```
/root/ros ws/src/erl
                          _assignment2/my_erl2
/include/my_erl2/grippermotion.h
/root/ros ws/src/erl
                                /root/ros ws/src/erl
                                                                /root/ros ws/src/erl
_assignment2/my_erl2
                                 assignment2/my erl2
                                                                 assignment2/my erl2
                                                                /src/save erloracle.cpp
/src/grippermotion.cpp
                                 /src/initial phase.cpp
```