

**Lecture 16.**Friday 6<sup>th</sup>

December, 2019.

Compiled:

Saturday 21<sup>st</sup>

December, 2019.

**0.1 Cubic term and first transition**

Let us consider more general forms of the Landau free energy. For example, in the case in which the symmetry is not violated, one can consider also odd terms such as the cubic one. In fact, we want to generalize to include multicritical points, or phase transitions. The phase transitions can be obtained by introducing a cubic term in the Landau expansion. Remember that in the Ising model we have phase transition derived by symmetry breaking. Now, we have another type of phase transition.

The simplest Landau free energy that depends on a particular field is:

$$\mathcal{L}(\eta, t, h) = at\eta^2 - w\eta^3 + \frac{b}{4}\eta^4 - h\eta \quad (1)$$

where  $t \equiv \frac{T-T^*}{2}$  and  $w$  is an additional parameter that we fix to be positive,  $w > 0$ .

*Remark.* For  $w < 0$  the results are the same, but in the  $\eta < 0$  diagram.

To satisfy thermodynamic stability we require  $b > 0$ , while

$$at = \frac{a}{2}(T - T^*) \quad \text{if} \quad \begin{cases} > 0 & T > T^* \\ < 0 & T < T^* \end{cases} \quad (2)$$

The equation of state for  $h \neq 0$  is:

$$\frac{\partial \mathcal{L}_G}{\partial \eta} = 0 \quad \Rightarrow \quad h = 2at\eta - 3w\eta^2 + b\eta^3 \quad (3)$$

Let us consider the equilibrium states when  $h = 0$ :

$$h = 0 \quad \Rightarrow \quad 0 = \eta(2at - 3w\eta + b\eta^2) \quad (4)$$

The possible solutions are

$$\begin{cases} \bar{\eta} = 0 & \text{disordered phase} \\ \bar{\eta} = \frac{1}{4b} \left( 3w \pm \sqrt{9w^2 - 16abt} \right) & \text{ordered phases} \end{cases} \quad (5)$$

Let us rewrite the 'ordered' solutions as

$$\bar{\eta}_{\pm} = c \pm \sqrt{c^2 - \frac{at}{b}} \quad (6)$$

where

$$c = \frac{3w}{4b} \quad (7)$$

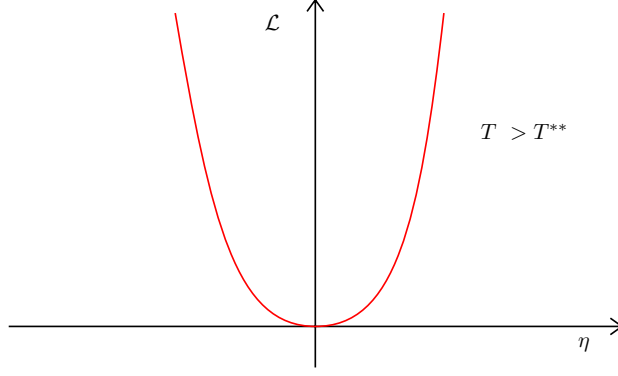
Note that

$$\bar{\eta}_{\pm} \in \mathbb{R} \iff c^2 > \frac{at}{b} \Rightarrow \frac{T - T^*}{2} < \frac{c^2 b}{a} \equiv t^{**} \equiv \frac{T^{**} - T^*}{2} \quad (8)$$

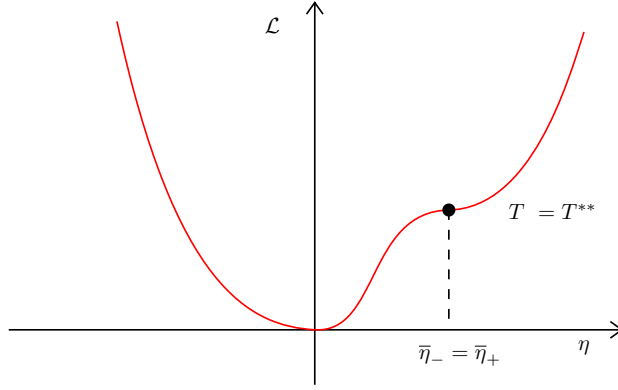
It implies:

$$T^{**} = T^* + \frac{2c^2 b}{a} \quad (9)$$

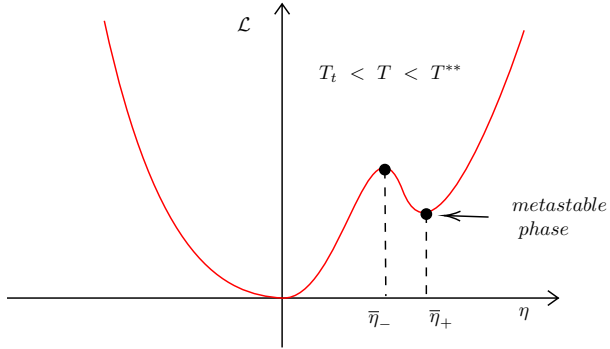
- If  $t > t^{**}$  ( $\iff T > T^{**}$ ), we have  $\bar{\eta}_{\pm} \notin \mathbb{R}$ . The only real solution is  $\bar{\eta} = 0$  that is also the absolute minimum of  $\mathcal{L}$ . The plot is shown in Figure 1.
- If  $t \leq t^{**}$  ( $\iff T \leq T^{**}$ ), we have  $\bar{\eta}_{\pm} = c \pm \sqrt{c^2 - \frac{at}{b}} \in \mathbb{R}$  are both possible solutions. One will be a local maximum and the other a local minimum.



**Figure 1:** Description.



**Figure 2:** Description.



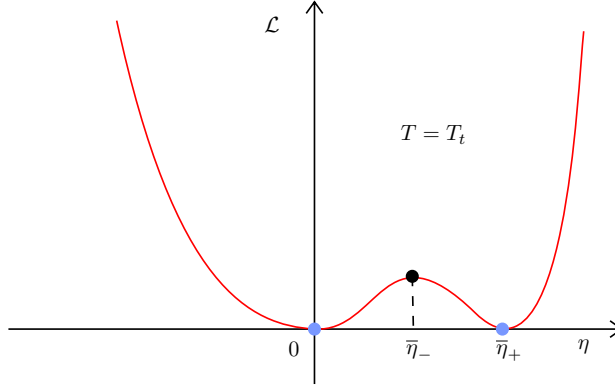
**Figure 3:** Description.

- At  $T = T^{**}$ ,  $\bar{\eta}_- = \bar{\eta}_+$  (flex point), as shown in Figure 2.
- For  $T_t < T < T^{**}$ ,  $\mathcal{L}(\bar{\eta}_+) > 0$ . Since  $\mathcal{L}(\bar{\eta} = 0)$ , the solution  $\bar{\eta}_+$  is a local minimum, as shown in Figure 3.
- By decreasing  $T$  further one eventually reaches the value  $T = T_t$  at which the local minimum  $\mathcal{L}(\bar{\eta}_+)$  becomes zero, as in Figure 4.  $T_t$  is given by the coexistence condition

$$\mathcal{L}(\bar{\eta}_+) = \mathcal{L}(0) \quad (10)$$

that is the coexistence between the disordered and ordered phases!

In the plot of Figure 4 we see that there are two minima in the same line, this is a first order transition. At  $T = T_t$  the system undergoes a first

**Figure 4:** Description.

order transition. To determine  $T_t$  we consider

$$\begin{cases} \frac{\partial \mathcal{L}}{\partial \eta} = 0 = \eta(2at - 3w\eta + 2b\eta^2) & \text{extreme condition} \\ \mathcal{L}(0) = \mathcal{L}(\eta_+) & \text{coexistence condition} \end{cases} \quad (11)$$

$$\Rightarrow \begin{cases} 2at - 3w\eta + 2b\eta^2 = 0 \\ at - w\eta + \frac{b}{2}\eta^2 = 0 \end{cases} \quad (12)$$

Solving with respect to  $\eta$  and  $t$  we get

$$\begin{cases} \bar{\eta}_{+t} = +\frac{w}{b} > 0 \\ t_t = \frac{w^2}{2ba} \equiv \frac{1}{2}(T_t - T^*) \end{cases} \quad (13)$$

$$T_t = \frac{w^2}{ba} + T^* \quad (14)$$

*Remark.* Note that  $T_t > T^*$ .

Since at  $T = T_t$  there is a first order transition does the system display latent heat?

$$s = -\left. \frac{\partial \mathcal{L}}{\partial T} \right|_{\eta_t} = -\frac{1}{2}a\bar{\eta}_t^2 = -\frac{a}{2}\left(\frac{w}{b}\right)^2 \quad (15)$$

*Remark.* There is an entropy jump.

The latent heat adsorbed to go from the ordered to the disordred phase is

$$q = -T_t s = \frac{a}{2}T_t\left(\frac{w}{b}\right)^2 \quad (16)$$

- Finally for  $T^* < T < T_t$ ,  $\eta = \bar{\eta}_+$  becomes the global minimum ordered phase is the only stable one (Figure 5).

## 0.2 Phase stability and behaviour of $\chi_T \equiv \frac{\partial \eta}{\partial h}$

Let us derive the equation of state with respect to  $h$

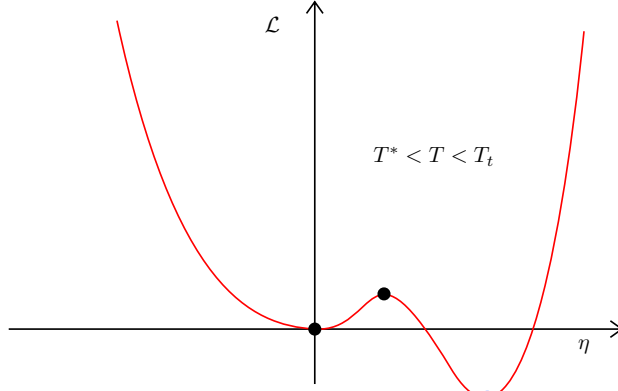
$$\frac{\partial}{\partial h} \left( \frac{\partial \mathcal{L}_G}{\partial \eta} = 0 \right) = \frac{\partial}{\partial h} (2at\eta - 3w\eta^2 + 2b\eta^3 = h) \quad (17)$$

$$\Rightarrow \chi(2at - 6w\eta + 6b\eta^2) = 1 \quad (18)$$

The results is

$$\chi_T = \frac{1}{2at - 6w\eta + 6b\eta^2} \quad (19)$$

We now make use of equation (19) to compute the limit of stability of the phases we have found.



**Figure 5:** Description.

### 0.2.1 Computation of $T^{**}$

$T = T^{**}$  is the value below which the ordered phase ( $\bar{\eta} = \bar{\eta}_+$ ) becomes a metastable state (local minima). Since this coincides with the flex point

$$\frac{\partial^2 \mathcal{L}}{\partial \eta^2} = 0 \quad \Rightarrow \quad \chi^{-1} = 2at - 6w\eta + 6b\eta^2 = 0 \quad (20)$$

Remember that at  $T = T^{**}$  the two solutions  $\eta_{\pm}$  do coincide

$$c^2 - \frac{at}{b} = 0 \Rightarrow \eta_{\pm} = \eta_2 = \frac{3w}{4b} \quad (21)$$

Inserting in the expression for  $\chi^{-1}$  since  $\chi^{-1} = 0$  we have

$$\chi^{-1} = 0 = 2at^{**} - 6w\bar{\eta}_2 + 6\bar{\eta}_2^2 \quad (22)$$

$$\Longleftrightarrow t^{**} = \frac{qw^2}{16ab} = \frac{1}{2}(T^{**} - T^*) \quad (23)$$

For  $T_t < T < T^{**}$  the ordered phase is metastable.

### 0.2.2 Computation of $T^*$

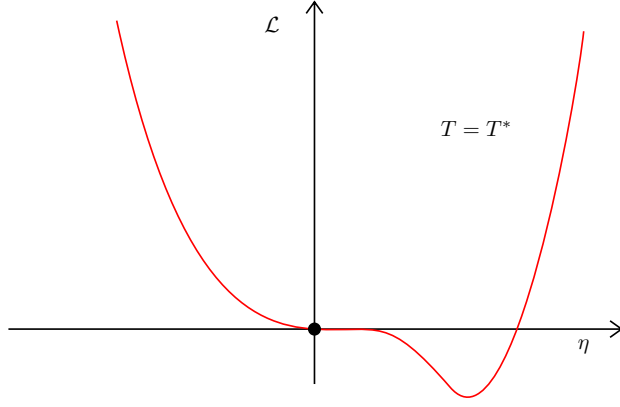
The instability of the disordered phase ( $\eta = 0$ ) is when  $\mathcal{L}$  presents a flex point at  $\eta = 0$ , as in Figure 6.

$$\chi^{-1}(\eta = 0) = 0 \Longleftrightarrow \chi^{-1}(\eta = 0) = 2at = 0 \Longleftrightarrow t = 0 \Rightarrow T = T^* \quad (24)$$

## 0.3 Landau theory and multicritical points

Tricritical point is a critical point that separates a line of first transition points from a line of critical points.

*Remark.* The introduction of a cubic term is not the only way to obtain a first order transition. Let allow the coefficient of  $\eta^4$  to change signs. We need the  $\eta^6$  term (See Blume-Emery-Griffith model).

**Figure 6:** Description.

$$\mathcal{L}_h(T, \Delta, \eta) = \frac{a(t, \Delta)}{2} \eta^2 + \frac{b(t, \Delta)}{4} \eta^4 + \frac{c}{6} \eta^6 - h\eta \quad (25)$$

where we have two parameters  $(T, \Delta)$  and  $c > 0$ , with  $\Delta$  that is the disordered field (% He<sup>3</sup> in the BEG model).

Now, consider  $\Delta$  ( $\Delta_c$  is a critical value). The phenomenology is

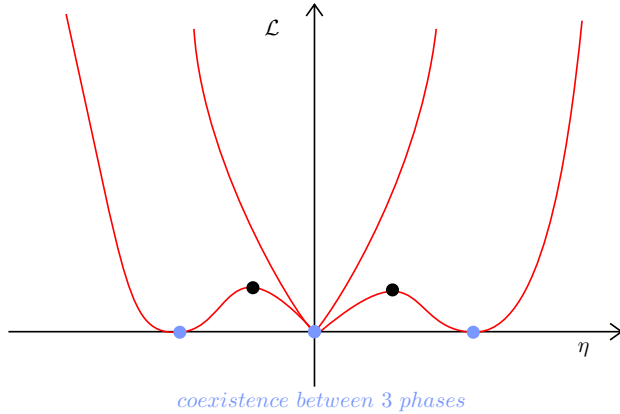
- $\Delta < \Delta_c$ : as  $T$  decreases,  $a(T, \Delta)$  decreases and at  $T = T_c(\Delta)$  becomes zero. In this region  $b(T, \Delta) > 0$  and the system displays the standard ( $\eta^4$ ) critical point.

$$T = T_c(\Delta) \Rightarrow \begin{cases} a(T_c, \Delta) = 0 \\ b(T_c, \Delta) > 0 \end{cases} \quad (26)$$

- $\Delta > \Delta_c$ : as  $T$  decreases,  $b(T, \Delta)$  becomes zero 'before'  $a(T, \Delta)$ . In this case one can show the existence of a line of first transition points:

$$b(\bar{T}, \Delta) = 0 \Rightarrow \mathcal{L} = a\eta^2 + c\eta^6, \quad a > 0 \quad (27)$$

$$\frac{\partial \mathcal{L}}{\partial \eta} = 2a\eta + 6c\eta^5 \Rightarrow \begin{cases} \eta = 0 \\ \eta_{1,2,3,4} \end{cases} \quad (28)$$

**Figure 7:** Description.

If  $b > 0$ ,  $\eta^6$  can be neglected.

- The Tricritical point is given by the values of  $\Delta = \Delta_t$  and  $T = T_c$  such that

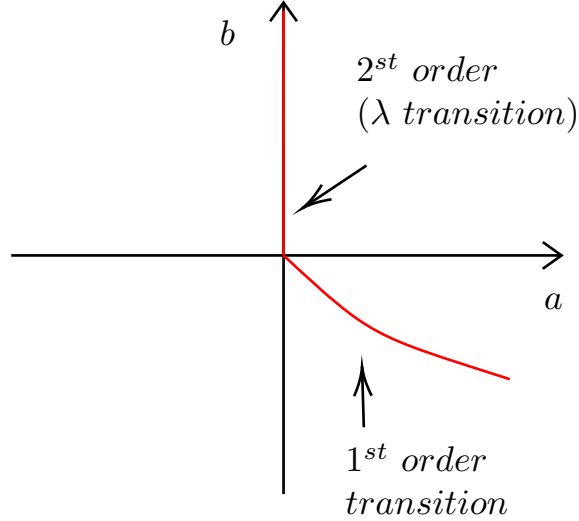
$$a(\Delta_t, T_t) = b(\Delta_t, T_t) = 0 \quad (29)$$

At this point the system is described by the following Landau free-energy

$$\mathcal{L}_t = c\eta^6 - h\eta \quad (30)$$

and equation of state

$$h = 6c\eta^5 \quad (31)$$



**Figure 8:** Description.

## 0.4 Landau-de Gennes theory of liquid crystals

A liquid crystal phase (LC) can be seen as an intermediate phase (mesophase) between a solid and a liquid phase. In this phase the system flows as a fluid but it also displays an orientational order typical of a crystal. Because of this order this phase displays *anisotropic* optical, magnetic and electrical properties.

Typical structural properties of the elementary constituents (molecules) giving rise to LC phase are the following

- Anisotropic (elongated) shape.
- The long axis can be approximated as a rigid backbone.
- Existence of strong dipoles and groups easy to polarize.

### 0.4.1 LC-phases

There are many possible LC phase, from *nematic*, *cholesteric*, *smectic*, *columnar*, etc. Here we focus on the most common one the *nematic phase*.

The nematic phase is characterized by a strong and long range orientational order. As a measure of this order, one considers the director  $\vec{n}(\vec{r})$ . This is a 'two arrow vector' that gives the local average alignment of the elementary constituents. In this description the amplitude of  $\vec{n}(\vec{r})$  is irrelevant and one takes  $\vec{n}(\vec{r})$  such that  $|\vec{n}(\vec{r})| = 1$ . Since there is no head-tail symmetry (apolar order),  $\vec{n} = -\vec{n}$ . From optical point of view the nematic phase is birefringent, i.e. two refraction indices, one parallel to  $\vec{n}$  and one perpendicular to  $\vec{n}$  (special index).

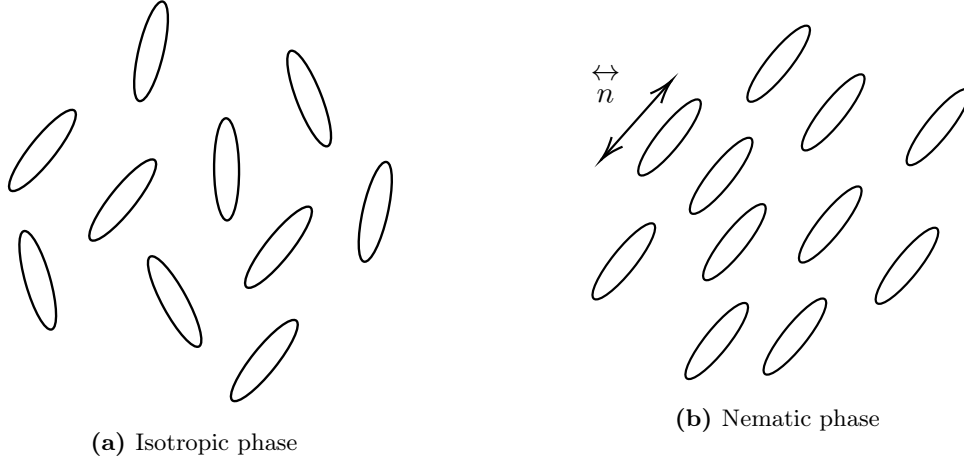


Figure 9

### 0.4.2 Order parameter

A macroscopic definition of an order parameter for LC phase is based on the system response when subject to magnetic or electric fields. For instance, given an external magnetic field  $\vec{\mathbf{H}}$  the (diamagnetic) response of the system can be written as

$$\vec{\mathbf{M}} = \bar{\bar{\chi}} \vec{\mathbf{H}} \quad (32)$$

where the matrix  $\bar{\bar{\chi}}$  is the response function.

In components

$$M_\alpha = \chi_{\alpha\beta} H_\beta \quad (33)$$

with  $\alpha, \beta = x, y, z$ . For a static  $\vec{\mathbf{H}}$ ,  $\chi_{\alpha\beta}$  is symmetric.

Clearly, for a isotropic fluid

$$\chi_{\alpha\beta} = \chi \delta_{\alpha\beta} \quad (34)$$

For a LC in the neumatic phase one has

$$\chi_{\alpha\beta} = \begin{pmatrix} \chi_\perp & 0 & 0 \\ 0 & \chi_\perp & 0 \\ 0 & 0 & \chi_\parallel \end{pmatrix} \quad (35)$$

One can then define an order parameter based on  $\chi_{\alpha\beta}$  as

$$Q_{\alpha\beta} = A \left( \chi_{\alpha\beta} - \frac{1}{3} \delta_{\alpha\beta} \text{Tr } \bar{\bar{\chi}} \right) \quad (36)$$

The order parameter is a second rank traceless tensor. It is possible to show that  $Q_{\alpha\beta}$  can be written in terms of the local average orientational order of the elementary constituents,  $\overleftrightarrow{n}(\vec{\mathbf{r}})$  and the degree of local order given by a scalar  $S(\vec{\mathbf{r}})$ .

$$Q_{\alpha\beta}(\vec{\mathbf{r}}) = S(\vec{\mathbf{r}}) \left( n_\alpha(\vec{\mathbf{r}}) n_\beta(\vec{\mathbf{r}}) - \frac{1}{3} \delta_{\alpha\beta} \right) \quad (37)$$

Note that by construction  $\bar{\bar{Q}}$  is symmetric and traceless.

Its more general expression is

$$Q_{\alpha\beta} = \begin{pmatrix} q_1 & q_2 & q_3 \\ q_2 & q_4 & q_5 \\ q_3 & q_5 & -q_1 - q_4 \end{pmatrix} \quad (38)$$

### 0.4.3 Landau free energy

The free energy must be invariant to rotations of the system. Since  $Q_{\alpha\beta}$  transforms as a tensor under rotations,  $\mathcal{L}$  must be a combination of terms as  $\text{Tr } \bar{\bar{Q}}^P$ . By keeping terms up to fourth order

$$\mathcal{L} = \mathcal{L}_0 + \frac{1}{2}A(T) \text{Tr } \bar{\bar{Q}}^2 + \frac{1}{3}B(T) \text{Tr } \bar{\bar{Q}}^3 + \frac{1}{4}C(T) \left[ \left( \text{Tr } \bar{\bar{Q}}^2 \right)^2 + \text{Tr } \bar{\bar{Q}}^4 \right] \quad (39)$$

In components,

$$\mathcal{L} = \mathcal{L}_0 + \frac{1}{2}A(T)Q_{\alpha\beta}Q_{\beta\alpha} + \frac{1}{3}B(T)Q_{\alpha\beta}Q_{\beta\gamma}Q_{\gamma\alpha} + \frac{1}{4}C(T)(Q_{\alpha\beta}Q_{\beta\alpha})^2 \quad (40)$$

*Remark.* Since each  $3 \times 3$  matrix satisfies the relation

$$\text{Tr } \bar{\bar{Q}}^4 = \frac{1}{2} \left( \text{Tr } \bar{\bar{Q}}^2 \right)^2 \quad (41)$$

the term proportional to  $C(T)$  can be written as  $\frac{1}{2}C(T) \text{Tr } \bar{\bar{Q}}^4$ .

*Remark.* The cubic term is here allowed since the rod like molecules have quadrupolar symmetry and the order parameter is a tensor for which the rotational invariance does not imply the absence of the odd powers.

For the most general case of a *biaxial nematic phase*  $\bar{\bar{Q}}$  can be diagonalized giving

$$Q_{\alpha\beta} = \begin{pmatrix} \frac{2}{3}s & 0 & 0 \\ 0 & -\frac{s+\eta}{3} & 0 \\ 0 & 0 & -\frac{(s-\eta)}{3} \end{pmatrix} \quad (42)$$

where  $\eta = 0$  corresponds to the standard uniaxial nematic phase.

In this cases

$$Q_{\alpha\beta} = \begin{pmatrix} \frac{2}{3}s & 0 & 0 \\ 0 & -\frac{s}{3} & 0 \\ 0 & 0 & -\frac{(s)}{3} \end{pmatrix} \quad (43)$$

and

$$\mathcal{L} = \mathcal{L}_0 + A(T)\frac{s^2}{3} + \frac{2}{27}B(T)s^3 + \frac{3}{81}C(T)s^4 \quad (44)$$

Assuming  $A(T) \simeq A(T - T^*)$ ,  $B(T) = B$  and  $C(T) = C$ :

$$\mathcal{L} = \mathcal{L}_0 + \frac{A}{3}(T - T^*)s^2 + \frac{2}{27}Bs^3 + \frac{C}{9}s^4 \quad (45)$$

that has the same form of the one studied before for the first order phase transition.

In particular

$$a = \frac{2}{3}A, \quad -w = \frac{2}{27}B, \quad b = \frac{2}{9}C \quad (46)$$

It is then easy to see that the isotropic-nematic transition is of the first order and occur at

$$T_t = \frac{w^2}{ba} + T^* = \frac{B^2}{27AC} + T^* \quad (47)$$



# Chapter 1

## Role of fluctuations in critical phenomena: Ginzburg criterium, Coarse-graining and Ginzburg-Landau theory of phase

### 1.1 Importance of fluctuations: the Ginzburg criterium

Maybe mean field is not a very good approximation in proximity of the critical point. Question: how bad is the mean field approximation in proximity of the critical point?

Mean field approximations neglect the fluctuations of the order parameter in the computation of  $Z$ . This is a rather strong assumption since the correlation length

$$\xi \stackrel{T \rightarrow T_c}{\sim} |T - T_c|^{-\nu} \quad (1.1)$$

diverges. Let us estimate the error one does in using the MF approximation.

To fix the ideas let us consider the Ising model. Since

$$\langle S_i S_j \rangle \xrightarrow{MF} \langle S_i \rangle \langle S_j \rangle \quad (1.2)$$

For each pair of spin  $(S_i, S_j)$  the relative error is

$$E_{ij} = \frac{|\langle S_i S_j \rangle - \langle S_i \rangle \langle S_j \rangle|}{\langle S_i \rangle \langle S_j \rangle} \quad (1.3)$$

We need to compute the correlation function

$$G_c(i, j) \equiv \langle S_i S_j \rangle - \langle S_i \rangle \langle S_j \rangle = \langle (S_i - \langle S_i \rangle)(S_j - \langle S_j \rangle) \rangle \quad (1.4)$$

Assuming *translational invariance*

$$G_c(i, j) \rightarrow G_c(|\vec{r}_i - \vec{r}_j|) \rightarrow G_c(r) \quad (1.5)$$

*Remark.* In order to compute  $G_c(r)$  we cannot assume homogeneity since  $\langle S_i \rangle = \langle S_j \rangle = m$ . It implies that  $G_c = 0$  identically in MF. We have to allow the system to display inhomogeneities in space!

*Remark.* If we want to compute the error in the mean field, it is always zero. So, if we want to calculate the average with respect to fluctuations it does not work. We can either look at the variation in which the field is the internal one, or we can somehow try to make a variation not because of thermal fluctuations but because we control it. We do this by using an external field. This is the response theory with a variation of the field. (lesson)

Let us discuss an important point. The function  $G_c$  does not only describe the spatial correlation of the fluctuations but also, through the linear response theory, the way in which  $m$  varies in response to an external non-homogeneous magnetic field. Within a mean field theory this is the only way to compute  $G_c$ !

Let us see how it works. In order to do that, instead using an  $H$  we use an  $H_i$ .

$$Z[H_i] = \text{Tr}_{\{S\}} \left( e^{-\beta(-J \sum_{\langle ij \rangle} S_i S_j - \sum_i H_i S_i)} \right) \quad (1.6)$$

The definition of the thermal average is

$$\langle S_i \rangle = \frac{\text{Tr}_{\{S\}} \left( S_i e^{-\beta(-J \sum_{\langle ij \rangle} S_i S_j - \sum_i H_i S_i)} \right)}{Z[H_i]} = \beta^{-1} \frac{\partial \ln Z}{\partial H_i} = -\frac{\partial F}{\partial H_i} \quad (1.7)$$

Similarly one can show that

$$\langle S_i S_j \rangle = \frac{\beta^{-1}}{Z} \frac{\partial^2 Z}{\partial H_i \partial H_j} \quad (\text{to do}) \quad (1.8)$$

Hence,

$$\begin{aligned} G_c(i, j) &= \frac{\beta^{-2}}{Z} \frac{\partial^2 Z}{\partial H_i \partial H_j} - \left( \frac{\beta^{-1}}{Z} \frac{\partial Z}{\partial H_i} \right) \left( \frac{\beta^{-1}}{Z} \frac{\partial Z}{\partial H_j} \right) \\ &= \beta^{-1} \frac{\partial^2 \ln Z}{\partial H_i \partial H_j} = -\frac{\partial^2 F(\{H_i\})}{\partial H_i \partial H_j} \end{aligned} \quad (1.9)$$

*Remark.* The response in  $i$  due to a variation of  $H$  in  $j$  is

$$\frac{\partial}{\partial H_j} \langle S_i \rangle = \frac{\partial}{\partial H_j} \left[ \beta^{-1} \frac{\partial \ln Z}{\partial H_i} \right] = \frac{\partial}{\partial H_j} \left[ -\frac{\partial F}{\partial H_i} \right] = \beta G_c(i, j) \quad (1.10)$$

The *generating functions* are:

- $Z[H_i]$ : generating function of  $G(i, j)$ .
- $\ln Z[H_i] = -\beta F$ : generating function of  $G_c(i, j)$ .

*Remark.* (lesson)

$$\frac{\partial M}{\partial H_j} = \sum_i \frac{\partial \langle S_i \rangle}{\partial H_j} = \sum_i G_c(i, j) \quad (1.11)$$

$$H_j = H_j(H) \quad (1.12)$$

$$\frac{\partial M}{\partial H} = \sum_j \frac{\partial M}{\partial H_j} \frac{\partial H_j}{\partial H} = \beta \sum_{ij} G_c(i, j) \quad (1.13)$$

the last one is the susceptibility  $\chi_T$ . Therefore,

$$\chi_T = \beta \sum_{i,j} G_c(i, j) \quad (1.14)$$

$$G_c(i, j) \rightarrow G_c(|i - j|) \sim G(|\vec{r}|) \quad (1.15)$$

## 1.2 Fluctuation-dissipation relation

$$Z_N = \text{Tr} \exp \left[ \beta J \sum_{\langle ij \rangle} S_i S_j + H \sum_i S_i \right] \quad (1.16)$$

where  $H_i = H \forall i$ .

$$M = \sum_i \langle S_i \rangle = \frac{1}{Z} \text{Tr} \sum_i S_i \exp \left[ \beta J \sum_{\langle ij \rangle} S_i S_j + H \sum_i S_i \right] = \frac{1}{\beta Z_N} \frac{\partial Z_N}{\partial H} \quad (1.17)$$

Similarly

$$\sum_{ij} \langle S_i S_j \rangle \stackrel{\text{todo}}{=} \frac{1}{\beta^2 Z_N} \frac{\partial^2 Z_N}{\partial H^2} \quad (1.18)$$

$$\begin{aligned} \chi_T &= \frac{\partial m}{\partial H} = \frac{\partial}{\partial H} \left[ -\frac{1}{N} \frac{\partial F}{\partial H} \right] = \frac{\partial}{\partial H} \left[ \frac{1}{N} k_B T \frac{\partial \ln Z}{\partial H} \right] \\ &= \frac{1}{N} k_B T \left[ \frac{\partial^2 \ln Z}{\partial H^2} \right] = \frac{1}{N} k_B T \left[ \frac{1}{Z} \frac{\partial^2 Z}{\partial H^2} - \frac{1}{Z^2} \left( \frac{\partial Z}{\partial H} \right)^2 \right] \\ &= \frac{1}{N\beta} \left[ \beta^2 \sum_{ij} \langle S_i S_j \rangle - \beta^2 \left( \sum_i \langle S_i \rangle \right)^2 \right] \\ &= \frac{\beta}{N} \sum_{ij} G_c(i, j) = \frac{\beta}{N} \sum_{ij} G_c(\vec{\mathbf{r}}_i - \vec{\mathbf{r}}_j) \\ &= \beta \sum_i G_c(\vec{\mathbf{x}}_i) = (a^d k_B T)^{-1} \int_{\Omega} d^d \vec{\mathbf{r}} G_c(\vec{\mathbf{r}}) \end{aligned} \quad (1.19)$$

where  $\vec{\mathbf{x}}_i \equiv \vec{\mathbf{r}}_i - \vec{\mathbf{r}}_j$ . This is the fluctuation dissipation relation.

### 1.2.1 Computation of $E_R$

The total relative error is the  $E_R(r)$  integrated over the region of radius  $R \leq \xi$ , i.e. where correlations are not negligible.

$$E_{TOT} = \frac{\int_0^\xi G_c(r) d^D \vec{\mathbf{r}}}{\int_0^\xi \langle S_i \rangle \langle S_j \rangle d^D \vec{\mathbf{r}}} \quad (1.20)$$

If  $T < T_c$ , there is a solution  $\eta(r) = \eta \neq 0$

$$\Rightarrow \langle S_i \rangle \langle S_j \rangle \approx \eta^2 \quad (1.21)$$

is uniform in the region  $|\vec{\mathbf{r}}| < \xi$ .

$$E_{TOT} \sim \frac{\int_0^\xi G_c(\vec{\mathbf{r}}) d^D \vec{\mathbf{r}}}{\int_0^\xi \eta^2 d^D \vec{\mathbf{r}}} \ll 1 \quad (1.22)$$

This is the Ginzburg criterium. If satisfied the mean field theory is a valid approximation.

### 1.2.2 Estimation of $E_{TOT}$ as $t \rightarrow 0^-$

The numerator of the (1.22) can be approximated as

$$\int_{V_\xi} G_c(r) d^D r \stackrel{\text{fluctuation dissipation}}{\sim} k_B T_c \chi_T \sim t^{-\gamma} \quad (1.23)$$

On the other hand, the denominator

$$\int_{V_\xi} \eta^2 d^D r \sim \xi^D |t|^{2\beta} \sim t^{2\beta - \nu D} \quad (1.24)$$

To satisfy the Ginzburg criterium

$$E_{TOT} \stackrel{t \rightarrow 0^-}{\sim} t^{-\gamma + \nu D - 2\beta} \ll 1 \quad (1.25)$$

As  $t \rightarrow 0^-$  this is possible only if  $-\gamma + \nu D - 2\beta > 0$ , hence

$$D > \frac{\gamma + 2\beta}{\nu} \equiv D_c \quad (1.26)$$

is called the upper critical dimension.

- For  $D < D_c$ : fluctuations are relevant and mean field is no a good approximation.
- For  $D > D_c$ : fluctuations are less important and mean field describes properly the critical point.
- For  $D = D_c$ : mean field critical exponents ok but strong correction to the scaling expected. For a Ising-like systems (in the mean field)

$$\beta = \frac{1}{2}, \quad \gamma = 1 \quad \Rightarrow D_c = \frac{2}{\nu} \quad (1.27)$$

In order to compute  $D_c$  we need to compute  $\nu$  withing the mean field approximation. We have to consider the system with spatial disomogeneitis!

*Remark.* We have  $\nu_{MF} = 1/2$ . Therefore, the dimension is  $D > 4$  for the mean field.

Now we have a lower critical dimension (remember the last lessons!) and an upper one.