## **System Interconnections in Simulink**

**LAB # 03** 



# Fall 2024 CSE-310L Control Systems Lab

Submitted by: Ali Asghar

Registration No.: 21PWCSE2059

Class Section: C

"On my honor, as student of University of Engineering and Technology, I have neither given nor received unauthorized assistance on this academic work."

Submitted to:

Dr. Muniba Ashfaq

Date:

20th October 2024

Department of Computer Systems Engineering
University of Engineering and Technology, Peshawar

### **Objectives:**

The objective of this lab is to learn about:

• Series, Parallel and feedback interconnection of systems

### **Series System Interconnection:**

Find the equivalent system of the following systems connected in series. Prove it using Simulink.

```
G1(s) = 1/(S+1)

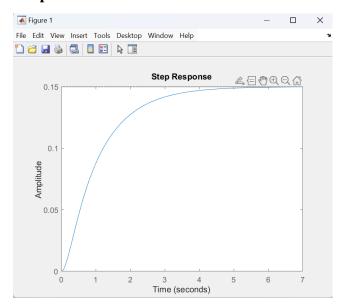
G2(s) = 1/(s+4)

G3(s) = (s+3)/(s+5)
```

### **MATLAB:**

#### Code:

```
Task1.m × Task.m × +
          G1 = tf([1], \dots
 1
 2
               [1,1]);
 3
          G2 = tf([1], ...]
 4
               [1,4]);
          G3 = tf([1,3], ...
 5
 6
               [1,5]);
 7
          %Connect in series
 8
 9
          G_mid_series = series(G1,G2);
          series_out = series(G_mid_series, G3)
10
11
          figure(1)
          step(series_out)
12
```

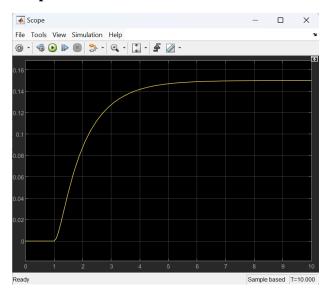


## Simulink:

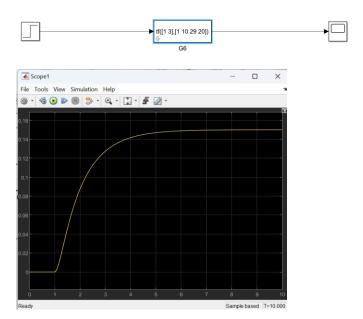
## **Block Design:**



## **Output:**



### **Equivalent System:**



## **Parallel System Interconnection:**

Find the equivalent system of the following systems connected in parallel. Prove it using Simulink.

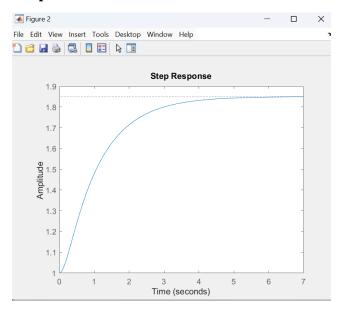
$$G1(s) = 1/(S+1)$$

$$G2(s) = 1/(s+4)$$

$$G3(s) = (s+3)/(s+5)$$

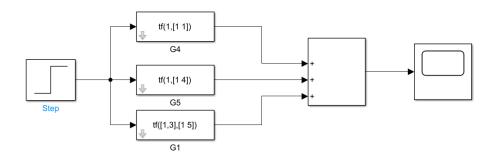
### **MATLAB:**

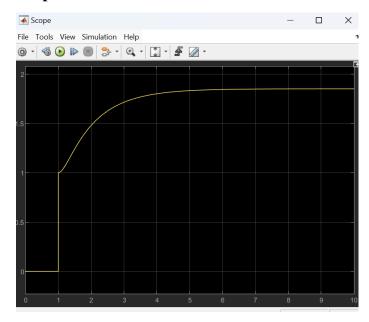
### **Code:**



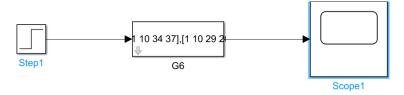
# Simulink:

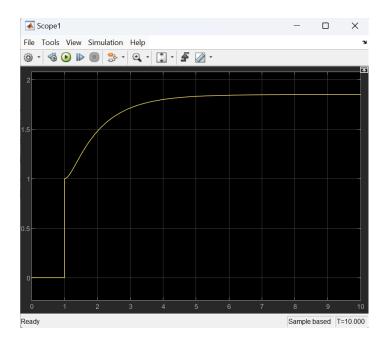
## **Block Design:**





# **Equivalent System:**





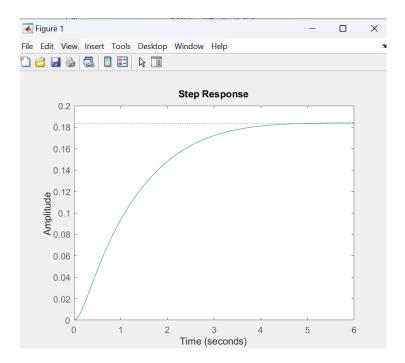
## **Negative feedback system interconnection:**

### **MATLAB:**

### Code:

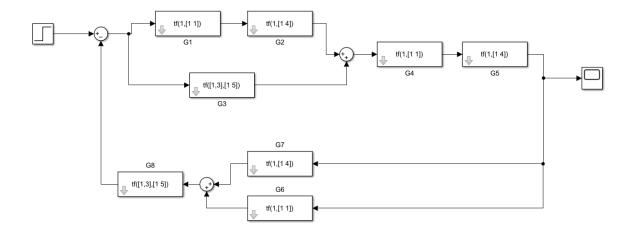
```
Task1.m × Task.m × +
 1
          G1 = tf([1], \dots
               [1,1]);
 2
 3
          G2 = tf([1], \dots
 4
               [1,4]);
          G3 = tf([1,3], ...
 5
 6
               [1,5]);
 7
          G_mid_series = series(G1,G2);
 8
          A = parallel(G_mid_series, G3);
 9
          B = series(A,G_mid_series);
10
          C=parallel(G1, G2);
          D = series(C,G3);
11
12
          out = feedback(B,D)
           step(out)
13
```

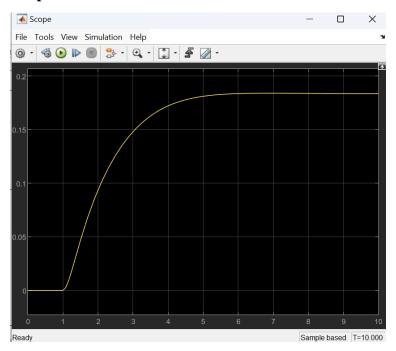
### **Output:**



# Simulink:

## **Block Design:**





## **Equivalent System:**

