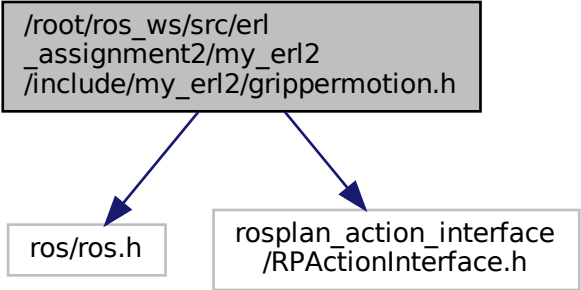


/root/ros_ws/src/erl
_assignment2/my_erl2
/include/my_erl2/grippermotion.h



```
graph TD; A["/root/ros_ws/src/erl_assignment2/my_erl2/include/my_erl2/grippermotion.h"] --> B["ros/ros.h"]; A --> C["rosplan_action_interface/RPActionInterface.h"]
```

ros/ros.h

rosplan_action_interface
/RPActionInterface.h