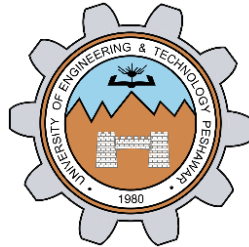


# **Convolution and LTI systems**

**LAB # 08**



**Spring 2023**

**CSE301L Signals & Systems Lab**

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Registration No. : **21PWCSE2059**

Class Section: **C**

“On my honor, as student of University of Engineering and Technology, I have neither given nor received unauthorized assistance on this academic work.”

Submitted to:

**Engr. Sumayyea Salahuddin**

Date:

**June 1, 2023**

**Department of Computer Systems Engineering**  
**University of Engineering and Technology, Peshawar**

### Lab Objective(s):

Objectives of this Lab are;

- Making Signals Causal and Non-Causal
- Convolution
- Properties of Convolution

### Task # 01:

Sample the signal given in above example to get its discrete-time counterpart (take 10 samples/sec as sampling rate). Make the resultant signal causal. Display the lollipop plot of each signal.

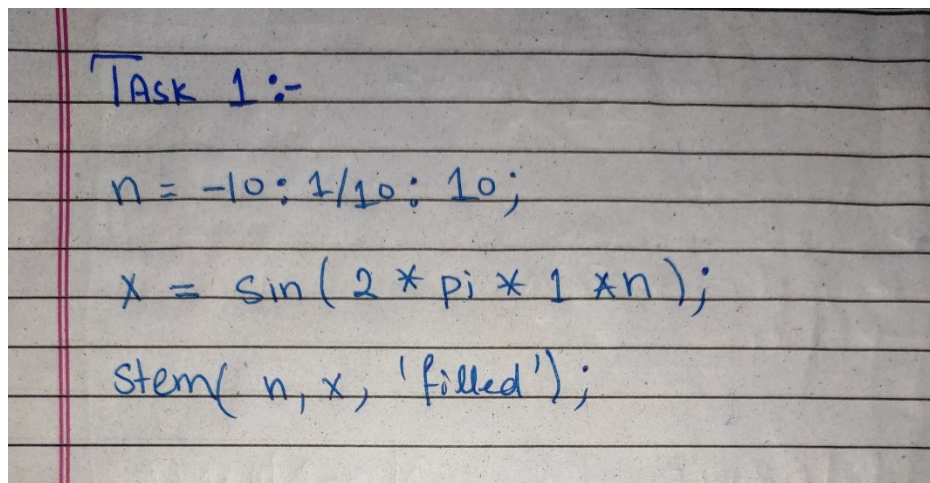
### Problem Analysis:

We can sample a signal in MATLAB.

### Algorithm:

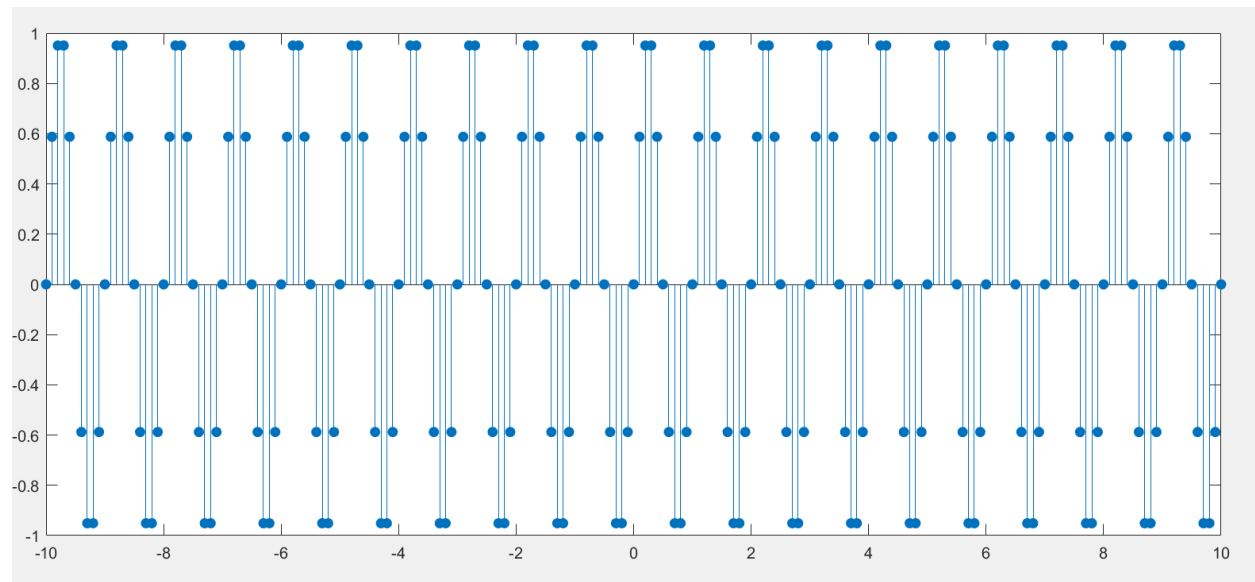
- Write the code
- Execute it
- Observe the output

### Code:



```
Task 1:-  
n = -10:1/10:10;  
x = sin(2 * pi * 1 * n);  
stem(n, x, 'filled');
```

## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can sample a signal in MATLAB.

## Task # 02:

A signal is said to be anti-causal if it exists for values of  $n < 0$ . Make the signal given in above example anti-causal.

## Problem Analysis:

We need to make an anti-causal signal in MATLAB.

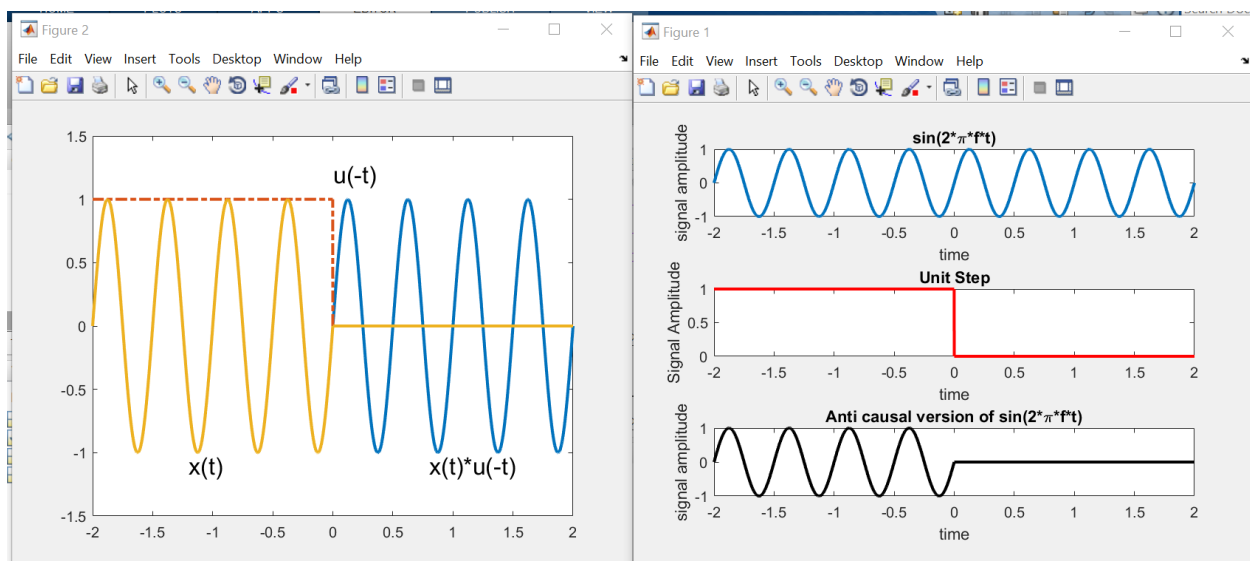
## Algorithm:

- Write the code
- Execute it
- Observe the output

Code:

```
Task 2:-  
  
t = -2: 1/1000: 2;  
x1 = sin(2*pi*2*t);  
  
subplot(3,1,1);  
plot(t, x1, 'lineWidth', 2);  
xlabel('time'); ylabel('signal amplitude');  
title('sin(2*\pi*f*t)');  
u = (t < 0);  
x2 = x1.*u;  
  
subplot(3,1,2);  
plot(t, x2, 'k', 'lineWidth', 2);  
xlabel('time'); ylabel('signal amplitude');  
title('Anti causal version of sin(2*\pi*f*t)');  
figure;  
plot(t, x1, t, x2, 'k', 'lineWidth', 2);  
text(0, 1.2, 'u(-t)', 'FontSize', 16);  
text(-1.2, -1.1, 'x(t)', 'FontSize', 16);  
text(0.8, -1.1, 'x(t)*u(-t)', 'FontSize', 16);  
axis([-2 2 -1.5 1.5]);
```

Output / Graphs / Plots / Results:



### Discussion and Conclusion:

We can make an anti-causal signal in MATLAB by using Unit Step Function.

### Task # 03:

Create a function by name of sig\_causal in matlab that has two input arguments: (i) a discrete-time signal, and (ii) a position vector. The function should make the given signal causal and return the resultant signal to the calling program.

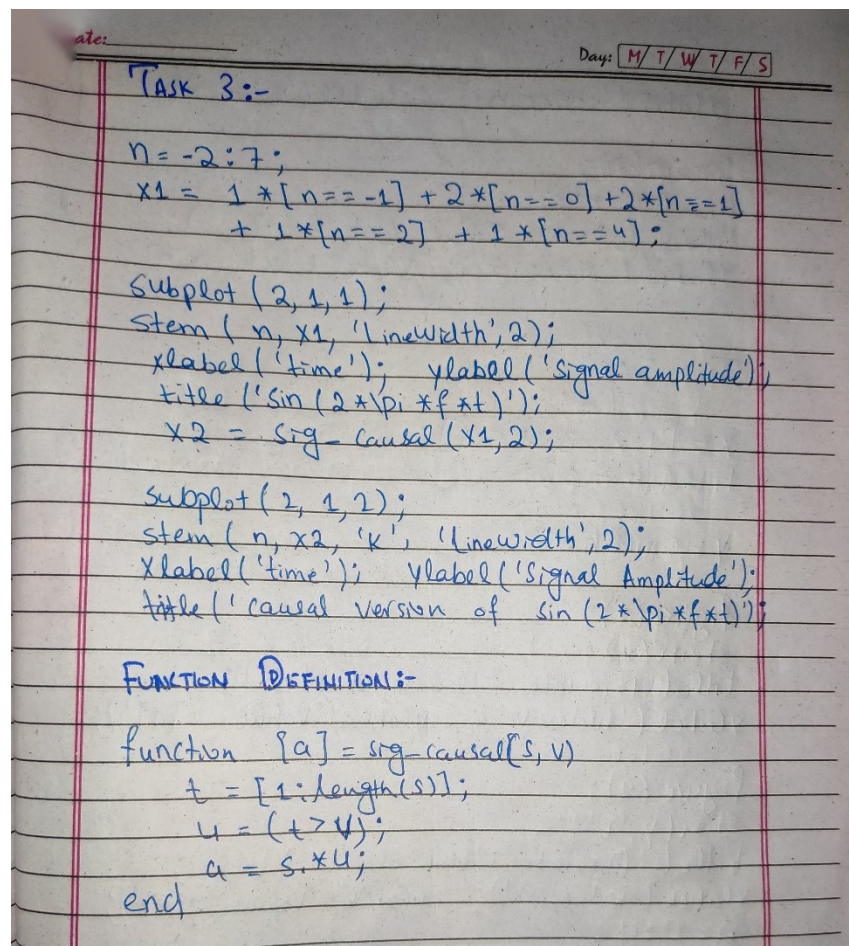
### Problem Analysis:

We can perform different operations of signals in MATLAB. Here we make a causal signal than change its causality.

### Algorithm:

- Write the code
- Execute it
- Observe the output

### Code:



```

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Task 3:-

n = -2:7;
x1 = 1*[n == -1] + 2*[n == 0] + 2*[n == 1]
      + 1*[n == 2] + 1*[n == 4];

subplot(2,1,1);
stem(n, x1, 'linewidth', 2);
xlabel('time'); ylabel('Signal amplitude');
title('sin(2*pi*f*t)');
x2 = sig_causal(x1, 2);

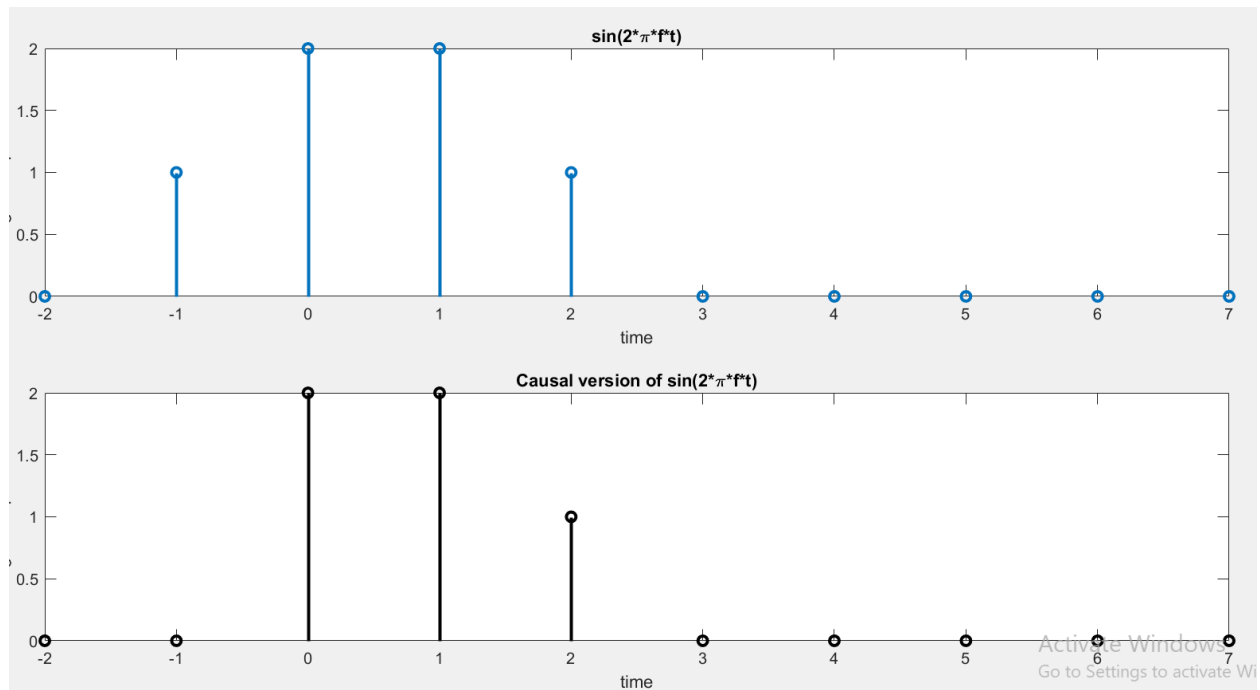
subplot(2,1,2);
stem(n, x2, 'k', 'linewidth', 2);
xlabel('time'); ylabel('Signal Amplitude');
title('causal version of sin(2*pi*f*t)');

FUNCTION DEFINITION:-

function [a] = sig_causal(s, v)
    t = [1:length(s)];
    u = (t > v);
    a = s.*u;
end

```

## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 04:

Convolve the following signals:

$x = [2 \ 4 \ 6 \ 4 \ 2];$

$h = [3 \ -1 \ 2 \ 1];$

Plot the input signal as well as the output signal.

### Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

### Algorithm:

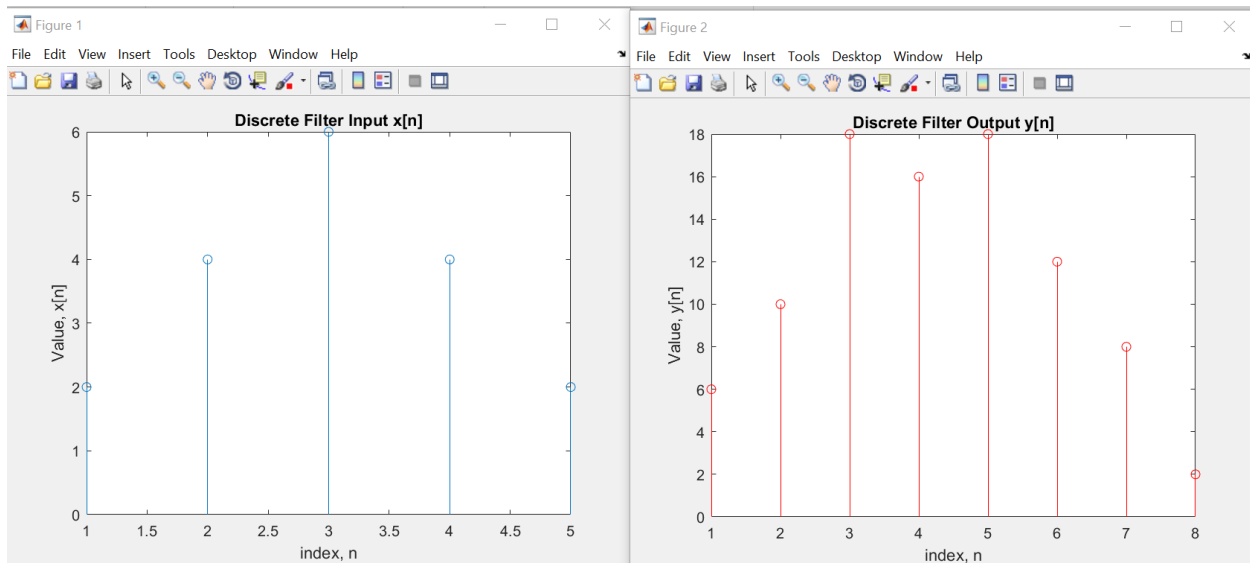
- Write the code
- Execute it
- Observe the output



## Code:

```
Task 4:-  
x=[2 4 6 4 2];  
h=[3 -1 2 1];  
y=conv(h,x);  
  
xlabel('index, n'); ylabel('value, x[n]');  
  
figure(2);  
stem(y, 'r');  
title('Discrete Filter Output y[n]');  
xlabel('index, n'); ylabel('value, y[n]');
```

## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

## Task # 05:

Convolution is associative. Given the three signal  $x1[n]$ ,  $x2[n]$ , and  $x3[n]$

As:  $x1[n] = [3 \ 1 \ 1]$

$$x2[n] = [4 \ 2 \ 1]$$

$$x3[n] = [3 \ 2 \ 1 \ 2 \ 3]$$

Show that  $(x1[n] * x2[n]) * x3[n] = x1[n] * (x2[n] * x3[n])$ .

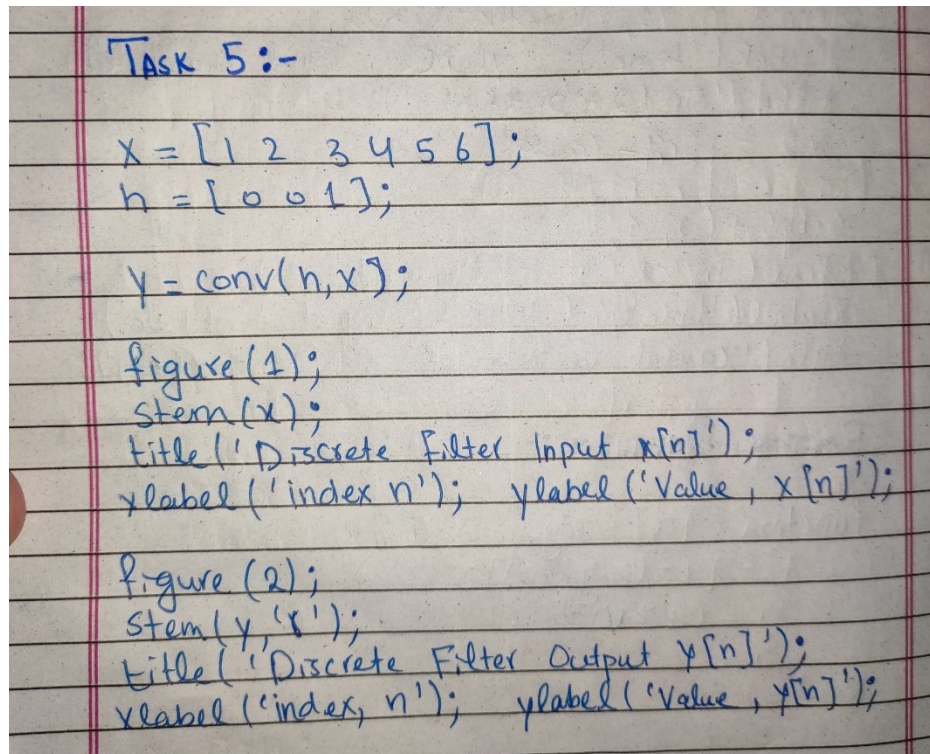
### Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

### Algorithm:

- Write the code
- Execute it
- Observe the output

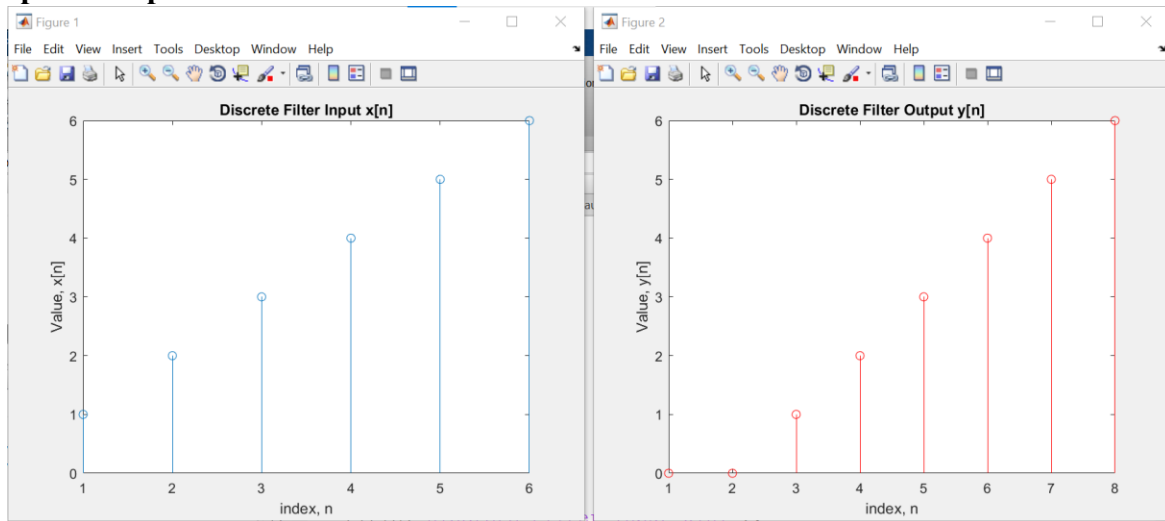
### Code:



```
Task 5:-  
  
x = [1 2 3 4 5 6];  
h = [0 0 1];  
  
y = conv(h, x);  
  
figure(1);  
stem(x);  
title('Discrete Filter Input x[n]');  
xlabel('index n'); ylabel('Value, x[n]');  
  
figure(2);  
stem(y, 'r');  
title('Discrete Filter Output y[n]');  
xlabel('index, n'); ylabel('Value, y[n]');
```



## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 06:

Convolution is associative. Given the three signal  $x1[n]$ ,  $x2[n]$ , and  $x3[n]$  as:

$$x1[n] = [3 \ 1 \ 1]$$

$$x2[n] = [4 \ 2 \ 1]$$

$$x3[n] = [3 \ 2 \ 1 \ 2 \ 3]$$

Show that  $(x1[n] * x2[n]) * x3[n] = x1[n] * (x2[n] * x3[n])$ .

## Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

## Algorithm:

- Write the code
- Execute it
- Observe the output

## Code:

```
Task 6 :-  
x1 = [3 1 1];  
x2 = [4 2 1];  
x3 = [3 2 1 2 3];  
  
y1 = conv(x1, x2);  
y2 = conv(y1, x3);
```

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```

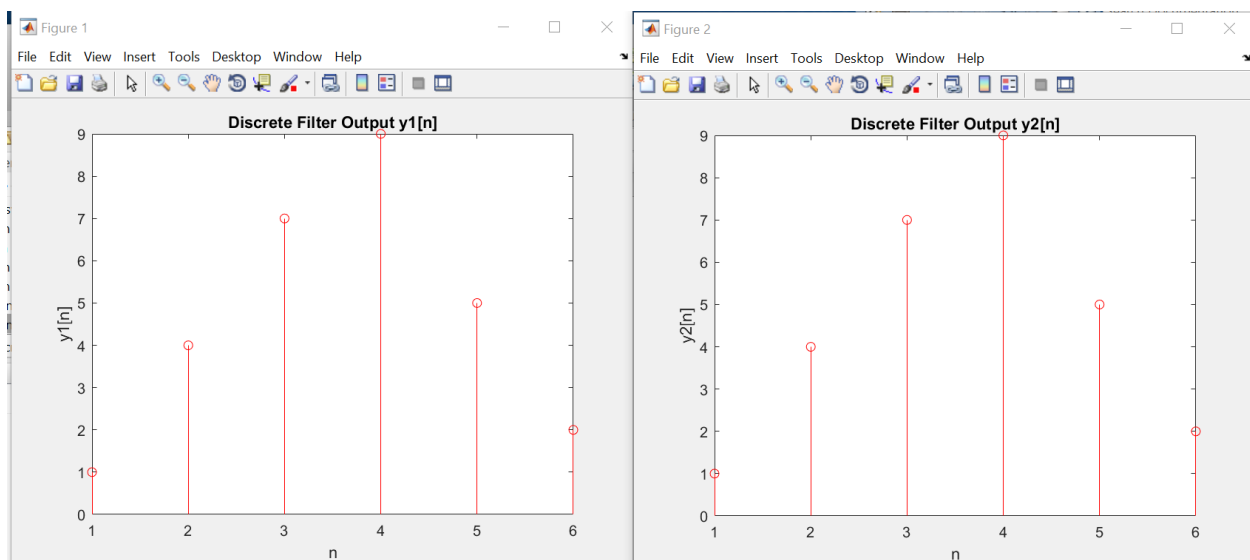
y2 = conv(x2, x3);
z2 = conv(x1, y2);

figure(1);
stem(z1);
title('LHS');
xlabel('index, n'); ylabel('Value, x[n]');

figure(2);
stem(z2, 'r');
title('RHS');
xlabel('index, n'); ylabel('Value, y1[n]');

```

### Output / Graphs / Plots / Results:



### Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 07:

Convolution is commutative. Given  $x[n]$  and  $h[n]$  as:  $X[n]=[1\ 3\ 2\ 1]$   $H[n]=[1\ 1\ 2]$   
 Show that  $x[n] * h[n] = h[n] * x[n]$ .

### Problem Analysis:

We need to show that Convolution is commutative.

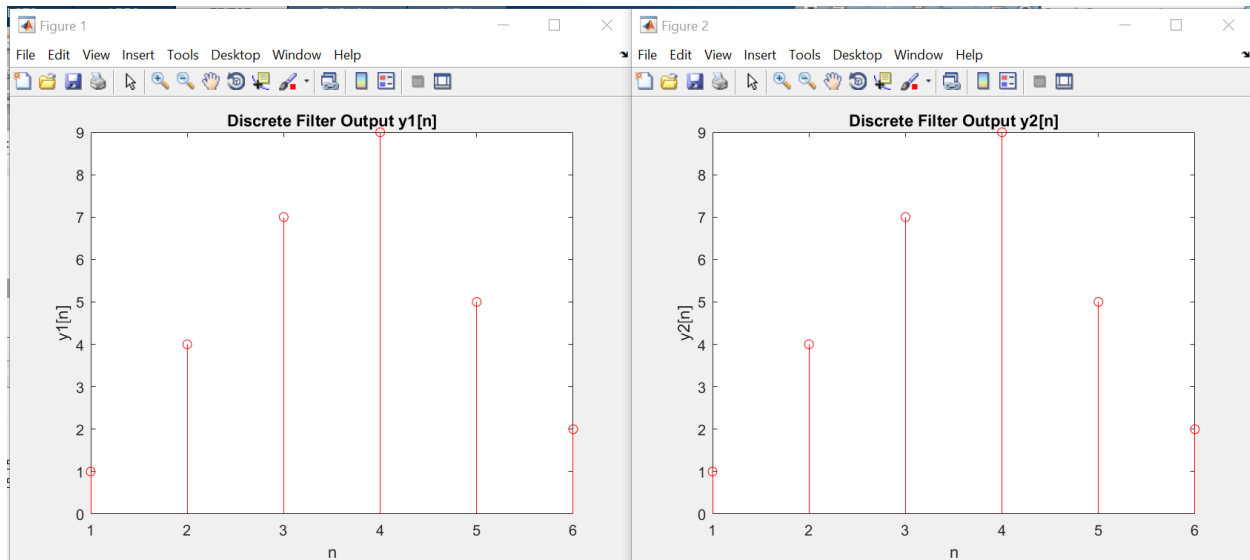
**Algorithm:**

- Write the code
- Execute it
- Observe the output

**Code:**

```
Task 7:-  
  
x = [1 3 2 1];  
h = [1 1 2];  
  
y1 = conv(h, x);  
y2 = conv(x, h);  
  
figure(1);  
stem(y1, 'x');  
title('Discrete Filter Output y1[n]');  
xlabel('n'); ylabel('y1[n]');  
  
figure(2);  
stem(y2, 'x');  
title('Discrete Filter Output y2[n]');  
xlabel('n'); ylabel('y2[n]');
```

## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

## Task # 08:

Determine  $h[n]$  for the system:

$$y[n] = \sum_{k=0}^{10} kx[n-k]$$

When  $x[n] = 2\delta[n]$ . Plot the input signal, impulse response, and output signal.

## Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

## Algorithm:

- Write the code
- Execute it
- Observe the output

Code:

### TASK 8:-

```
n = -10:10;
x = 2*(n==0);
h = cumsum(x);
y = conv(x, h, 'same');

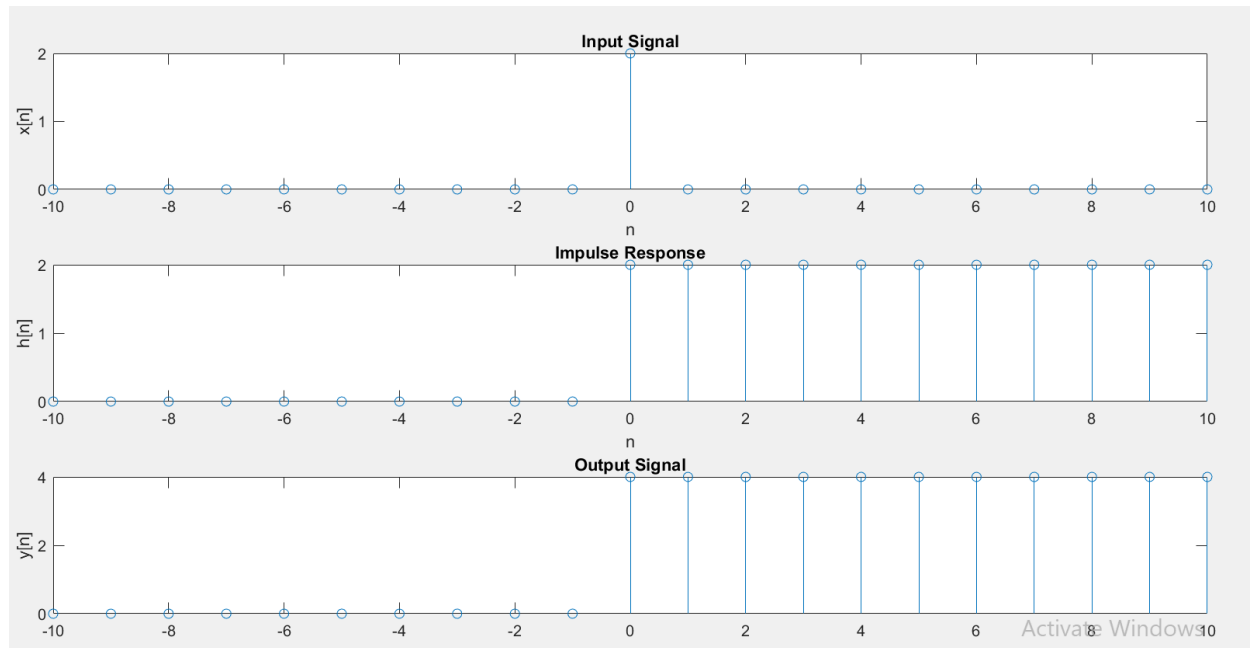
figure;
subplot(3, 1, 1);
stem(n, x);
title('Input Signal');
xlabel('n'); ylabel('x[n]');

subplot(3, 1, 2);
stem(n, h);
title('Impulse Response');
xlabel('n'); ylabel('h[n]');

subplot(3, 1, 3);
stem(n, y);
title('output signal');
xlabel('n'); ylabel('y[n]');
```



## Output / Graphs / Plots / Results:



## Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 09:

Given the impulse response of the systems as:  $h[n] = 2\delta[n] + \delta[n-1] + 2\delta[n-2] + 4\delta[n-3] + 3\delta[n-4]$   
If the input  $x[n] = \delta[n] + 4\delta[n-1] + 3\delta[n-2] + 2\delta[n-3]$  is applied to the system, determine the output of the system.

### Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

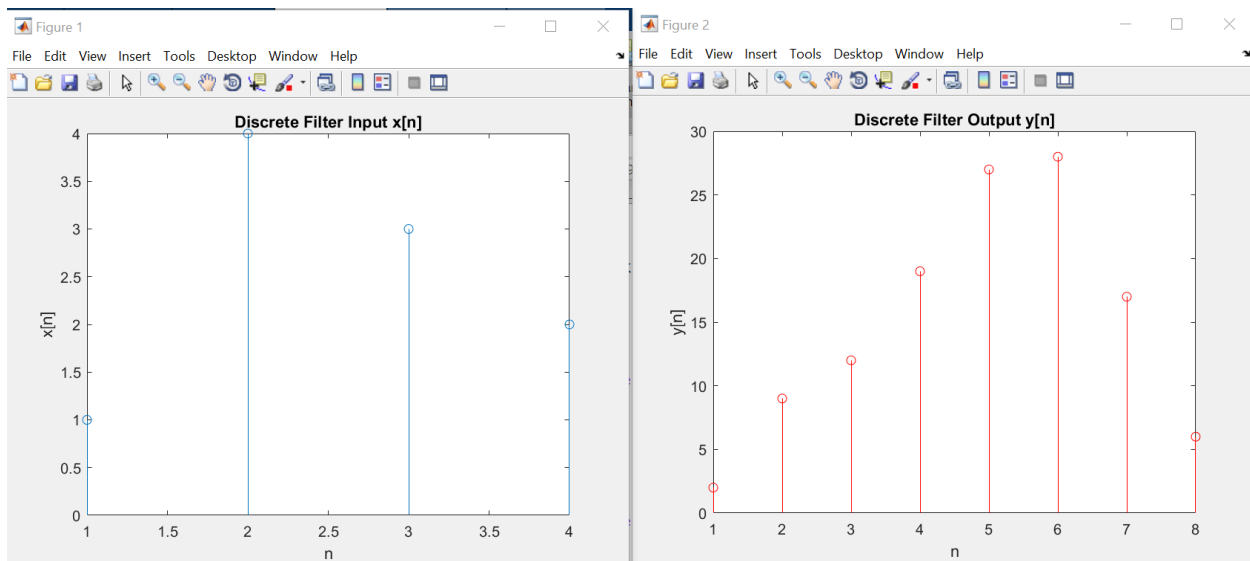
### Algorithm:

- Write the code
- Execute it
- Observe the output

### Code:

```
Task Q:-  
  
n = 0:4;  
  
h = [2 1 2 4 3];  
x = [1 4 3 2];  
  
y = conv(h, x);  
  
figure(1);  
stem(x);  
title('Discrete Filter Input x[n]');  
xlabel('n');  
ylabel('x[n]');  
  
figure(2);  
stem(y, 'r');  
title('Discrete Filter Output y[n]');  
xlabel('n');  
ylabel('y[n]');
```

### Output / Graphs / Plots / Results:

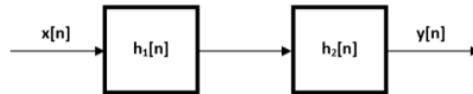


### Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 10:

Two systems are connected in cascade:



$$h1[n]=[1 \ 3 \ 2 \ 1]$$

$$h2[n]=[1 \ 1 \ 2]$$

If the input  $x[n] = \delta[n] + 4\delta[n-1] + 3\delta[n-2] + 2\delta[n-3]$  is applied, determine the output.

### Problem Analysis:

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

### Algorithm:

- Write the code
- Execute it
- Observe the output

### Code:

```
Task 10:-  
  
n=0:4;  
  
h1=[1 3 2 1];  
h2=[1 1 2];  
x=[1 4 3 2];  
  
y1=conv(h1,x);  
y=conv(y1,h2);  
  
figure(1);  
stem(x);  
title('Discrete Filter Input x[n]');
```

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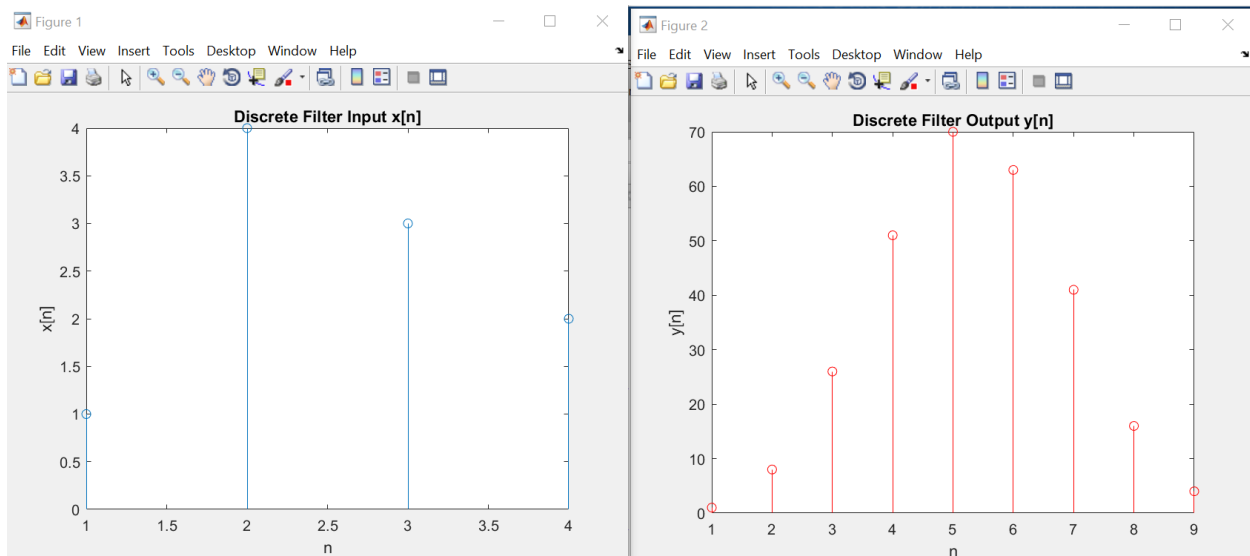
```

xlabel('n'); ylabel('x[n]');

figure(2);
stem(y, 'r');
title('Discrete Filter Output y[n]');
xlabel('n'); ylabel('y[n]');

```

### Output / Graphs / Plots / Results:



### Discussion and Conclusion:

We can perform different operations of signals in MATLAB.

### Task # 11:

Given the signals:

$$x1[n] = 2\delta[n] - 3\delta[n-1] + 3\delta[n-2] + 4\delta[n-3] - 2\delta[n-4]$$

$$x2[n] = 4\delta[n] + 2\delta[n-1] + 3\delta[n-2] - \delta[n-3] - 2\delta[n-4]$$

$$x3[n] = 3\delta[n] + 5\delta[n-1] - 3\delta[n-2] + 4\delta[n-3]$$

Verify that

$$x1[n] * (x2[n] * x3[n]) = (x1[n] * x2[n]) * x3[n]$$

$$x1[n] * x2[n] = x2[n] * x1[n]$$

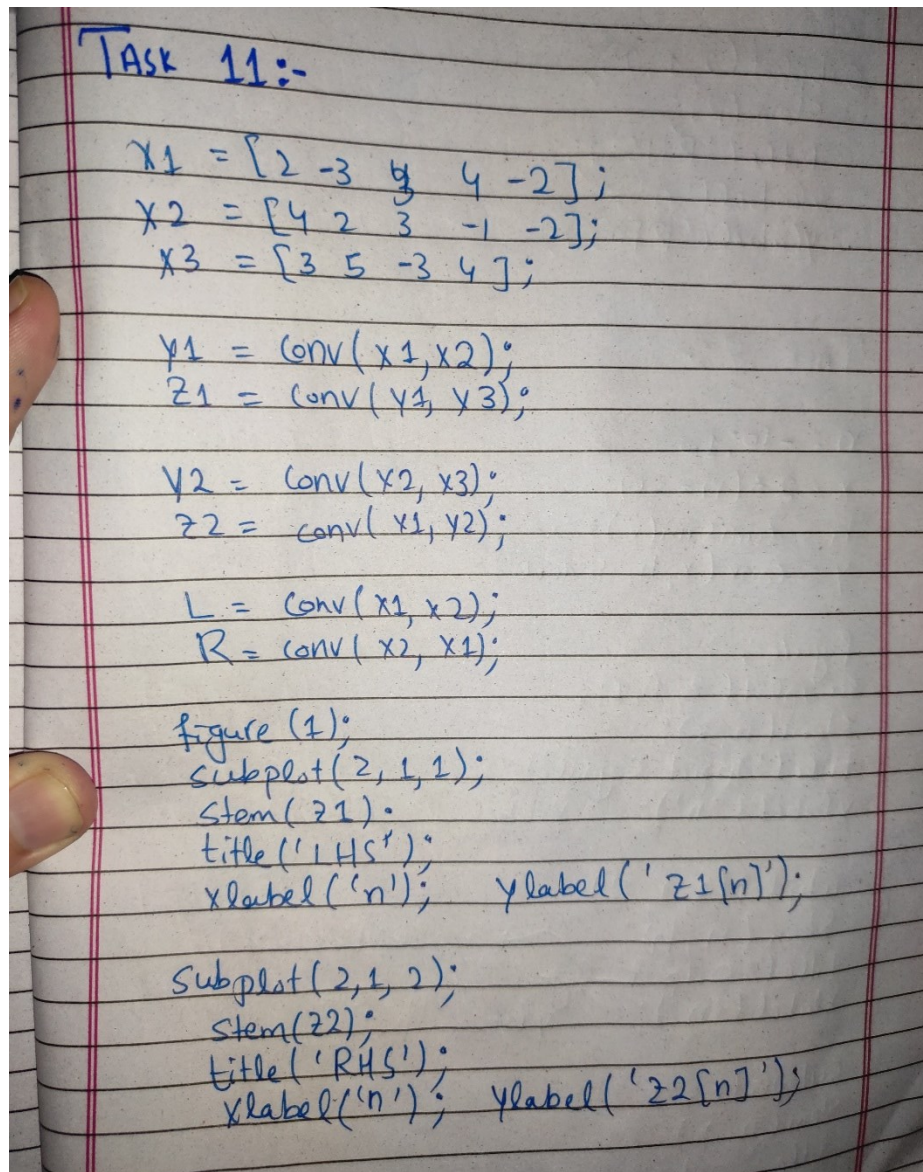


**Problem Analysis:**

We can perform different operations of signals in MATLAB. We perform Convolution in MATLAB.

**Algorithm:**

- Write the code
- Execute it
- Observe the output

**Code:**

Task 11:-

```
x1 = [2 -3 4 4 -2];  
x2 = [4 2 3 -1 -2];  
x3 = [3 5 -3 4];  
  
y1 = conv(x1, x2);  
z1 = conv(y1, x3);  
  
y2 = conv(x2, x3);  
z2 = conv(x1, y2);  
  
L = conv(x1, x2);  
R = conv(x2, x1);  
  
figure(1);  
subplot(2, 1, 1);  
stem(z1);  
title('LHS');  
xlabel('n'); ylabel('z1[n]');  
  
subplot(2, 1, 2);  
stem(z2);  
title('RHS');  
xlabel('n'); ylabel('z2[n]');
```



Date: \_\_\_\_\_ Day:  M / T / W / T / F / S

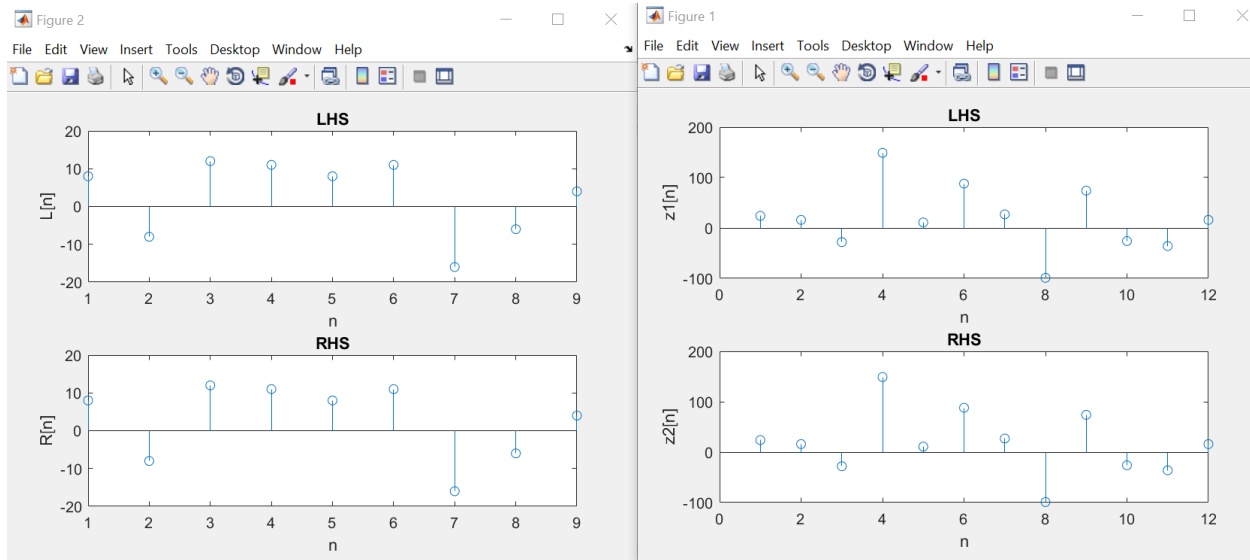
```

figure(2);
subplot(2,1,1);
stem(L);
title('LHS');
xlabel('n'); ylabel('L[n]');

subplot(2,1,2);
stem(R);
title('RHS');
xlabel('n'); ylabel('R[n]');

```

### Output / Graphs / Plots / Results:



### Discussion and Conclusion:

We can verify different convolution properties in MATLAB.