

MASSACHUSETTS INSTITUTE OF TECHNOLOGY  
Department of Electrical Engineering & Computer Science  
**6.041/6.431: Probabilistic Systems Analysis**  
(Spring 2010)

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**Problem Set 11<sup>1</sup> (never due)**

1. A sequence of  $n$  i.i.d. Bernoulli trials with unknown  $p$  (probability of success in the first trial) yields  $K_n$  successes.
  - (a) Let  $M_n$  be the number of the trials *before* the *first* success has occurred (for example,  $M_n = 0$  when the first trial was a success, and  $M_n = n$  when  $K_n = 0$ ). Find, in terms of  $K_n$ ,  $n$ , and  $p$ , a minimal probability of error estimator  $\hat{M}_n$  for  $M_n$  given  $K_n$ . Given  $K_n$ ,  $n$ , and  $p$ , is  $\hat{M}_n$  uniquely defined?
  - (\*b) Given  $n$  and  $K_n$ , what is the maximal likelihood estimate of  $p^2$ ? Is it unbiased? Is consistent as  $n \rightarrow \infty$ ?
  - (\*c) Consider the case when  $n = 9$  and the probability of success in the first trial  $p$  is either  $1/2$  or  $2/3$ . Among all functions  $g : \{0, 1, \dots, n\} \mapsto \{0, 1\}$  such that  $\mathbf{P}(1 = g(K_n))$  is not larger than  $0.5$  when  $p = 1/2$ , find the one that achieves the smallest  $\beta = \mathbf{P}(0 = g(K_n))$  when  $p = 2/3$ . Also find the corresponding value of  $\beta$ .
2. Real parameter  $\Theta$  is measured by a device which introduces multiplicative measurement noise  $W$ , modeled as a random variable which is uniformly distributed over the interval  $[0, 1]$ , so that the measurement is  $Y = \Theta W$ .

In questions (a)-(d) assume that  $\Theta$  is a random variable which is independent of  $W$  and is uniformly distributed over the interval  $[-1, 1]$ .

  - (a) the MAP estimator for  $\Theta$  given  $Y$ ;
  - (b) the least mean squares estimator for  $\Theta$  given  $Y$ ;
  - (c) the linear least mean squares estimator for  $\Theta$  given  $Y$ ;
  - (d) the least mean absolute error estimator for  $\Theta$  given  $Y$ .

In question (e),(f) no a-priori distribution information about  $\Theta$  is assumed, apart from  $\Theta$  being a *positive* number.

  - (\*e) Find the ML estimate  $\hat{\Theta}$  of  $\Theta$  given  $Y$ .
  - (\*f) What is the minimal real number  $\rho$  for which  $(Y, \rho Y)$  is a 95 percent confidence interval for  $\Theta$ ?
3. A factory produces light bulbs for which the life time  $T$  (measured in hours) has exponential distribution with parameter  $\lambda = 1$ . One such light bulb is turned on, then checked in exactly 1 hour, 2 hours, etc. Let the  $K$ th check (i.e. exactly  $K \in \{1, 2, 3, \dots\}$  hours after being turned on) be the first one when the light bulb was found not working.
  - (a) Find function  $g_0 : \{1, 2, 3, \dots\} \mapsto [0, \infty)$  which produces the MAP estimate  $\hat{T} = g_0(K)$  of  $T$ .
  - (b) Find function  $g_1 : \{1, 2, 3, \dots\} \mapsto [0, \infty)$  which produces least mean absolute error estimate  $\hat{T} = g_1(K)$  i.e. the one minimizing  $\mathbf{E}[|g(K) - T|]$ .
  - (c) Find function  $g_2 : \{1, 2, 3, \dots\} \mapsto [0, \infty)$  which produces least mean squares error estimate  $\hat{T} = g_2(K)$  i.e. the one minimizing  $\mathbf{E}[|g(K) - T|^2]$ .

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<sup>1</sup>Questions marked \* rely on the material to be presented during the week of May 10-14

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4. John tests rubber ducks produced at the plant where he works. Squeezing and then releasing a grade A duck produces a squeak of sound intensity (measured in dB) which can be modeled as a sum of two independent random variables uniformly distributed in the range 25 to 55. Accordingly, the noise generated by a grade B duck can be modeled as a sum of two independent random variables uniformly distributed in the range 10 to 40.<sup>2</sup>
- ( a) Assuming that one third of the rubber ducks are grade A, and the rest are grade B, find a function  $g = g_{mpe} : [20, 110] \mapsto \{A, B\}$  defining a minimal probability of error estimator  $\hat{U} = g(Y)$  for a rubber duck's grade  $U \in \{A, B\}$ , based on the intensity  $Y \in [20, 110]$  of the sound it produces.
- (\*b) Assuming that no a-priori information is given about the relative frequency of grade A and grade B ducks, find a function  $g = g_{ML} : [20, 110] \mapsto \{A, B\}$  defining the maximal likelihood estimator  $\hat{U} = g(Y)$  of  $U$  given  $Y$ .
- (\*c) Assuming that no a-priori information is given about the relative frequency of grade A and grade B ducks, among all functions  $g : [20, 110] \mapsto \{A, B\}$  such that  $\mathbf{P}(B = g(Y))$  is not larger than  $1/18$  for a grade A duck, find the one ( $g = g_*$ ) that achieves the smallest  $\mathbf{P}(A = g(Y))$  for a grade B duck. What is the corresponding optimal value of  $\mathbf{P}(A = g_*(Y))$  for a grade B duck?
5. Random variables  $X, N$  are independent:  $N$  is a geometric with parameter  $p = 1 - e^{-1}$ , and  $X$  is uniformly distributed on  $[0, 1]$ . Knowing that  $X^N = e^{-12}$ , find the most likely value of  $N$ .

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<sup>2</sup>Questions marked \* rely on the material to be presented during the week of May 10-14