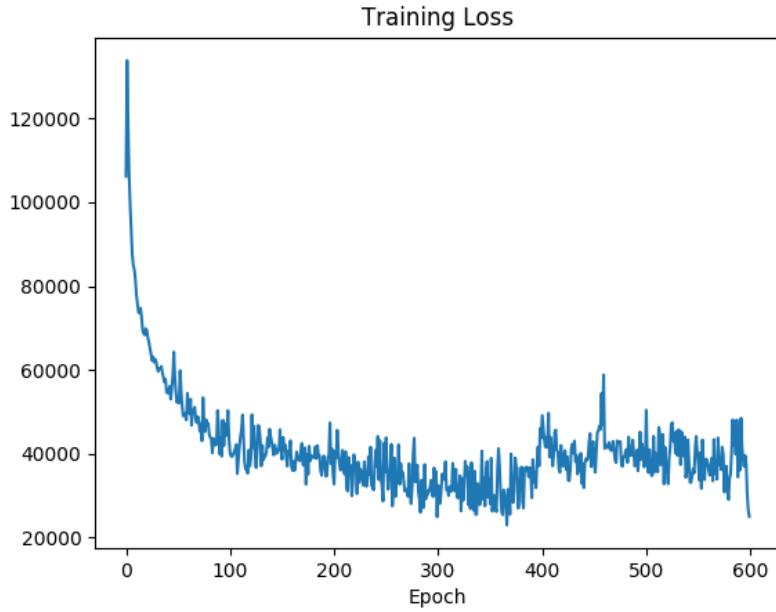


Generator Net

```
In [1]: import os  
# os.getcwd()  
os.chdir('./GenNet')  
%run main.py  
  
/usr/local/lib/python3.5/dist-packages/h5py/_init_.py:36: FutureWarning: Conversion of the second argument of issubdtype from `float` to `np.floating` is deprecated. In future, it will be treated as `np.float64 = np.dtype(float).type`.  
from ._conv import register_converters as _register_converters  
  
Loading dataset: ./Image/lion_tiger  
Data loaded, shape: (11, 64, 64, 3)  
Start training ...  
Epoch[ 0], train_loss: 106186.218750  
Epoch[50], train_loss: 52933.664062  
Epoch[100], train_loss: 40062.992188  
Epoch[150], train_loss: 38601.976562  
Epoch[200], train_loss: 32662.742188  
Epoch[250], train_loss: 43796.933594  
Epoch[300], train_loss: 32383.611328  
Epoch[350], train_loss: 27960.781250  
Epoch[400], train_loss: 49114.019531  
Epoch[450], train_loss: 37361.585938  
Epoch[500], train_loss: 50371.351562  
Epoch[550], train_loss: 37657.484375
```





The figures above shows the training loss and generated images in 600 epoch. The training loss is fluctuating as we introduced randomness in the langevine sampling process. Despite fluctuations, the loss decrease monotonely, as the generated images increase in clarity. The model is a nonlinear generalization of factor analysis. It is proved by the interpolated images synthesized on a grid of two latent factors, from those images it can be observed that the two factors corresponds to the features of tiger and lion. On both factors, higher positive loadings gives rise to image resembling lion, while negative loadings represents the features of tiger.

Descriptor Net

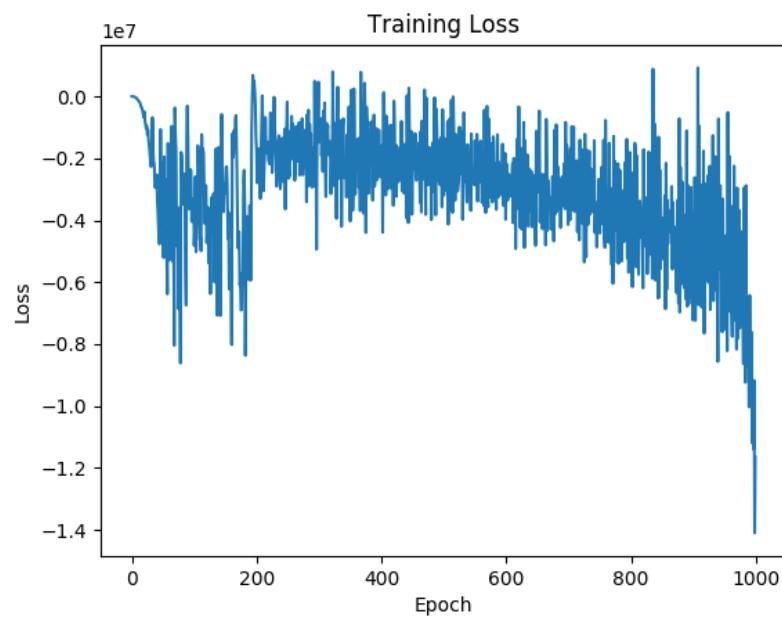
```
In [1]: import os
# os.getcwd()
os.chdir('./DesNet')
%run main.py

/usr/local/lib/python3.5/dist-packages/h5py/_init__.py:36: FutureWarning: Conversion of the second argument of issubtype from `float` to `np.floating` is deprecated. In future, it will be treated as `np.float64 = np.dtype(float).type`.
from ._conv import register_converters as _register_converters

Loading dataset: ./Image/egret
Data loaded, shape: (7, 64, 64, 3)
Start training ...
Epoch[ 0], train_loss: 0.447842
Epoch[100], train_loss: -4821099.500000
Epoch[200], train_loss: -1786476.000000
Epoch[300], train_loss: -1484442.000000
Epoch[400], train_loss: -2397879.000000
Epoch[500], train_loss: -3194498.000000
Epoch[600], train_loss: -2350266.000000
Epoch[700], train_loss: -2374108.000000
Epoch[800], train_loss: -4010210.000000
Epoch[900], train_loss: -3783428.000000
```



The figure above showed the generated images in 900 epochs. Because we use mean image as the initial input, the constructed image is colored patch at the beginning, then the quality of the images gradually increase in the training process as more complex features are learned.



The training loss for the descriptor net is negative with big fluctuations. The output of the descriptor net is a score for how "real" the input image is, so the training loss as the difference between the score for the fake and the real is negative. In the learning process, the descriptive ability of this score is also improved, so there are big fluctuations in the loss.