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# PROJECT1: PRESSURE CONTROLLER

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LEARN IN DEPTH

MASTERING EMBEDDED SYSTEM ONLINE DIPLOMA

Eng. Keroles

# Embedded System Architecting/Design Sequence

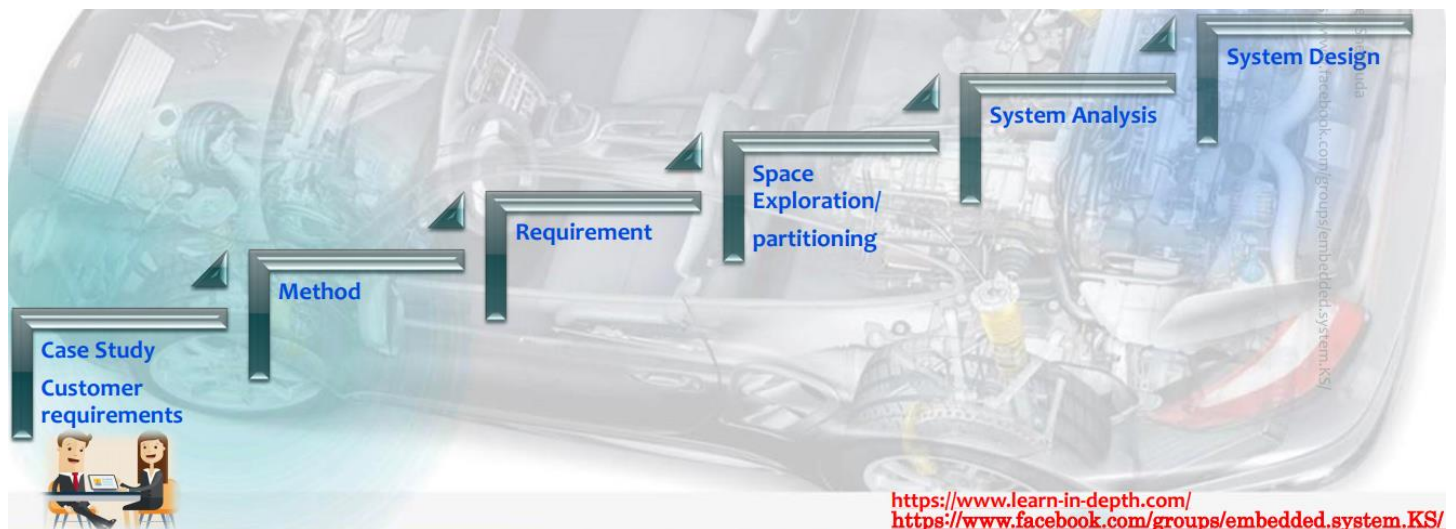
## 1. Case Study

A "client" expects you to deliver the software of the following system:

- ▶ Specification (from the client)
- ▶ A **pressure controller** informs the crew of a cabin with an alarm **when the pressure exceeds 20 bars in the cabin**
- ▶ The **alarm duration** equals 60 seconds.

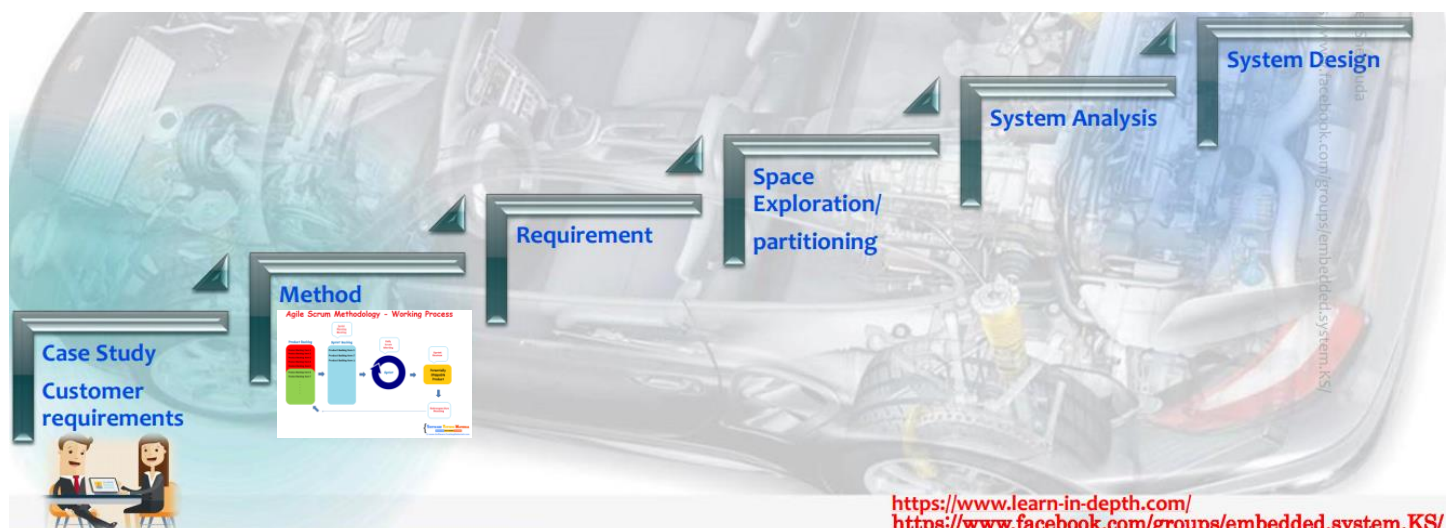


- ▶ Pressure Controller: Assumptions
- ▶ The controller set up and shutdown procedures are not modeled
- ▶ The controller maintenance is not modeled
- ▶ The pressure sensor never fails
- ▶ The alarm never fails
- ▶ The controller never faces power cut



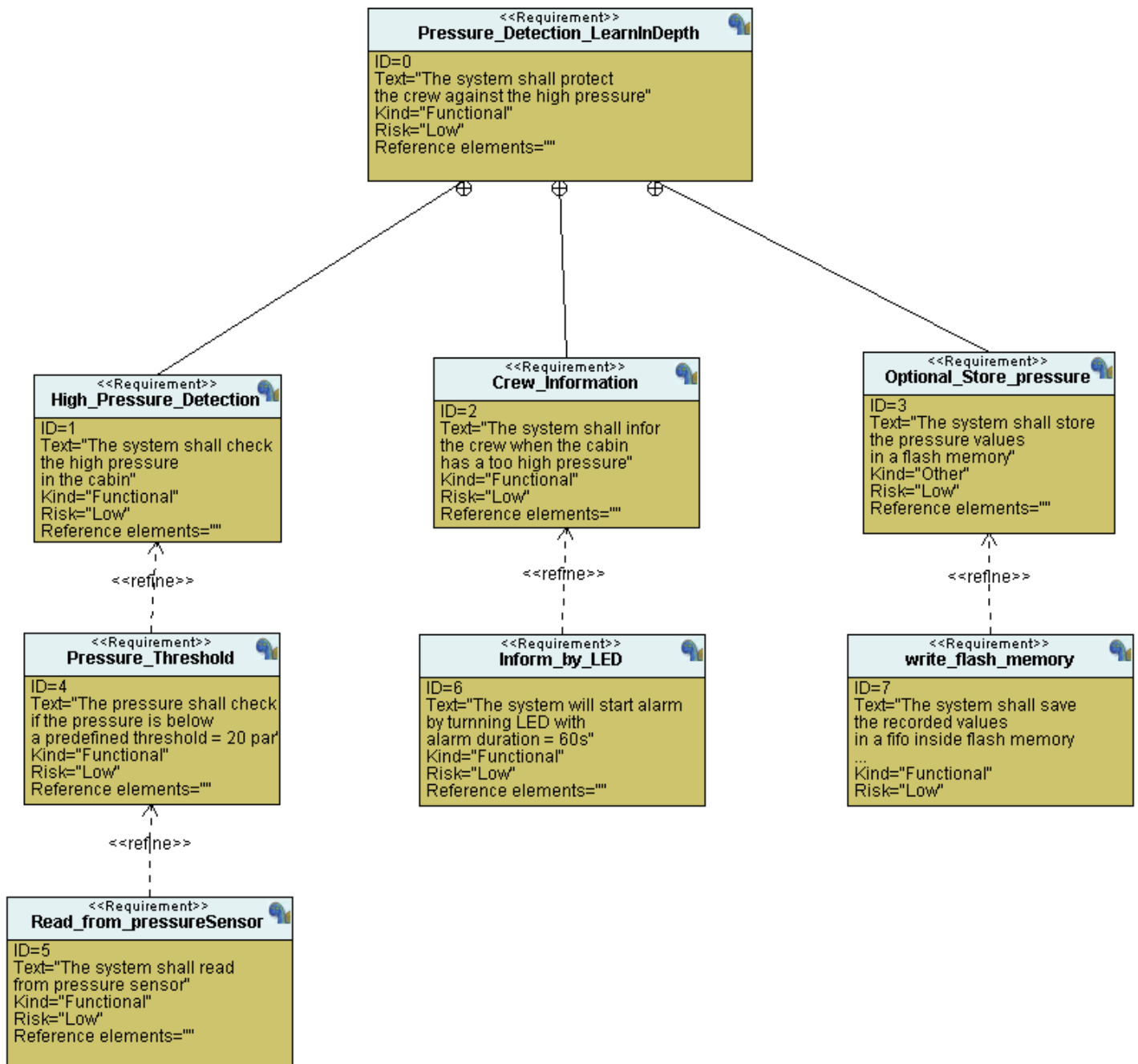
## 2. Method

I choose the Agile Scrum methodology to work with my project



### 3. Requirements

Here are the requirements in the project



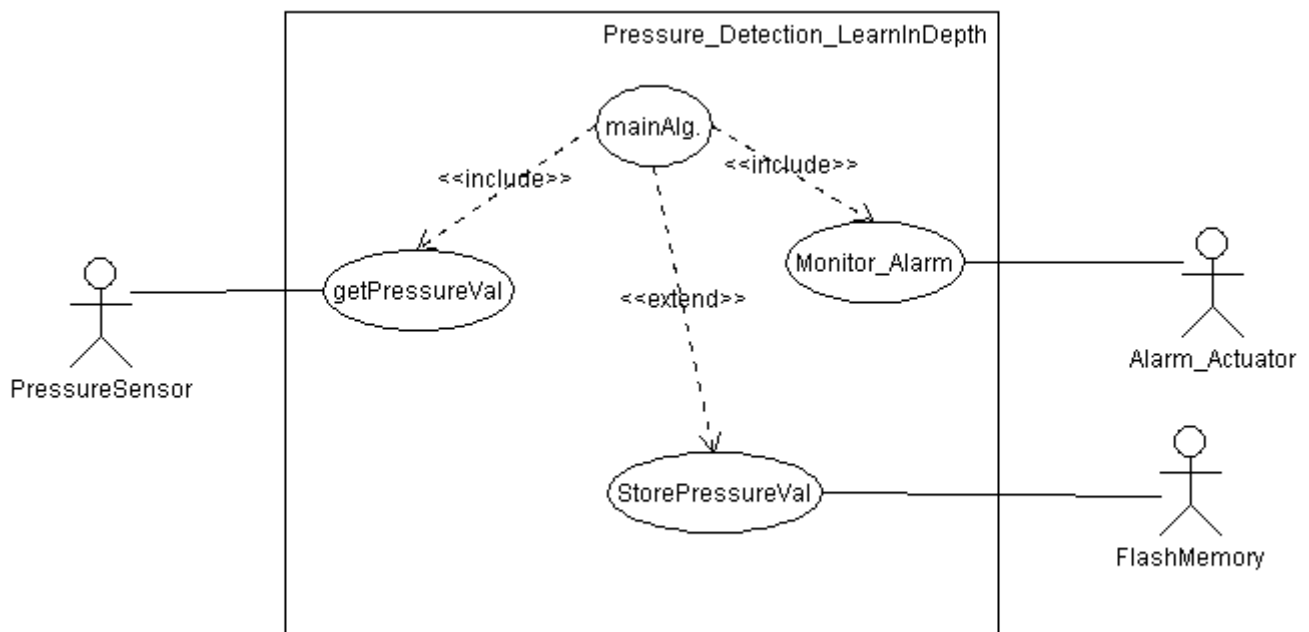
#### 4. Space Exploration/partitioning

After some search I found that the best MC that fit my project is STM32F103



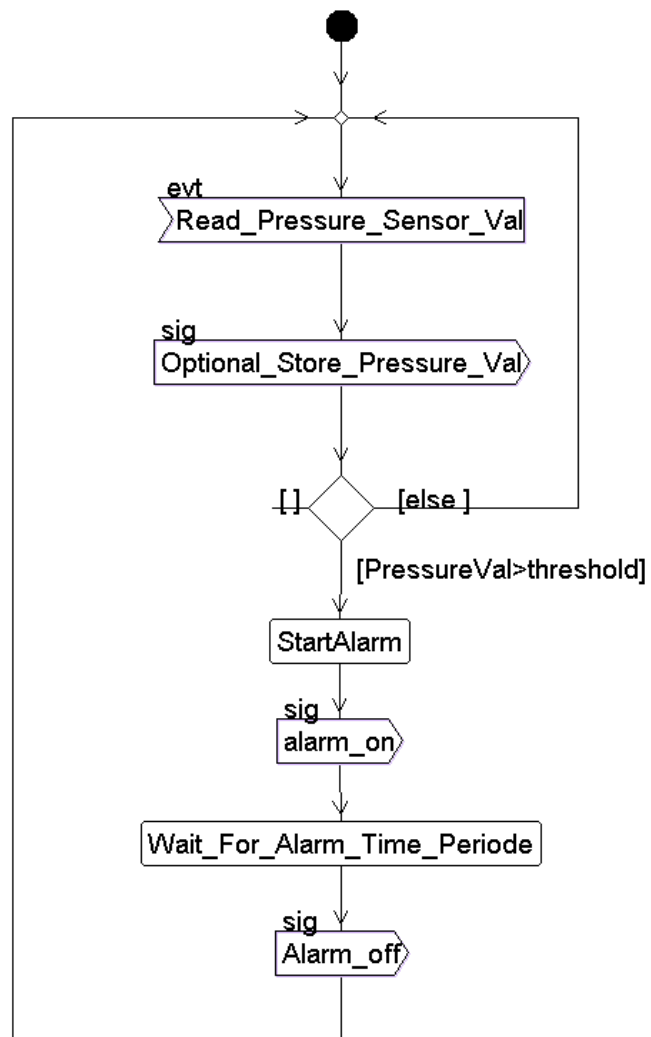
#### 5. System Analysis

##### a. UML:Use Case Diagram



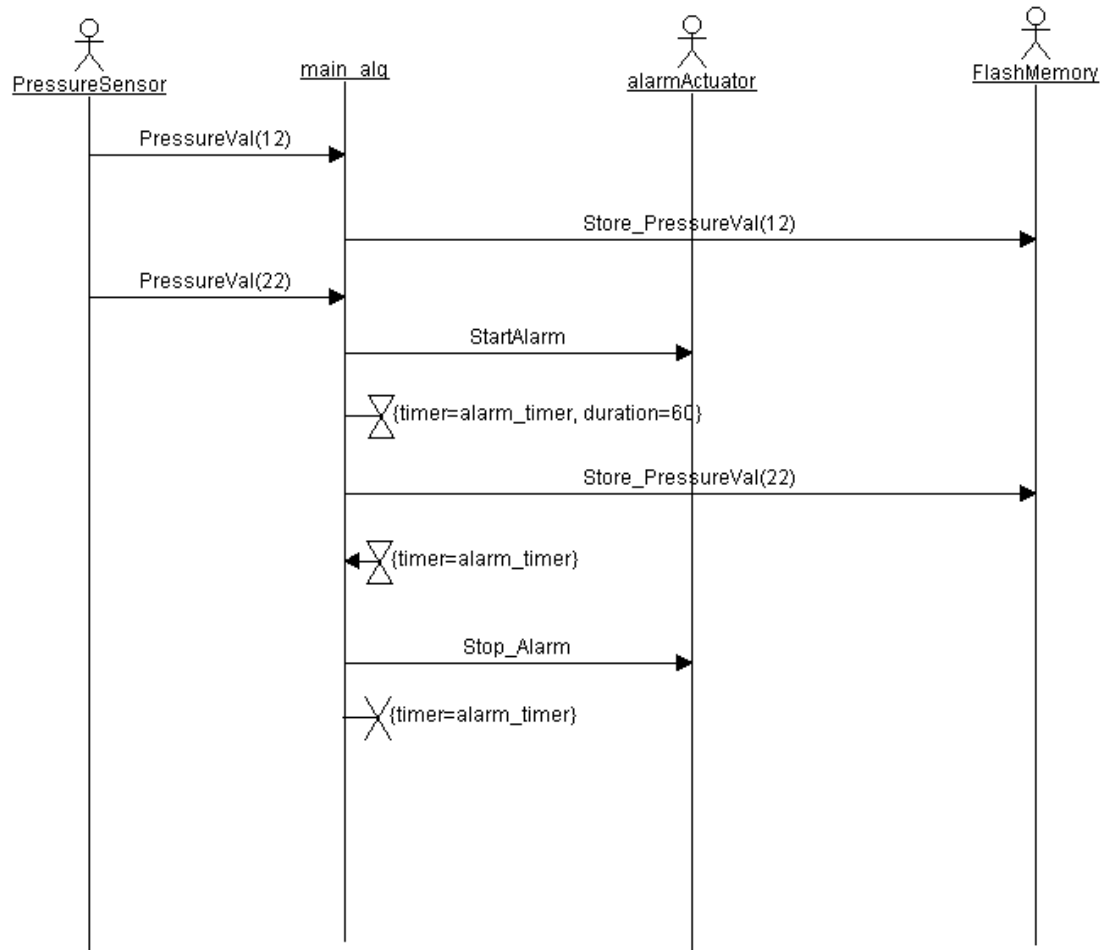
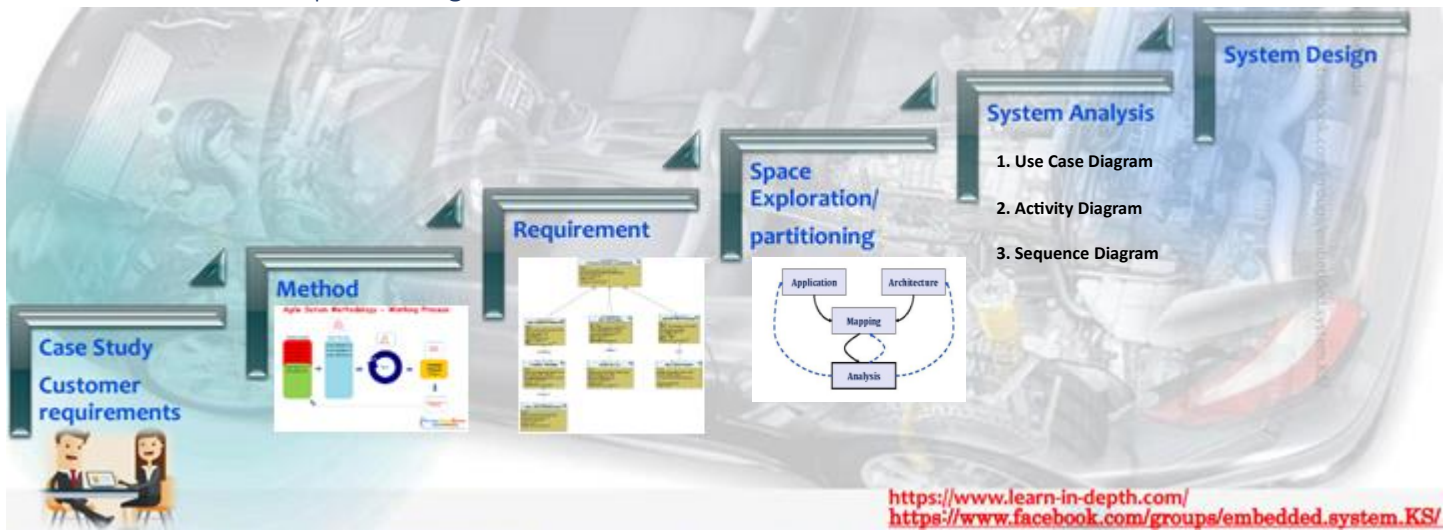


b. UML: Activity Diagram



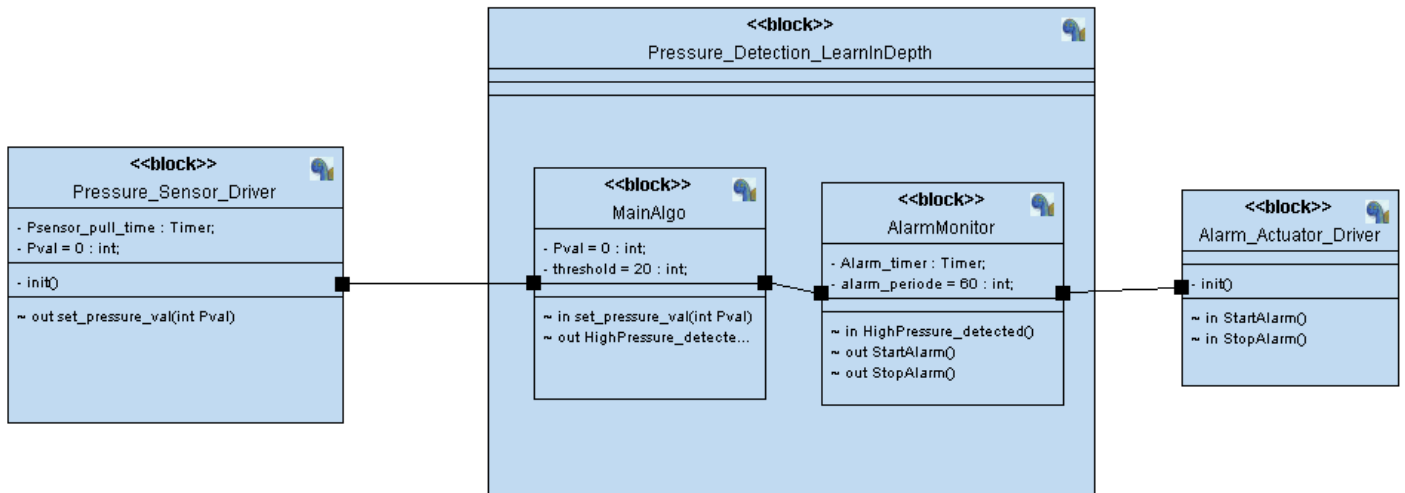


## c. UML: Sequence Diagram

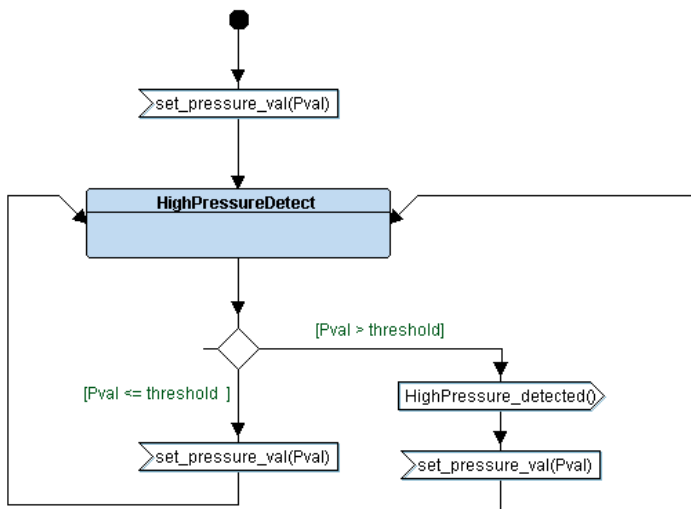


## 6. System Design

### a. Block Diagram of the system



### b. Main Algorithm



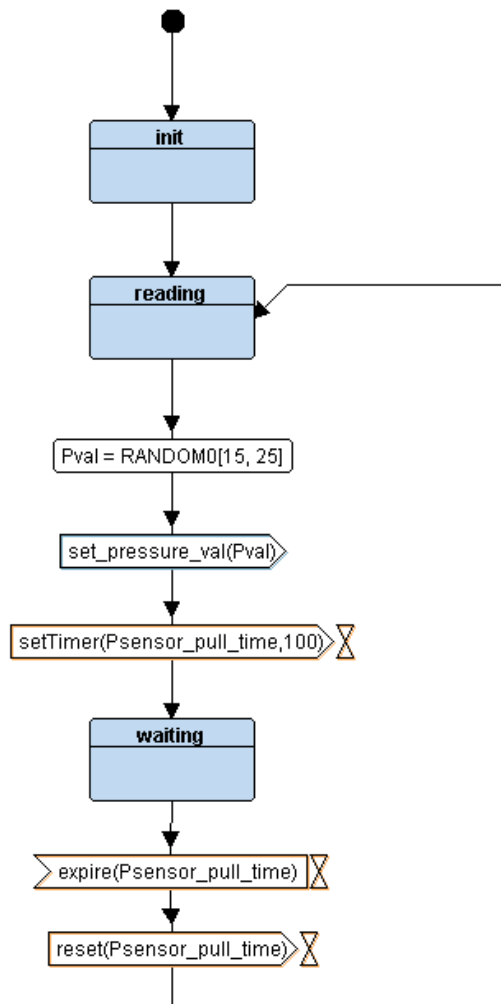
```

C MainAlgo.c U X
C MainAlgo.c > ...
1  #include <stdint.h>
2  #include <stdio.h>
3  #include "MainAlgo.h"
4  #include "AlarmMonitor.h"
5  #include "driver.h"
6  #include "PressureSensor.h"
7  int threshold = 20;
8  int Pval;
9  void init(void)
10 {
11     GPIO_INITIALIZATION();
12     StopAlarm();
13 }
14
15 void app(void)
16 {
17     Pval = getPressureVal();
18     Delay(1100000); // delay between each reading
19     if (HighPressureDetected())
20     {
21         StartAlarm();
22         Delay(1000000); // delay to set alarm
23         StopAlarm();
24     }
25 }
26

```

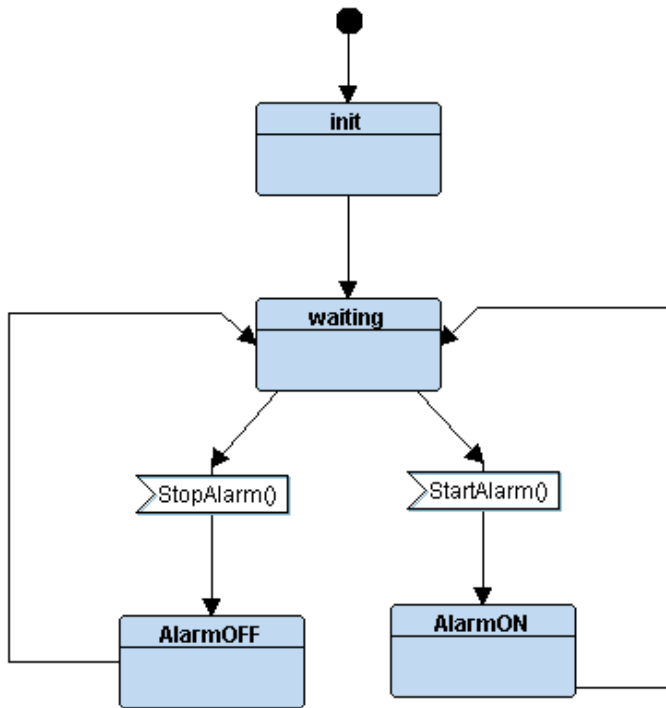


c. Pressure Sensor Driver



```
C PressureSensor.c U X
C PressureSensor.c > ...
1  #include "PressureSensor.h"
2  extern threshold;
3  extern Pval;
4  int HighPressureDetected(void)
5  {
6      Pval = getPressureVal();
7      if (Pval > threshold)
8          return 1;
9      else
10         return 0;
11 }
12
```

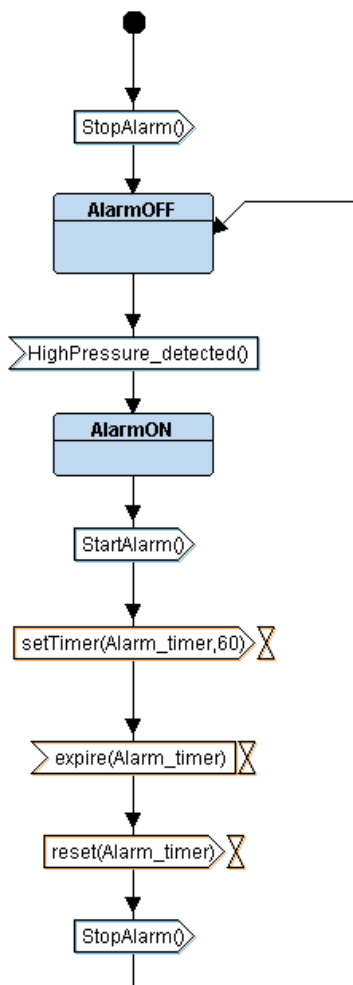
#### d. Alarm Monitor



```

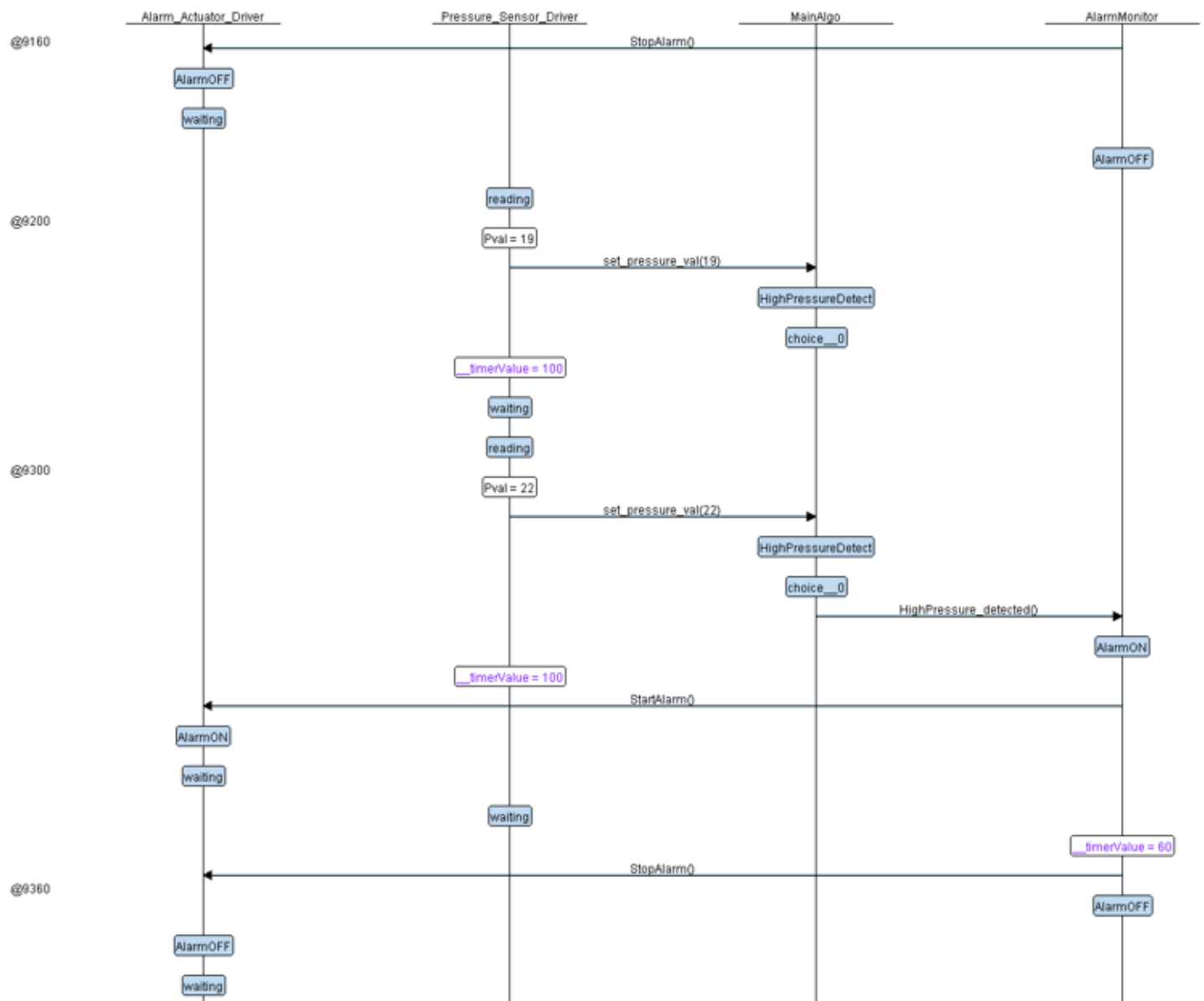
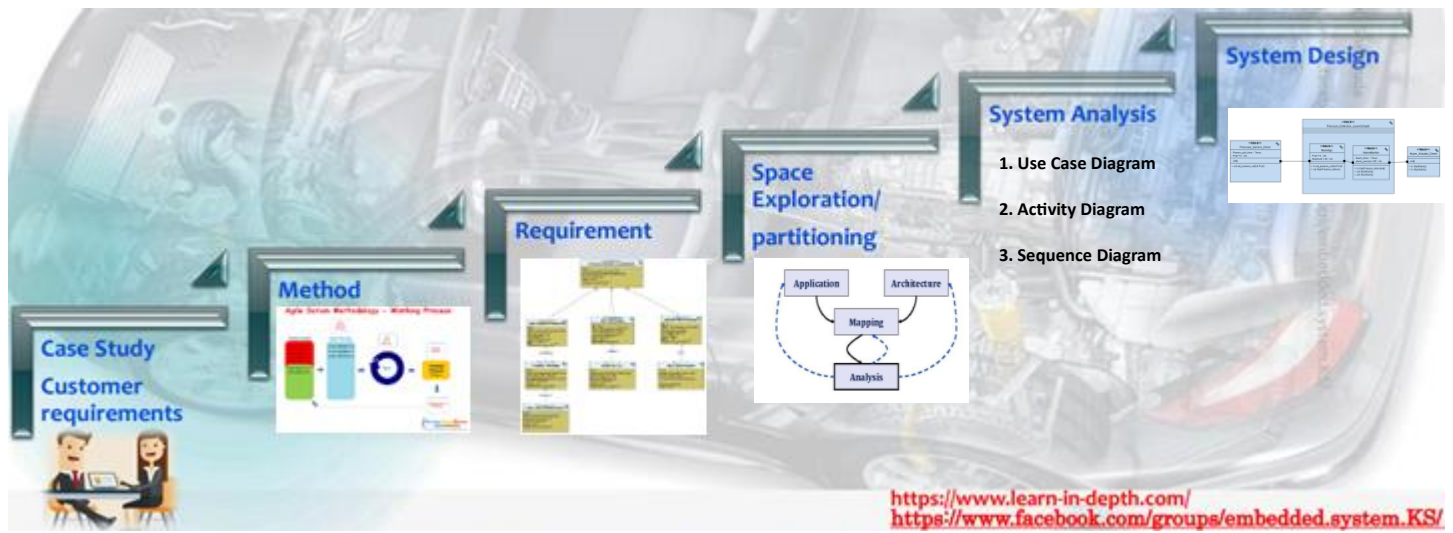
C AlarmMonitor.c U X
C AlarmMonitor.c > StopAlarm(void)
1  #include "AlarmMonitor.h"
2
3  void StartAlarm(void)
4  {
5      Set_Alarm_actuator(0);
6  }
7  void StopAlarm(void)
8  {
9      Set_Alarm_actuator(1);
10 }
  
```

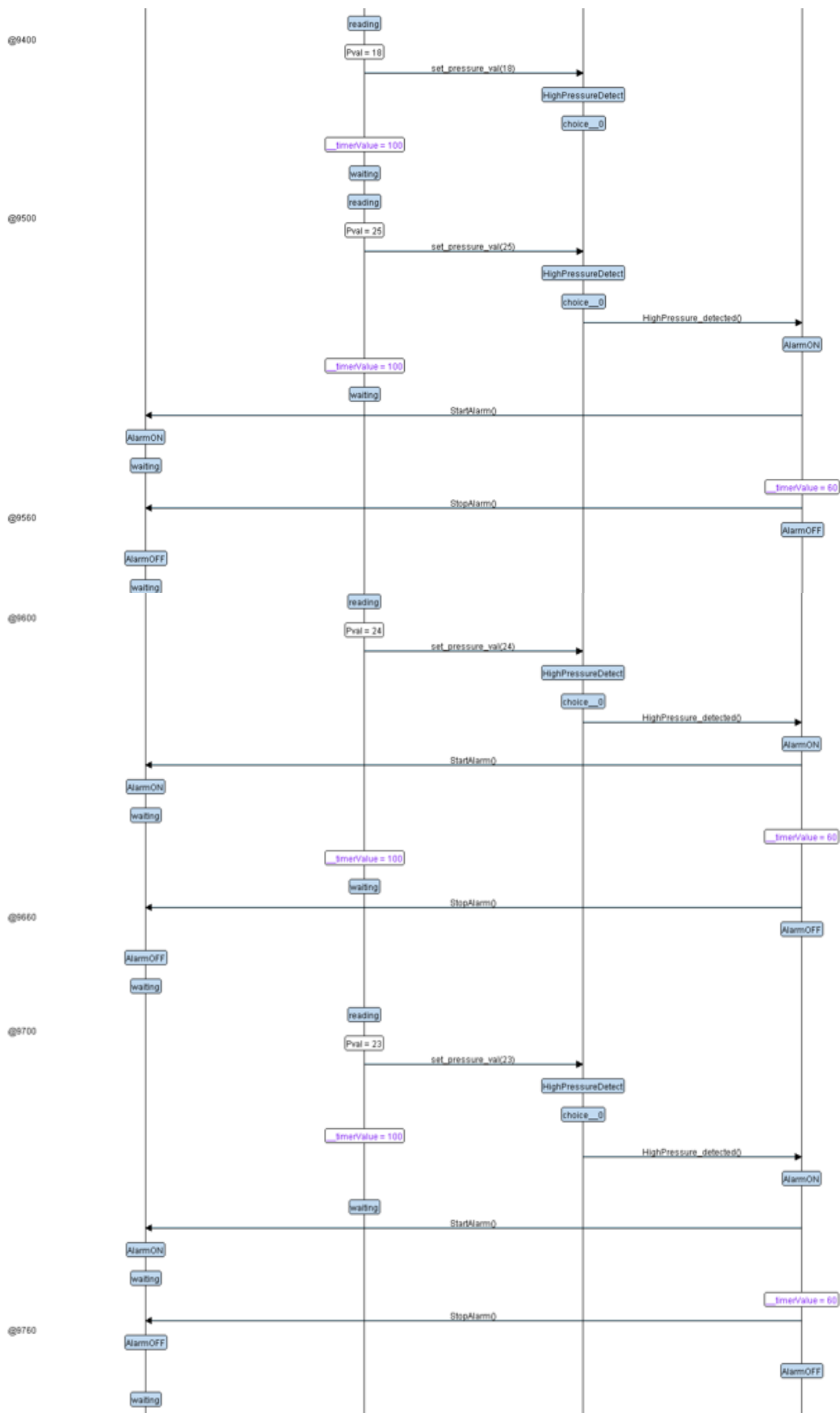
#### e. Alarm Actuator Driver



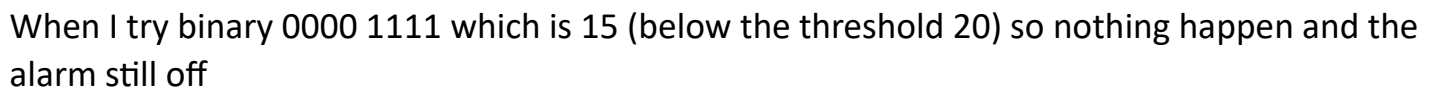
```

C AlarmMonitor.c U X
C AlarmMonitor.c > StopAlarm(void)
1  #include "AlarmMonitor.h"
2
3  void StartAlarm(void)
4  {
5      Set_Alarm_actuator(0);
6  }
7  void StopAlarm(void)
8  {
9      Set_Alarm_actuator(1);
10 }
  
```

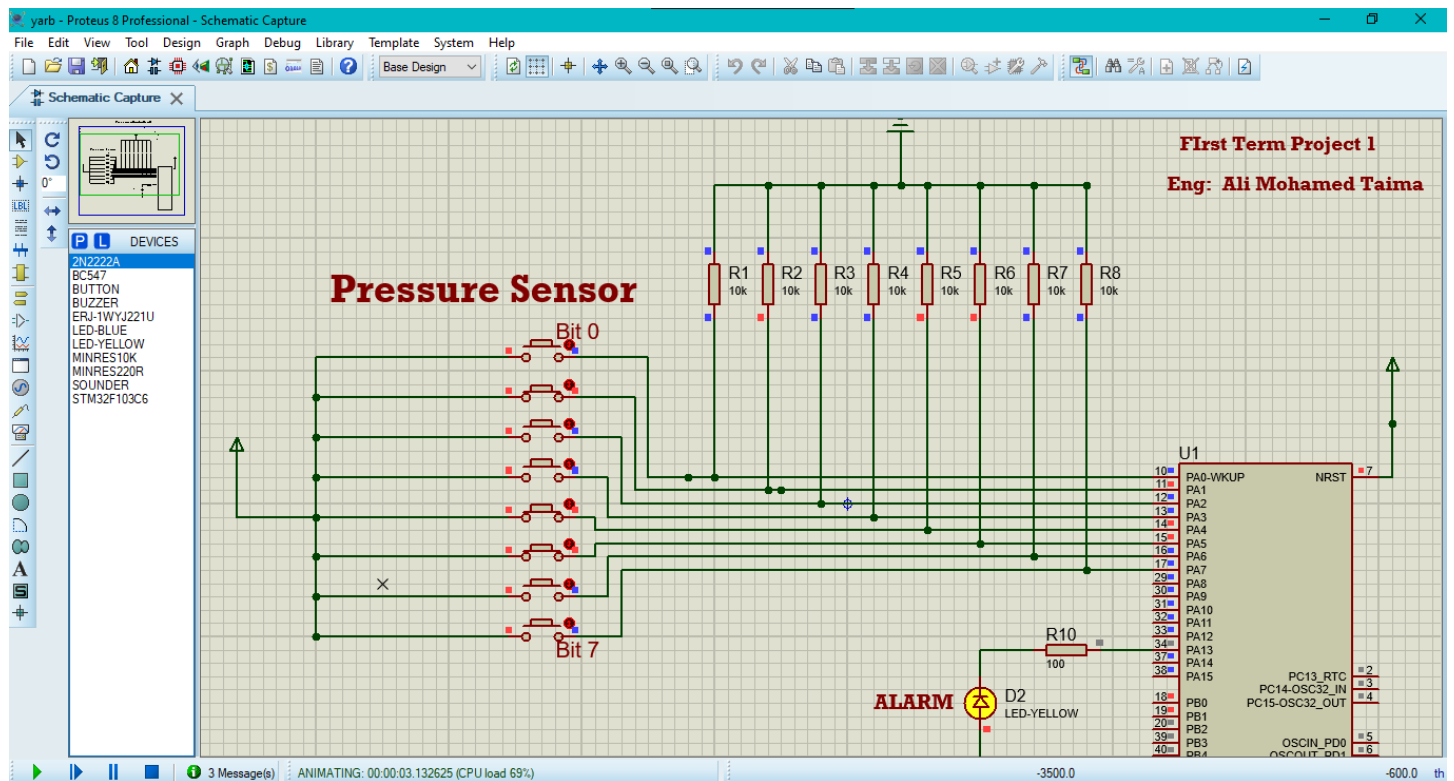




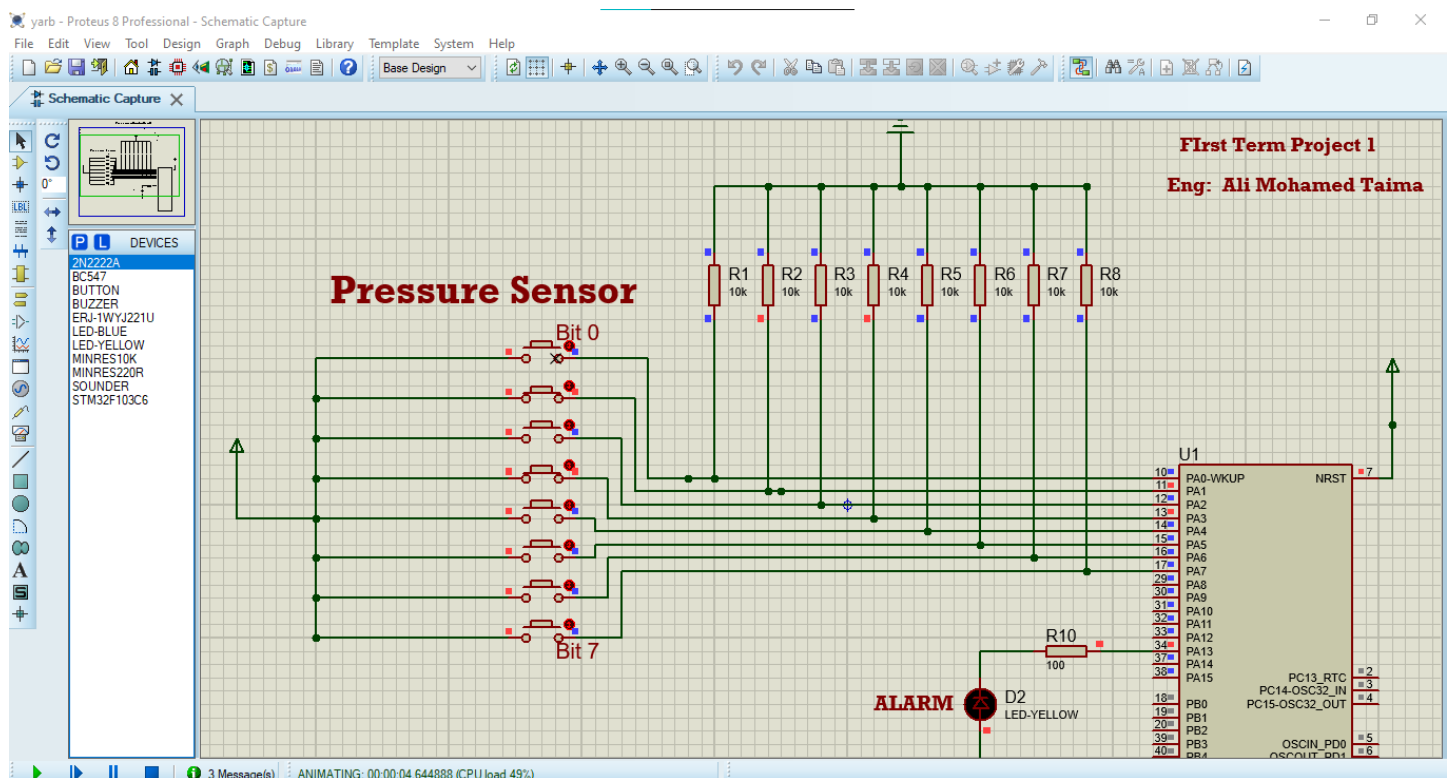
For binary 0001 0101 which is 21 and make High pressure detected the so the alarm get on for 60 seconds



For binary 0011 0010 which is 50 and make High pressure detected the so the alarm get on for 60 seconds



When I try binary 0000 1010 which is 10 (below the threshold 20) so nothing happen and the alarm still off



## SW analysis

.map file

Allocating common symbols

Common symbol	size	file
---------------	------	------

Pval	0x4	MainAlgo.o
------	-----	------------

## Memory Configuration

Name	Origin	Length	Attributes
flash	0x08000000	0x00020000	xr
sram	0x20000000	0x00005000	xrw
*default*	0x00000000	0xffffffff	

As I write in the linker file the memory initialized

```
MEMORY
{
    flash(RX) : ORIGIN = 0x08000000, LENGTH = 128K
    sram(RWX) : ORIGIN = 0x20000000, LENGTH = 20K
}
```

## Linker script and memory map

<u>.text</u>	0x08000000	0x2a0
*(.vectors*)		
.vectors	0x08000000	0x1c startup.o
	0x08000000	vectors
*(.text*)		
.text	0x0800001c	0xbc startup.o
	0x0800001c	NMI_Handler
	0x0800001c	Bus_Fault_Handler
	0x0800001c	Usage_Fault_Handler
	0x0800001c	Default_Handler

I compine the different sections with each other as in my linker

.text section

```
SECTIONS
{
    .text : {
        *(.vectors*)
        *(.text*)
        *(.rodata)
        _E_text = .;
    } > flash
```



	0x0800001c	H_fault_Handler	
	0x0800001c	NM_Fault_Handler	
	0x08000028	Reset_Handler	
.text	0x080000d8	0x10 main.o	
	0x080000d8	main	
.text	0x080000e8	0x3c PressureSensor.o	
	0x080000e8	HighPressureDetected	
.text	0x08000124	0x50 MainAlgo.o	
	0x08000124	init	
	0x08000134	app	
.text	0x08000174	0x10c driver.o	
	0x08000174	Delay	
	0x08000198	getPressureVal	
	0x080001b0	Set_Alarm_actuator	
	0x08000200	GPIO_INITIALIZATION	
.text	0x08000280	0x20 AlarmMonitor.o	
	0x08000280	StartAlarm	
	0x08000290	StopAlarm	
<b>*(.rodata)</b>			
	0x080002a0	<b><u>E_text</u> = .</b>	
.glue_7	0x080002a0	0x0	
.glue_7	0x00000000	0x0 linker stubs	
.glue_7t	0x080002a0	0x0	
.glue_7t	0x00000000	0x0 linker stubs	
.vfp11_veneer	0x080002a0	0x0	
.vfp11_veneer	0x00000000	0x0 linker stubs	

Cont.  
.text section

.v4_bx	0x080002a0	0x0
.v4_bx	0x00000000	0x0 linker stubs

.iplt	0x080002a0	0x0
.iplt	0x00000000	0x0 startup.o

.rel.dyn	0x080002a0	0x0
.rel.iplt	0x00000000	0x0 startup.o

<b><u>.data</u></b>	0x20000000	0x4 load address 0x080002a0
---------------------	------------	-----------------------------

0x20000000	<b><u>_S_DATA = .</u></b>
------------	---------------------------

**\*(.data)**

.data	0x20000000	0x0 startup.o
.data	0x20000000	0x0 main.o
.data	0x20000000	0x0 PressureSensor.o
.data	0x20000000	0x4 MainAlgo.o
	0x20000000	threshold
.data	0x20000004	0x0 driver.o
.data	0x20000004	0x0 AlarmMonitor.o
	0x20000004	<b><u>_E_DATA = .</u></b>

.data section

```
.data : {
    _S_DATA = .;
    *(.data)
    _E_DATA = .;
} > sram AT> flash
```

.igot.plt	0x20000004	0x0 load address 0x080002a4
.igot.plt	0x00000000	0x0 startup.o

<b><u>.bss</u></b>	0x20000004	0x1004 load address 0x080002a4
--------------------	------------	--------------------------------

0x20000004	<b><u>_S_bss = .</u></b>
------------	--------------------------

**\*(.bss)**

.bss	0x20000004	0x0 startup.o
------	------------	---------------

```
.bss : {
    _S_bss = .;
    *(.bss)
    . = ALIGN(4);
    _E_bss = .;

    . = ALIGN(4);
    . = . + 0x1000;
    stack_top = .;
}
```

.bss	0x20000004	0x0 main.o	
.bss	0x20000004	0x0 PressureSensor.o	
.bss	0x20000004	0x0 MainAlgo.o	.bss section
.bss	0x20000004	0x0 driver.o	
.bss	0x20000004	0x0 AlarmMonitor.o	
	0x20000004	. = ALIGN (0x4)	
	0x20000004	_E_bss = .	
	0x20000004	. = ALIGN (0x4)	
	0x20001004	. = (. + 0x1000)	
*fill*	0x20000004	0x1000	
	0x20001004	_stack_top = .	Stack top
COMMON	0x20001004	0x4 MainAlgo.o	
	0x20001004	Pval	

LOAD startup.o

LOAD main.o

LOAD PressureSensor.o

LOAD MainAlgo.o

LOAD driver.o

LOAD AlarmMonitor.o

OUTPUT(Project1\_pressure\_controller.elf elf32-littlearm)

.debug_info	0x00000000	0x496
.debug_info	0x00000000	0x168 startup.o
.debug_info	0x00000168	0x46 main.o
.debug_info	0x000001ae	0x75 PressureSensor.o
.debug_info	0x00000223	0xca MainAlgo.o
.debug_info	0x000002ed	0x103 driver.o
.debug_info	0x000003f0	0xa6 AlarmMonitor.o
.debug_abbrev	0x00000000	0x2a5
.debug_abbrev	0x00000000	0xc2 startup.o
.debug_abbrev	0x000000c2	0x37 main.o
.debug_abbrev	0x000000f9	0x62 PressureSensor.o
.debug_abbrev	0x0000015b	0x6b MainAlgo.o
.debug_abbrev	0x000001c6	0x9d driver.o
.debug_abbrev	0x00000263	0x42 AlarmMonitor.o

```
.debug_loc 0x00000000 0x234
.debug_loc 0x00000000 0x64 startup.o
.debug_loc 0x00000064 0x2c main.o
.debug_loc 0x00000090 0x2c PressureSensor.o
.debug_loc 0x000000bc 0x58 MainAlgo.o
.debug_loc 0x00000114 0xc8 driver.o
.debug_loc 0x000001dc 0x58 AlarmMonitor.o
```

```
.debug_aranges 0x00000000 0xc0
.debug_aranges
    0x00000000 0x20 startup.o
.debug_aranges
    0x00000020 0x20 main.o
.debug_aranges
    0x00000040 0x20 PressureSensor.o
.debug_aranges
    0x00000060 0x20 MainAlgo.o
.debug_aranges
    0x00000080 0x20 driver.o
.debug_aranges
    0x000000a0 0x20 AlarmMonitor.o
```

```
.debug_line 0x00000000 0x24e
.debug_line 0x00000000 0xad startup.o
.debug_line 0x000000ad 0x3f main.o
.debug_line 0x000000ec 0x43 PressureSensor.o
.debug_line 0x0000012f 0x45 MainAlgo.o
.debug_line 0x00000174 0x99 driver.o
.debug_line 0x0000020d 0x41 AlarmMonitor.o
```

```
.debug_str 0x00000000 0x1fc
.debug_str 0x00000000 0x13b startup.o
    0x16f (size before relaxing)
.debug_str 0x0000013b 0xc main.o
    0x65 (size before relaxing)
.debug_str 0x00000147 0x44 PressureSensor.o
    0x9d (size before relaxing)
.debug_str 0x0000018b 0x10 MainAlgo.o
    0x10a (size before relaxing)
.debug_str 0x0000019b 0x3d driver.o
    0x140 (size before relaxing)
```

```
.debug_str 0x000001d8 0x24 AlarmMonitor.o
           0x10f (size before relaxing)

.comment 0x00000000 0x11
.comment 0x00000000 0x11 startup.o
           0x12 (size before relaxing)
.comment 0x00000000 0x12 main.o
.comment 0x00000000 0x12 PressureSensor.o
.comment 0x00000000 0x12 MainAlgo.o
.comment 0x00000000 0x12 driver.o
.comment 0x00000000 0x12 AlarmMonitor.o
```

```
.ARM.attributes
           0x00000000 0x33

.ARM.attributes
           0x00000000 0x33 startup.o

.ARM.attributes
           0x00000033 0x33 main.o

.ARM.attributes
           0x00000066 0x33 PressureSensor.o

.ARM.attributes
           0x00000099 0x33 MainAlgo.o

.ARM.attributes
           0x000000cc 0x33 driver.o

.ARM.attributes
           0x000000ff 0x33 AlarmMonitor.o
```

```
.debug_frame 0x00000000 0x1a8
.debug_frame 0x00000000 0x48 startup.o
.debug_frame 0x00000048 0x2c main.o
.debug_frame 0x00000074 0x2c PressureSensor.o
.debug_frame 0x000000a0 0x48 MainAlgo.o
.debug_frame 0x000000e8 0x78 driver.o
.debug_frame 0x00000160 0x48 AlarmMonitor.o
```