x(t) = \sum_{k=-\infty}^{\infty} r \delta(r t - k T_0)$$

نوعی قطار ضربی است.

$$T = \frac{T_0}{r} \Rightarrow \omega_0 = \frac{r \pi}{\frac{T_0}{r}} = \frac{r \pi}{T_0}$$

$$a_i = \frac{1}{\frac{T_0}{r}} \int_{-\frac{T_0}{r}}^{+\frac{T_0}{r}} \left(\sum_{k=-\infty}^{\infty} r \delta(r t - k T_0) \right) e^{-j i \omega_0 t} dt$$

$$\frac{-T_0}{r} < t < \frac{T_0}{r} \Rightarrow t = 0$$

$$= \frac{r}{T_0} \times r = \frac{r^2}{T_0} \Rightarrow a_i = \frac{r^2}{T_0}$$

$$b) x(t) = \cos\left(\frac{r}{r} t\right) (r + r \cos t) = r \cos\left(\frac{r}{r} t\right) + \cos\left(\frac{v}{r} t\right) + \cos\left(\frac{t}{r}\right)$$

$$= \frac{r}{r} \left(e^{\frac{r}{r} t j} + e^{-\frac{r}{r} t j} \right) + \frac{1}{r} \left(e^{\frac{v}{r} t j} + e^{-\frac{v}{r} t j} + e^{\frac{t}{r} j} + e^{-\frac{t}{r} j} \right)$$

$$= \frac{1}{r} e^{j(-v) \frac{t}{r}} + \frac{r}{r} e^{j(-r) \frac{t}{r}} + \frac{1}{r} e^{j(-1) \frac{t}{r}} + \frac{1}{r} e^{j \frac{t}{r}} + \frac{r}{r} e^{j(r) \frac{t}{r}}$$

$$+ \frac{1}{r} e^{j(v) \frac{t}{r}}$$

$$\Rightarrow a_k = \begin{cases} \frac{1}{r} & k = \pm 1, \pm v \\ \frac{r}{r} & k = \pm r \\ 0 & \text{o.w} \end{cases}$$

$$\begin{aligned}
 c) x(t) &= e^{j\frac{\pi}{r}t} \left(\cos\left(\frac{\pi}{r}t\right) + \sin\left(\frac{\pi}{r}t + \frac{\pi}{r}\right) \right) \\
 &= e^{j\frac{\pi}{r}t} \left(\frac{e^{j\frac{\pi}{r}t} + e^{-j\frac{\pi}{r}t}}{2} + \frac{e^{j(\frac{\pi}{r}t + \frac{\pi}{r})} - e^{-j(\frac{\pi}{r}t + \frac{\pi}{r})}}{2j} \right) \\
 &= \frac{1}{r} e^{-j\frac{r\pi}{r}t} - \frac{e^{-\frac{\pi}{r}j}}{2j} e^{j\frac{\pi}{r}t} + \frac{e^{\frac{\pi}{r}j}}{2j} e^{j\frac{\omega\pi}{r}t} + \frac{1}{r} e^{j\frac{9\pi}{r}t} \\
 \Rightarrow \begin{cases} a_{-r} = \frac{1}{r} \\ a_1 = -\frac{e^{-\frac{\pi}{r}j}}{2j} \end{cases} \quad \begin{cases} a_{\omega} = \frac{e^{\frac{\pi}{r}j}}{2j} \\ a_9 = \frac{1}{r} \end{cases} \quad a_{\text{بقیه}} = 0
 \end{aligned}$$

$$d) x(t) = \cos(r\pi t) + V \sin(t)$$

$$\frac{r\pi}{r\pi} = 1 \quad \begin{matrix} \swarrow 2\pi \\ \searrow r\pi \end{matrix}$$

سری فوریه ندارد
↑

نسبت به هم توانا نیستند
⇒ غیر متناوب

$$e) x[n] = e^{j\frac{\pi}{r}n} \cos\left(\frac{\pi}{r}n\right) = \frac{1}{r} e^{j\frac{\omega\pi}{r}n} + \frac{1}{r} e^{j\frac{11\pi}{r}n} \quad T = r\pi$$

$$\Rightarrow a_{\omega} = a_{11} = \frac{1}{r}, \quad a_{\text{بقیه}} = 0$$

در یک دوره متناوب $\cdot \langle k \leq r \rangle$

$$f) x[n] = e^{j\frac{r\pi}{\omega}n} = e^{j(r)(\frac{r\pi}{\omega})n} \Rightarrow a_r = 1, \quad a_{\text{بقیه}} = 0$$

در یک دوره متناوب $\cdot \langle k \leq r \rangle$

9) $x[n] = \sin\left(\frac{\pi}{r}n\right) + \cos\left(\frac{r\pi}{\omega}n\right)$ $\rho_k = (r, 1) = r_0 = T$

$\frac{r\pi}{\omega} = r = T_1 \quad \swarrow$ $\searrow \quad \frac{r\pi}{\omega} = \frac{1}{r} \rightarrow T_r = 1$ $\downarrow \quad 0 \leq k \leq 19$

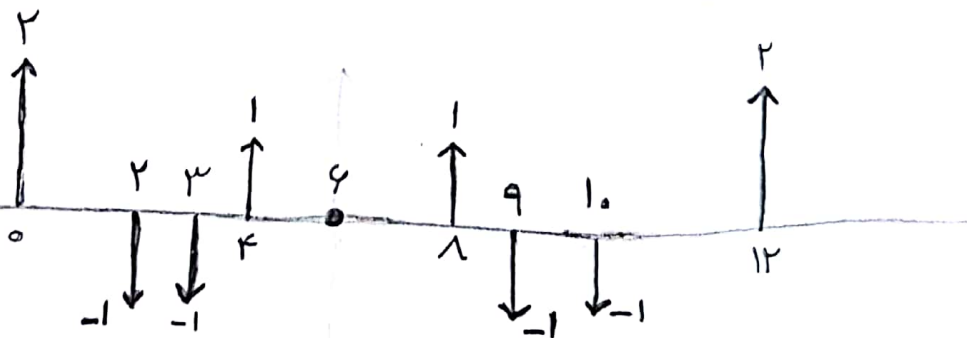
$$x[n] = \frac{e^{j\frac{\omega\pi}{10}n} - e^{-j\frac{\omega\pi}{10}n}}{rj} + \frac{e^{j\frac{r\pi}{10}n} + e^{-j\frac{r\pi}{10}n}}{r}$$

$$= \frac{1}{r} e^{-j\frac{r\pi}{10}n} - \frac{1}{rj} e^{-j\frac{\omega\pi}{10}n} + \frac{1}{rj} e^{j\frac{\omega\pi}{10}n} + \frac{1}{r} e^{j\frac{r\pi}{10}n}$$

$$\Rightarrow \begin{cases} a_{-r} = a_{-r+r_0} = a_{1r} = \frac{1}{r} \\ a_{-\omega} = a_{-\omega+r_0} = a_{1\omega} = -\frac{1}{rj} \end{cases} \quad \begin{matrix} a_{\omega} = \frac{1}{rj} \\ a_r = \frac{1}{r} \end{matrix}$$

$a = 0$
بعبارة
در دوره تناوب

h) $x[n] = \sum_{m=-\infty}^{\infty} (-1)^m [\delta[n-rm] + \delta[n+rm]]$



$T = 12$

$$P(t) = (x(t))^r = x(t) \times x^*(t) \quad \left. \begin{aligned} x(t) &= \sum_{k=-\infty}^{\infty} a_k e^{jk\omega t} \end{aligned} \right\} \Rightarrow P(t) = \sum_{k=-\infty}^{\infty} |a_k|^r \quad (1)$$

$$\begin{aligned} \Rightarrow P(t) &= \sum_{k=-\infty}^{\infty} r^{-r|k|} = \left(r \sum_{k=1}^{\infty} r^{-rk} \right) + 1 \\ &= r \left(\frac{\frac{1}{r}}{1 - \frac{1}{r}} \right) + 1 = \frac{r}{r-1} + 1 = \frac{\omega}{r} \end{aligned}$$

$$P[n] = \text{مقدار متوسط} = \frac{1}{N} \sum_{k=\langle N \rangle} |x[n]|^r = \sum_{k=\langle N \rangle} |a_k|^r \quad (2)$$

$$x[n] = \cos^r\left(\frac{n\pi}{10}\right) = \frac{1 + \cos\left(\frac{n\pi}{5}\right)}{r} = \frac{1}{r} + \frac{1}{r} \cos\left(\frac{n\pi}{5}\right)$$

$$\Rightarrow \frac{r\pi}{\pi} = 10 = N$$

$$x[n] = \frac{1}{r} + \frac{1}{r} \left(e^{j\frac{\pi}{5}n} + e^{-j\frac{\pi}{5}n} \right) = \frac{1}{r} e^{-j\frac{\pi}{5}n} + \frac{1}{r} + \frac{1}{r} e^{j\frac{\pi}{5}n}$$

$$a_{-1} = a_9 = \frac{1}{r}, \quad a_0 = \frac{1}{r}, \quad a_1 = \frac{1}{r}$$

$$\Rightarrow P[n] = \left(\frac{1}{r}\right)^r + \left(\frac{1}{r}\right)^r + \left(\frac{1}{r}\right)^r = \frac{r}{\wedge}$$

$$b_k = \begin{cases} 1+j^k & 1 \leq k \leq r \\ j^0 = 1 & k=0 \end{cases} \quad (3)$$

$$\Rightarrow P[n] = \sum_{k=\langle r \rangle} |b_k|^r = 1 + (\sqrt{r})^r + (1-1)^r + (\sqrt{r})^r$$

$$= 1 + r + 0 + r = \omega \Rightarrow P[n] = \omega$$

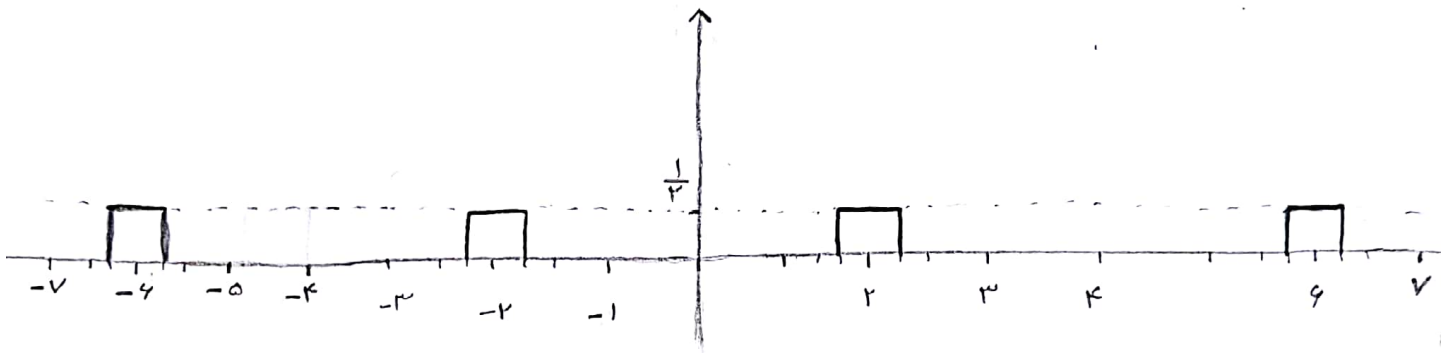
$$a_k = \frac{(-1)^k}{1\tau} \frac{\sin \frac{k\pi}{\Lambda}}{k \frac{\pi}{\Lambda}} = \frac{(-1)^k}{1\tau} \text{Sinc}\left(\frac{k}{\Lambda}\right) \quad (2)$$

$$\text{duty cycle} = \frac{1}{\Lambda} = d \Rightarrow a_k = \frac{(-1)^k}{\tau} d \text{Sinc}(kd)$$

$$\omega_0 = \frac{2\pi}{T} = \frac{\tau\pi}{T} \Rightarrow T = \tau \Rightarrow d = \frac{\tau T_1}{T} \Rightarrow T_1 = \frac{1}{\tau}$$

$$a_k = \frac{1}{\tau} e^{-jk\pi} \text{Sinc}(kd)$$

$$e^{-j \frac{\tau\pi}{T} k(\tau)} \rightarrow \text{واله شين زياتي}$$



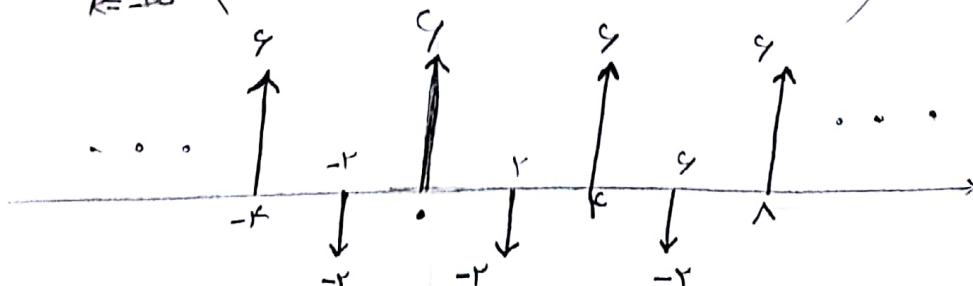
$$\{a_k\}_{k=-\infty}^{\infty} \Rightarrow \sum_{k=-\infty}^{\infty} \delta(t - kT) \xleftrightarrow{FS} \frac{1}{T} \quad (4)$$

$$a_k = b_k - c_k \longleftrightarrow x(t) = y(t) - z(t)$$

$$b_k = \tau \Rightarrow y(t) = \tau \sum_{k=-\infty}^{\infty} \delta(t - \tau k)$$

$$c_k = \begin{cases} 1 & \text{زوج } k \\ 0 & \text{فرد } k \end{cases} \Rightarrow z(t) = \tau \sum_{k=-\infty}^{\infty} \delta(t - 2k)$$

$$\Rightarrow x(t) = \sum_{k=-\infty}^{\infty} \left(\tau \delta(t - \tau k) - \tau \delta(t - 2k) \right)$$



$$Y(t) = \sum_{k=-\infty}^{\infty} a_k H(k\omega_0) e^{jk\omega_0 t} \quad T = T \Rightarrow \omega_0 = \frac{2\pi}{T} \quad (V)$$

$$a_k = \frac{1}{T} \int_{-1}^1 x(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \left(\int_{-1}^{-\frac{1}{r}} -e^{-j\frac{k\pi}{r}t} dt + \int_{-\frac{1}{r}}^{\frac{1}{r}} t e^{-j\frac{k\pi}{r}t} dt + \int_{\frac{1}{r}}^1 e^{-j\frac{k\pi}{r}t} dt \right) = \frac{1}{rk\pi j} e^{-j\frac{k\pi}{r}t} \Big|_{-\frac{1}{r}}^{-1} - \frac{1}{rk\pi j} e^{-j\frac{k\pi}{r}t} \Big|_{-\frac{1}{r}}^{\frac{1}{r}} + \frac{1}{rk\pi j} e^{-j\frac{k\pi}{r}t} \Big|_{\frac{1}{r}}^1$$

$$= \frac{e^{j\frac{k\pi}{r}} - e^{-j\frac{k\pi}{r}}}{rk\pi j} - \frac{e^{-j\frac{k\pi}{r}} - e^{j\frac{k\pi}{r}}}{rk\pi j} + \frac{e^{-j\frac{k\pi}{r}} - e^{j\frac{k\pi}{r}}}{rk\pi j} = \frac{-2\cos(\frac{k\pi}{r}) + 2\sin(\frac{k\pi}{r})}{rk\pi j}$$

$$\frac{-2\sin(\frac{k\pi}{r})}{rk\pi j} = \frac{-1}{rk\pi j} \left(\cos(\frac{k\pi}{r}) - \sin(\frac{k\pi}{r}) + \frac{r\sin(\frac{k\pi}{r})}{rk\pi j} \right)$$

$$b_k = H(k\omega_0) a_k = H\left(\frac{k\pi}{r}\right) a_k \rightarrow -1 \ll \frac{k\pi}{r} \ll 1 \Rightarrow k=0$$

$$Y(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t} \Leftrightarrow b_k = a_k \Leftrightarrow H\left(\frac{k\pi}{r}\right) = 1 \quad \leftarrow$$

① خطی از روابط ها توسط این فیلتر به سطر راست می شود

← سیستم وارون نیز نیست.

$$b_k = \underbrace{j^k}_{c_k} \underbrace{\frac{\sin \frac{k\pi}{r}}{k\pi}}_{d_k}$$

$$\begin{cases} a_k \leftrightarrow x(t) \\ b_k \leftrightarrow y(t) \\ d_k \leftrightarrow z(t) \end{cases}$$

(9)

$$\begin{cases} d_k = \frac{\sin \frac{k\pi}{r}}{k\pi} = \frac{1}{r} \sin\left(\frac{k}{r}\right) = d \operatorname{sinc}(kd), \quad d = d_0 = \frac{1}{r} \\ d = \frac{r T_1}{T} = \frac{r T_1}{r} = \frac{1}{r} \Rightarrow T_1 = \frac{1}{r} \end{cases}$$

$$\begin{cases} c_k = j^k = \left(j \sin\left(\frac{\pi}{r}\right)\right)^k = e^{j \frac{k\pi}{r}}, \quad \omega_0 = \frac{\pi}{r} \end{cases}$$

$$y(t) = z(t-1) \leftrightarrow b_k, \quad b_0 = d_0 = \frac{1}{r}$$

$$\Rightarrow \begin{cases} x(t) = y(t) - \frac{1}{r} = z(t-1) - \frac{1}{r} \\ a_0 = 0 \end{cases}$$

$\leftarrow z(t)$ موج مربعی با دوره تناوب $T = r$ ، $\text{duty cycle} = \frac{1}{r}$

$\Leftarrow x(t)$ هم انتقال یافته $z(t)$ است ، در رسم:

