

Concordia University
Department of Computer Science and Software
Engineering
SOEN 331:
Formal Methods for Software Engineering

Exercise in Z

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Temperature monitoring system with the Z specification

Consider a system called 'TempMonitor' that keeps a number of sensors, where each sensor is deployed in a separate location in order to read the location's temperature. Before the system is deployed, all locations are marked on a map, and each location will be addressed by a sensor. The formal specification of the system introduces the following three types:

SENSOR_TYPE, LOCATION_TYPE, TEMPERATURE_TYPE

We also introduce an enumerated type *MESSAGE* which will assume values that correspond to success and error messages.

Provide a formal specification in Z, with the following operations:

- **DeploySensorOK**: Places a new sensor to a unique location. You may assume that some (default) temperature is also passed as an argument.
- **ReadTemperatureOK**: Obtain the temperature reading from a sensor, given the sensor's location.

Provide appropriate success and error schemata to be combined with the definitions above to produce robust specifications for the following interface:

- **DeploySensor**,
- **ReadTemperature**.

Solution:

TempMonitor

$deployed' : \mathbb{P} \text{ SENSOR_TYPE}$ $map : \text{SENSOR_TYPE} \rightarrow \text{LOCATION_TYPE} \quad \text{--partial bijective}$ $read : \text{SENSOR_TYPE} \rightarrow \text{TEMPERATURE_TYPE}$
$deployed = \text{dom } map$ $deployed = \text{dom } read$

DeploySensorOK

$\Delta \text{TempMonitor}$ $sensor? : \text{SENSOR_TYPE}$ $location? : \text{LOCATION_TYPE}$ $temperature? : \text{TEMPERATURE_TYPE}$
$sensor? \notin deployed$ $location? \notin \text{ran } map$ $deployed' = deployed \cup \{sensor?\}$ $map' = map \cup \{sensor? \mapsto location?\}$ $read' = read \cup \{sensor? \mapsto temperature?\}$

ReadTemperatureOK

$\exists \text{TempMonitor}$ $location? : \text{LOCATION_TYPE}$ $temperature! : \text{TEMPERATURE_TYPE}$
$location? \in \text{ran } map$ $temperature! = read(map^{-1}(location?))$

Success

$\exists \text{TempMonitor}$ $response! : \text{MESSAGE}$
$response! = 'ok'$

$\text{SensorAlreadyDeployed}$
$\exists \text{TempMonitor}$ $\text{sensor?} : \text{SENSOR_TYPE}$ $\text{response!} : \text{Message}$
$\text{sensor?} \in \text{deployed}$ $\text{response!} = \text{'Sensor deployed'}$

$\text{LocationAlreadyCovered}$
$\exists \text{TempMonitor}$ $\text{location?} : \text{LOCATION_TYPE}$ $\text{response!} : \text{Message}$
$\text{location?} \in \text{ran map}$ $\text{response!} = \text{'Location already covered'}$

LocationUnknown
$\exists \text{TempMonitor}$ $\text{location?} : \text{LOCATION_TYPE}$ $\text{response!} : \text{Message}$
$\text{location?} \notin \text{ran map}$ $\text{response!} = \text{'Location not covered'}$

$$\text{DeploySensor} \hat{=} (\text{DeploySensorOK} \wedge \text{Success}) \oplus (\text{SensorAlreadyDeployed} \vee \text{LocationAlreadyCovered})$$

$$\text{ReadTemperature} \hat{=} (\text{ReadTemperatureOK} \wedge \text{Success}) \oplus \text{LocationUnknown}$$