**Steady State Error Analysis using Simulink**

**LAB # 09**



**Fall 2024**

**CSE-310L Control Systems Lab**

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Class Section: **C**

“On my honor, as student of University of Engineering and Technology, I have neither given nor received unauthorized assistance on this academic work.”

Submitted to:

**Dr. Muniba Ashfaq**

Date:

10**th December 2024**

**Department of Computer Systems Engineering**

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**Objectives:**

To analyze the steady state error analysis for different test signals in Simulink

**Steady state error:**

Steady state error is the difference between the input and the output for the prescribed test input as t (time) approaches to infinity. The objective of this lab to analyze the steady state error analysis for different test signals in Simulink.

Following are the test signals that will be used for analysis of steady state error.

A diagram of a mathematical function

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**Task 1:**

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Plot on graph the error signal for the input of **5u(t)** with different values of **k=50,500,1000,5000.**

**MATLAB:**

**Code:**

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**Output:**

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**Simulink:**

**Block Diagram:**

**A diagram of a computer program

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**A screenshot of a computer program

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**Output:**

**A screenshot of a computer screen

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We can see that for **k=1000,** i.e sum3 wave has the least value indicating least error for the model.

**Task 2:**

Plot on one graph Plot on graph the error signal for the input of **5tu(t)** with different values of **k=50,500,1000,5000.**

**Model:**

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**A screenshot of a computer

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**Output:**

**A screen shot of a graph

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We can see from the waves that the minium value is of the sum3 value which is for k = 5000, so for this k, the system shows steady state error.

**Task 3:**

Plot on one graph Plot on graph the error signal for the input of 5t2u(t) with different values of **k=50,500,1000,5000.**

**Code:**

**A diagram of a computer program

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**Output:**

**A screen shot of a graph

Description automatically generated**

We can see from the waves that the minium value is of the sum3 value which is for k = 5000, so for this k, the system shows steady state error.