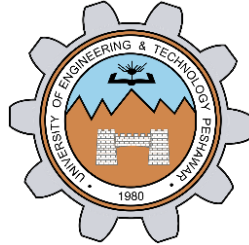


System Design using Sisotool

LAB # 12



Fall 2024

CSE-310L Control Systems Lab

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Class Section: **C**

“On my honor, as student of University of Engineering and Technology, I have neither given nor received unauthorized assistance on this academic work.”

Submitted to:

Dr. Muniba Ashfaq

Date:

31st December 2024

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Task:

For $K < 2$, design a system (second order) with the following characteristics:

- Percent overshoot < 50
- Damping ratio > 0.2
- Stable system

Introduction:

Percent overshoot: Systems may be stable system, unstable system and marginally stable system. A stable system may overshoot for some values at the start before coming to the stable level. Similarly in this lab a system is designed whose percent overshoot is < 50 .

Damping ratio:

Damping ratio is a parameter that indicates that whether system is over damped ($\zeta > 1$), under damped ($\zeta < 1$) or critically stable ($\zeta = 1$). In this lab a system is designed which must have damping ratio > 0.2 .

Stable system:

Third condition which the system must satisfy is it must be stable for $K < 2$, also all the values (damping ratio and % overshoot) are set. It must be unstable for $K \geq 2$.

Task:

Code:

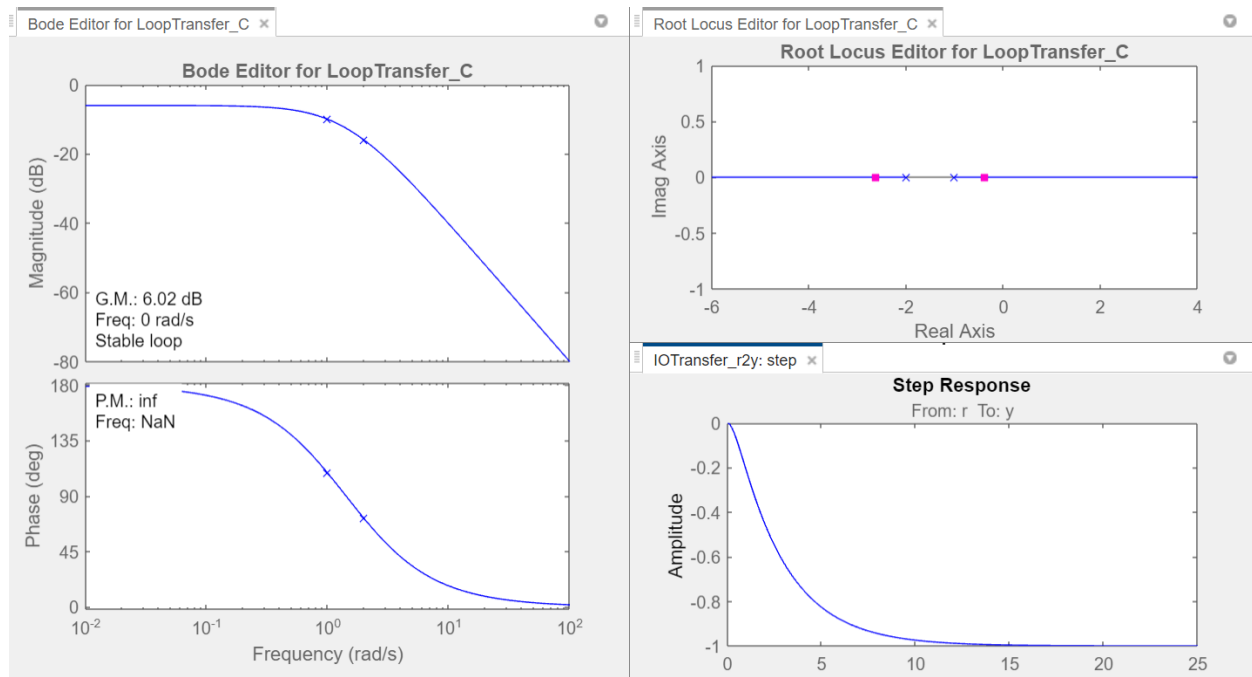
```
MatlabCode.m  Tasks.m  +
1      num=[0 0 -1];
2      den=[1 3 2];
3
4      sys = tf(num,den)
5      sisotool(sys)
```

Output:

```
sys =
      -1
-----
s^2 + 3 s + 2

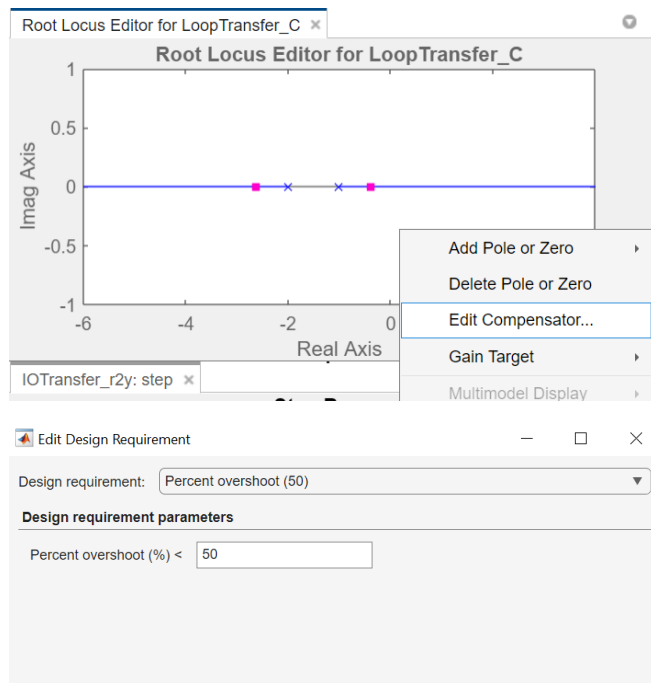
Continuous-time transfer function.
Model Properties
fx >>
```

Sisotool Output:

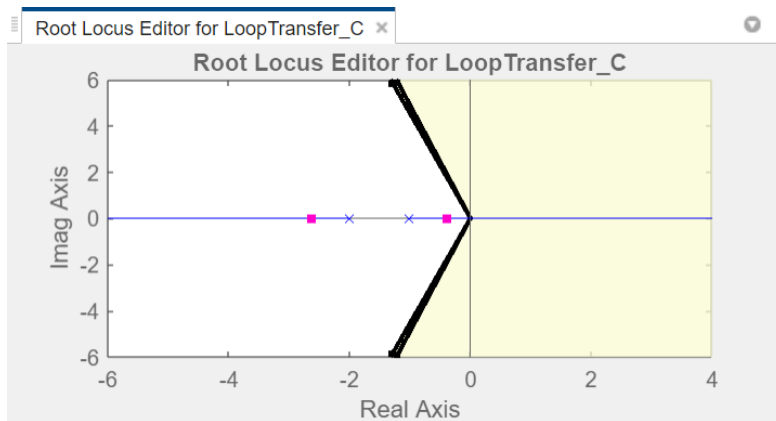
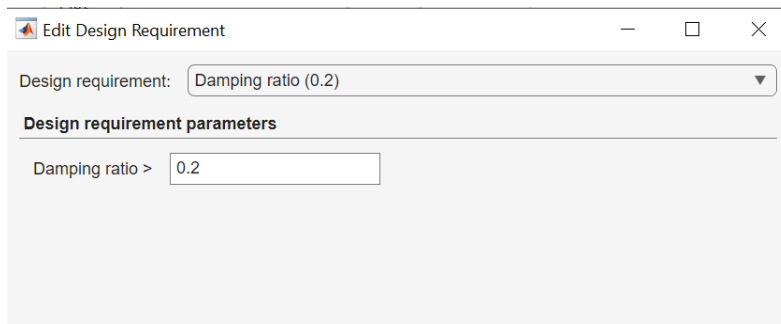


For $k=1$

Setting %Overshoot to <50:

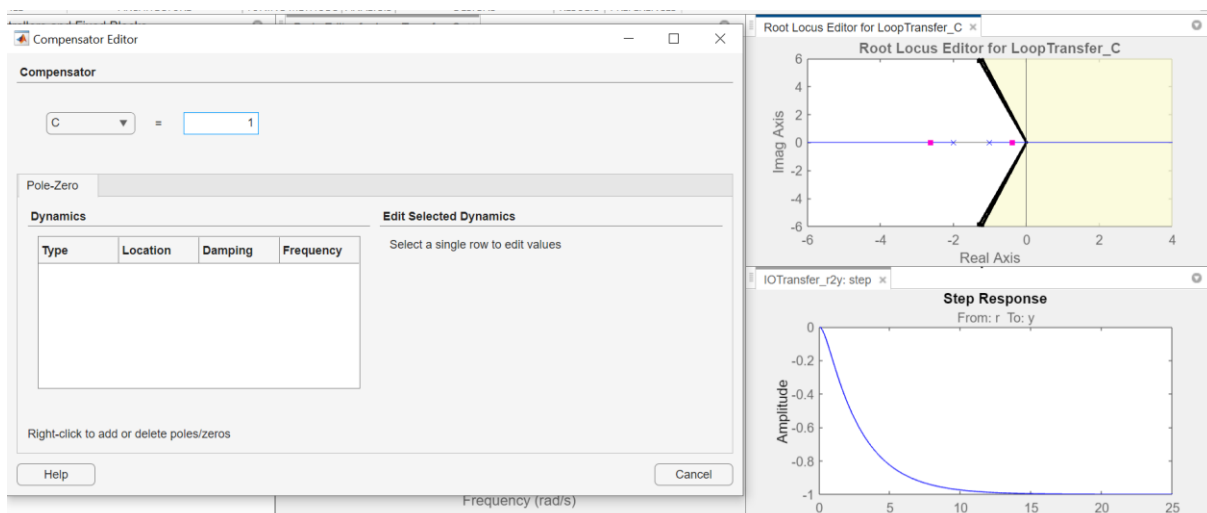


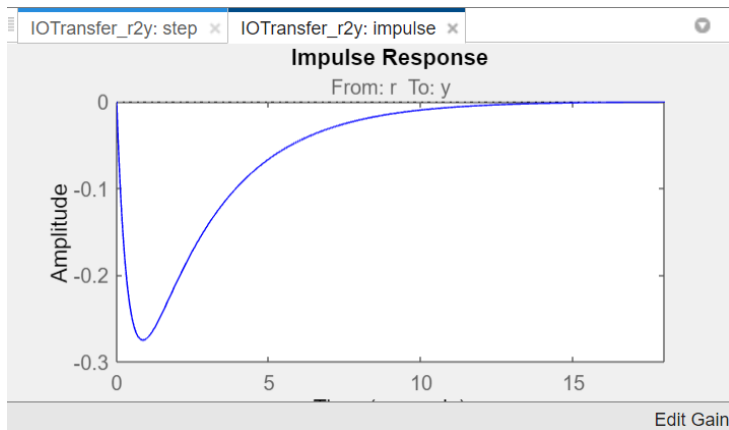
Setting Damping Ratio to >0.2 :



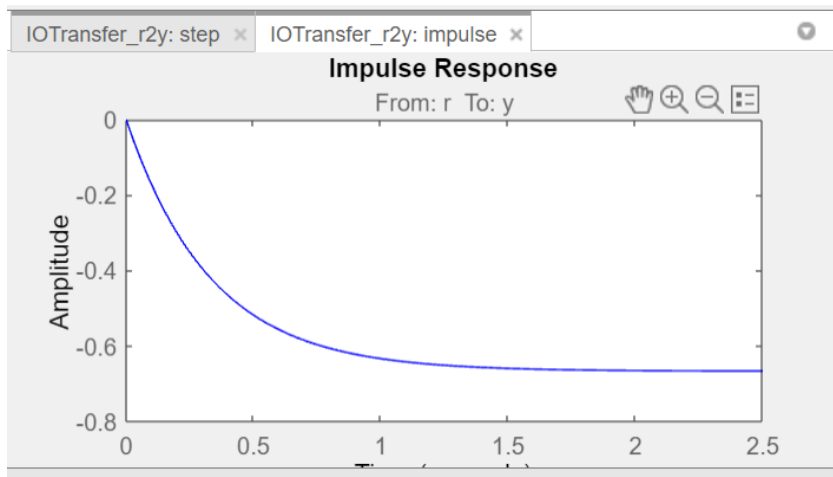
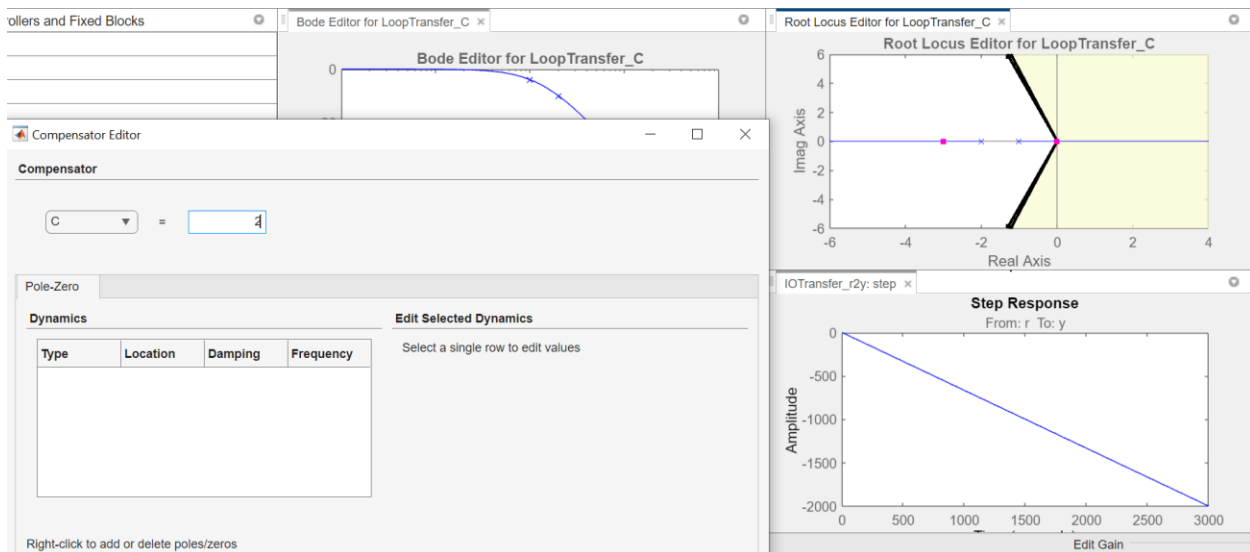
Checking Stability for different k values:

For $k = 1$ (Stable System)

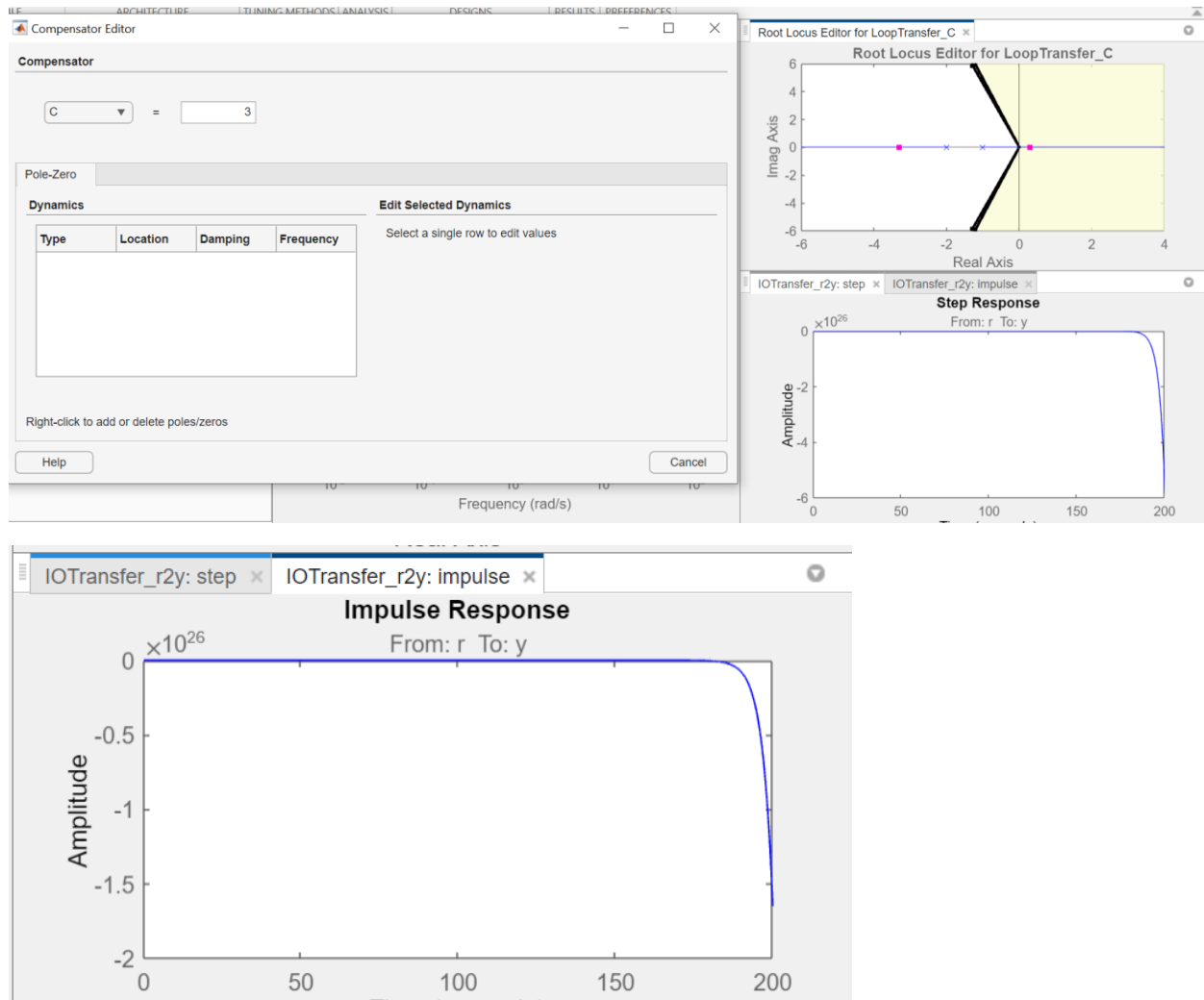




For $k = 2$ (Marginally Stable System)



For $k = 3$ (Unstable System)



Conclusion:

All the requirements for system are satisfied. The System is stable for all $K=2$. So this system fulfills all the conditions.