

Question 1

(a) $x(2t+3)$

Method 1 ① $t \leftarrow t+3 \Rightarrow x(t+3)$ (shift left) (3 units)

② $t \leftarrow 2t \Rightarrow x(2t+3)$ (compress) (factor=2)⁵

Method 2

① $t \leftarrow 2t \Rightarrow x(2t)$ (compress) (factor=2)

② $t \leftarrow t + \frac{3}{2} \Rightarrow x(2(t + \frac{3}{2})) = x(2t+3)$ (shift left) (3/2 units)¹⁰

(b) $x(-2t) \rightarrow$ compress & reverse (factor=2)

(c) $x(-3t-4)$

① $t \leftarrow t-4 \Rightarrow x(t-4)$ (shift right) (4 units)¹⁵

② $t \leftarrow 3t \Rightarrow x(3t-4)$ (compress) (factor=3)

③ $t \leftarrow -t \Rightarrow x(-3t-4)$ (reverse)²⁰

(d) $x(\frac{t-1}{3}) = x(\frac{1}{3}t - \frac{1}{3})$

① $t \leftarrow t - \frac{1}{3} \Rightarrow x(t - \frac{1}{3})$ (shift left) ($\frac{1}{3}$ units)²⁵

② $t \leftarrow \frac{1}{3}t \Rightarrow x(\frac{1}{3}t - \frac{1}{3})$ (expand) (factor = $\frac{1}{3}$)

Question 2

$$(a) x(t) = e^{-5t} \cos(t) u(t)$$

$$\rightarrow x(-t) = e^{5t} \cos(-t) u(-t) = e^{5t} \cos(t) u(-t)$$

$$\mathcal{E}\{x(t)\} = \frac{x(t) + x(-t)}{2} = \frac{1}{2} \left[\cos(t) (e^{-5t} u(t) + e^{5t} u(-t)) \right]$$

$$\mathcal{O}\{x(t)\} = \frac{x(t) - x(-t)}{2} = \frac{1}{2} \left[\cos(t) (e^{-5t} u(t) - e^{5t} u(-t)) \right]$$

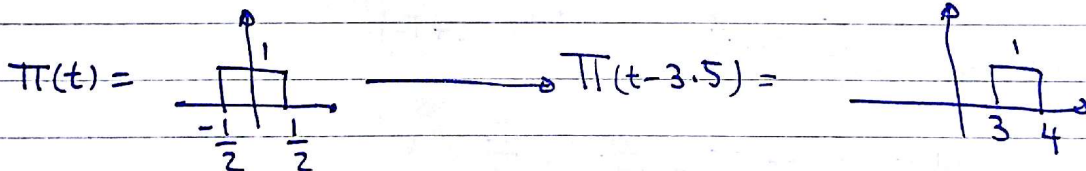
$$(b) x(t) = e^{-6|t|} \cos(t)$$

$$x(-t) = e^{-6|-t|} \cos(-t) = e^{-6|t|} \cos(t) = x(t)$$

$$\Rightarrow \mathcal{E}\{x(t)\} = \frac{2x(t)}{2} = x(t) = e^{-6|t|} \cos(t)$$

$$\mathcal{O}\{x(t)\} = \frac{0}{2} = 0$$

$$(c) \Pi(t-3.5) = x(t)$$



$$\Rightarrow x(-t) = \text{graph of a rectangular pulse from } t = -4 \text{ to } t = -3 \text{ with height } 1$$

$$\Rightarrow \mathcal{E}\{x(t)\} = \text{graph of two rectangular pulses: one from } t = -4 \text{ to } t = -3 \text{ with height } \frac{1}{2}, \text{ and another from } t = 3 \text{ to } t = 4 \text{ with height } \frac{1}{2}$$

$$\mathcal{O}\{x(t)\} = \text{graph of two rectangular pulses: one from } t = -4 \text{ to } t = -3 \text{ with height } -\frac{1}{2}, \text{ and another from } t = 3 \text{ to } t = 4 \text{ with height } \frac{1}{2}$$

Question 3

$$(a) x(t) = \sin^2(4t - \frac{\pi}{4})$$

$$\cos(2\alpha) = \cos^2(\alpha) - \sin^2(\alpha) = 1 - 2\sin^2\alpha$$

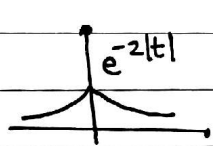
$$\Rightarrow \sin^2(\alpha) = \frac{1}{2}(1 - \cos(2\alpha))$$

$$\Rightarrow \sin^2(4t - \frac{\pi}{4}) = \frac{1}{2} \underbrace{(1 - \cos(8t - \frac{\pi}{2}))}_{\omega(t)}$$

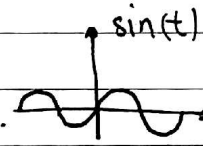
$x(t)$ is periodic if $\omega(t)$ is.

$$\omega(t) = \cos(8t - \frac{\pi}{2}) \quad T_0 = \frac{2\pi}{\omega_0} = \frac{2\pi}{8} = \frac{\pi}{4}$$

$$(b) x(t) = e^{-2|t|} \sin(t)$$



*



= periodic? No

$$(c) x(t) = e^{3j(8t + \frac{\pi}{3})} = e^{j(24t + \pi)}$$

$$\omega_0 = 24 \Rightarrow T_0 = \frac{2\pi}{24} = \frac{\pi}{12} \quad \checkmark$$

$$(d) x(t) = \sin^3(5t)$$

$$\sin(3\alpha) = 3\sin(\alpha) - 4\sin^3(\alpha)$$

$$\Rightarrow \sin^3(\alpha) = \frac{1}{4}(3\sin(\alpha) - \sin(3\alpha))$$

$$\Rightarrow x(t) = \sin^3(5t) = \frac{1}{4} \left(\underbrace{3\sin(5t)}_{x_1} - \underbrace{\sin(15t)}_{x_2} \right)$$

$$T_{01} = \frac{2\pi}{5} \quad T_{02} = \frac{2\pi}{15} \quad \rightarrow T_0 = \text{lcm}\left(\frac{2\pi}{5}, \frac{2\pi}{15}\right) = \frac{2\pi}{5} = 0.4\pi$$

(e) $x[n] = 3\sin(4\pi n)$

$$\frac{2\pi}{\omega_0} = \frac{2\pi}{4\pi} = \frac{1}{2} \rightarrow \text{Rational} \Rightarrow N_0 = 1$$

(f) $x[n] = 3\sin(4n)$

$$\frac{2\pi}{\omega_0} = \frac{2\pi}{4} = \frac{\pi}{2} \rightarrow \text{Not Rational} \Rightarrow \text{Not Periodic}$$

(g) $x[n] = e^{\frac{jn}{2}} + e^{\frac{jn}{3}}$

Neither $e^{\frac{jn}{2}}$ nor $e^{\frac{jn}{3}}$ is periodic

\Rightarrow Not Periodic

(h) $x[n] = e^{\frac{jn\pi}{2}} + e^{\frac{jn\pi}{3}}$

Period₁: $\frac{2\pi}{\omega_0} = \frac{2\pi}{\pi/2} = \frac{4}{1} \Rightarrow N_{01} = 4$

Period₂: $\frac{2\pi}{\omega_0} = \frac{2\pi}{\pi/3} = \frac{6}{1} \Rightarrow N_{02} = 6$

$$N_0 = \text{LCM}(4, 6) = 12$$

Question 4

(a) $y(t) = e^{x(t)}$

- Memoryless : Yes
- Causal : Yes
- Stable : Yes, BIBO applies
- TI : Yes

$$\text{input} = x_1(t) \Rightarrow y_1(t) = e^{x_1(t)}$$

$$\text{input} = x_2(t) = x_1(t-t_0) \Rightarrow y_2(t) = e^{x_1(t-t_0)}$$

$$y_1(t-t_0) = e^{x_1(t-t_0)} \Rightarrow \text{Yes}$$

- Linear : No

$$x_1(t) \rightarrow y_1(t) = e^{x_1(t)}$$

$$x_2(t) \rightarrow y_2(t) = e^{x_2(t)}$$

$$x_3(t) = ax_1(t) + bx_2(t) \rightarrow y_3(t) = e^{x_3(t)} = e^{ax_1(t) + bx_2(t)} = e^{ax_1(t)} e^{bx_2(t)}$$

$$\neq ay_1(t) + by_2(t)$$

(b) $y(t) = \cos(3t) x(t)$

- Memoryless : Yes
- Causal : Yes
- Stable : Yes, BIBO applies
- TI : No

$$\text{input} = x_1(t) \Rightarrow y_1(t) = \cos(3t) x_1(t)$$

$$\text{input} = x_1(t-t_0) \Rightarrow y_2(t) = \cos(3t) x_1(t-t_0)$$

$$y_1(t-t_0) = \cos(3(t-t_0)) x_1(t-t_0) \Rightarrow \text{No}$$

- Linear : Yes

$$x_1(t) \rightarrow y_1(t) = \cos(3t) x_1(t)$$

$$x_2(t) \rightarrow y_2(t) = \cos(3t) x_2(t)$$

$$ax_1(t) + bx_2(t) \rightarrow y_3(t) = \cos(3t) x_3(t) = \cos(3t) (ax_1 + bx_2) = ay_1 + by_2$$

$$(c) y(t) = \int_{-\infty}^{2t} x(\tau) d\tau$$

- Memoryless : No, $y(t)$ needs $x(2t)$
- Causal : No, $y(t)$ needs $x(2t)$
- Stable : No, if $x(t)=1 \Rightarrow y(t) = \int_{-\infty}^{2t} 1 d\tau = \infty$

• TI : No

$$\text{input} = x_1(t) \Rightarrow y_1(t) = \int_{-\infty}^{2t} x_1(\tau) d\tau$$

$$\text{input} = x_2(t) = x_1(t-t_0) \Rightarrow y_2(t) = \int_{-\infty}^{2t} x_1(\tau-t_0) d\tau$$

$$y_1(t-t_0) = \int_{-\infty}^{2(t-t_0)} x_1(\tau) d\tau \rightarrow \text{No}$$

• Linear : Yes

$$x_1(t) \rightarrow y_1(t) = \int_{-\infty}^{2t} x_1(\tau) d\tau$$

$$x_2(t) \rightarrow y_2(t) = \int_{-\infty}^{2t} x_2(\tau) d\tau$$

$$ax_1 + bx_2 \rightarrow y_3(t) = \int_{-\infty}^{2t} (ax_1(\tau) + bx_2(\tau)) d\tau = ay_1(t) + by_2(t) \checkmark$$

$$(d) y(t) = \sin(x(t))$$

- Memoryless : Yes
- Causal : Yes
- Stable : Yes : $-1 \leq y(t) \leq +1$
- TI : Yes

$$\text{input} = x_1(t) \rightarrow y_1(t) = \sin(x_1(t))$$

$$\text{input} = x_2(t) = x_1(t-t_0) \rightarrow y_2(t) = \sin(x_1(t-t_0))$$

$$y_1(t-t_0) = \sin(x_1(t-t_0)) \checkmark$$

• Linear : No

$$\sin(ax_1(t) + bx_2(t)) \neq a\sin(x_1(t)) + b\sin(x_2(t))$$

(e) $y[n] = x[4n+1]$

• Memoryless : No, $y[0] = x[1]$

• Causal : No, $y[0] = x[1]$

• Stable : Yes, BIBO applies

• TI : No

$$\text{input} = x_1[n] \Rightarrow y_1[n] = x_1[4n+1]$$

$$\text{input} = x_2[n] = x_1[n-n_0] \Rightarrow y_2[n] = x_2[4n+1] = x_1[4n+1-n_0]$$

$$y_1[n-n_0] = x_1[4(n-n_0)+1]$$

• Linear : Yes

$$x_1[n] \rightarrow y_1[n] = x_1[4n+1]$$

$$x_2[n] \rightarrow y_2[n] = x_2[4n+1]$$

$$x_3[n] = ax_1[n] + bx_2[n] \rightarrow y_3[n] = x_3[4n+1] = ax_1[4n+1] + bx_2[4n+1] \\ = ay_1[n] + by_2[n]$$

(f) $y[n] = (n-2)x[n]$

• Memoryless : Yes

• Causal : Yes.

• Stable : ~~Yes~~ BIBO applies

No, if $x[n] = 1 \rightarrow y[\infty] = \infty \Rightarrow$ Not Bounded

• TI : No

$$\text{input} = x_1[n] \Rightarrow y_1[n] = (n-2)x_1[n]$$

$$\text{input} = x_2[n] = x_1[n-n_0] \Rightarrow y_2[n] = (n-2)x_2[n] = (n-2)x_1[n-n_0]$$

$$y_1[n-n_0] = (n-n_0-2)x_1[n-n_0]$$

• Linear : Yes

$$x_1[n] \rightarrow y_1[n] = (n-2)x_1[n]$$

$$x_2[n] \rightarrow y_2[n] = (n-2)x_2[n]$$

$$x_3[n] = ax_1[n] + bx_2[n] \rightarrow y_3[n] = (n-2)(ax_1[n] + bx_2[n]) = ay_1[n] + by_2[n]$$

$$(g) y[n] = x[n] \sum_{k=-\infty}^{+\infty} \delta[n - (2k+1)] = \begin{cases} x[n] & n \text{ is odd} \\ 0 & \text{o.w} \end{cases}$$

- Memoryless : Yes
- Causal : Yes
- Stable : Yes, BIBO applies
- TI : No

$$\text{input} = x_1[n] \Rightarrow y_1[n] = x_1[n] \sum_{k=-\infty}^{+\infty} \delta[n - (2k+1)]$$

$$\text{input} = x_2[n] = x_1[n - n_0] \Rightarrow y_2[n] = x_1[n - n_0] \sum_{k=-\infty}^{+\infty} \delta[n - (2k+1)]$$

$$y_1[n - n_0] = x_1[n - n_0] \sum_{k=-\infty}^{+\infty} \delta[n - n_0 - (2k+1)]$$

اگر n_0 فرد باشد معنی است این سیگنال شبیه TI در نظر گرفته شود.

- Linear : Yes

$$(h) y[n] = \sum_{k=-\infty}^n x[k+3] \xrightarrow[\text{قاعده تغییر متغیر}]{k \leftarrow k-3} y[n] = \sum_{k=-\infty}^{n+3} x[k]$$

- Memoryless : No, $y[0] = x[3] + x[2] + x[1] + \dots$

- Causal : No, //

- Stable : No, if $x[n] = 1$, $y[0] = \sum_{k=-\infty}^3 1 = -\infty$

- TI : Yes

$$\text{input} = x_1[n] \Rightarrow y_1[n] = \sum_{k=-\infty}^{n+3} x_1[k]$$

$$\text{input} = x_2[n] = x_1[n - n_0] \Rightarrow y_2[n] = \sum_{k=-\infty}^{n+3} x_1[k - n_0]$$

$$y_1[n - n_0] = \sum_{k=-\infty}^{n - n_0 + 3} x_1[k] \xrightarrow[\text{تغییر متغیر}]{k \leftarrow k - n_0} \sum_{k=-\infty}^{n+3} x_1[k - n_0]$$

- Linear : Yes, Σ is linear

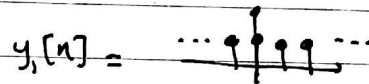
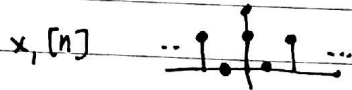
$$\Sigma ax_1 + bx_2 = a \Sigma x_1 + b \Sigma x_2 = ay_1 + by_2$$

Question 5

(a) $y(t) = \frac{d}{dt} x(t) \rightarrow$ Not Invertible

$x_1(t) = 5t+3$
 $x_2(t) = 5t+4 \rightarrow y_1(t) = y_2(t) = 5$

(b) $y[n] = x[2n] \rightarrow$ Not Invertible

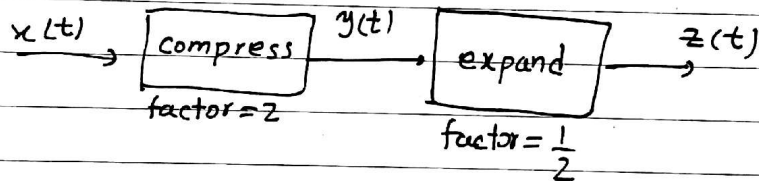


$x_1[n] = 1$

$y_1[n] = 1$

(c) $y(t) = x(2t) -$ Invertible

$z(t) = y(\frac{t}{2})$



Question 6

(a) $x(t) = e^{-8t} u(t)$



$$E_{\infty} = \int_{-\infty}^{+\infty} |x(t)|^2 dt = \int_0^{\infty} e^{-16t} dt = \frac{-1}{16} (0 - 1) = \frac{1}{16}$$

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^{+T} |x(t)|^2 dt = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_0^T e^{-16t} dt$$

$$= \frac{-1}{16} \lim_{T \rightarrow \infty} \frac{1}{2T} (e^{-16T} - 1) = \frac{0}{\infty} = 0$$

(b) $x(t) = e^{j(3t + \frac{\pi}{8})}$

$$|x(t)|^2 = \sqrt{\cos^2(\dots) + \sin^2(\dots)} = 1$$

$$E_{\infty} = \int_{-\infty}^{+\infty} dt = \infty$$

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T dt = \lim_{T \rightarrow \infty} \frac{1}{2T} 2T = 1$$

(c) $x[n] = \left(\frac{1}{3}\right)^n u[n]$

$$E_{\infty} = \sum_{n=-\infty}^{+\infty} |x[n]|^2 = \sum_{n=0}^{\infty} \left(\frac{1}{3}\right)^{2n} = \sum_{n=0}^{\infty} \left(\frac{1}{9}\right)^n$$

$$= 1 + \frac{1}{9} + \frac{1}{81} + \dots$$

$$= \frac{1}{1 - \frac{1}{9}} = \frac{9}{8}$$

$$P_{\infty} = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{+N} |x[n]|^2 = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^N \left(\frac{1}{9}\right)^n = \frac{9/8}{\infty} = 0$$