

# Linear Algebra

EE25872



Spring Semester 1402-03  
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## 1 (15pt)

Vector  $\mathbf{v}$  is defined in  $\mathbb{R}^3$  space as  $\mathbf{v} = \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$

1.1 elaborate this vector by basis of  $\mathbf{B}$

Since  $\mathbf{b}$  is the basis vectors of the 3D space, (or the transformation matrix is the identity) which results:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} = \mathbf{v}$$

$$\mathbf{v} = a_1\mathbf{b}_1 + a_2\mathbf{b}_2 + a_3\mathbf{b}_3 \rightsquigarrow \mathbf{A} = \mathbf{v}^T = [3 \quad 2 \quad -1]$$

$$a_1 = 3, a_2 = 2, a_3 = -1$$

1.2 elaborate this vector by basis of  $\mathbf{C}$

$$\mathbf{C} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \mathbf{v}$$

Which Is a linear system of equations

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix}$$

Which we solve using gaussian elimination method:

$$\rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ -2 \end{bmatrix}$$

Whee we conclude

$$\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}$$

1.3 find matrix  $P$  in  $\mathbf{v} = P\mathbf{w}$

$$\begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix} = P \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}$$

As we wrote down, the matrix  $\mathbf{P} = [c_1 \ c_2 \ c_3] = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$  is the transformation matrix

1.4 then we try to find inverse:

$$\mathbf{P}^{-1} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}$$

$$\det(A) = 1 \cdot (0 \cdot 1 - 1 \cdot 1) - 1 \cdot (1 \cdot 1 - 0 \cdot 1) + 0 \cdot (1 \cdot 1 - 0 \cdot 1) = -2$$

$$\text{adj}(A) = \begin{bmatrix} -1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & -1 \end{bmatrix}^T = \begin{bmatrix} -1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & -1 \end{bmatrix}$$

$$A^{-1} = -\frac{1}{2} \begin{bmatrix} -1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & -1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$\mathbf{P}^{-1} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$\mathbf{v} = P^{-1}\mathbf{w} \rightsquigarrow \mathbf{P}^{-1}\mathbf{w} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}$$

Which is pretty unreasonable and I think the question meant that :

$$P^{-1}\mathbf{v} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 3 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix} = \mathbf{w}$$

## 2 (10pt)

2.1 subset of  $\mathbb{R}^2$  close to sum/subtraction but not close to scalar multiplication:

$$\mathbf{V} = \{(x, y) \in \mathbb{R}^2 : x, y \in \mathbb{Z}\}$$

$$(x_1, y_1) \in \mathbf{V}$$

$$(x_2, y_2) \in \mathbf{V}$$

$$(x_1 + x_2, y_1 + y_2) \in \mathbb{Z}$$

But for example (1,-1) and scalar value 0.5 we have (0.5,-0.5) which is not inside the set

2.2 subset of  $\mathbb{R}^2$  not-close to sum/subtraction but close to scalar multiplication:

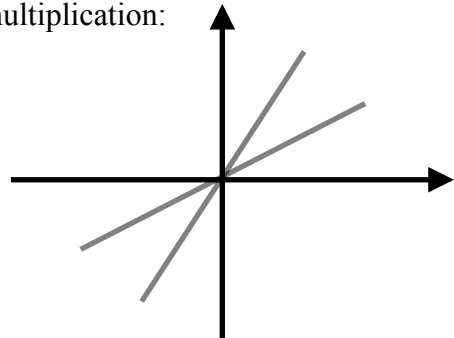
Imagine the span of two intersecting lines

$$\mathbf{V} = \{(x, y) \in \mathbb{R}^2 : y = 0.5x \cup y = 2x\}$$

$$(x_1, 0.5x_1) \in \mathbf{V} \rightsquigarrow (kx_1, k/2x_1) \in \mathbf{V}$$

$$(x_1, 2x_1) \in \mathbf{V} \rightsquigarrow (kx_1, 2kx_1) \in \mathbf{V}$$

$$(2x_1, 2.5x_1) \notin \mathbf{V}$$



## 3 (15 pt)

$$C = \{(x_1, x_2) \mid x_1, x_2 \in \mathbb{C}\}$$

$$(x_1, x_2) + (y_1, y_2) = (x_1 + y_1 + 1, x_2 + y_2 + 1)$$

$$\alpha(x_1, x_2) = (\alpha x_1 + \alpha - 1, \alpha x_2 + \alpha - 1)$$

3.1 what is the zero vector?

$$-1(x_1, x_2) = (-x_1 - 2, -x_2 - 2)$$

$$-(x_1, x_2) + (x_1, x_2) = (-x_1 - 2 + x_1 + 1, -x_2 - 2 + x_2 + 1) = (-1, -1)$$

3.2 prove the identity  $\alpha(u + v) = \alpha u + \alpha v$

$$\alpha(u + v) = \alpha(u_1 + v_1 + 1, u_2 + v_2 + 1) = (\alpha u_1 + \alpha v_1 + \alpha + \alpha - 1, \alpha u_2 + \alpha v_2 + \alpha + \alpha - 1)$$

$$= (\alpha u_1 + \alpha v_1 + 2\alpha - 1, \alpha u_2 + \alpha v_2 + 2\alpha - 1) = (\alpha u_1 + \alpha v_1 + 2\alpha - 2 + 1, \alpha u_2 + \alpha v_2 + 2\alpha - 2 + 1) =$$

$$= (x_1, x_2) + (y_1, y_2) \text{ where } x_1 = \alpha u_1 + \alpha - 1, x_2 = \alpha u_2 + \alpha - 1 \text{ and } y_1 = \alpha v_1 + \alpha - 1, y_2 = \alpha v_2 + \alpha - 1$$

$$(x_1, x_2) = \alpha(u_1, u_2) = \alpha u$$

$$(y_1, y_2) = \alpha(v_1, v_2) = \alpha v$$

$$\rightsquigarrow (\alpha u_1 + \alpha v_1 + 2\alpha - 2 + 1, \alpha u_2 + \alpha v_2 + 2\alpha - 2 + 1) = (x_1, x_2) + (y_1, y_2) = \alpha u + \alpha v = \alpha(u + v)$$

4 (15 pt)

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

4.1 Four main sub spaces:

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 0 & 0 & 5/3 & 10/3 & -10/3 \\ 0 & 0 & 13/3 & 26/3 & -26/3 \end{bmatrix} = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 0 & 0 & 5/3 & 10/3 & -10/3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\mathbf{C}(A) = \text{Span}\left(\begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}\right)$$

$$\mathbf{C}(A^T) = \text{Span}\left(\begin{bmatrix} -3 \\ 6 \\ -1 \\ 1 \\ -7 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 2 \\ 3 \\ -1 \end{bmatrix}\right)$$

$$\mathbf{N}(A) = \text{Span}\left(\begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}\right)$$

$$\mathbf{N}(A^T) = \text{Span}\left(\begin{bmatrix} -1/5 \\ -13/5 \\ 1 \end{bmatrix}\right)$$

4.2

$$\text{rank}(A) = 2$$

$$\dim(\mathbf{C}(A)) = r = 2$$

$$\dim(\mathbf{C}(A^T)) = r = 2$$

$$\dim(\mathbf{N}(A)) = n - r = 3$$

$$\dim(\mathbf{N}(A^T)) = m - r = 1$$

4.3

The basis vectors of Part one are the ones written down earlier:

$$\mathbf{C}(A) \rightsquigarrow \begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}, \dots$$

4.4

$$\begin{bmatrix} -1 & 2 & 5 \end{bmatrix} \begin{bmatrix} -1/5 \\ -13/5 \\ 1 \end{bmatrix} = 0, \dots \text{ and the result is zero for every other inner product of this type} \\ \rightarrow C(A) \perp N(A^T)$$

$$\begin{bmatrix} -3 & 6 & -1 & 1 & -7 \end{bmatrix} \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix} = 0, \dots \text{ and the result is zero for every other inner product of this type} \\ \rightarrow C(A^T) \perp N(A)$$

5 (15 pt)

By using the definition of Null Space we have:

$$A\underline{x} = 0$$

Which yields these immediate results:

$\underline{x}$  is perpendicular to matrix A rows

$\underline{x}$  is perpendicular to matrix A combination of rows

$\underline{x}$  is perpendicular to matrix A row space

$$C(A^T) \perp N(A)$$

$$\dim(C(A^T)) + \dim(N(A)) = n$$

$$\dim(N(A)) = n - r$$

$$\dim(N(A)) + \text{rank}(A) = n$$

6 (20 pt)

6.1 Null space basis:

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rightsquigarrow \underline{x}_n = x_2 \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \end{bmatrix} + x_4 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

6.2 the number of free variables will increase this way:

$$\hat{A} = \begin{bmatrix} 1 & 0 & 2 & 3 & 4 \\ 1 & 0 & 2 & 4 & 6 \\ 0 & 0 & 0 & 1 & 2 \end{bmatrix} \rightarrow \hat{A} = \begin{bmatrix} 1 & 0 & 2 & 3 & 4 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$x_2$  can take infinite different values thus we have infinite distinct basis values. In other words, we need another vector to span the space ( a unit vector in the direction of added column).

6.3 Null space will have no changes, the only change will be on left null space and column space

$$\bar{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 4 & 6 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$6.4 C(A) = \text{span}\left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix}\right)$$

$$\dim(C(A)) = 2$$

$$C(A) \in \mathbb{R}^3$$

6.5

$$b = \begin{bmatrix} \alpha \\ 6 \\ 1 \end{bmatrix} \text{ and } Ax = b$$

$$\begin{bmatrix} 1 & 2 & 3 & 4 & \alpha \\ 1 & 2 & 4 & 6 & 6 \\ 0 & 0 & 1 & 2 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 & \alpha \\ 0 & 0 & 1 & 1 & 6 - \alpha \\ 0 & 0 & 0 & 0 & \alpha - 5 \end{bmatrix}$$

$$\rightsquigarrow \alpha = 5$$

6.6

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix}$$

$$x_p = \begin{bmatrix} 2 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

6.7

$$A^T = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 2 & 0 \\ 3 & 4 & 1 \\ 4 & 6 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$N(A^T) = \text{span}\left(\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\right) \rightsquigarrow [1 \quad -1 \quad 1] \begin{bmatrix} 5 \\ 6 \\ 1 \end{bmatrix} = 0$$

$$\underline{b} \perp N(A^T)$$



7 (10 pt)

For  $r < m$  one column will be zero and for some values of  $b$  we won't have answers

For  $m = r$  and  $n > r$  we will have infinity answers according to Null Space special answers

For  $m > r$  and  $n = r$  we will have zero / or / one answer

For  $n = m = r$  we will have exactly one answer for  $b$