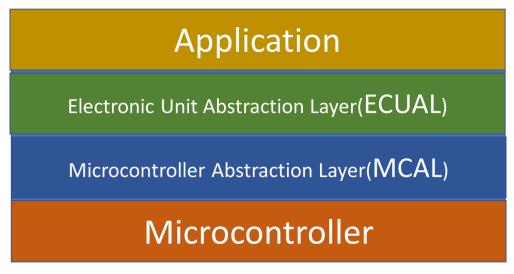
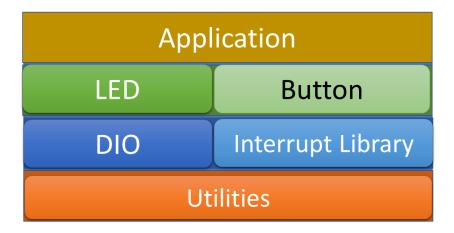
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Drivers in each layer

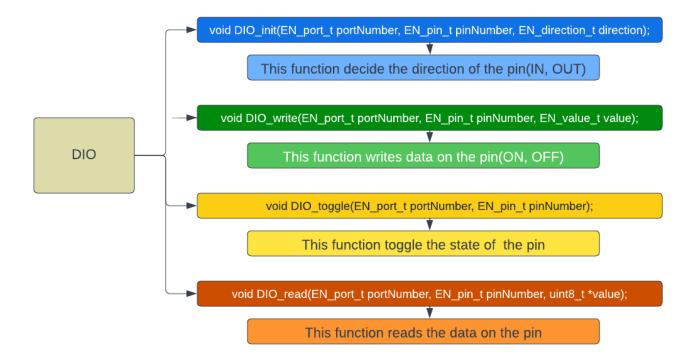


system description

Microcontroller layer

Utilities Driver

- This driver contains mainly two header files(registers.h, types.h)
 - o registers.h
 - i/o registers(PORTA, PORTB, PORTC, PORTD)
 - timer0 registers
 - external interrupts registers
 - o types.h
 - Defines important data types

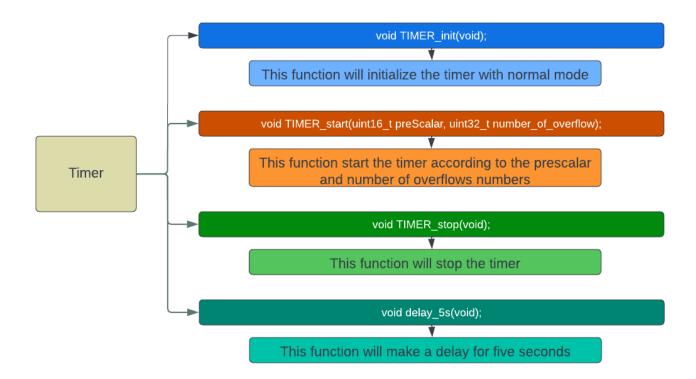


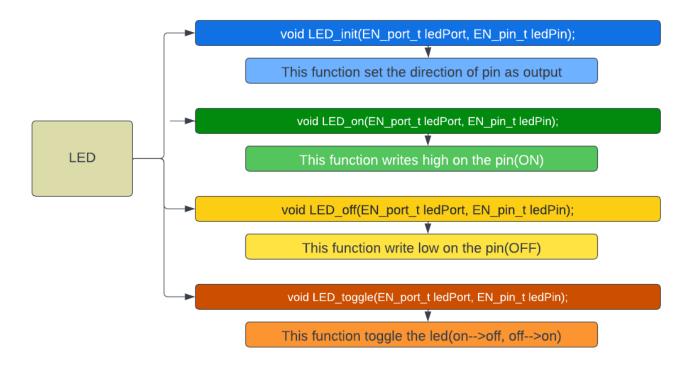
- Has helpful macros to facilitate the programming
- Has enums to define the directions, pins and ports

Interrupt Library

- 1. This library defines the external interrupt vectors, macros to set OR clear global register and ISR macro
 - o Make function to initialize the interrupt

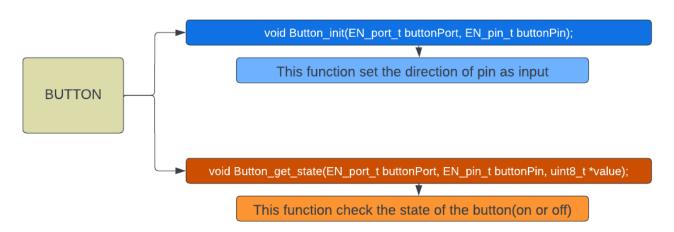
Timer Driver



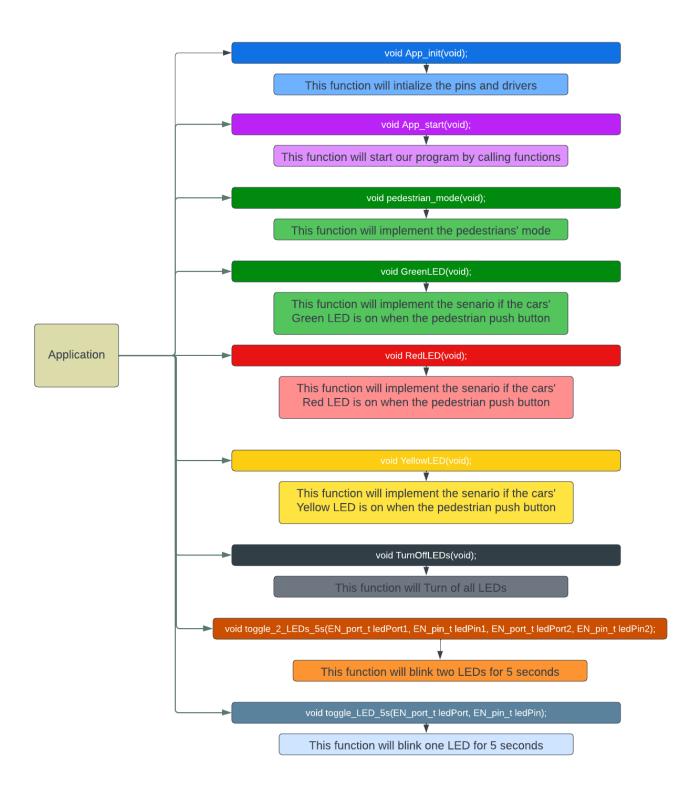


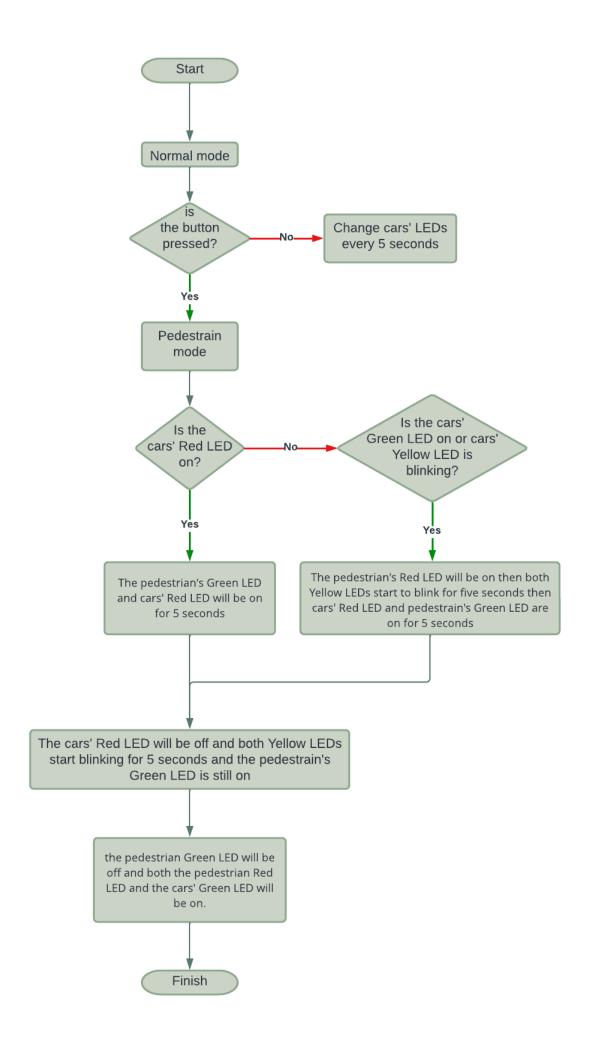
• There are helpful macros to facilitate the program

BUTTON Driver



• There are helpful macros to facilitate the program





Description

- 1. Checking the mode(Normal, Pedstrians)
- 2. Assuming Normal mode
 - 1. turn off all LEDs, to prevent the errors if it return from the pedestrain's mode
 - 2. turn on cars' Red LED and the pedestrian's Green LED
 - check if the user push the button during this duration or not, to call the pedestrian's mode
 - 3. blink cars' Yellow LED and turn on the pedestrians' Red LED
 - check if the user push the button during this duration or not, to call the pedestrian's mode
 - 4. Trun on cars' Green LED and blink the pedestrians' Yellow LED
- 3. Assuming Pedestrians' mode
 - 1. check the color of cars' LED when the pedestrian push the button
 - 2. implement the mode according to the cars' LED color
 - 3. continue the pedestrain mode until led cars pass
 - 1. turn off cars' Red LED
 - 2. blink cars' Yellow LED and pedestrians' Yellow LED for 5 s
 - 3. Turn off Pedestrian's Yellow and Green LEDs and cars' Yellow LED
 - 4. Turn on cars' Red LED and the pedestrian's Green LED, to let cars pass
 - After finishing the pedestrian mode the normal mode will be run