



Multi-Path Fading Channel

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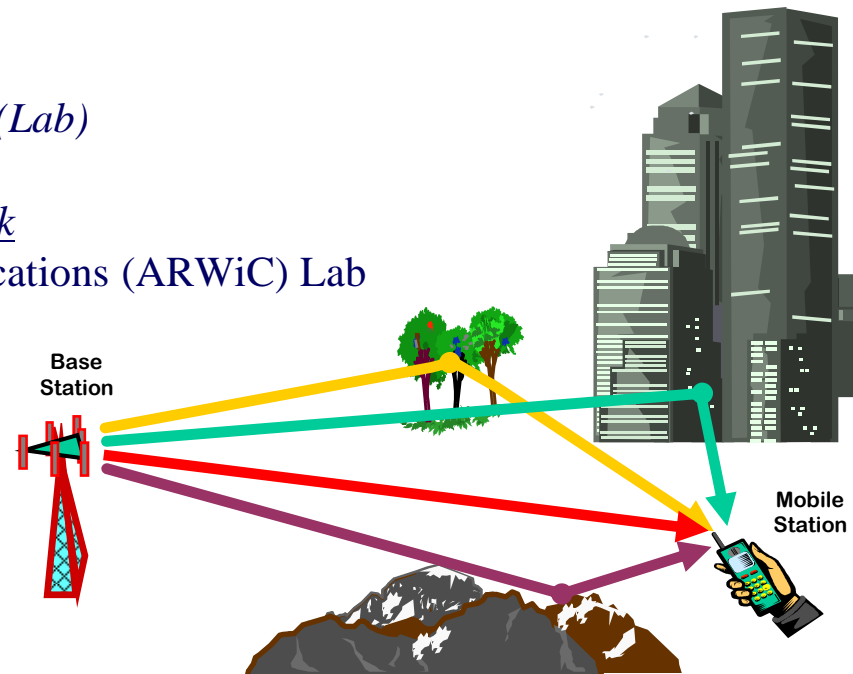
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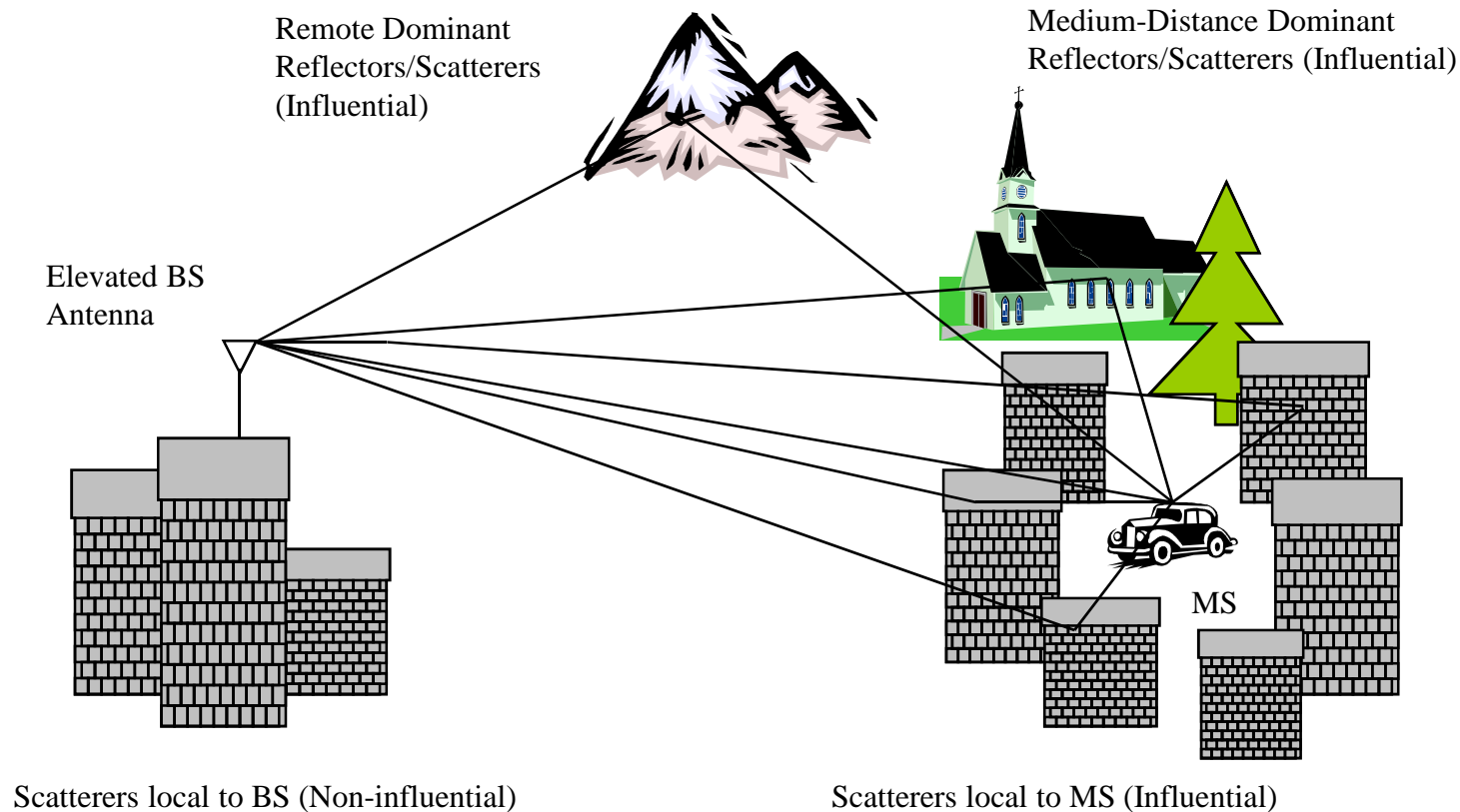
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Typical Cellular Mobile Environment



Fading



- **Fading:** The interference between two or more versions of the transmitted signal which arrive at the receiver at **slightly** different times
- **Multipaths:** Above mentioned versions of the transmitted signal

Fading (Continued)



Delay Spread \leftrightarrow Coherence Bandwidth

Frequency separation at which two frequency components of Tx signal undergo independent attenuations

Doppler Spread \leftrightarrow Coherence Time

Time separation at which two time components of Tx signal undergo independent attenuations



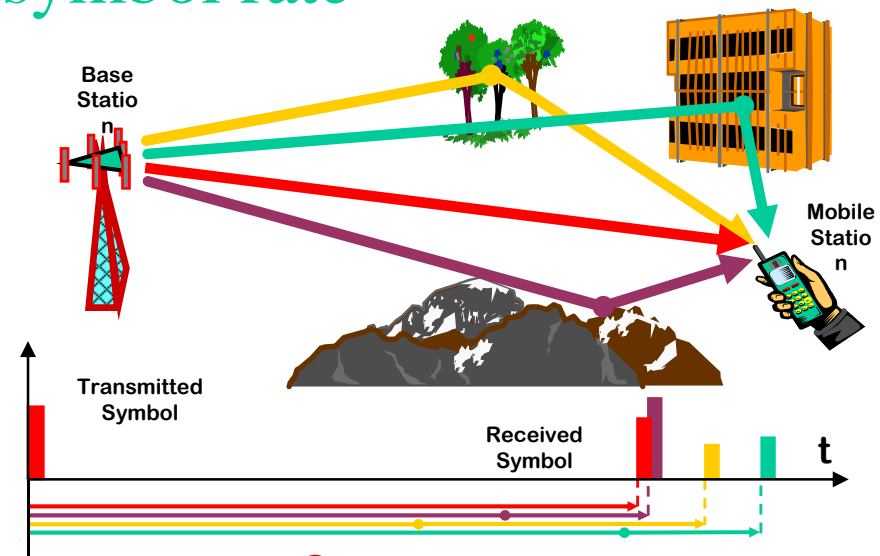
Mobile Channel Parameters

- Time delay spread |
- Coherence Bandwidth | -> ISI
- Doppler Spread |
- Coherence Time | -> Unstable channel
- Flat fading
- Frequency selective fading
- Fast fading
- Slow fading



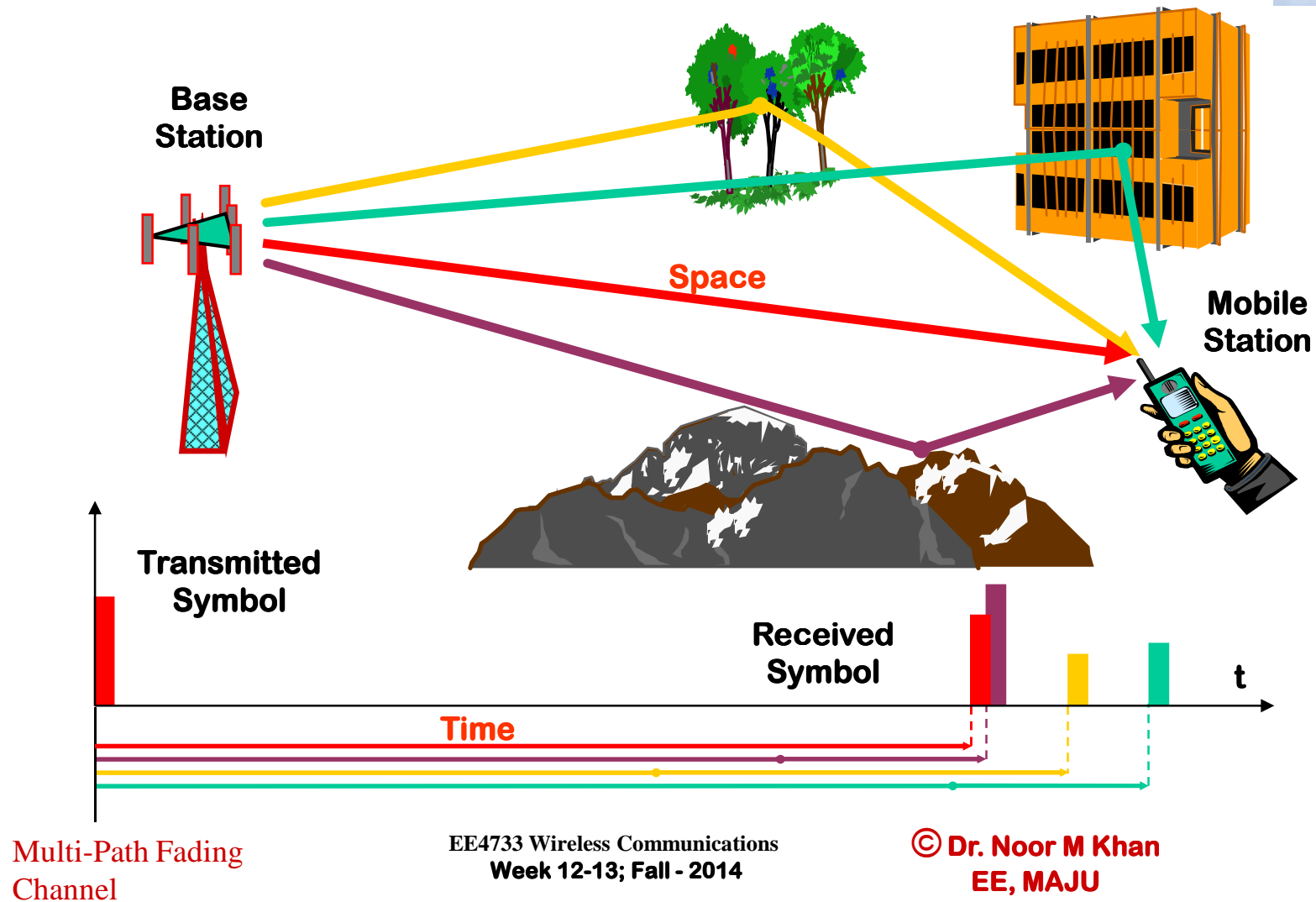
Multi-path Propagation

- Multi-path smears or spreads out the signal
 - delay spread
- Causes inter-symbol interference
 - limits the maximum symbol rate



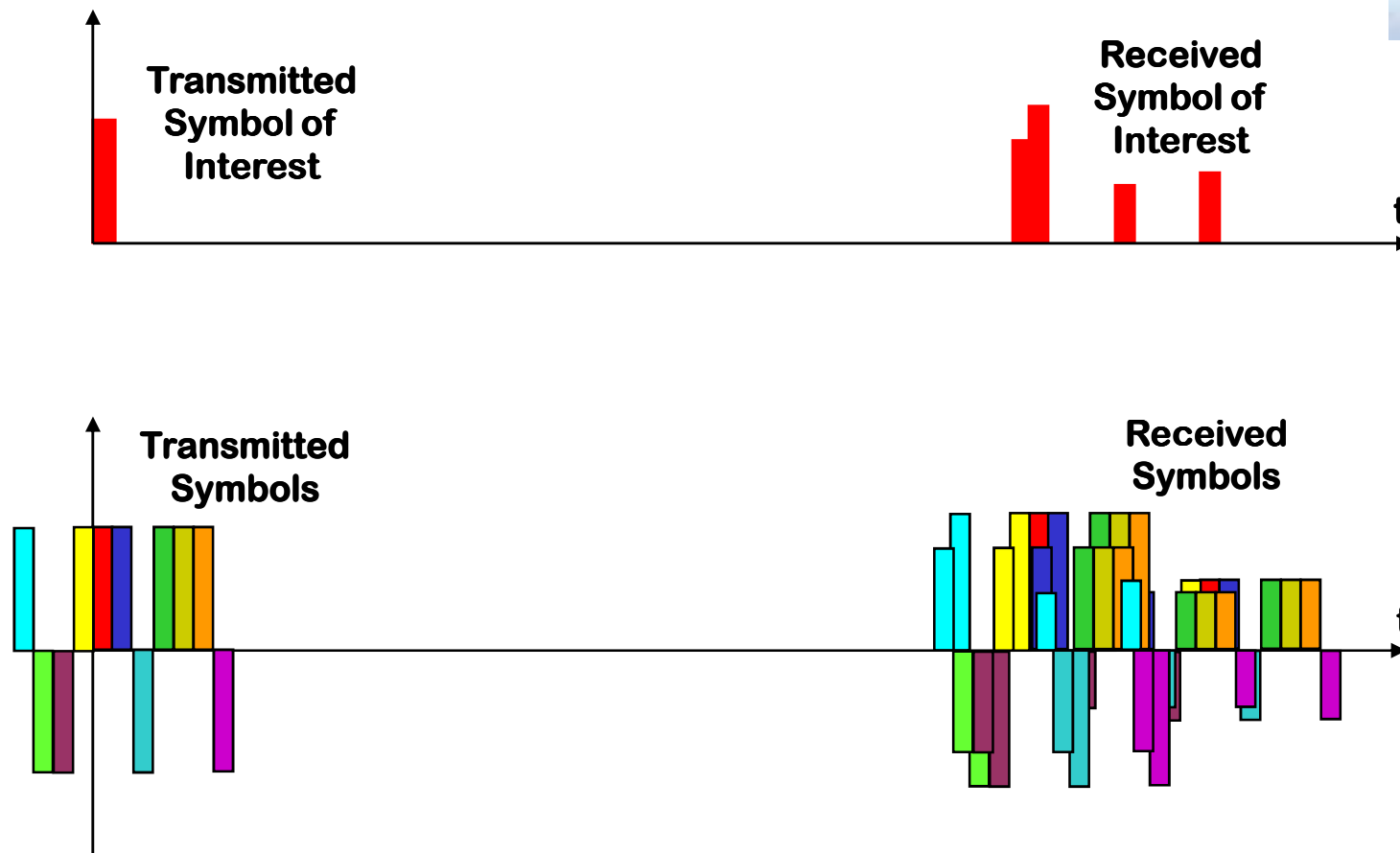


Delay Spread





Intersymbol Interference

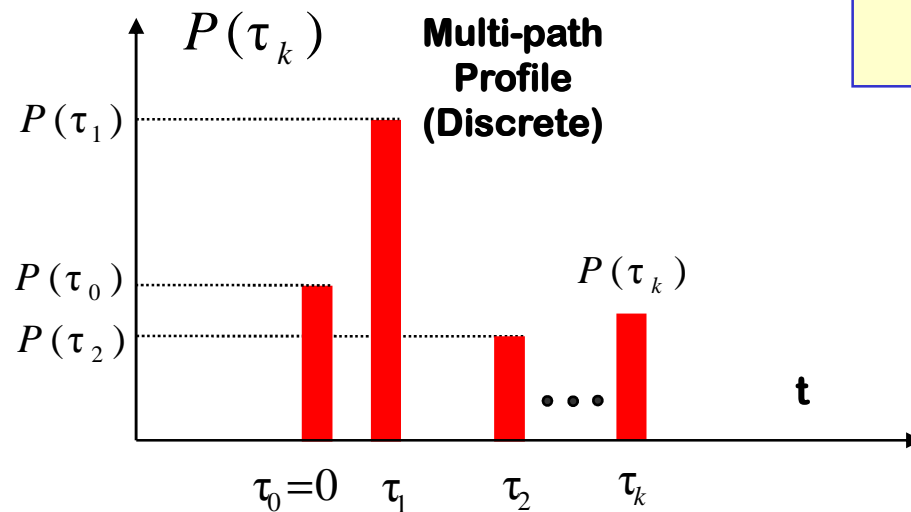




Average Delay Spread

- Average delay spread $\bar{\tau}$

$$\bar{\tau} = \frac{\sum_k |a_k|^2 \tau_k}{\sum_k |a_k|^2} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$$





RMS Delay Spread (Discrete)

- RMS delay spread σ_τ

$$\sigma_\tau = \sqrt{\overline{\tau^2} - \bar{\tau}^2}$$

$$\bar{\tau}^2 = \frac{\sum_k |a_k|^2 \tau_k^2}{\sum_k |a_k|^2} = \frac{\sum_k P(\tau_k) \tau_k^2}{\sum_k P(\tau_k)}$$

Average Delay Spread (Continuous Delay Profile)



- Average delay spread $\overline{\tau}$

$$\overline{\tau} = \frac{\int_0^{\infty} t P(t) dt}{\int_0^{\infty} P(t) dt}$$

- Representative delay functions

exp $P(t) = \frac{1}{\sigma_{\tau}} e^{-\frac{t}{\sigma_{\tau}}}$

uniform $P(t) = \frac{\sigma_{\tau}}{2} \quad 0 \leq t \leq 2\tau_d$ and zero elsewhere



Measurements

<i>Type of Environment</i>	<i>Delay Spread τ_d (μs)</i>
Open area	<0.2
Suburban area	0.5
Urban area	3



Coherence Bandwidth

- Coherence bandwidth B_c is a range of frequencies over which the channel can be considered flat
 - passes all spectral components with approximately equal gain and linear phase
- Bandwidth where the correlation function $R_T(\omega)$ for signal envelopes is high
- Therefore two sinusoidal signals with frequencies that are farther apart than the coherence bandwidth will fade independently.



Coherence Bandwidth

- If $R_T(\omega) > 0.9$

$$B_C = \frac{1}{50\sigma_\tau}$$

- If $R_T(\omega) > 0.5$

$$B_C = \frac{1}{5\sigma_\tau}$$

- An exact relationship between coherence bandwidth & delay spread does not exist



Inter-symbol Interference

- For no Inter-symbol Interference the transmission rate R for a digital transmission is limited by delay spread and is represented by:
 $R < 1/5\sigma_{\tau}$;
- If $R > 1/5\sigma_{\tau}$ Inter-symbol Interference (ISI) occurs
- Need for ISI removal measures (Equalizers)

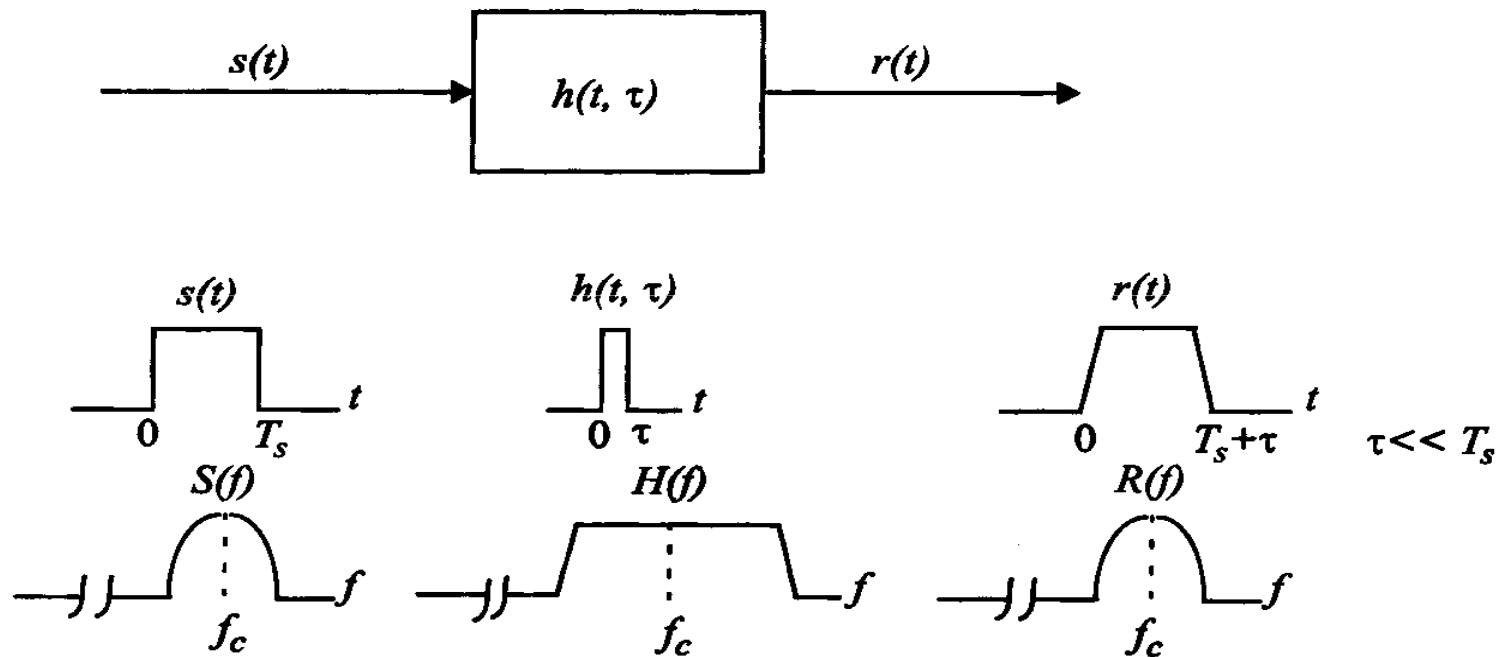


Flat Fading 1

- If the mobile radio channel has a constant gain and linear phase over a bandwidth *greater* than the bandwidth of the transmitted signal - the received signal will undergo *flat fading*
- Please, observe that the fading is flat (or frequency selective) depending on the signal bandwidth relative to the channel coherence bandwidth.



Flat Fading 2



- $BS \ll B_C \text{ \& } T_S \gg \sigma_\tau$

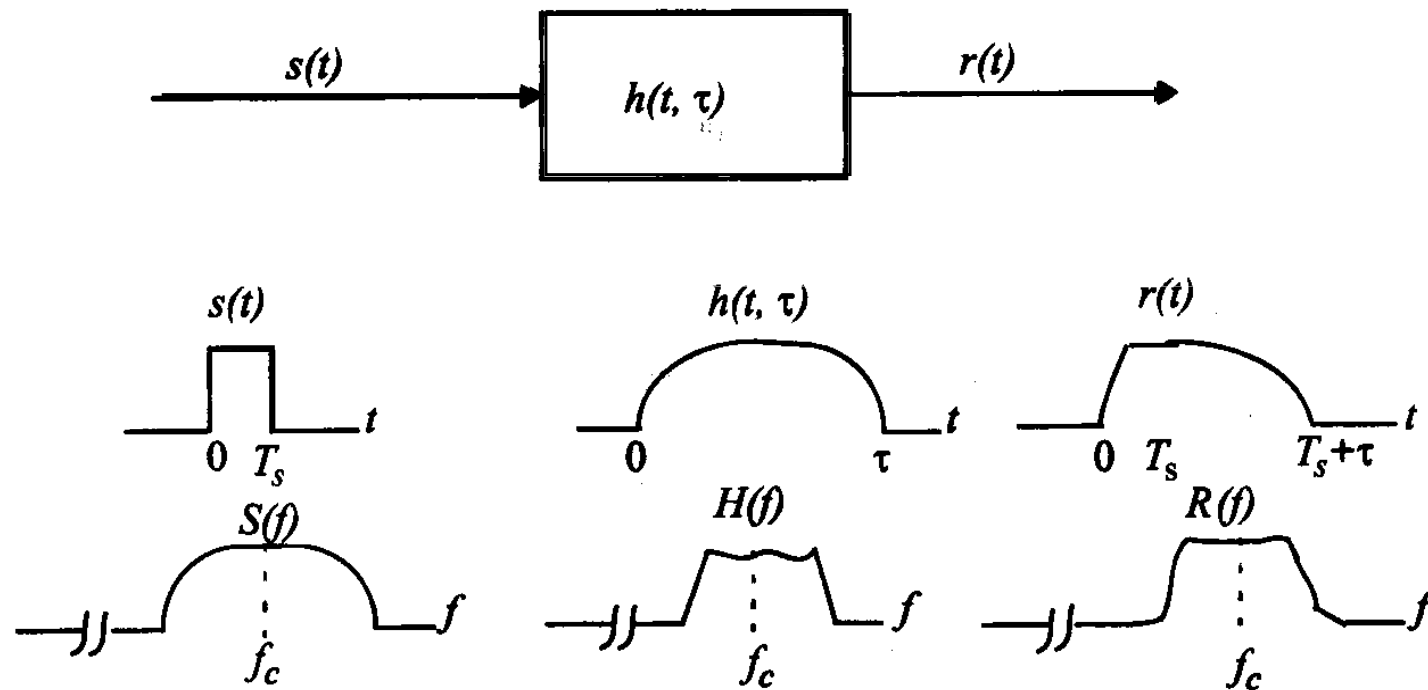


Frequency Selective Fading 1

- If the mobile radio channel has a constant gain and linear phase over a coherence bandwidth, *smaller* than the bandwidth of the transmitted signal - the received signal will undergo *frequency selective fading*
- Again, the signal bandwidth is wider than the channel coherence bandwidth, causing one or more areas of attenuation of the signal within the signal bandwidth



Frequency Selective Fading 2



- $BS > B_C$ & $T_S < \sigma_\tau$



Comm. System Design Problem

The power delay profile of a channel has four paths: -10 dBm at 0 μ s, 0 dBm at 10 μ s, -10 dBm at 20 μ s, and -20 dBm at 30 μ s.

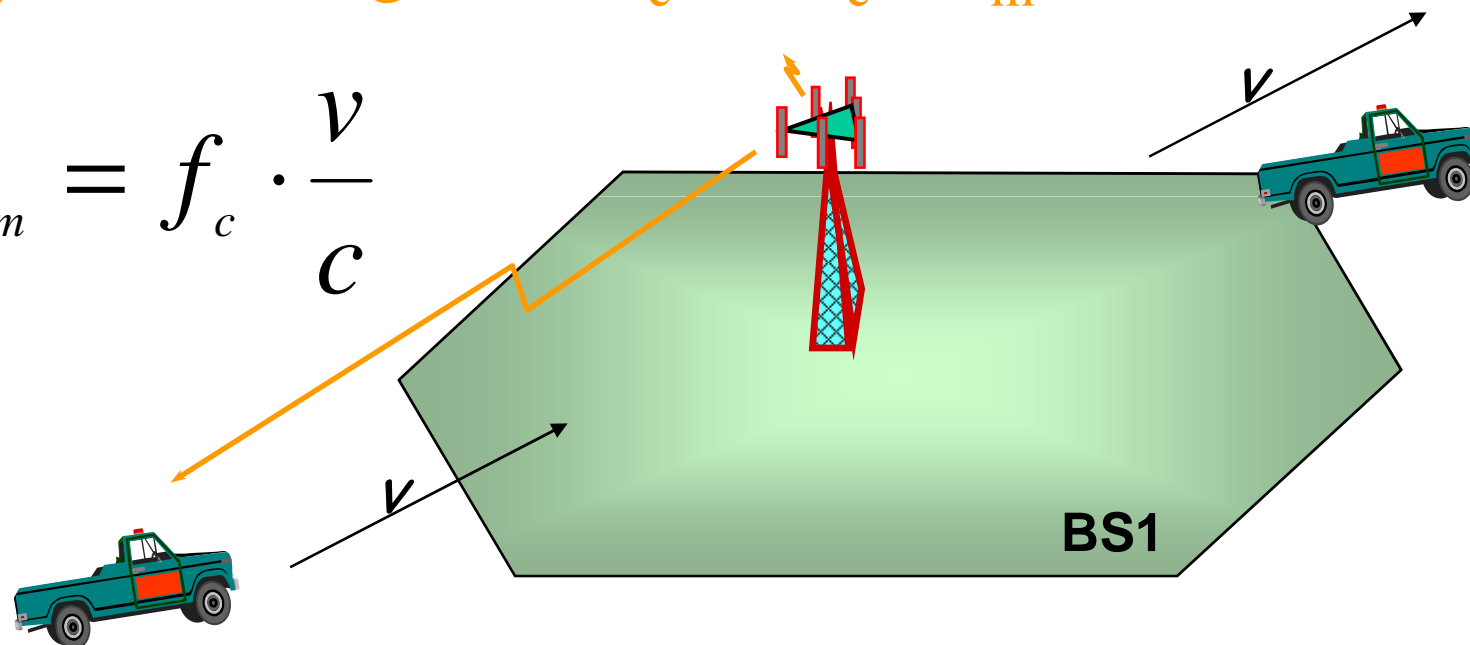
- Sketch the power delay profile with correctly marked axis. What is the maximum Diversity order for this channel?
- Find the mean excess delay and rms delay spread σ_τ of the channel
- Determine maximum excess delay (10 dB)
- If an equalizer is required whenever the symbol duration T_s is less than $5\sigma_\tau$, calculate the maximum symbol rate supported without an equalizer.
- Calculate the 50 % correlation Coherence bandwidth.



Doppler Shift

- f_c broadening from f_c to $(f_c + f_m)$

$$f_m = f_c \cdot \frac{v}{c}$$



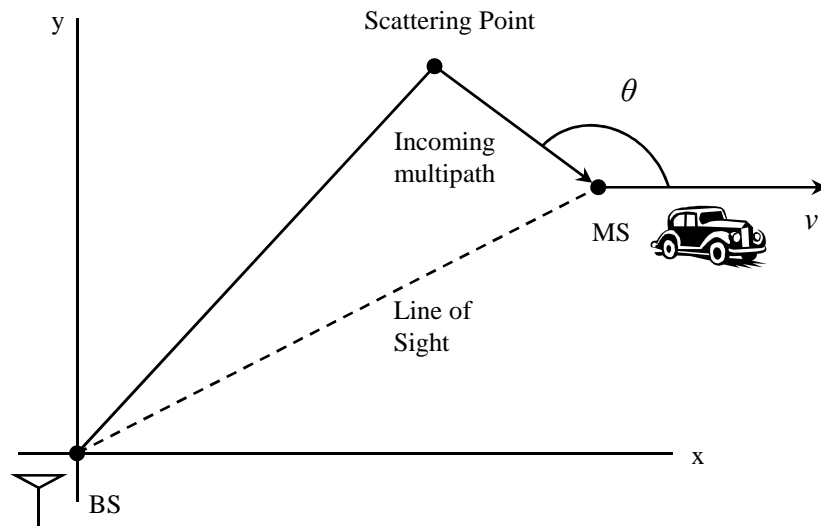
Doppler Spread



The **Doppler** effect (in addition to the fading effect) renders the received pulse to be **time-varying**

The **State Transitions** are determined from the dynamics of the fading channel (Fading Correlation Function or The **Doppler Spectrum**)

Doppler Spread (Continued)



f : carrier frequency

c : speed of light

v : mobile speed

θ : Angle of motion with
incoming multipath

Doppler Spread (Continued)



$$f_d = \frac{f v \cos \theta}{c}$$

f : carrier frequency

c : speed of light

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incoming multipath



Relativistic Doppler Frequency

The observed frequency is

$$f = f_c \cdot \sqrt{\frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}} \quad f_d = f - f_c \approx f_c \cdot \frac{v}{c}$$

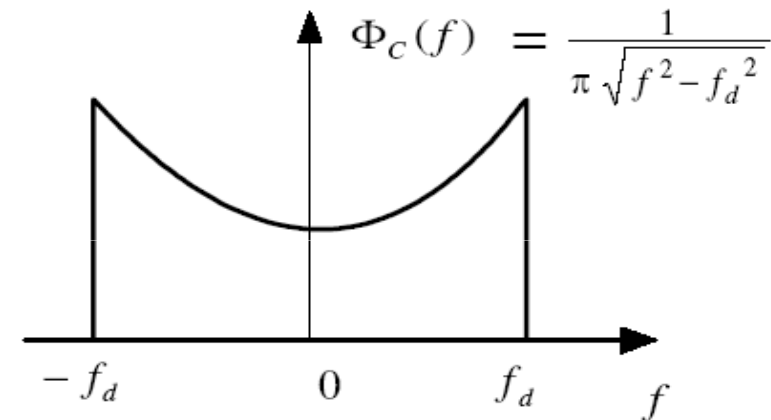
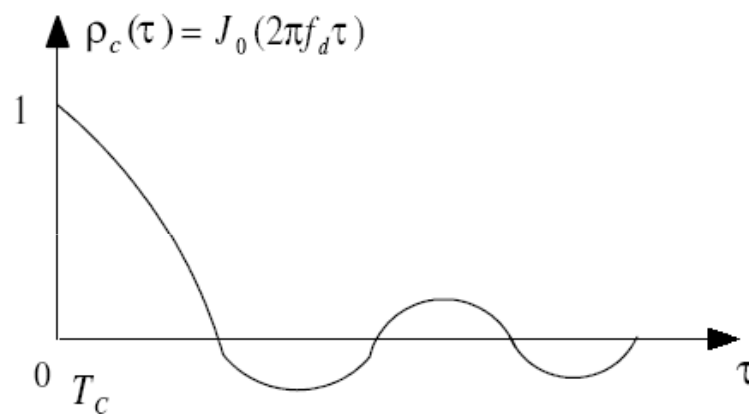
where the relative velocity v is positive if the source is approaching and negative if receding.

f_c - carrier freq., c -speed of light, f_d -Doppler shift



Doppler Spread (Continued)

For the land mobile fading spectrum,



The Auto-Correlation Function

Doppler Fading Spectrum



Doppler Spread & Coherence Time

- Describes the time varying nature of the channel in a local area
- Doppler Spread B_D , is a measure of the spectral broadening caused by the time rate of change
- f_c broadening from $(f_c - f_m)$ to $(f_c + f_m)$
- If the base-band signal bandwidth is much greater than B_D , the effects of Doppler spread are negligible at the receiver



Coherence Time

- Coherence Time is the time domain dual of Doppler spread
- Doppler spread and coherence time are inversely proportional
- $T_C = 1/f_m$
- Statistical measure of the time duration over which the channel impulse response is invariant



Coherence Time

- If the coherence time is defined as the time over which the correlation function is above 0.5, then

$$T_c \approx \frac{9}{16\pi f_m}$$

- Rule of thumb for modern digital communication defines TC as the geometric mean of the above two expressions for TC

$$T_c = \sqrt{\frac{9}{16\pi f_m^2}}$$



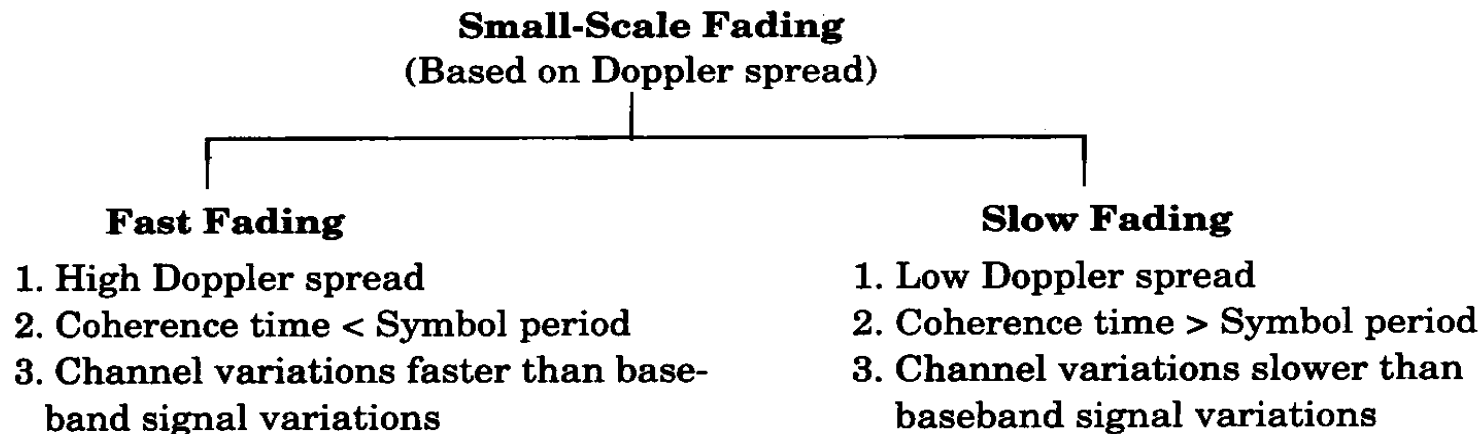
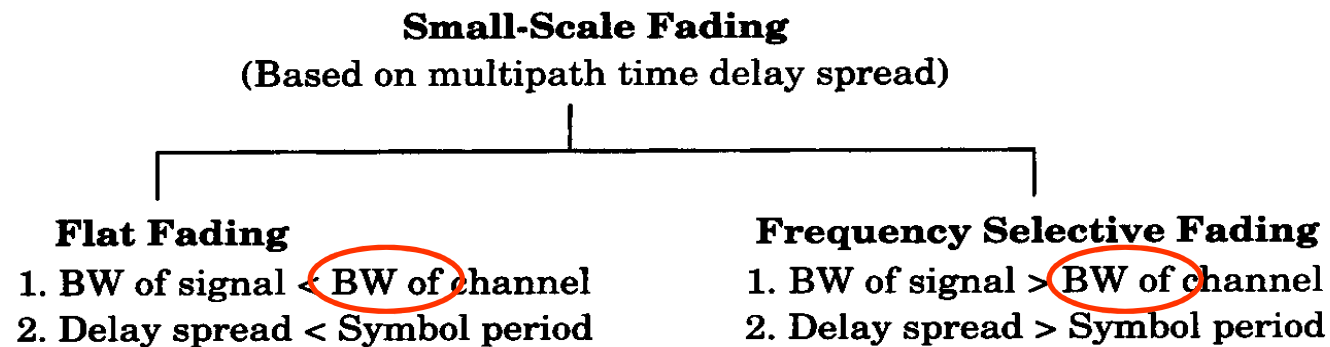
Comm. System Design Problem

The power delay profile of a channel has four paths: -10 dBm at 0 μ s, 0 dBm at 10 μ s, -10 dBm at 20 μ s, and -20 dBm at 30 μ s.

- a) If an equalizer is required whenever the symbol duration T_s is less than $5\sigma_\tau$, calculate the maximum symbol rate supported without an equalizer.
- b) For a mobile travelling with a speed of 36 km/hr, receiving the signal at the carrier frequency of 900 MHz through the channel, calculate the time over which the channel appears stationary.
- c) For the results found in parts (a), and (b), determine if the channel is slow fading or fast fading.



Types of Small-Scale Fading





Fast Fading

- The channel impulse response changes rapidly within the symbol duration - coherence time $<$ symbol period
- $T_S > T_c$ and $B_S < B_D$
- Channel specifies as a fast or slow fading channel does not specify whether the channel is flat fading or frequency selective fading



Slow Fading

- The channel impulse response changes at a rate much slower than the transmitted base-band signal.
- Doppler spread is much less than the bandwidth of the base-band signal
- $T_S \ll T_c$ and $B_S \gg B_D$
- Velocity of the MS and the base-band signaling determines whether a signal undergoes fast or slow fading



Summary

- Fast and slow fading deal with the relationship between the time rate of change in the channel and the transmitted signal, NOT with propagation path loss models



Fading in Brief

Large Doppler Spread



Time-Selective Fading

Large Delay Spread



Frequency-Selective Fading

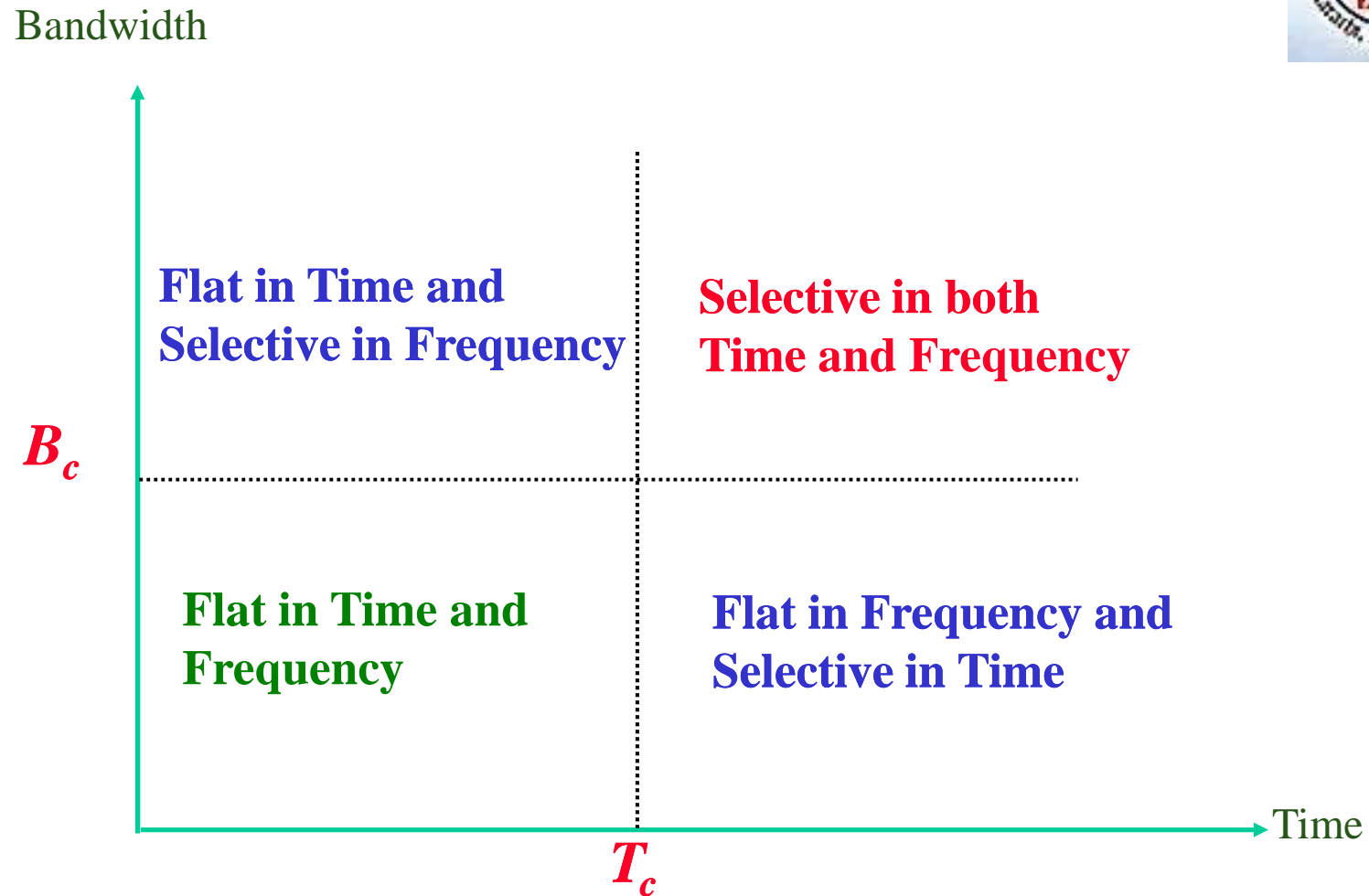
Large Angle Spread



Space-Selective Fading



Fading (Continued)



Fading (Continued)



Fast and Slow Fading

If the channel response changes within a symbol interval, then the channel is regarded **FAST FADING**

Otherwise

the channel is regarded as **SLOW FADING**

Fast Fading



When?

The channel impulse response changes rapidly within the symbol period of the transmitted signal.

What?

The Doppler Spread causes frequency dispersion which leads to signal distortion.

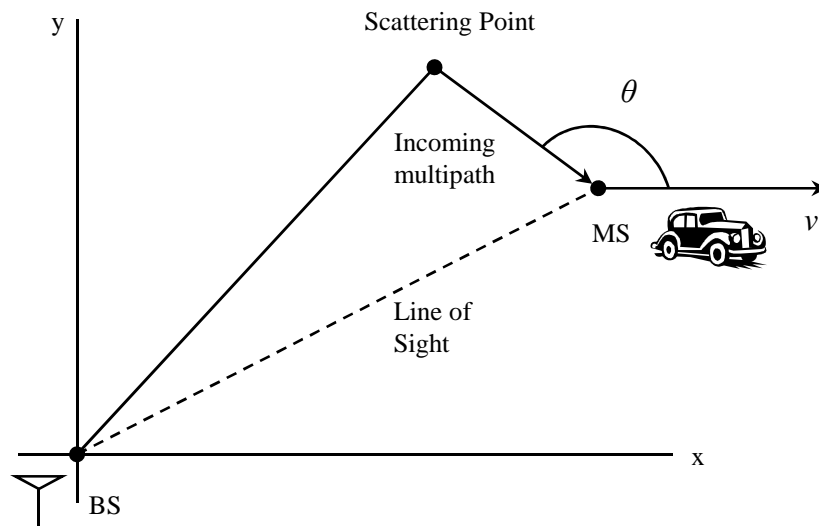
Doppler Spread



The **Doppler** effect (in addition to the fading effect) renders the received pulse to be **time-varying**

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Doppler Spread (Continued)



f : carrier frequency

c : speed of light

v : mobile speed

θ : Angle of motion with
incoming multipath

Doppler Spread (Continued)



$$f_d = \frac{f v \cos \theta}{c}$$

f : carrier frequency

c : speed of light

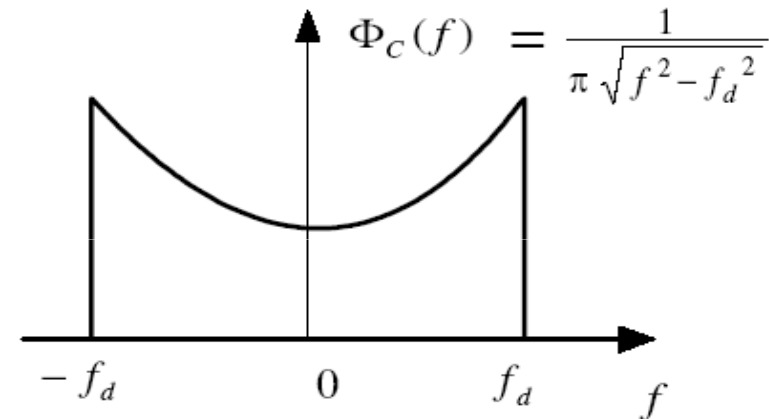
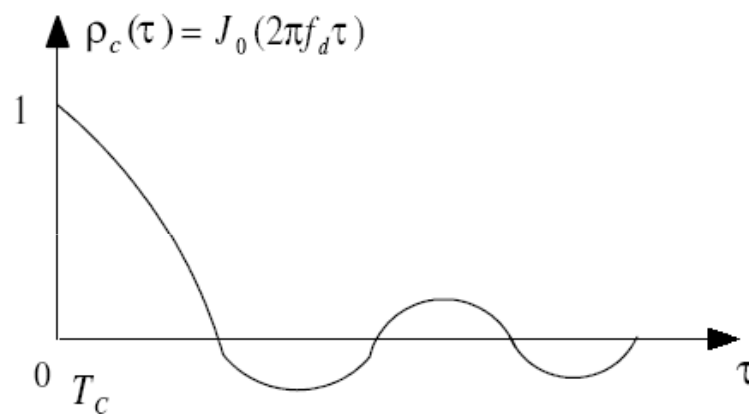
v : mobile speed

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Doppler Spread (Continued)

For the land mobile fading spectrum,



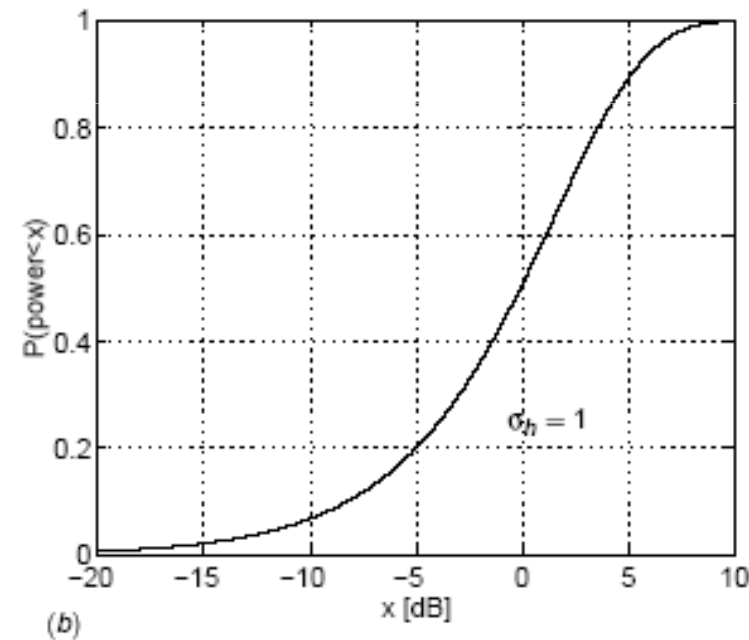
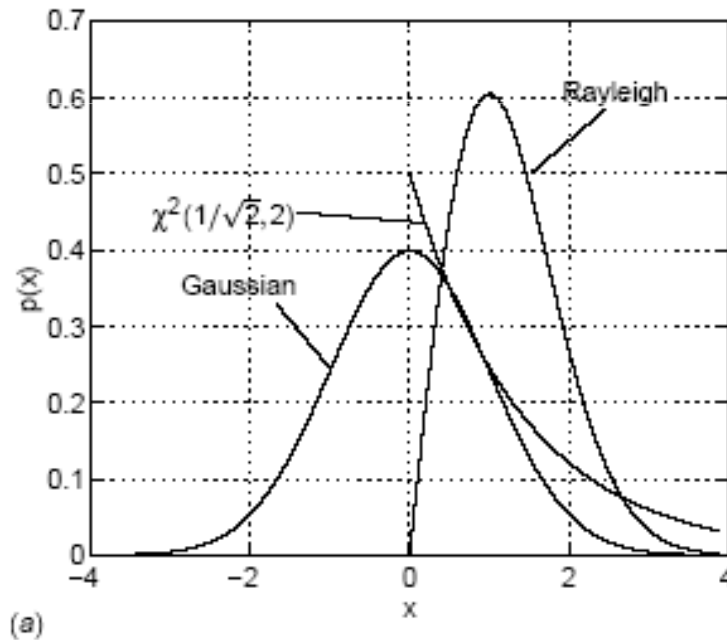
The Auto-Correlation Function

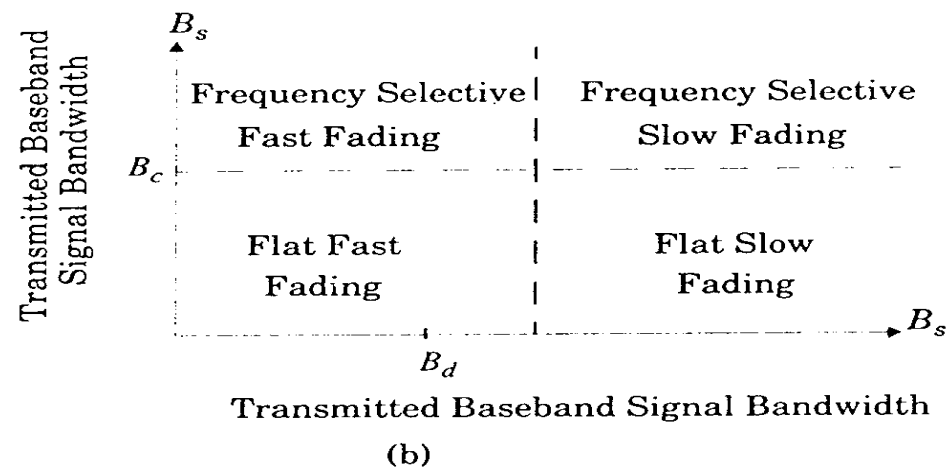
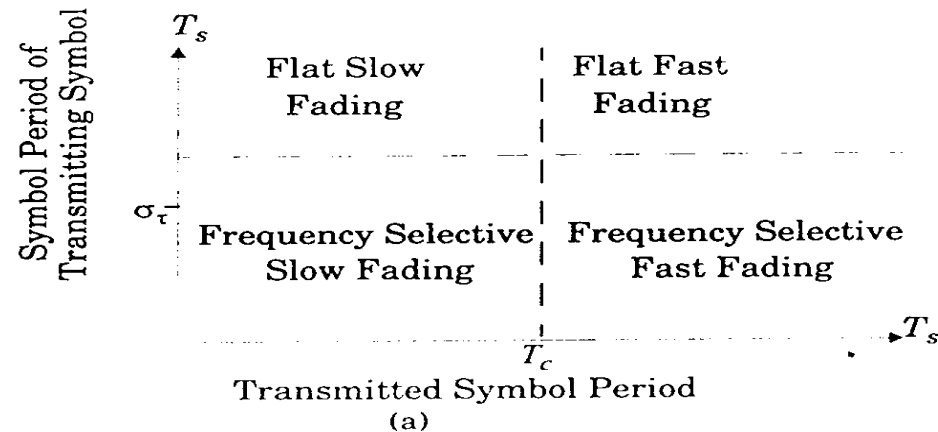
Doppler Fading Spectrum

Doppler Spread (Continued)



- h is the channel impulse response
- h has a complex normal distribution with zero mean
- $|h|$ is Rayleigh distributed
- Phase ϕ is uniformly distributed between 0 and 2π
- $|h|^2$ is *Chi-square* distributed







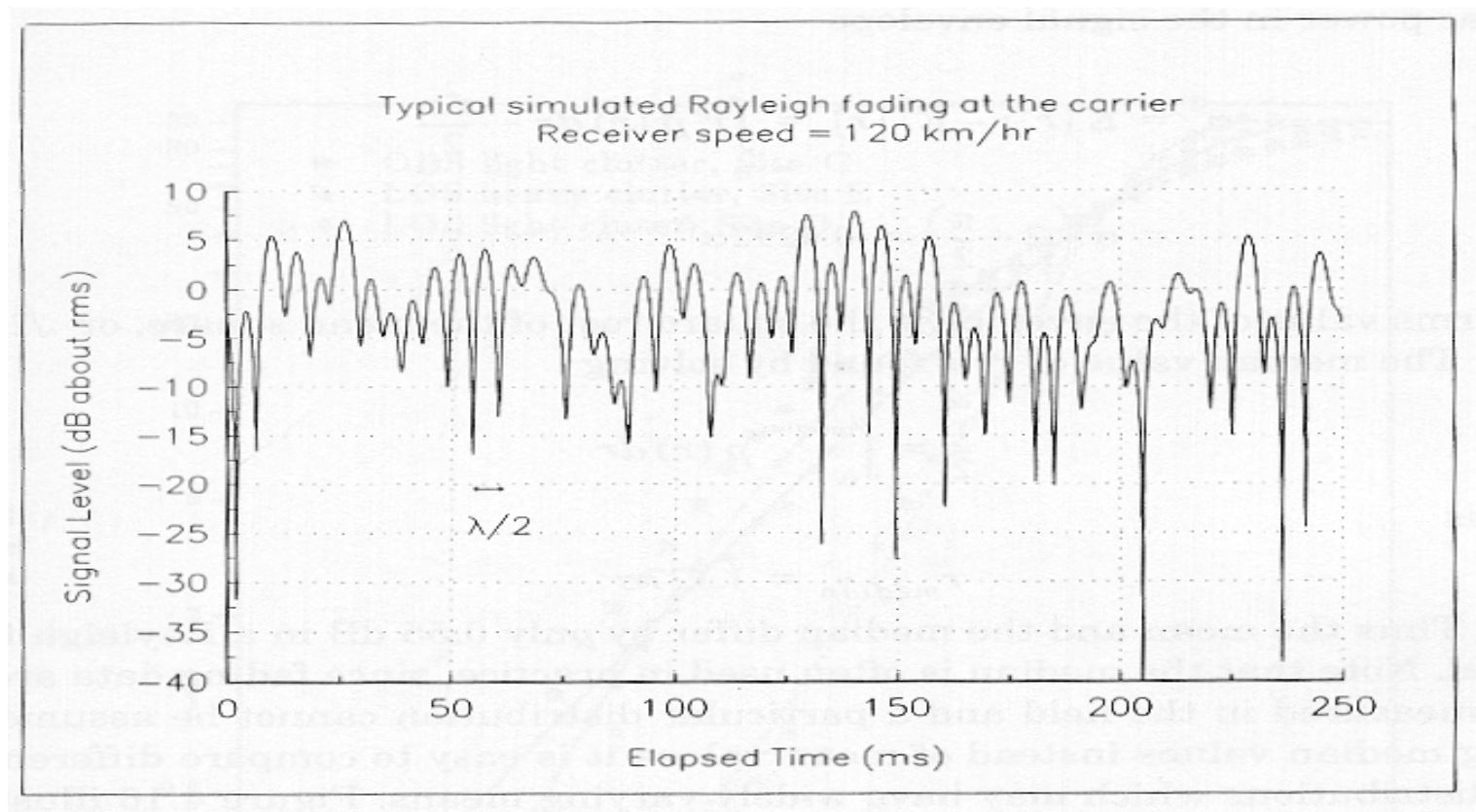
Rayleigh Fading 1

- The received envelope (amplitude) of a flat fading signal is described as a Rayleigh distribution
 - Square root sum r , of two quadrature Gaussian noise signals x_I and y_Q has a Rayleigh distribution (Papoulis65)

$$r = \sqrt{x_I^2 + y_Q^2} \quad p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right); & (0 \leq r \leq \infty) \end{cases}$$



Rayleigh Fading 2





Rayleigh Fading PDF

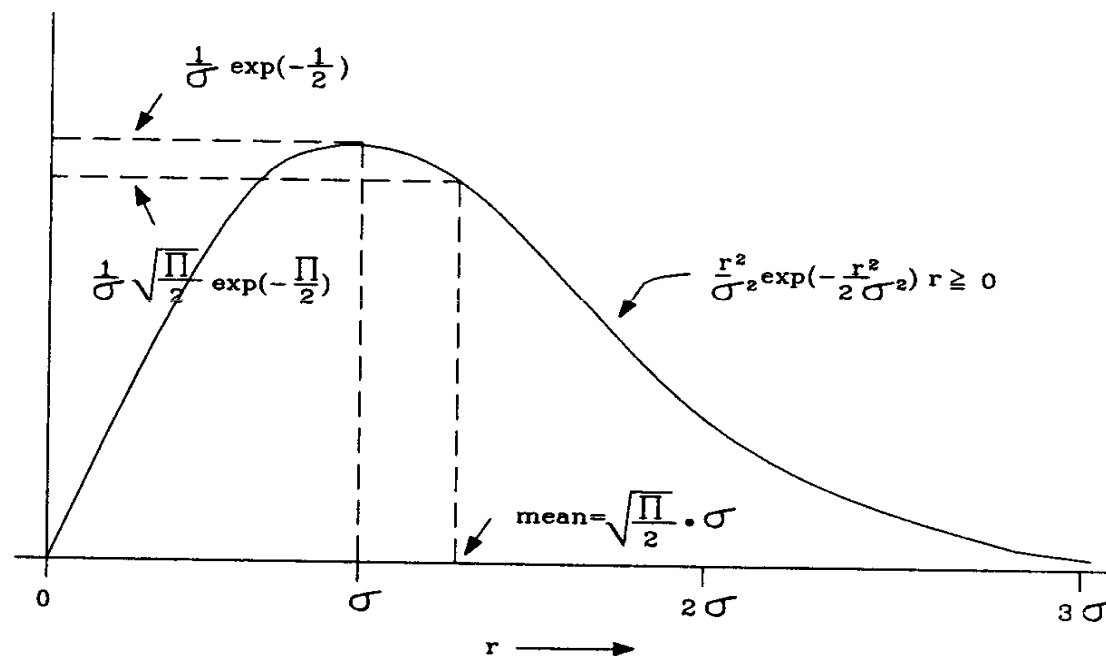


Figure 1.2: Rayleigh PDF.



Rayleigh Fading 3

$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) & (0 \leq r \leq \infty) \end{cases}$$

- σ - rms value of the received voltage signal before envelope detection
- σ^2 - time average power before envelope detection
- The probability that the received signal envelope does not exceed R is given by:

$$P(R) = \Pr(r \leq R) = \int_0^R p(r) dr = 1 - \exp\left(-\frac{R^2}{2\sigma^2}\right)$$



Rayleigh Fading 4

- The median value of r is found by solving

$$\frac{1}{2} = \int_0^{r_{median}} p(r) dr$$

$$r_{median} = 1.77\sigma$$

- Mean and median differ by only 0.55dB



Ricean Fading 1

- When there is a dominant stationary signal component
- At the output of an envelope detector - adding a DC component to the random multi-path

$$p(r) = \frac{r}{\sigma^e} e^{-\frac{(r^2 + A^2)}{2\sigma^2}} I_0\left(\frac{Ar}{\sigma^2}\right); \quad \text{for } (A \geq 0, r \geq 0)$$



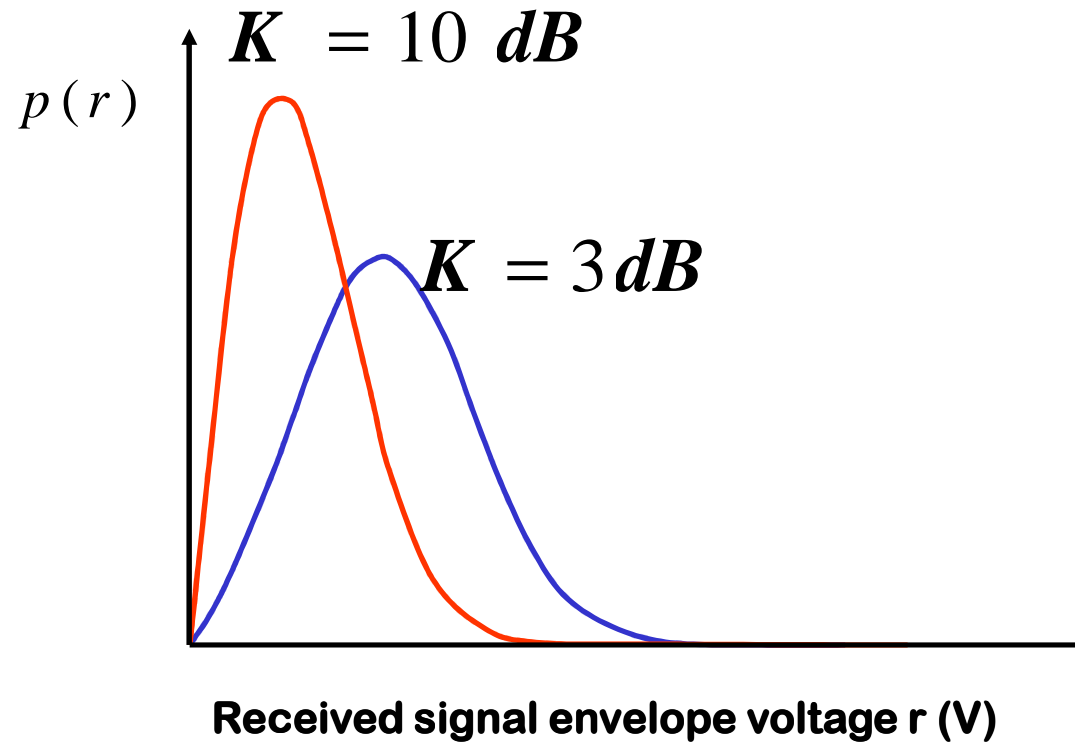
Ricean Fading 2

- A - peak amplitude of the dominant signal
- $I_0()$ - modified Bessel function of the first kind and zero order
- Described in terms of a Ricean factor, K

$$K(dB) = 10 \log \frac{A^2}{2\sigma^2} (dB)$$



Ricean PDF





Clarks Model for Flat Fading 1

- Statistical Characteristics of the EM fields of the received signal at the MS are obtained from scattering
- Assumes
 - Fixed transmitter & vertically polarized antenna
 - Fields incident on the mobile antenna comprises of N waves in azimuth plane with arbitrary carrier phases and azimuth angels of arrival
 - equal average signal amplitude



Clarks Model for Flat Fading 2

- The model shows that the random received signal envelope r has a Rayleigh distribution and is given by:

$$p(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right); \quad 0 < r \leq \infty$$



Effect of Doppler Spread

- It can be shown that if the angle of the received signals, α_i is uniformly distributed that the Doppler frequency has a random cosine distribution.
- Then the Doppler power spectral density $S(f)$ can be computed by equating the incident received power in an angle $d\alpha$ with Doppler power $S(f)df$
 - df is found by differentiating the Doppler term $f_m \cos \alpha$ wrt α .

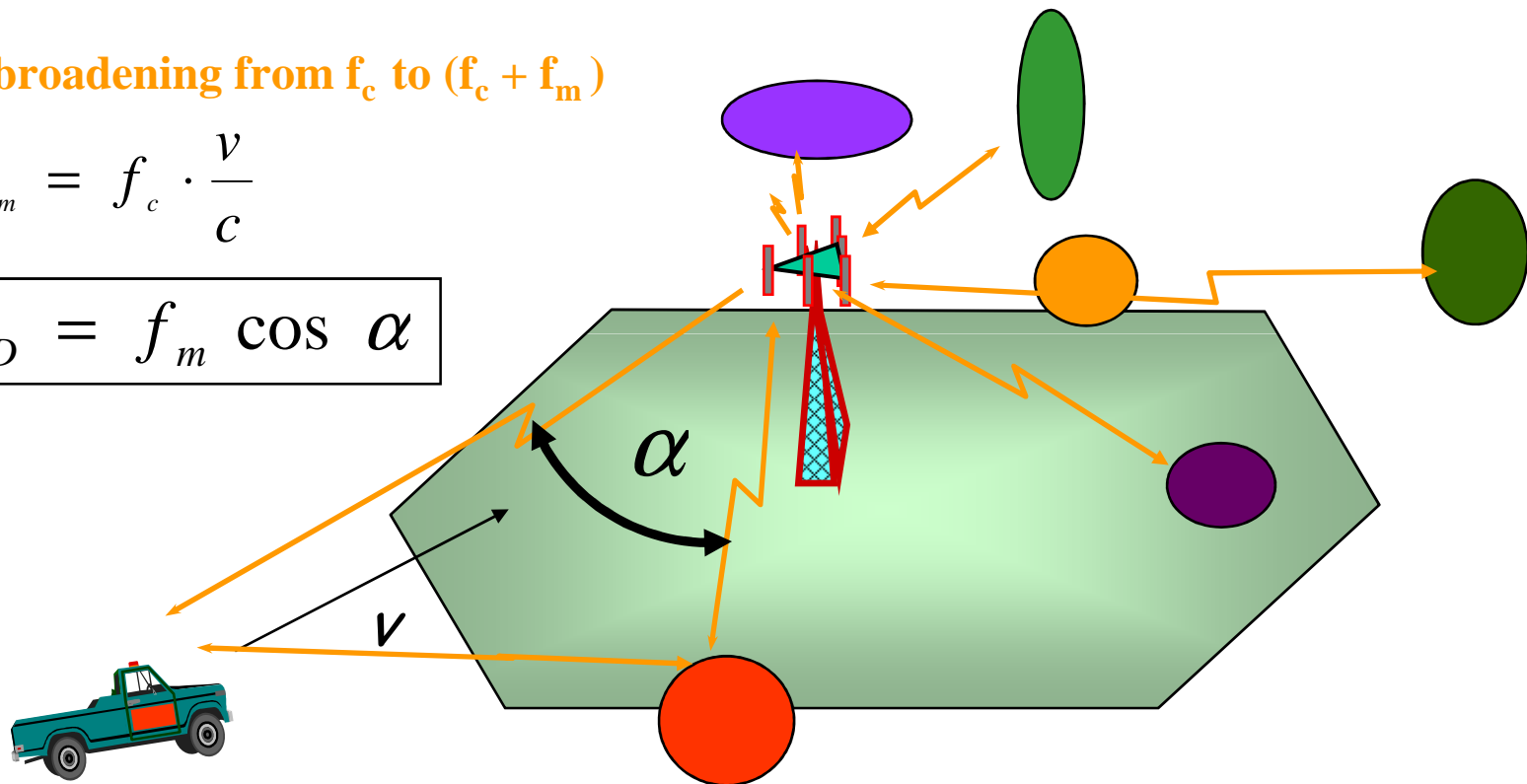


Doppler Shift

- f_c broadening from f_c to $(f_c + f_m)$

$$f_m = f_c \cdot \frac{v}{c}$$

$$f_D = f_m \cos \alpha$$





Effect of Doppler Spread

$$f = f_m \cos \alpha \quad \alpha - \text{uniformly distributed } (0, 2\pi)$$

$$S_f(f) = \frac{S_\alpha(\alpha)}{|(f_m \cos \alpha)|}$$

$$S_f(f) = \frac{1}{2\pi f_m \sin \alpha}$$

$$S_f(f) = \frac{1}{2\pi f_m \sqrt{1 - \frac{f^2}{f_m^2}}}$$

$$\sin \alpha = \sqrt{1 - \cos^2 \alpha}$$

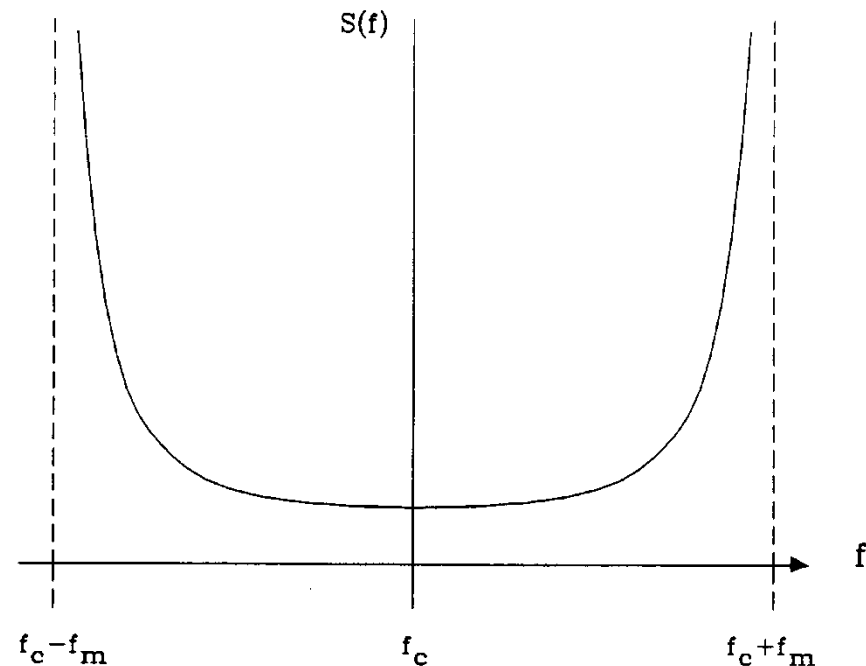
$$\cos \alpha = \frac{f}{f_m}$$



Doppler Spectrum

- the incident received power at the MS depends on the power gain of the antenna and the polarization used

$$S(f) = \frac{A}{\sqrt{1 - (f / f_m)^2}}$$



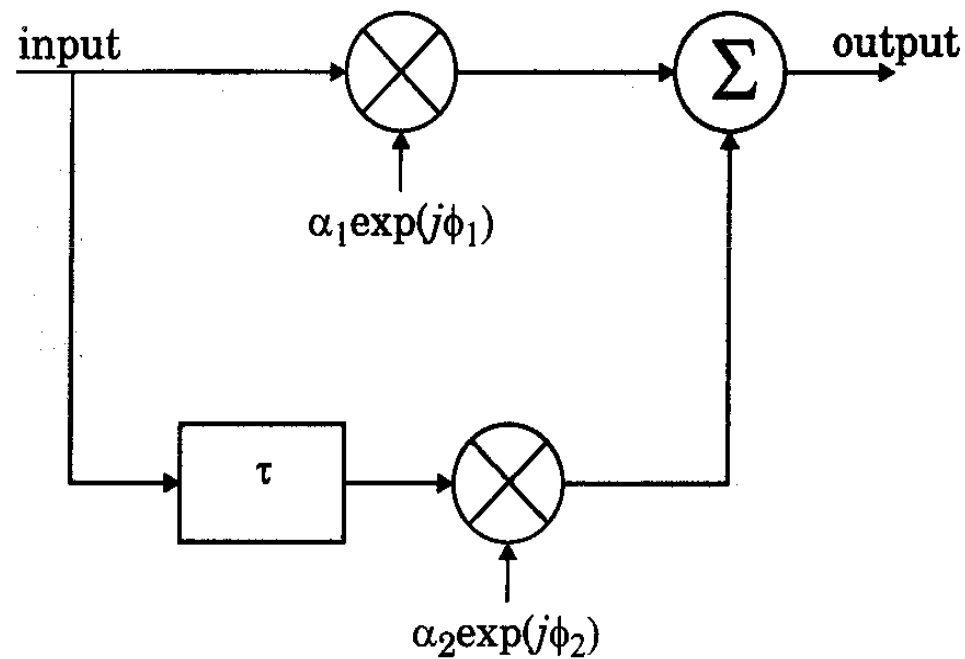


Two-ray Rayleigh Fading Model

- Clarke's model for flat fading
- It is necessary to model multi-path delay spread as well
- Commonly used model is the two-ray model



Two-ray Rayleigh Fading Model





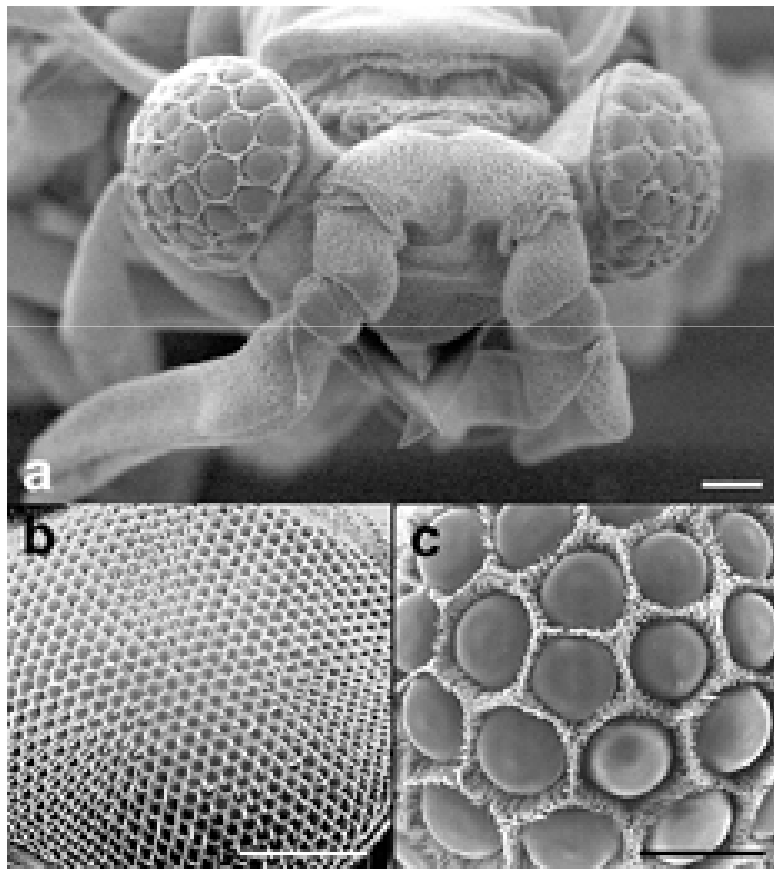
Two-ray Rayleigh Fading Model

- The impulse response of the model

$$h_b = \alpha_1 \exp(j\phi_1) \delta(t) + \alpha_2 \exp(j\phi_2) \delta(t - \tau)$$

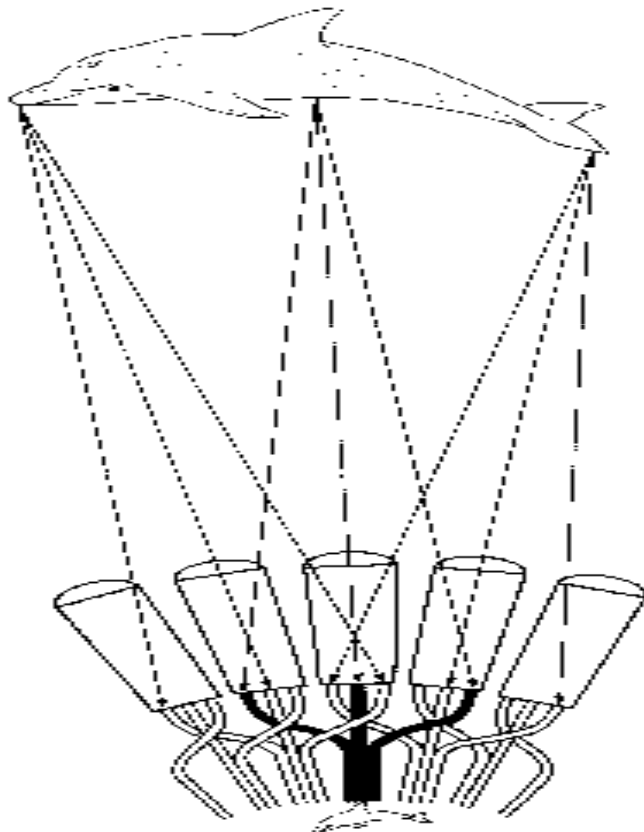
- α_1 and α_2 are independent and Rayleigh distributed
- ϕ_1 and ϕ_2 are independent and uniformly distributed over $[0, 2\pi]$
- τ - time delay between the two rays
- By varying τ it is possible to create a wide range of frequency selective fading effects

Beyond Current Engineering Practice



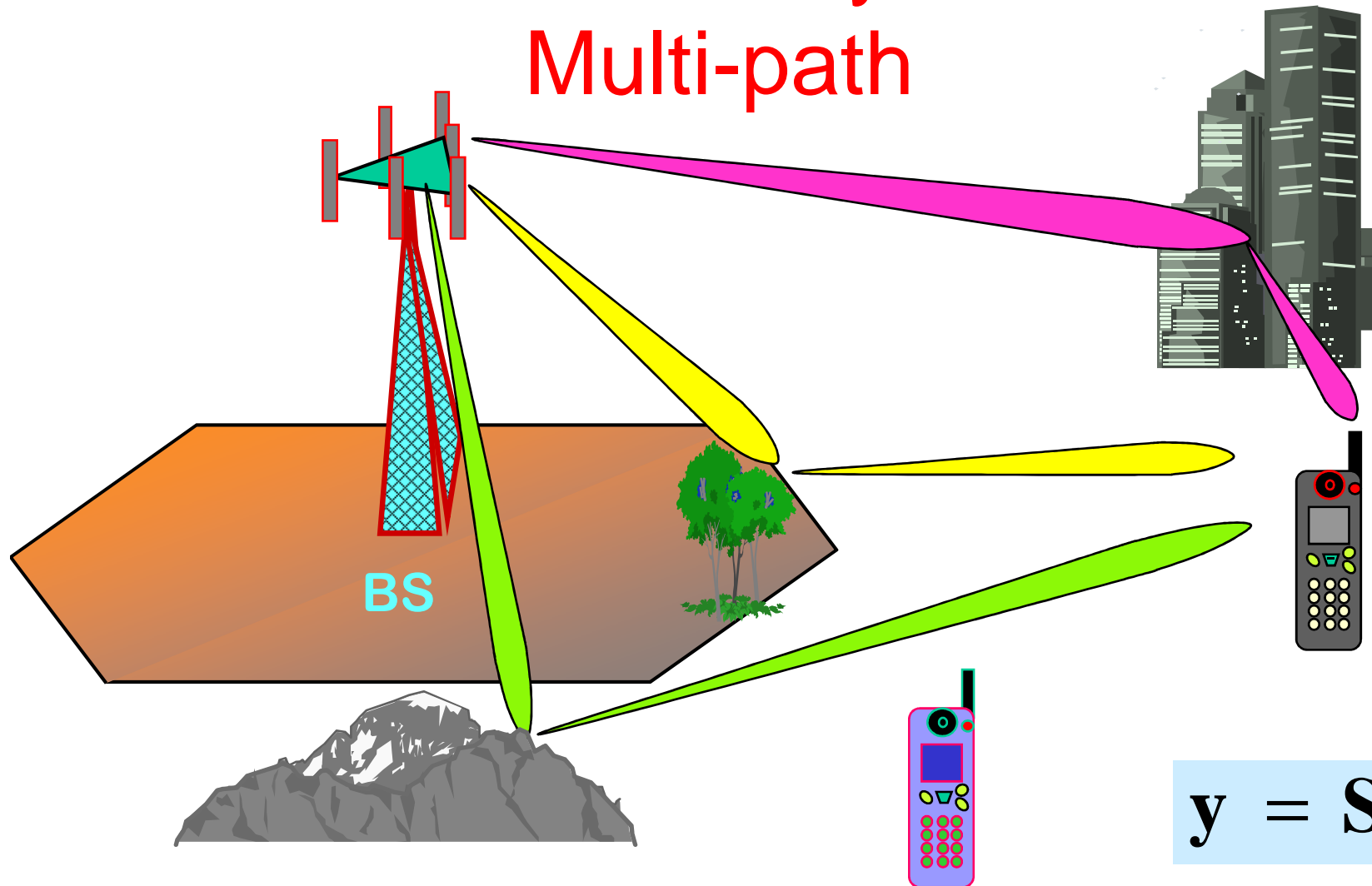


Antenna Arrays are Electromagnetic Eyes





Smart Antenna System with Multi-path



$$y = Sx + n$$

Multi-Path Fading
Channel

EE4733 Wireless Communications
Week 12-13; Fall - 2014

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Array of N Elements

