Massachusetts Institute of Technology

Department of Electrical Engineering & Computer Science

6.041/6.431: Probabilistic Systems Analysis (Fall 2011)

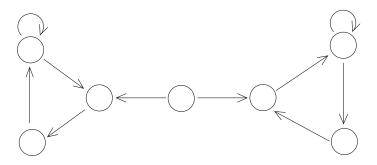
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1. For any finite Markov chain, we define

$$r_{ij}(n) \equiv \mathbf{P}(X_n = j | X_0 = i)$$
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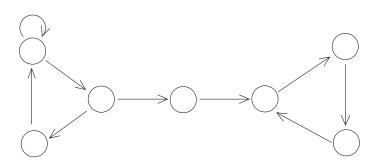
We define π_j as the steady state probability of being in state j, provided $r_{ij}(n)$ converges as $n \to \infty$ and the value to which it converges does not depend on the starting state i. The arrows correspond to positive single-step transition probabilities. Determine if each statement is true or false for each of the chains below.

(a)



- i. $r_{ij}(n)$ converges to a limit as $n \to \infty$ for each pair of states (i, j).
- ii. Statement (i) is true and $\lim_{n\to\infty} r_{ij}(n) = \pi_j$ (not varying with i) for each pair of states (i,j).
- iii. Statement (ii) is true and $\pi_j > 0$ for each state j.

(b)



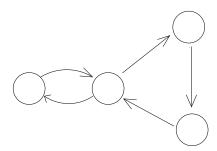
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(c)

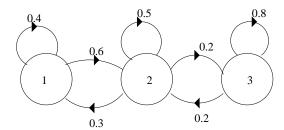


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- ii. Statement (i) is true and $\lim_{n\to\infty} r_{ij}(n) = \pi_j$ (not varying with i) for each pair of states (i,j).
- iii. Statement (ii) is true and $\pi_i > 0$ for each state j.
- 2. Problem 7.18, page 386 in textbook.

The parking garage at MIT has installed a card operated gate, which, unfortunately, is vulnerable to absent-minded faculty and staff. In particular, in each day a car crashes the gate with probability p, in which case a new gate must be installed. Also a gate that has survived for m days must be replaced as a matter of periodic maintenance. What is the steady-state expected frequency of gate replacements?

3. Problem 7.13, page 385 in textbook.

Consider the Markov chain below. Let us refer to a transition that results in a state with a higher (respectively, lower) index as a birth (respectively, death). Calculate the following quantities, assuming that when we start observing the chain, it is already in steady-state.



- (a) For each state i, the probability that the current state is i.
- (b) The probability that the first transition we observe is a birth.
- (c) The probability that the first change of state we observe is a birth.
- (d) The conditional probability that the process was in state 2 before the first transition that we observe, given that this transition was a birth.
- (e) The conditional probability that the process was in state 2 before the first change of state that we observe, given that this change of state was a birth.
- (f) The conditional probability that the first observed transition is a birth given that it resulted in a change of state.
- (g) The conditional probability that the first observed transition leads to state 2, given that it resulted in a change of state.