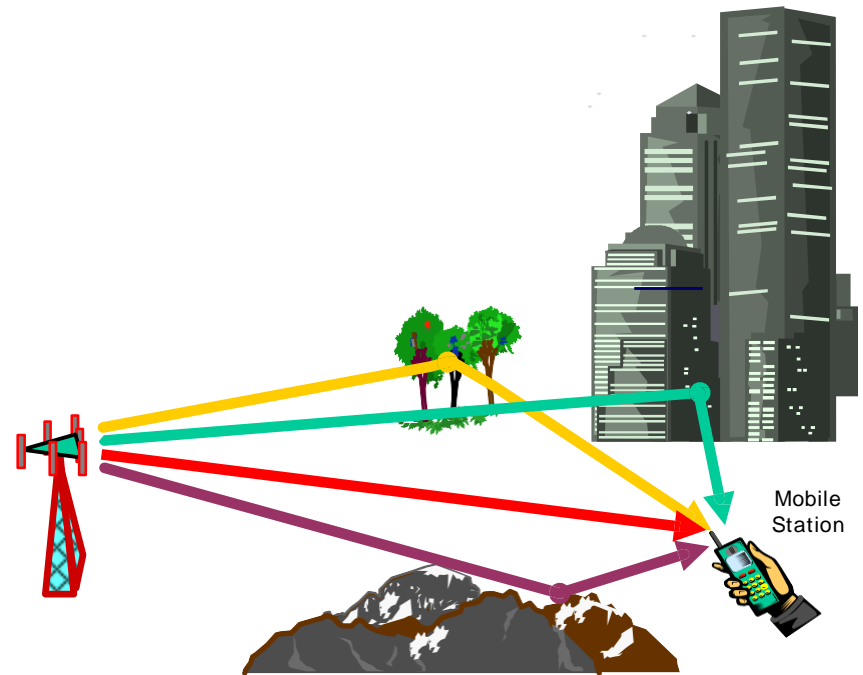
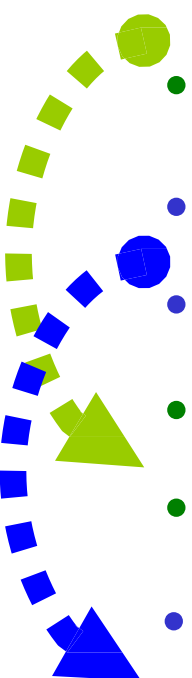


# ***Multi-Path Fading Channel***

*Department of Computer System  
Engineering University Of Engineering and  
Technology Peshawar Pakistan.*

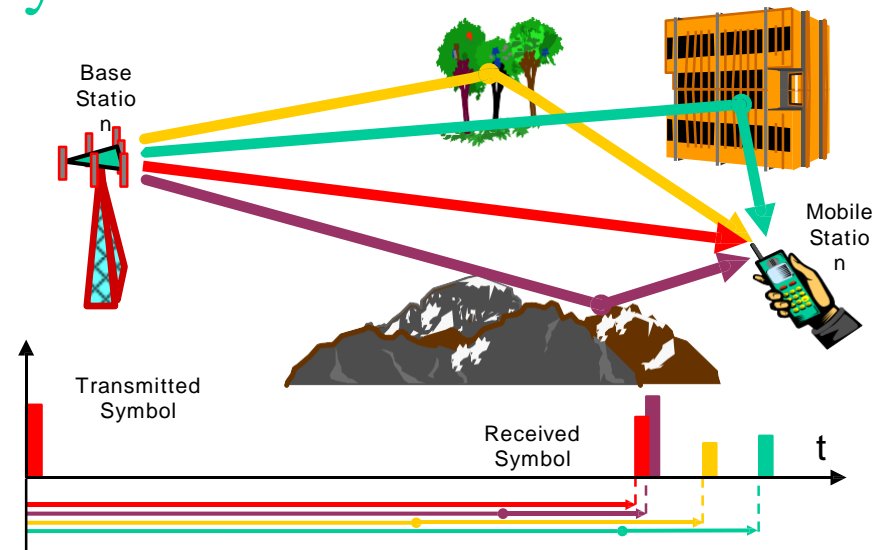


# Mobile Channel Parameters

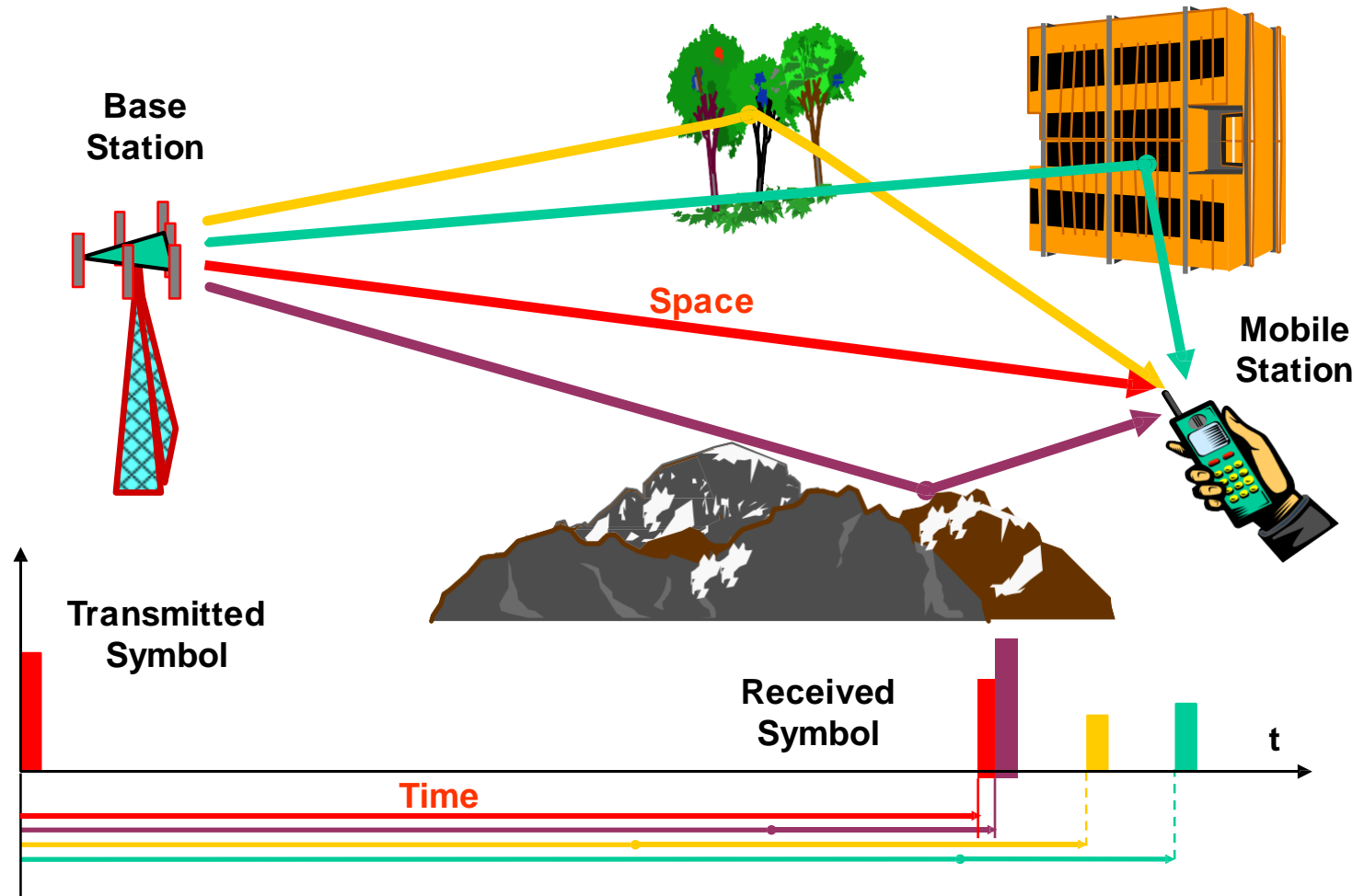
- 
- Time delay spread |
  - Coherence Bandwidth | -> ISI
  - Doppler Spread |
  - Coherence Time | -> Unstable channel
  - Flat fading
  - Frequency selective fading
  - Fast fading
  - Slow fading

# Multi-path Propagation

- Multi-path smears or spreads out the signal
  - delay spread
- Causes inter-symbol interference
  - limits the maximum symbol rate



# Delay Spread



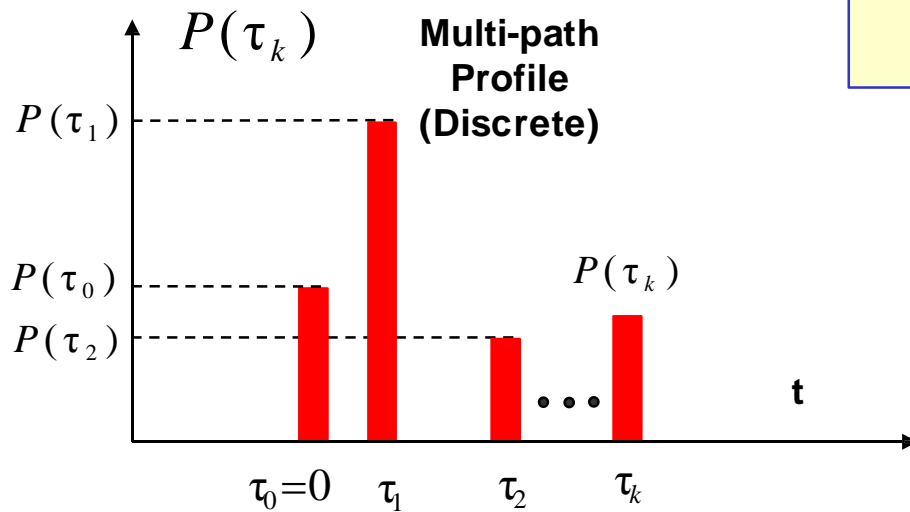
# Intersymbol Interference



# Average Delay Spread

- Average delay spread  $\bar{\tau}$

$$\bar{\tau} = \frac{\sum_k |a_k|^2 \tau_k}{\sum_k |a_k|^2} = \frac{\sum_k P(\tau_k) \tau_k}{\sum_k P(\tau_k)}$$



# RMS Delay Spread (Discrete)

- RMS delay spread  $\sigma_\tau$

$$\sigma_\tau = \sqrt{\overline{\tau^2} - \bar{\tau}^2}$$

$$\sigma_\tau^2 = \frac{\sum_k |a_k|^2 \tau_k^2}{\sum_k |a_k|^2} = \frac{\sum_k P(\tau_k) \tau_k^2}{\sum_k P(\tau_k)}$$

# Coherence Bandwidth

- Coherence bandwidth  $B_c$  is a range of frequencies over which the channel can be considered flat
  - passes all spectral components with approximately equal gain and linear phase
- Bandwidth where the correlation function  $R_T(\omega)$  for signal envelopes is high
- Therefore two sinusoidal signals with frequencies that are farther apart than the coherence bandwidth will fade independently.



# Coherence Bandwidth

- If  $R_T(\omega) > 0.9$

$$B_C = \frac{1}{50\sigma_\tau}$$

- If  $R_T(\omega) > 0.5$

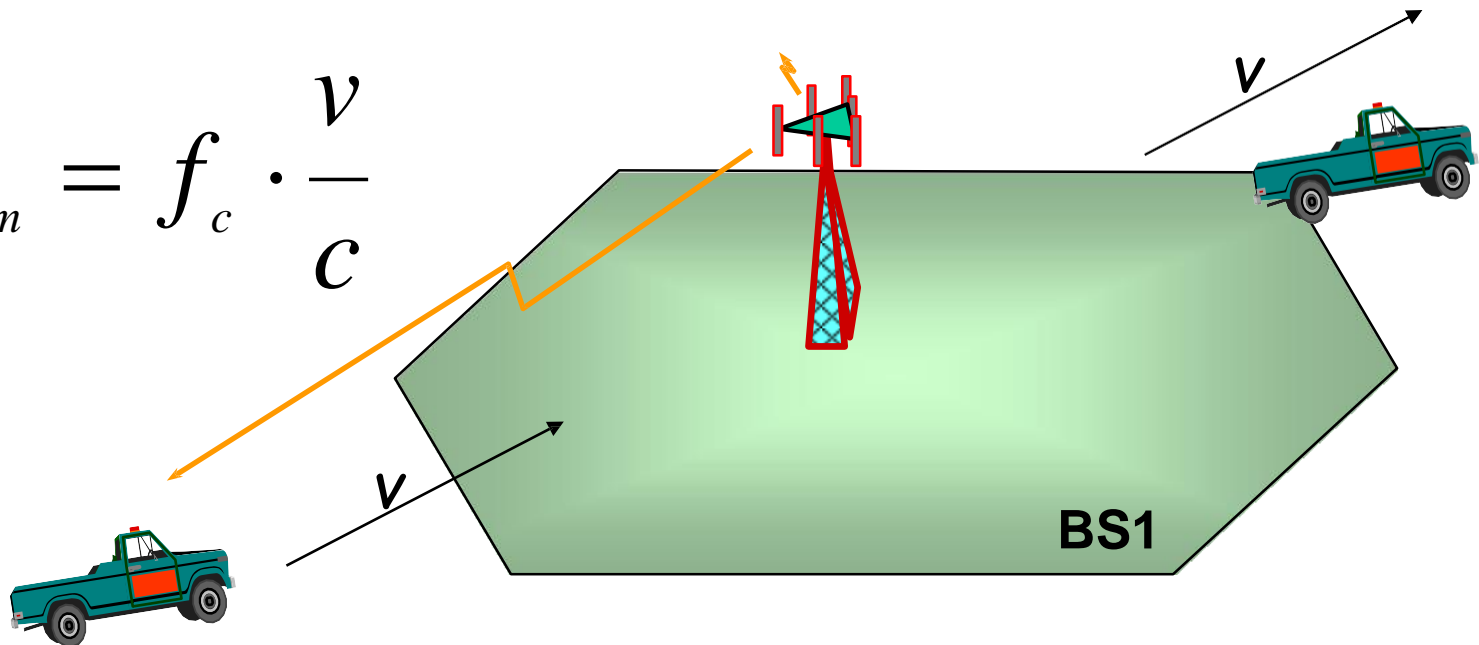
$$B_C = \frac{1}{5\sigma_\tau}$$

- An exact relationship between coherence bandwidth & delay spread does not exist

# Doppler Shift

- $f_c$  broadening from  $f_c$  to  $(f_c + f_m)$

$$f_m = f_c \cdot \frac{v}{c}$$



# Relativistic Doppler Frequency

**The observed frequency is**

$$f = f_c \cdot \sqrt{\frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}} \quad f_d = f - f_c \approx f_c \cdot \frac{v}{c}$$

**where the relative velocity  $v$  is positive if the source is approaching and negative if receding.**

$f_c$ - carrier freq.,  $c$ -speed of light,  $f_d$ -Doppler shift

# Doppler Spread & Coherence Time

- Describes the time varying nature of the channel in a local area
- Doppler Spread  $B_D$ , is a measure of the spectral broadening caused by the time rate of change
- $f_c$  broadening from  $(f_c - f_m)$  to  $(f_c + f_m)$
- If the base-band signal bandwidth is much greater than  $B_D$ , the effects of Doppler spread are negligible at the receiver

# Coherence Time

- Coherence Time is the time domain dual of Doppler spread
- Doppler spread and coherence time are inversely proportional
- $T_C = 1/f_m$
- Statistical measure of the time duration over which the channel impulse response is invariant

# Coherence Time

- If the coherence time is defined as the time over which the correlation function is above 0.5, then

$$T_c \approx \frac{9}{16\pi f_m}$$

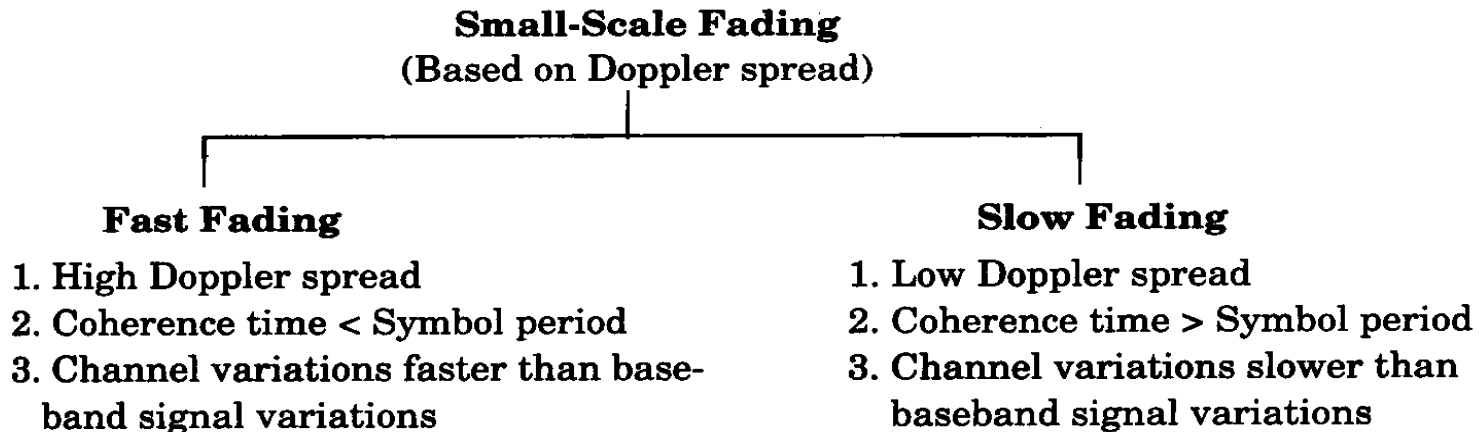
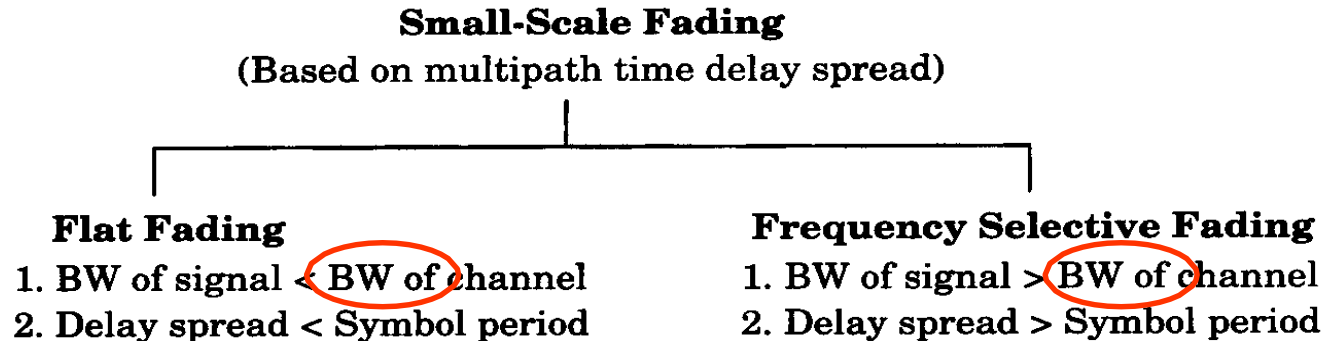
- Rule of thumb for modern digital communication defines TC as the geometric mean of the above two expressions for TC

$$T_c = \sqrt{\frac{9}{16\pi f_m^2}}$$

# Inter-symbol Interference

- For no Inter-symbol Interference the transmission rate  $R$  for a digital transmission is limited by delay spread and is represented by:  
 $R < 1/2\sigma_\tau$ ;
- If  $R > 1/2\sigma_\tau$  Inter-symbol Interference (ISI) occurs
- Need for ISI removal measures (Equalizers)

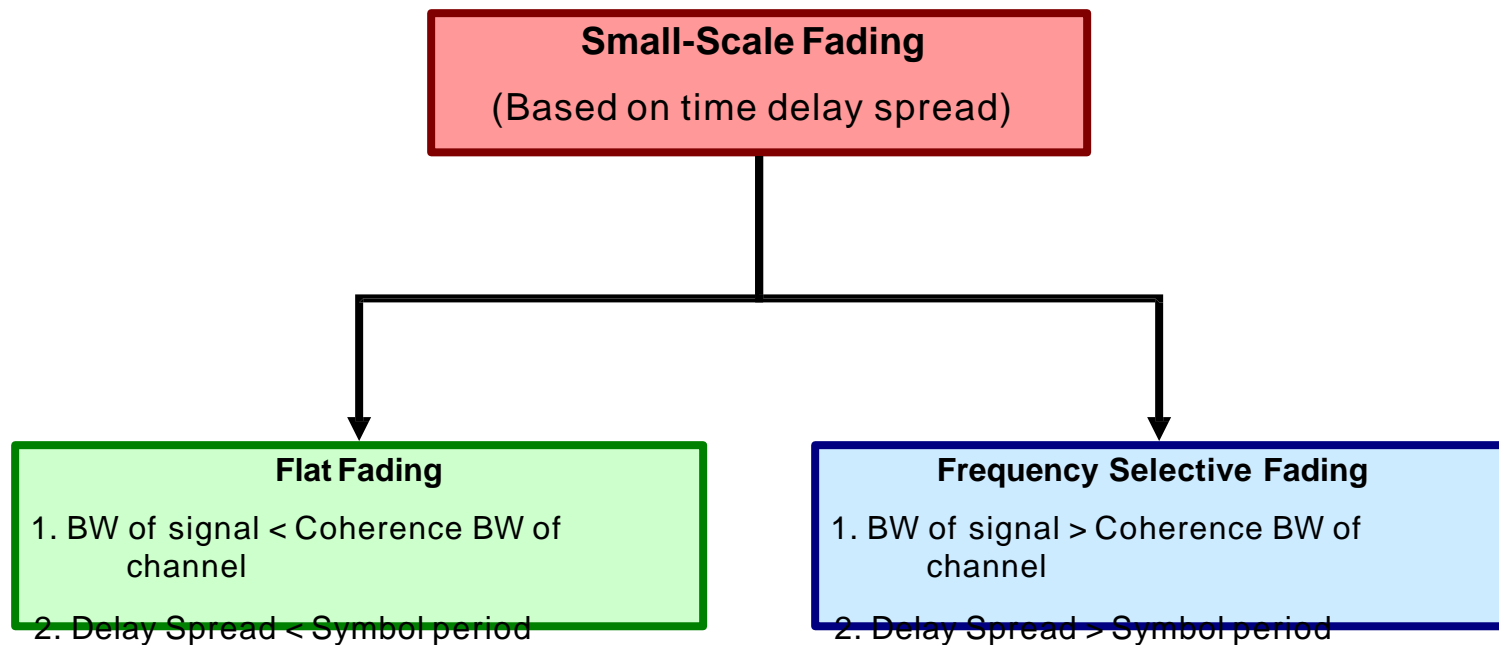
# Types of Small-Scale Fading



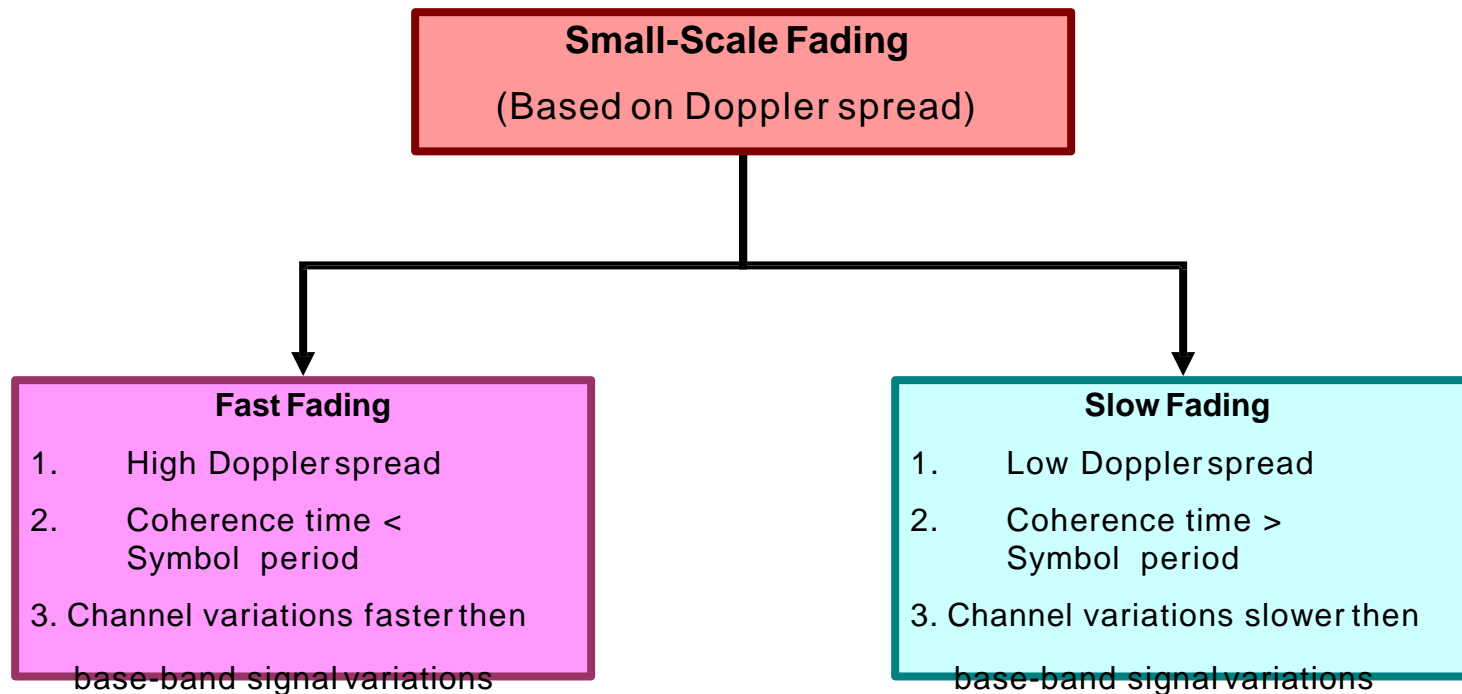


# Small-Scale Fading

## Delay Spread



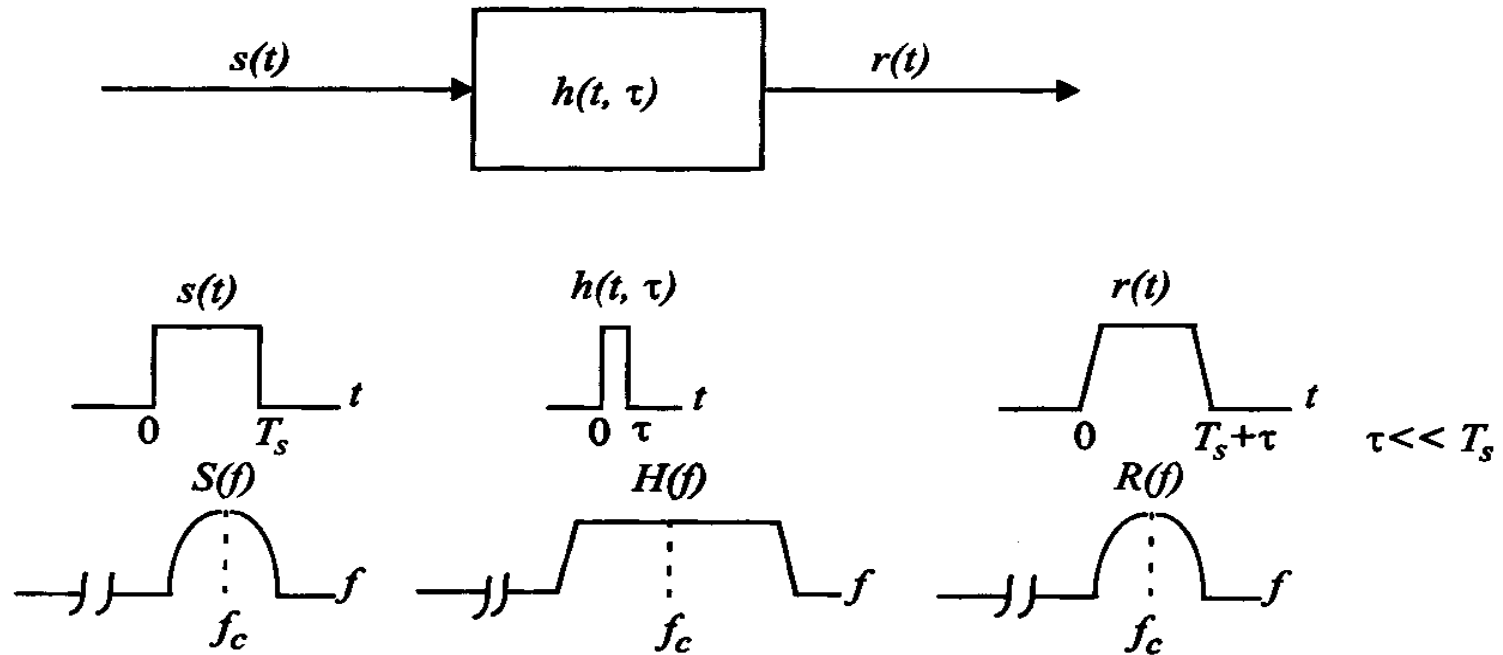
# Small-Scale Fading Time Variations



# Flat Fading 1

- If the mobile radio channel has a constant gain and linear phase over a bandwidth *greater* than the bandwidth of the transmitted signal - the received signal will undergo *flat fading*
- Please, observe that the fading is flat (or frequency selective) depending on the signal bandwidth relative to the channel coherence bandwidth.

# Flat Fading 2

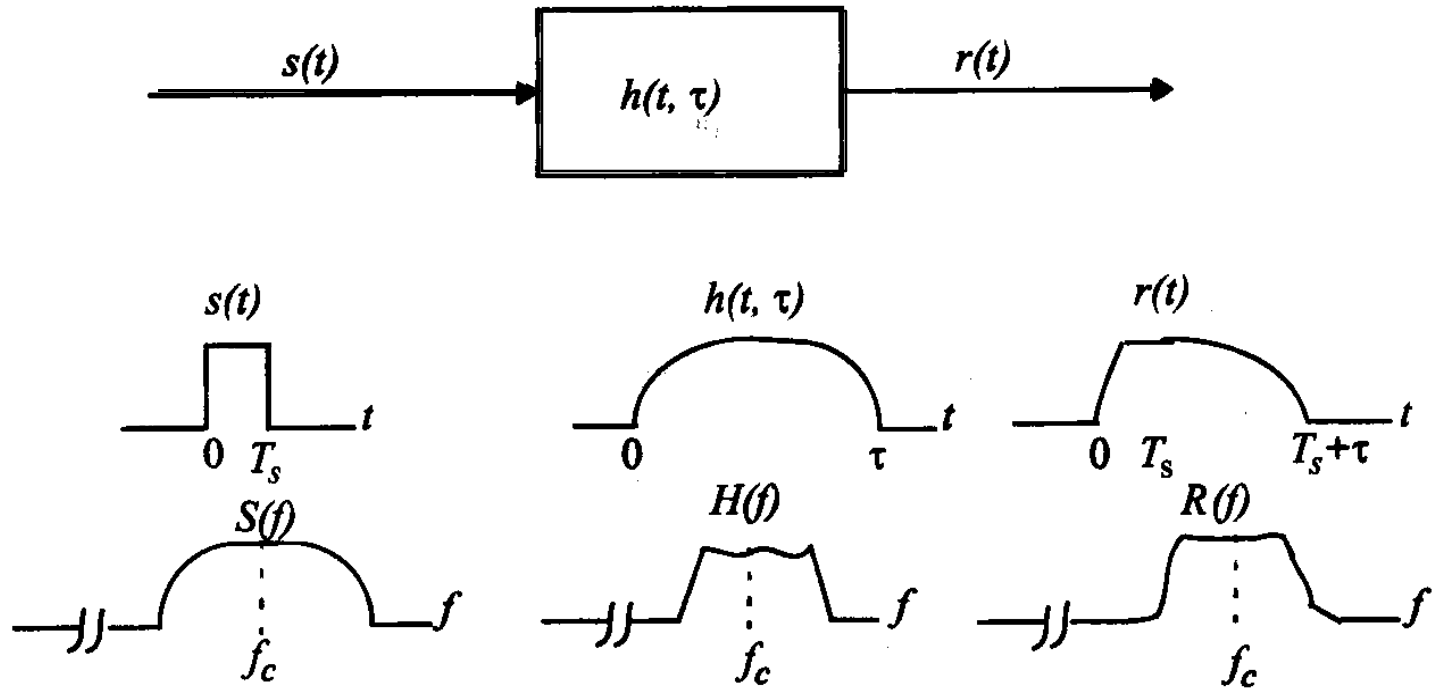


- $B_S \ll B_C$  &  $T_S \gg \sigma_\tau$

# Frequency Selective Fading 1

- If the mobile radio channel has a constant gain and linear phase over a coherence bandwidth, *smaller* than the bandwidth of the transmitted signal - the received signal will undergo *frequency selective fading*
- Again, the signal bandwidth is wider than the channel coherence bandwidth, causing one or more areas of attenuation of the signal within the signal bandwidth

# Frequency Selective Fading 2



- $BS > B_C$  &  $T_S < \sigma_\tau$

# Fast Fading

- The channel impulse response changes rapidly within the symbol duration - coherence time  $<$  symbol period
- $T_S > T_c$  and  $B_S < B_D$
- Channel specifies as a fast or slow fading channel does not specify whether the channel is flat fading or frequency selective fading

# Slow Fading

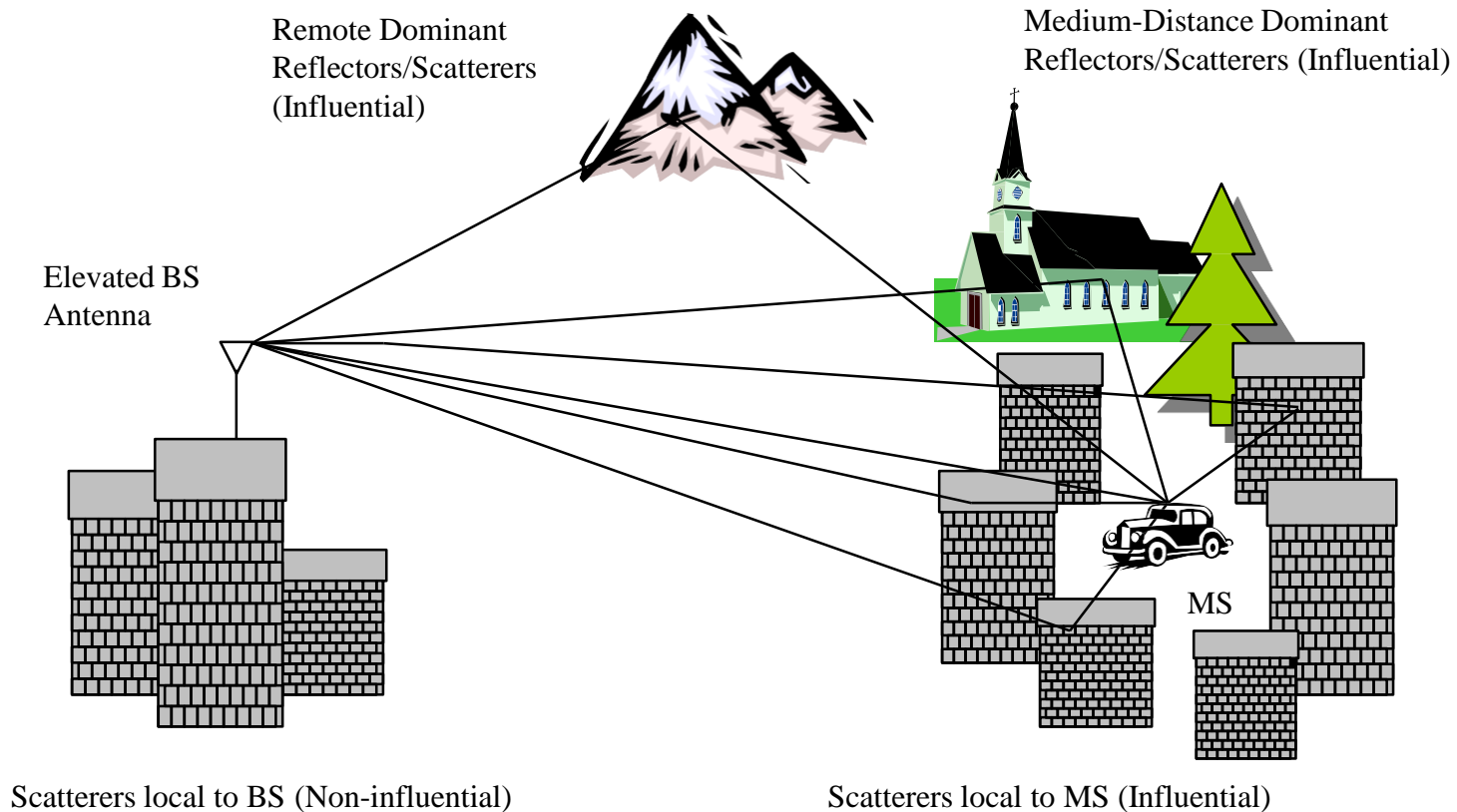
- The channel impulse response changes at a rate much slower than the transmitted base-band signal.
- Doppler spread is much less than the bandwidth of the base-band signal
- $T_s \ll T_c$  and  $B_s \gg B_D$
- Velocity of the MS and the base-band signaling determines whether a signal undergoes fast or slow fading



# Summary

- Fast and slow fading deal with the relationship between the time rate of change in the channel and the transmitted signal, NOT with propagation path loss models

# Typical Cellular Mobile Environment



# Fading

- **Fading:** The interference between two or more versions of the transmitted signal which arrive at the receiver at **slightly** different times
- **Multipaths:** Above mentioned versions of the transmitted signal

# Fading (Continued)

Delay Spread  $\leftrightarrow$  Coherence Bandwidth

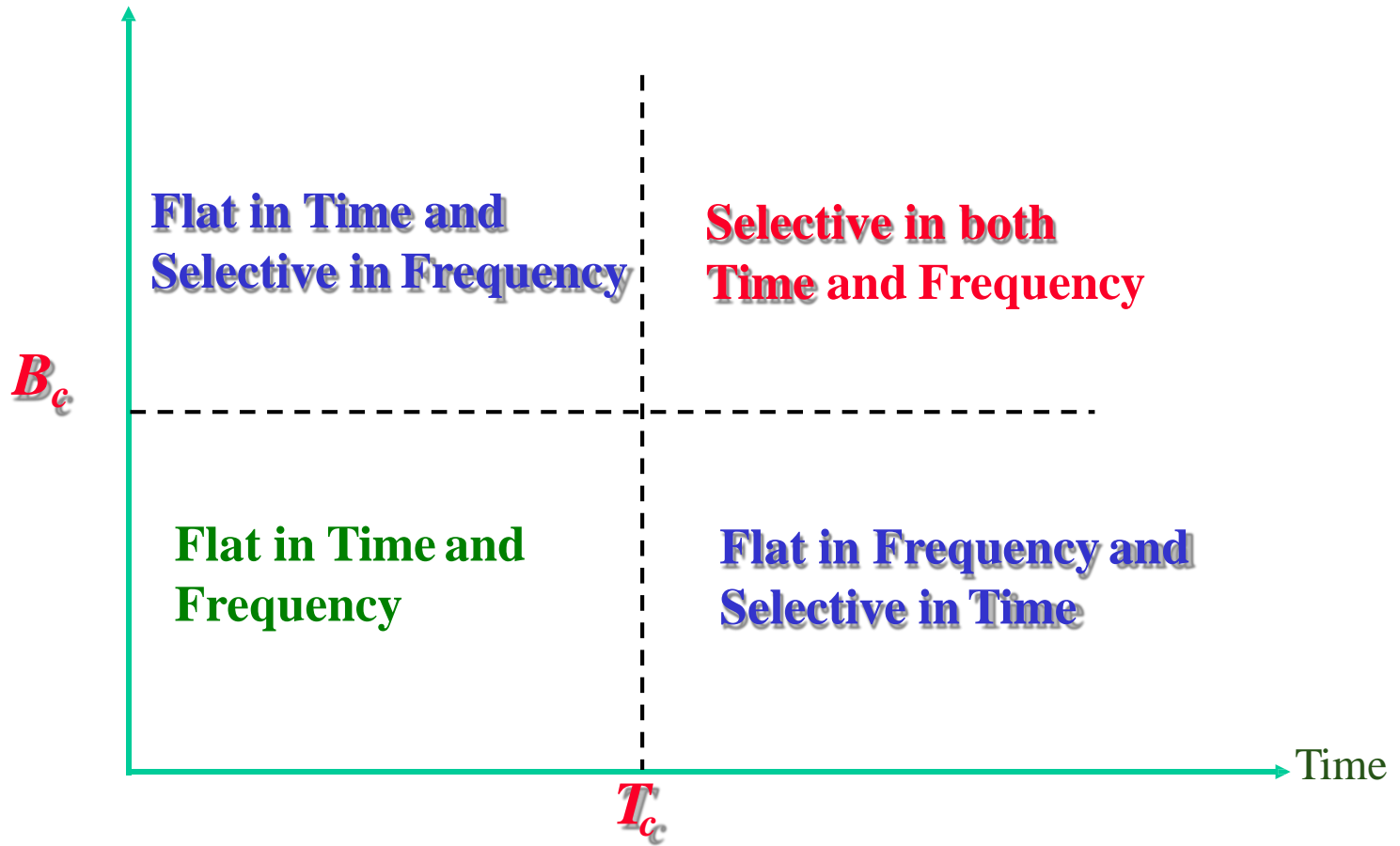
Frequency separation at which two frequency components of Tx signal undergo independent attenuations

Doppler Spread  $\leftrightarrow$  Coherence Time

Time separation at which two time components of Tx signal undergo independent attenuations

# Fading (Continued)

Bandwidth



# Fading (Continued)

## Fast and Slow Fading

If the channel response changes within a symbol interval, then the channel is regarded **FAST FADING**

Otherwise

the channel is regarded as **SLOW FADING**

# Fast Fading

## When?

The channel impulse response changes rapidly within the symbol period of the transmitted signal.

## What?

The Doppler Spread causes frequency dispersion which leads to signal distortion.

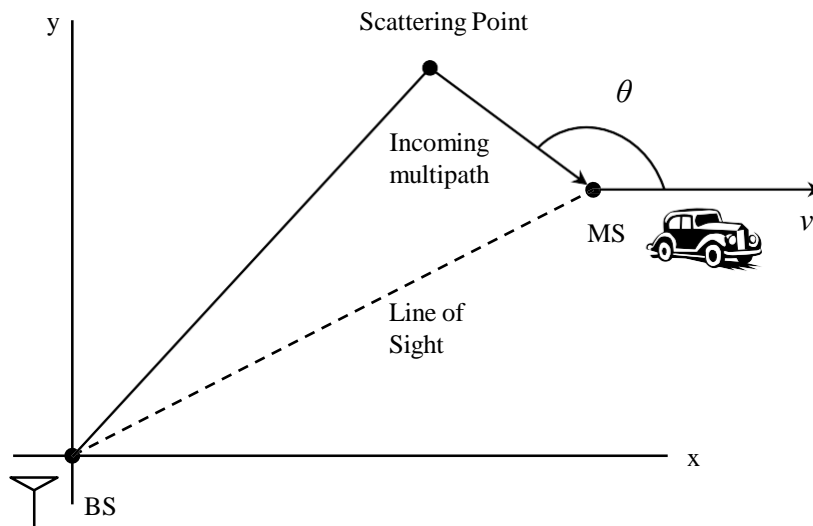
# Doppler Spread

The **Doppler** effect (in addition to the fading effect) renders the received pulse to be **time-varying**

The **State Transitions** are determined from the dynamics of the fading channel (Fading Correlation Function or The **Doppler Spectrum**)



# Doppler Spread (Continued)



$f$ : carrier frequency

$c$ : speed of light

$v$ : mobile speed

$\theta$ : Angle of motion with  
incoming multipath

# Doppler Spread (Continued)

$$f_d = \frac{f v \cos \theta}{c}$$

$f$ : carrier frequency

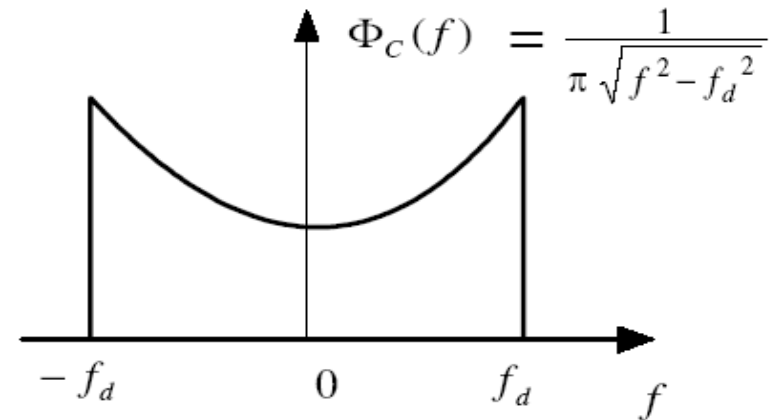
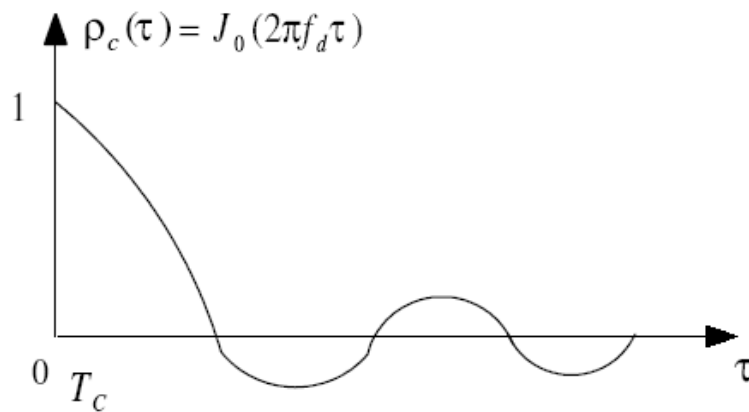
$c$ : speed of light

$v$ : mobile speed

$\theta$ : Angle of motion with  
incoming multipath

# Doppler Spread (Continued)

For the land mobile fading spectrum,

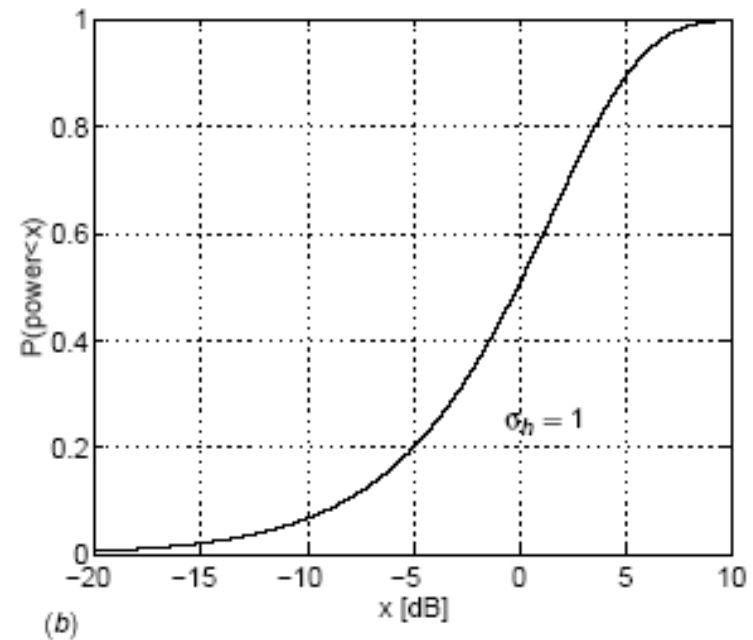
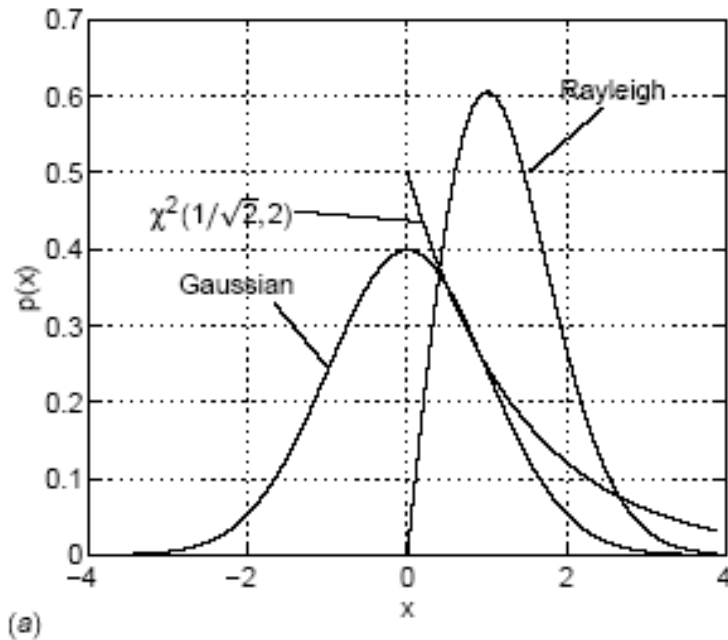


The Auto-Correlation Function

Doppler Fading Spectrum

# Doppler Spread (Continued)

- $h$  is the channel impulse response
- $h$  has a complex normal distribution with zero mean
- $|h|$  is Rayleigh distributed
- Phase  $\phi$  is uniformly distributed between 0 and  $2\pi$
- $|h|^2$  is *Chi-square* distributed



# Fading in Brief

Large Doppler Spread



Time-Selective Fading

Large Delay Spread

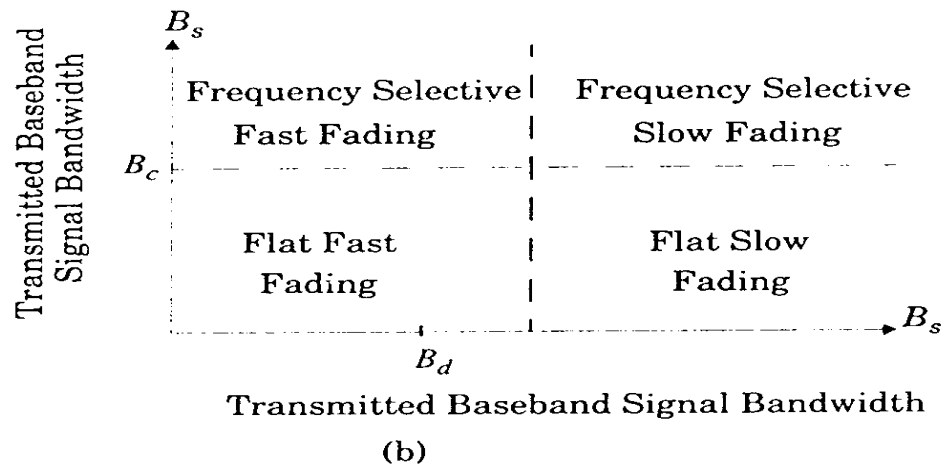
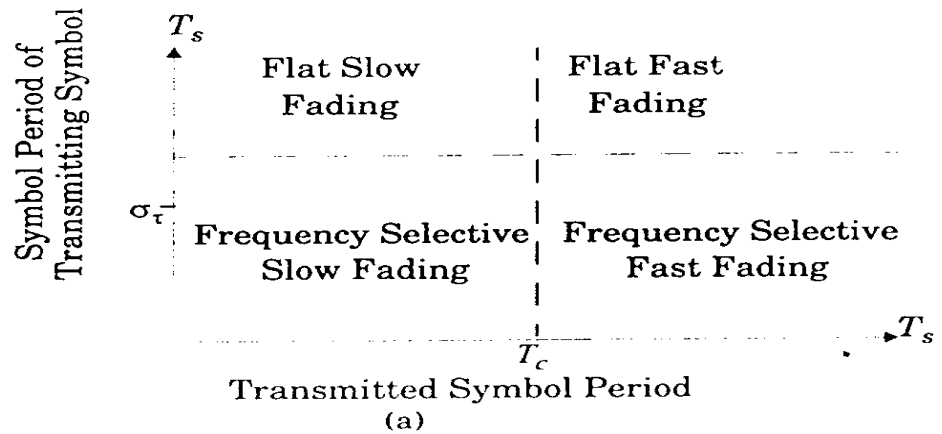


Frequency-Selective Fading

Large Angle Spread



Space-Selective Fading

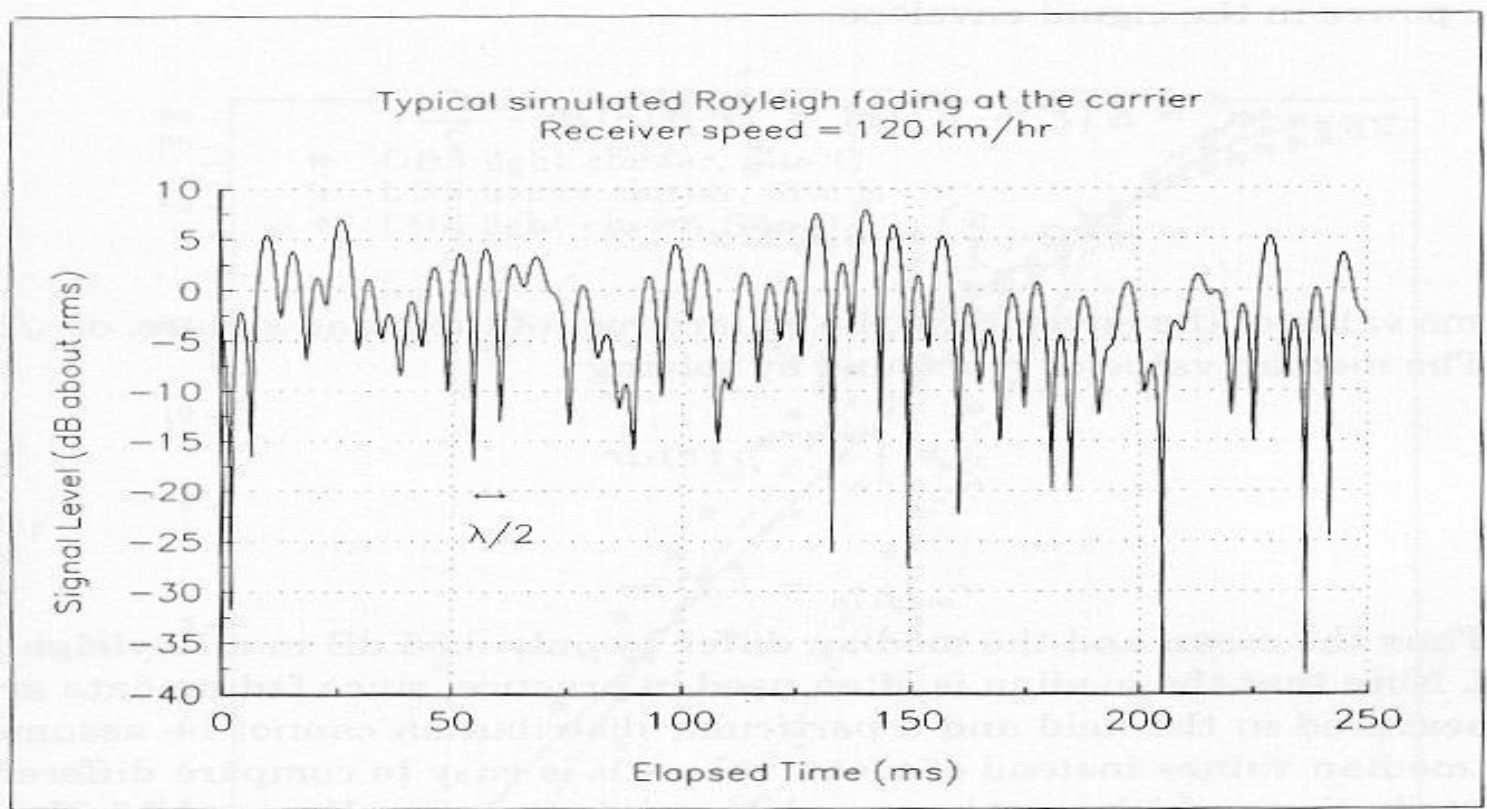


# Rayleigh Fading 1

- The received envelope (amplitude) of a flat fading signal is described as a Rayleigh distribution
  - Square root sum  $r$ , of two quadrature Gaussian noise signals  $x_I$  and  $y_Q$  has a Rayleigh distribution (Papoulis65)

$$r = \sqrt{x_I^2 + y_Q^2} \quad p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right); & (0 \leq r \leq \infty) \end{cases}$$

# Rayleigh Fading 2





# Rayleigh Fading PDF

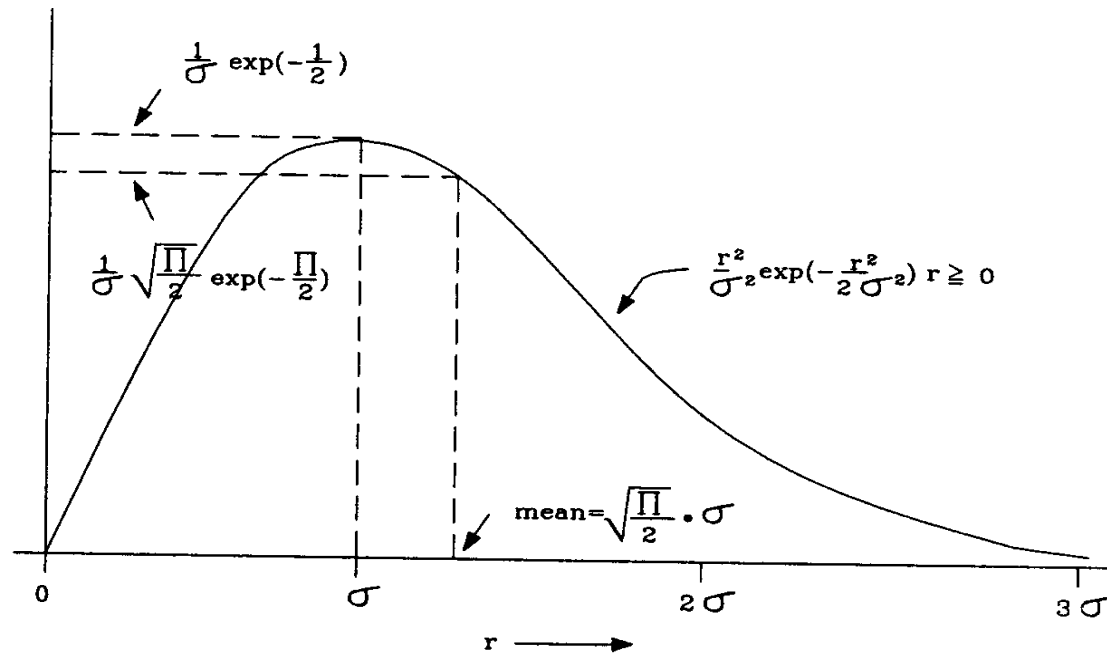


Figure 1.2: Rayleigh PDF.

# Rayleigh Fading 3

$$p(r) = \begin{cases} \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right) & (0 \leq r \leq \infty) \end{cases}$$

- $\sigma$  - rms value of the received voltage signal before envelope detection
- $\sigma^2$  - time average power before envelope detection
- The probability that the received signal envelope does not exceed  $R$  is given by:

$$P(R) = \Pr(r \leq R) = \int_0^R p(r) dr = 1 - \exp\left(-\frac{R^2}{2\sigma^2}\right)$$

# Rayleigh Fading 4

- The median value of  $r$  is found by solving

$$\frac{1}{2} = \int_0^{r_{median}} p(r) dr$$

$$r_{median} = 1.77 \sigma$$

- Mean and median differ by only 0.55dB

# Ricean Fading 1

- When there is a dominant stationary signal component
- At the output of an envelope detector - adding a DC component to the random multi-path

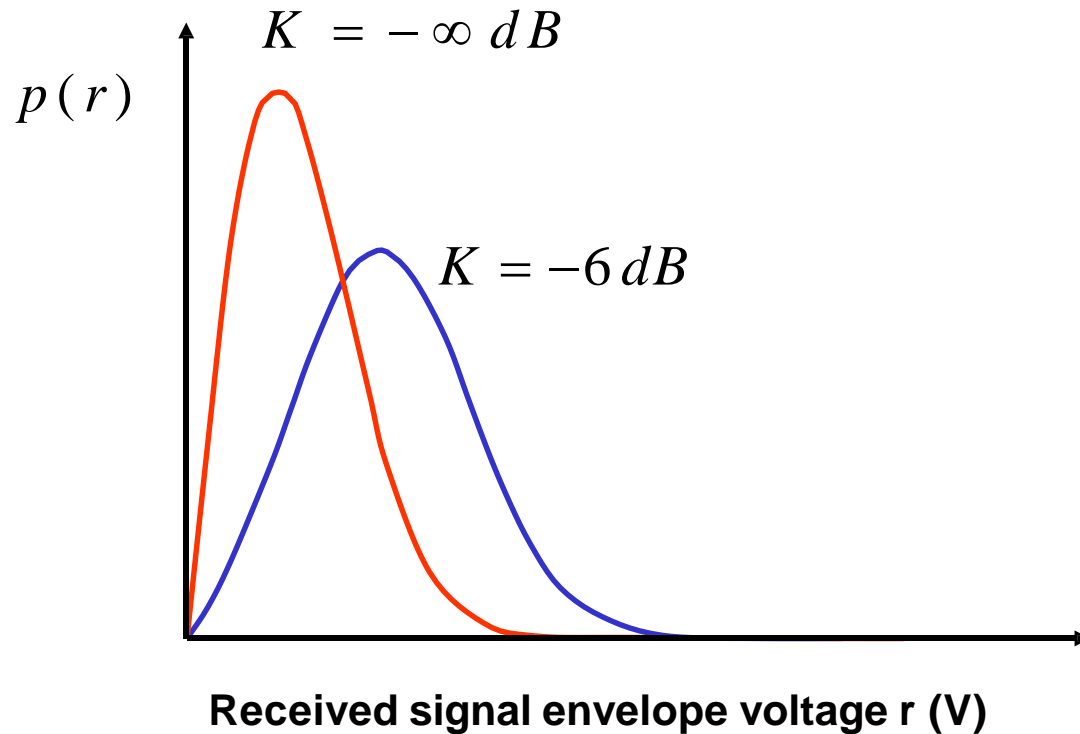
$$p(r) = \frac{r}{\sigma^2} e^{-\frac{(r^2 + A^2)}{2\sigma^2}} I_0\left(\frac{Ar}{\sigma^2}\right); \quad \text{for } (A \geq 0, r \geq 0)$$

# Ricean Fading 2

- $A$  - peak amplitude of the dominant signal
- $I_0()$  - modified Bessel function of the first kind and zero order
- Described in terms of a Ricean factor,  $K$

$$K(dB) = 10 \log \frac{A^2}{2\sigma^2} (dB)$$

# Ricean PDF



# Clarks Model for Flat Fading 1

- Statistical Characteristics of the EM fields of the received signal at the MS are obtained from scattering
- Assumes
  - Fixed transmitter & vertically polarized antenna
  - Fields incident on the mobile antenna comprises of  $N$  waves in azimuth plane with arbitrary carrier phases and azimuth angels of arrival
  - equal average signal amplitude

# Clarks Model for Flat Fading 2

- The model shows that the random received signal envelope  $r$  has a Rayleigh distribution and is given by:

$$p(r) = \frac{r}{\sigma^2} \exp\left(-\frac{r^2}{2\sigma^2}\right); \quad 0 < r \leq \infty$$



# Effect of Doppler Spread

- It can be shown that if the angle of the received signals,  $\alpha_i$  is uniformly distributed that the Doppler frequency has a random cosine distribution.
- Then the Doppler power spectral density  $S(f)$  can be computed by equating the incident received power in an angle  $d\alpha$  with Doppler power  $S(f)df$ 
  - $df$  is found by differentiating the Doppler term  $f_m \cos \alpha$  wrt  $\alpha$ .

# Function of One Random Variable

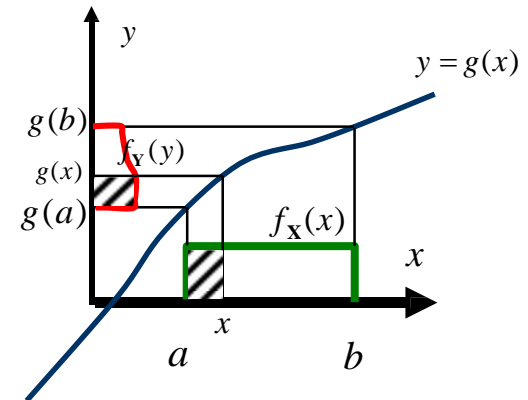
x - random variable

$$\int_a^b f_X(x) dx = 1$$

$y = g(x)$ ; function of x

y - random variable

$$\int_{g(a)}^{g(b)} f_Y(y) dy = 1$$



$$\int_{g(a)}^{g(b)} f_Y(y) dy = 1$$

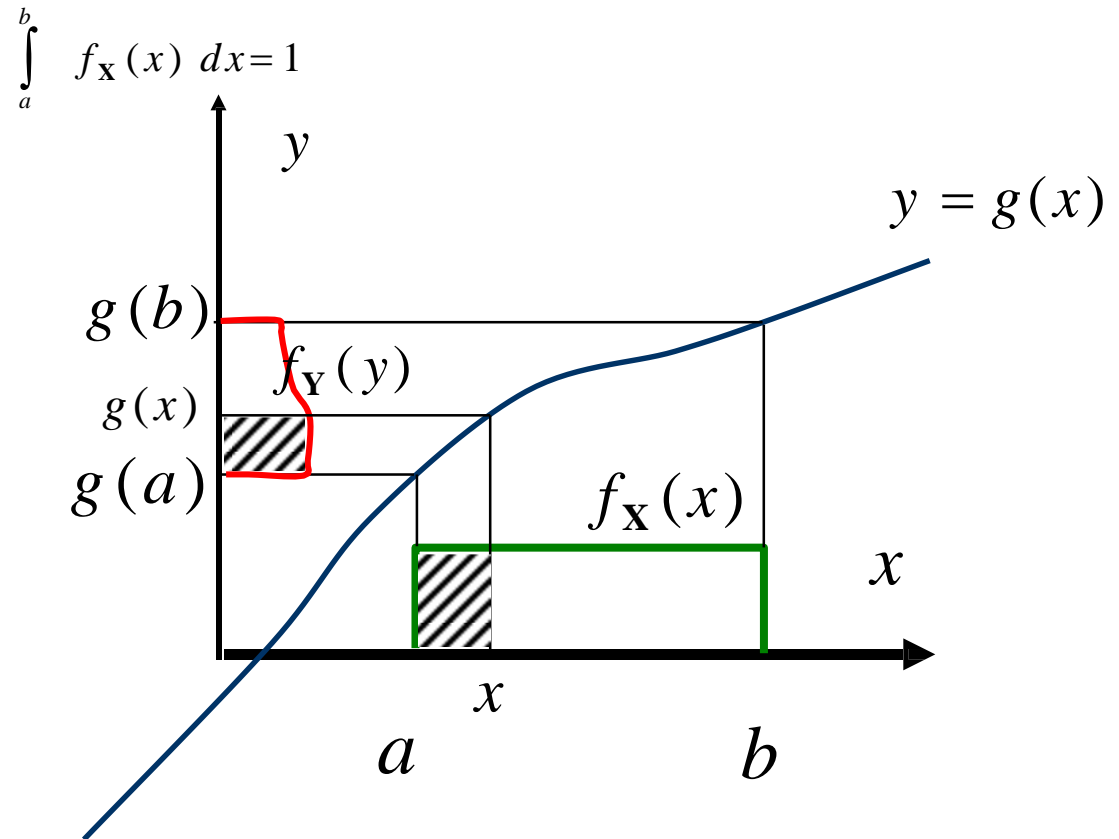
$$f_Y(y) dy = f_X(x) dx$$

# Function of One Random Variable

$x$  - random variable

$y = g(x)$ ; function of  $x$

$y$  - random variable



$$f_Y(y) dy = f_X(x) dx$$

# Function of One Random Variable

y - random  
variable

$y = g(x)$ ; function of x

$y = g(x)$ ; substitution  
in

$$y \Big|_{g(a)}^{g(b)}$$

$$\int_{g(a)}^{g(b)} f_Y(y) dy = 1$$

$$\int_{g(a)}^{g(b)} f_Y(y) dy = 1$$

$$f_Y(y) = f_Y(g(x)); \quad dy = g'(x) dx; \quad y \Big|_{g(a)}^{g(b)} \Rightarrow x \Big|_a^b$$

$$\int_a^b f_Y(g(x)) g'(x) dx = \int_a^b f_X(x) dx = 1$$

$$\int_a^{g(x)} f_Y(g(x)) g'(x) dx = \int_a^x f_X(x) dx$$

# Function of One Random Variable

$$\int_a^{g(x)} f_Y(g(x)) g'(x) dx = \int_a^x f_X(x) dx$$

$$f_Y(g(x)) g'(x) = f_X(x)$$

$$f_Y(y) g'(x) = f_X(x)$$

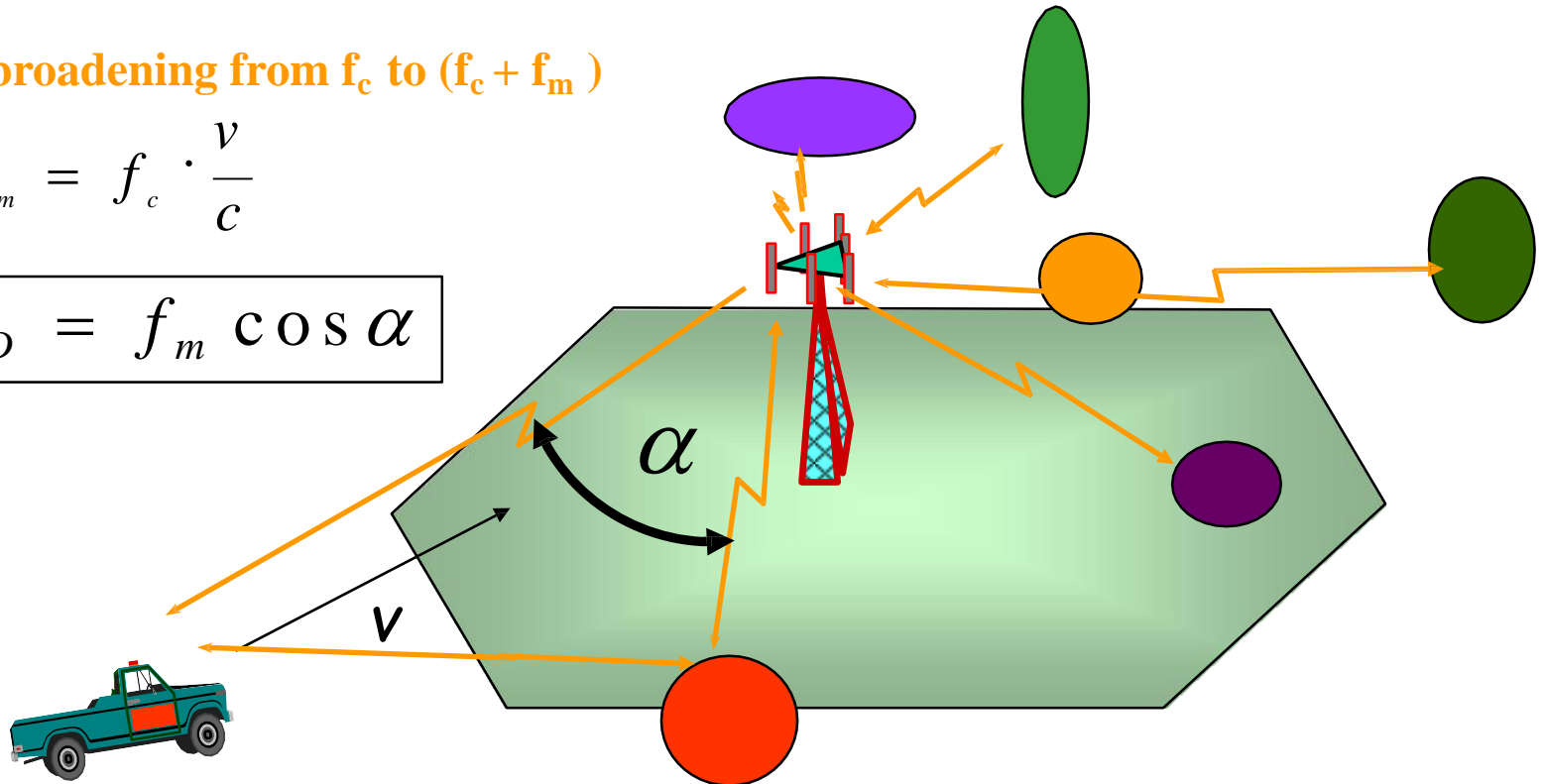
$$f_Y(y) = \frac{f_X(x)}{|g'(x)|}$$

# Doppler Shift

- $f_c$  broadening from  $f_c$  to  $(f_c + f_m)$

$$f_m = f_c \cdot \frac{v}{c}$$

$$f_D = f_m \cos \alpha$$



# Effect of Doppler Spread

$$f = f_m \cos \alpha \quad \alpha - \text{uniformly distributed } (0, 2\pi)$$

$$S_f(f) = \frac{S_\alpha(\alpha)}{\left| \left( f_m \cos \alpha \right)' \right|}$$

$$S_f(f) = \frac{1}{2\pi f_m \sin \alpha}$$

$$\sin \alpha = \sqrt{1 - \cos^2 \alpha}$$

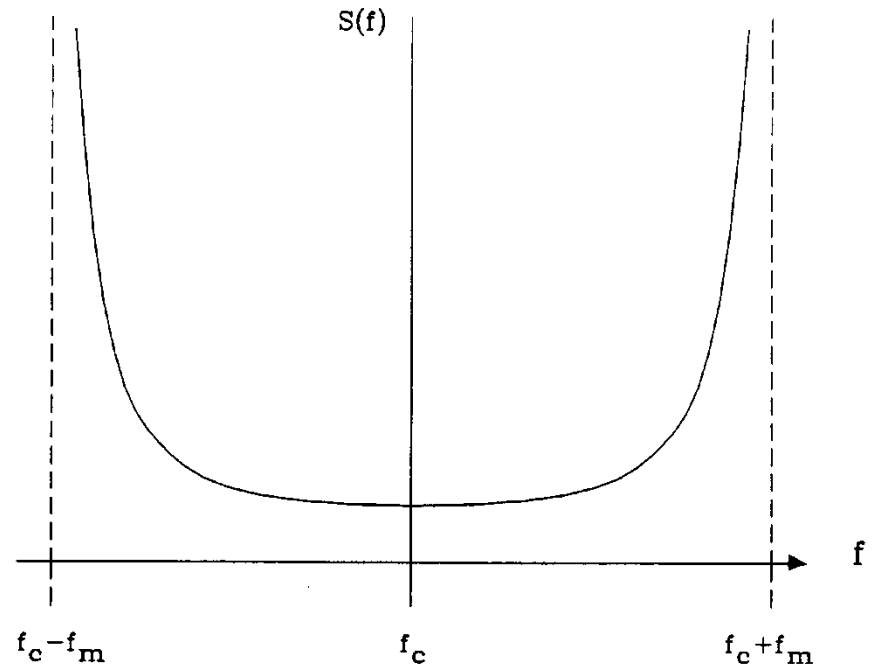
$$\cos \alpha = \frac{f}{f_m}$$

$$S_f(f) = \frac{1}{2\pi f_m \sqrt{1 - \frac{f^2}{f_m^2}}}$$

# Doppler Spectrum

- the incident received power at the MS depends on the power gain of the antenna and the polarization used

$$S(f) = \frac{A}{\sqrt{1 - (f/f_m)^2}}$$

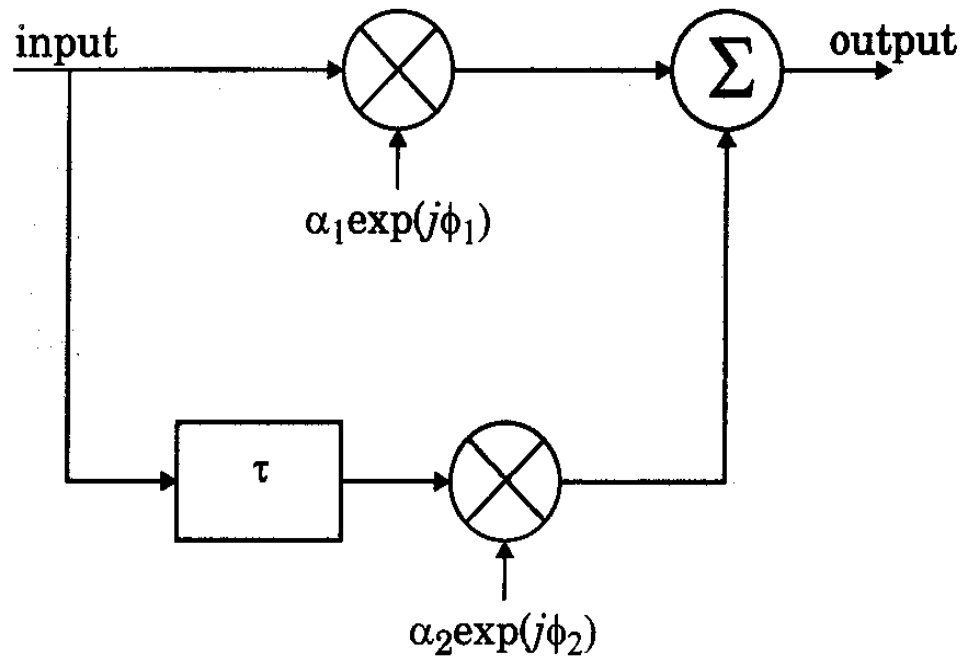




# Two-ray Rayleigh Fading Model

- Clarke's model for flat fading
- It is necessary to model multi-path delay spread as well
- Commonly used model is the two-ray model

# Two-ray Rayleigh Fading Model



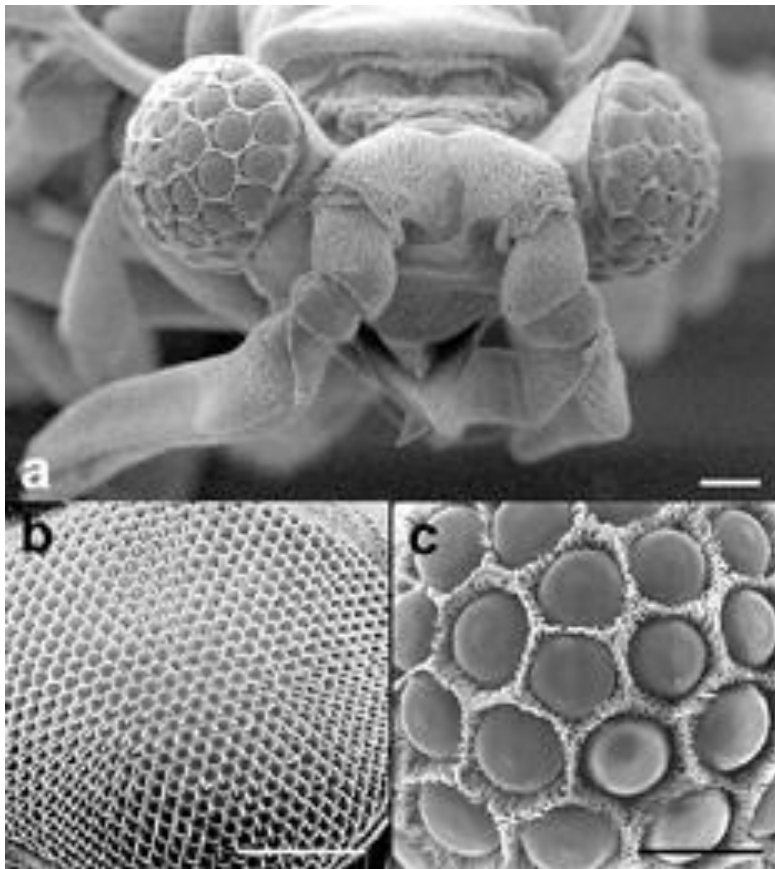
# Two-ray Rayleigh Fading Model

- The impulse response of the model

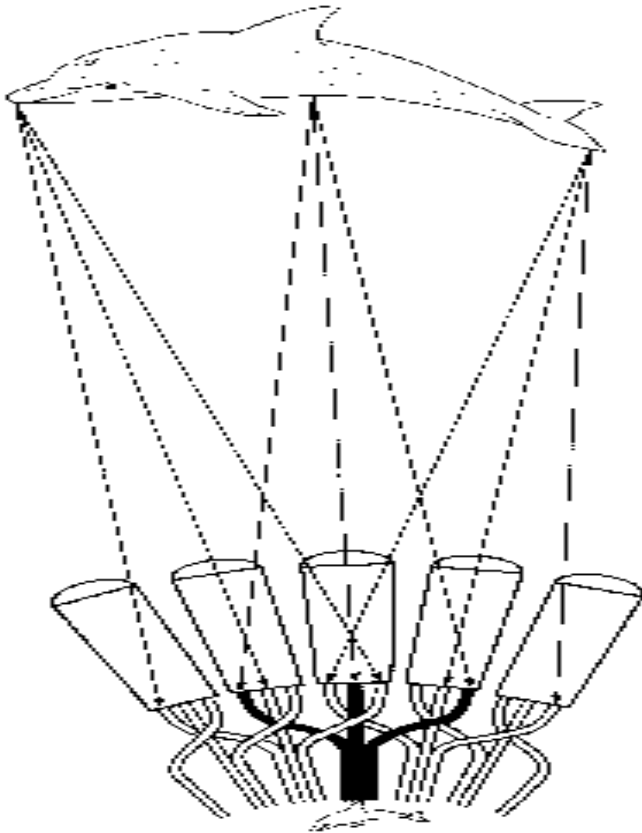
$$h_b = \alpha_1 \exp(j\phi_1) \delta(t) + \alpha_2 \exp(j\phi_2) \delta(t - \tau)$$

- $\alpha_1$  and  $\alpha_2$  are independent and Rayleigh distributed
- $\phi_1$  and  $\phi_2$  are independent and uniformly distributed over  $[0, 2\pi]$
- $\tau$  - time delay between the two rays
- By varying  $\tau$  it is possible to create a wide range of frequency selective fading effects

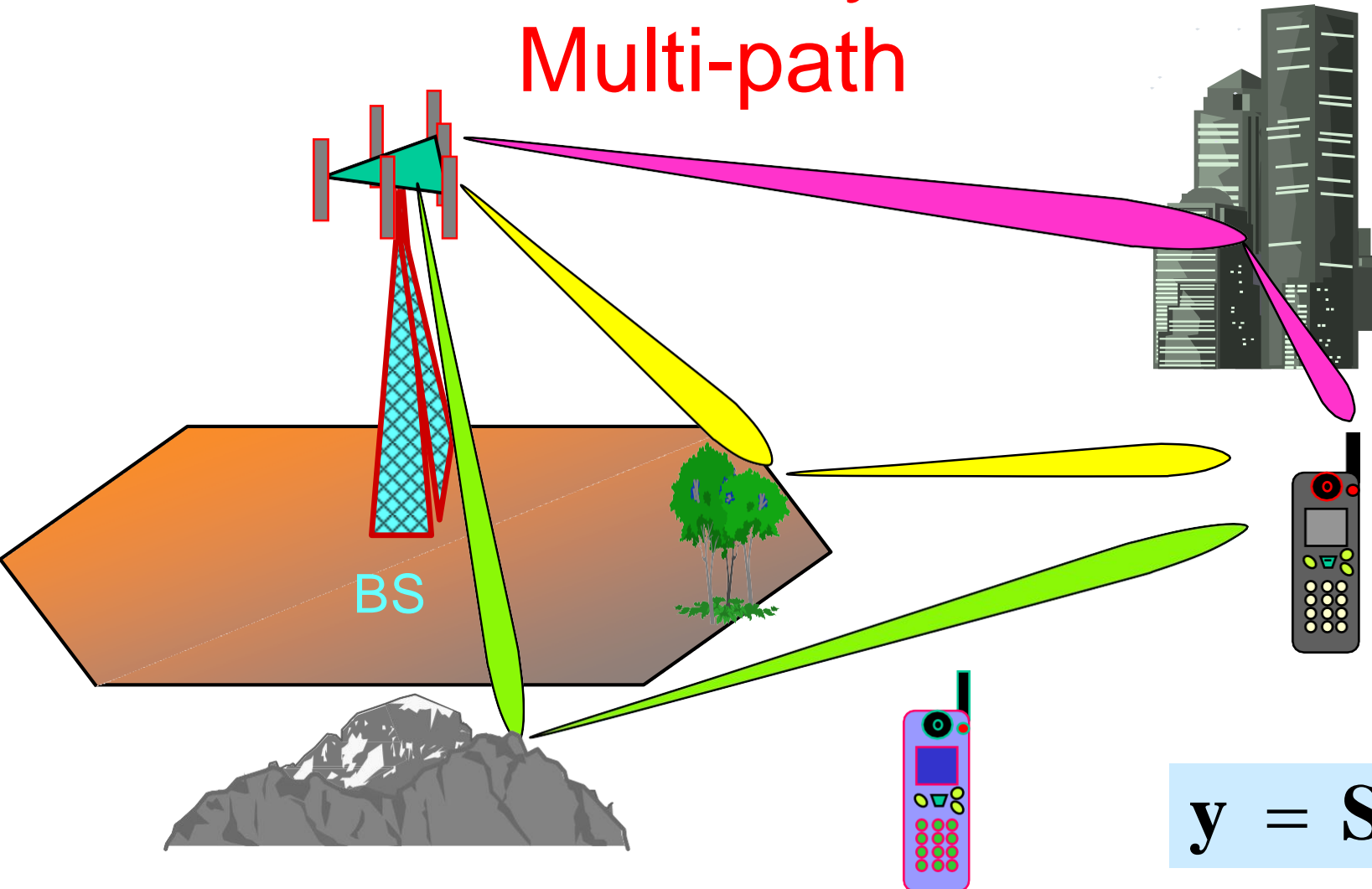
# Beyond Current Engineering Practice



# Antenna Arrays are Electromagnetic Eyes



# Smart Antenna System with Multi-path



$$\mathbf{y} = \mathbf{S} \mathbf{x} + \mathbf{n}$$

# Multi-user System Model

$$\mathbf{y} = \mathbf{S} \mathbf{x} + \mathbf{n}$$

$$E\{\mathbf{n}\mathbf{n}^H\} = \sigma^2 \mathbf{I}$$

- $\mathbf{y}$  - received signal ( $N \times 1$ ) dimensional vector
- $\mathbf{S}$  - signature matrix ( $N \times K$ ) dimensional matrix
- $\mathbf{x}$  - transmitted symbols ( $K \times 1$ ) dimensional vector
- $\mathbf{n}$  - Gaussian noise ( $N \times 1$ ) dimensional vector
- $N$  - Number of antenna elements
- $K$  - Number of **Users**

# Multi-user System Information Capacity

$$\mathbf{y} = \mathbf{S}\mathbf{x} + \mathbf{n}$$

$$C = \log_2 \left| \mathbf{I} + \frac{\mathbf{S} \mathbf{V}_x \mathbf{S}^H}{\sigma_n^2} \right|$$

$$\mathbf{V}_x = E\{\mathbf{x}\mathbf{x}^H\} = P\mathbf{I} - \text{Signal symbol power}$$

$$\sigma_n^2 - \text{Noise } \mathbf{n} \text{ (variance) power}$$

$$C = \log_2 \left( 1 + \frac{P}{\sigma_n^2} \right)$$



# Multuser Spatial Filter

$$\mathbf{y} = \mathbf{S}\mathbf{x} + \mathbf{n}$$

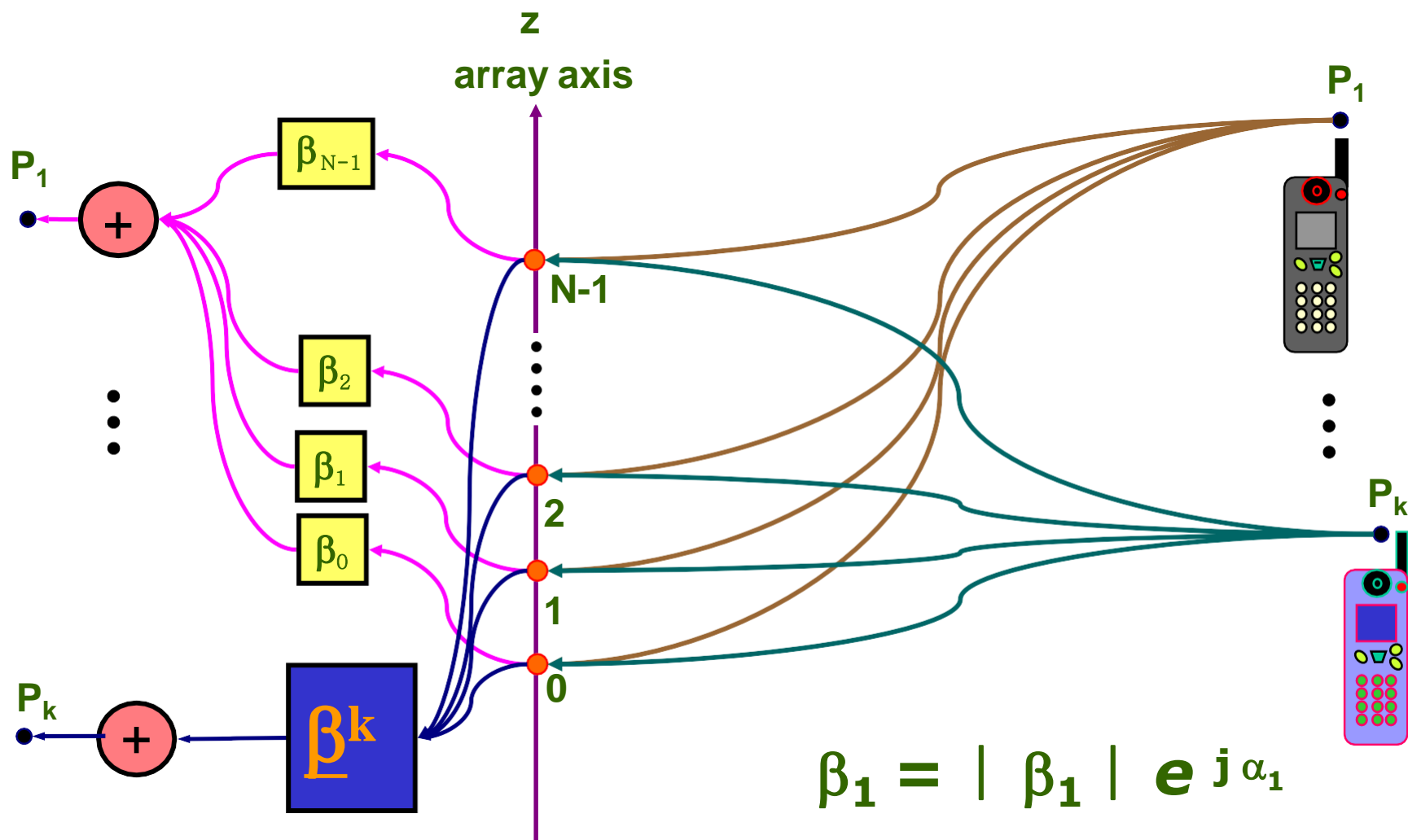
$$\boldsymbol{\beta} = (\mathbf{S}^H \mathbf{S})^{-1} \mathbf{S}^H$$

Moore-Penrose  
Pseudo Inverse

Optimum  
Spatial  
Filter

$$\begin{aligned}\hat{\mathbf{x}} &= (\mathbf{S}^H \mathbf{S})^{-1} \mathbf{S}^H \cdot \mathbf{y} \\ &= (\mathbf{S}^H \mathbf{S})^{-1} \mathbf{S}^H \cdot \mathbf{S} \mathbf{x} + (\mathbf{S}^H \mathbf{S})^{-1} \mathbf{S}^H \mathbf{n} \\ &= \mathbf{x} + 0_{MAI} + \tilde{\mathbf{n}}\end{aligned}$$

# Array of N Elements



# Capacity of 2G/3G vs Achievable Capacity

$$C = 0.1 \log_2 \left( 1 + \frac{1}{0.1} \right) = 0.3 \text{ bits / Hz / s}$$

2G/3G

$$C = 30 \log_2 \left( 1 + \frac{1}{0.001} \right) = 300 \text{ bits / Hz / s}$$

3G+

$$300 / 0.3 = 1000$$

**Capacity improvement factor**