

Chapter 1

Renormalization group theory. Universality

1.1 Renormalization group theory (RG)

Kadanoff's argument for the Ising model allows us to explain the scaling form of the free energy density and of the correlation length near the critical point; in particular, the Kadanoff's block spin transformation justifies the Widom scaling hypothesis and identifies λ with l . We have obtained the results:

$$\begin{cases} f_s(t, h) = l^{-d} f_s(tl^{y_t}, hl^{y_h}) \\ G(\vec{r}, t, h) = l^{-2(d-y_h)} G\left(\frac{\vec{r}}{l}, tl^{y_t}, hl^{y_h}\right) \\ t_l = tl^{y_t}, \quad h_l = hl^{y_h} \end{cases}$$

where we did two crucial assumptions:

1. 1st assumption:

$$\mathcal{H}_l = \mathcal{H}_\Omega$$

2. 2nd assumption:

$$\begin{cases} t_l = tl^{y_t} \\ h_l = hl^{y_h} \end{cases}$$

However, as we have seen, the Kadanoff's theory is unable to predict the values of the scaling exponents y_t and y_h (and thus ultimately of the critical exponents), nor can it explain why universality occurs.

Remark. Open problems are: how an iterative procedure of coarse-graining can produce the 2nd assumption? How this can give rise to the singular behaviour of f_s ? How can we explain universality of the critical points?

We will see that these problems are solved with the introduction of the Renormalization Group (done by K. G. Wilson at the beginning of the '70s), which we will call simply "RG" from now on for the sake of simplicity. The RG is based upon the correct "intuition" of Kadanoff's argument that the coupling constants of a Hamiltonian change if we coarse-grain the system (or in other words we "look" at it on different spatial scales); however, this "intuition" strictly speaking is not correct since we have seen that in Kadanoff's procedure we assume that after the coarse-graining procedure the Hamiltonian of the system has exactly the same form: as we will see, this is not true in general because new terms can appear after we coarse-grain the system.

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1.1.1 Main goals of RG

The main goals of the Renormalization Group theory are:

1. To furnish an algorithm way to perform systematically the coarse graining procedure.

More specifically, the realization of a coarse graining procedure, also called decimation, is like the one introduced by Kadanoff for the Ising model; in general, this procedure must integrate the degrees of freedom of the system on scales of linear dimension la which must be much larger than the characteristic microscopic scale a of the system, but also much smaller than the correlation length ξ :

$$a \ll la \ll \xi$$

After the decimation, we are left with a new effective Hamiltonian that describes the system at larger length scales. We will see that this is equivalent to find a transformation between the coupling constants $K \rightarrow K'$.

2. Identify the origin of the critical behaviour and explain universality.

The coarse graining procedure will give rise to a system with $\xi_l = \xi/l$, this means that the new correlation length is smaller than the original one, so our system is farther from criticality after the decimation.

To make an example, suppose we are given a generic Hamiltonian $\mathcal{H} = \mathcal{H}([K])$ which depends on an arbitrary number of coupling constants $[K] = \vec{K} = (K_1, K_2, \dots, K_n)$ (in the case of an Ising model with nearest-neighbour interaction and an external field there are only two coupling constants, $K = K_1$ and $h = K_2$).

Let us suppose we apply a coarse-graining procedure, in which we integrate the degree of freedom within distance l with $a \leq la \leq L$. For what we have just stated, the action of the RG can be expressed as a transformation of the coupling constants:

$$[K'] = \mathcal{R}_l[K], \quad l > 1 \tag{1.1}$$

where \mathcal{R}_l is called *RG transformation*, while this last equation is referred to as *recursive relation*.

Properties of \mathcal{R}_l

We suppose that the function \mathcal{R}_l satisfy the following properties:

1. \mathcal{R}_l is **analytic** (sum of a finite number of degrees of freedom, no matter how complicated it may be).
2. The set of transformations \mathcal{R}_l forms a **semigroup**, because if we subsequently apply two transformations \mathcal{R}_{l_1} and \mathcal{R}_{l_2} on two different length scales l_1 and l_2 we have:

$$\begin{cases} [K'] = \mathcal{R}_{l_1}[K] \\ [K''] = \mathcal{R}_{l_2}[K'] = \mathcal{R}_{l_2} \circ \mathcal{R}_{l_1}[K] \end{cases}$$

Hence, we have the relation

$$\mathcal{R}_{l_2 l_1}[K] = \mathcal{R}_{l_2} \circ \mathcal{R}_{l_1}[K] \tag{1.2}$$

Remark. Note that it is a *semigroup* and not a *group*, since in general does not exist the inverse transformation; in fact, we should have always $l > 1$.

There is no general way to construct the function \mathcal{R}_l : depending on the system and on the case considered we can choose different ways to carry out the decimation, and in general (as we will see) for a given system many different RG transformations can be built. In general such procedures can be done either in coordinate space (real space Renormalization Group) or in Fourier space (momentum shell Renormalization Group).

In terms of the coupling constants $[K]$ the partition function of the original system is:

$$Z_N[K] = \text{Tr } e^{-\beta \mathcal{H}[K]}$$

while the free energy density is

$$f_N[K] = -\frac{k_B T}{N} \log Z_N[K]$$

Now, if the RG transformation integrates the degrees of freedom on the spatial scale la then the number of degrees of freedom will decrease by a factor l^d , if d is the dimensionality of the system; in other words, after the RG transformation \mathcal{R}_l , the number N of degrees of freedom is reduced by

$$N_l = \frac{N}{l^d}$$

3. The new hamiltonian $\mathcal{H}_l[K']$ can be (and in general it is) different from the previous one $\mathcal{H}[K]$ (this is the main difference with the Kadanoff's theory), but the effective Hamiltonian $\mathcal{H}_l[K']$ must have the same symmetry properties of the original one!

This means (and this is the great improvement with respect to Kadanoff's argument) that the decimation can make some new terms appear in the coarse-grained Hamiltonian, as long as they respect the same symmetries of the original system. In other words, if $K_m = 0$ in \mathcal{H}_N but its relative term is allowed by the symmetry group of \mathcal{H}_N itself, then we can have $K'_m \neq 0$ in $\mathcal{H}'_{N'}$.

For example, if we start from

$$\mathcal{H}_N = NK_0 + K_2 \sum_{ij} S_i S_j$$

if the term K_3 is not allowed by the symmetry group of \mathcal{H}_N , we cannot produce

$$\mathcal{H}'_{N'} = N'K'_0 + K'_1 \sum_I S_I + K'_2 \sum_{IJ} S_I S_J + K'_3 \sum_{IJK} S_I S_J S_K$$

4. The invariance condition is not in \mathcal{H} (as in Kadanoff's theory) but in Z ; hence, the coarse-graining procedure (decimation) leaves invariant the partition function instead of the Hamiltonian:

$$Z_{N'}[K'] = Z_N[K] \tag{1.3}$$

this invariance condition has a consequence on the free-energy:

$$f_N[K] \simeq \frac{1}{N} \log Z_N[K] \simeq \frac{l^d}{l^d N} \log Z_{N'}[K'] \simeq l^{-d} \frac{1}{N'} \log Z_{N'}[K']$$

where $N' = N/l^d$. Hence,

$$f[K] \propto l^{-d} f[K'] \tag{1.4}$$

which is the scaling form of the free energy density as obtained by Kadanoff.

1.1.2 Singular behaviour in RG

We have stated that the RG transformations \mathcal{R}_l are analytic, hence a single \mathcal{R}_l involves the integration of a finite number of degrees of freedom and the free energy cannot develop the singularity behaviour we are looking for; so, we might ask: where does the singular behaviour of a system near a critical point come from? This occurs in the thermodynamic limit, which in this case is obtained when we apply the RG transformation an infinite number of times. Indeed, in order to integrate a thermodynamic number of degrees of freedoms, one has to apply an infinite number of RG transformations.

In general, after the n -th iteration of the RG, the coarse-graining length of the system will be $l \rightarrow l^n$ and the coupling constants $[K] \rightarrow [K^{(n)}]$. As n increases the "vector" of coupling constants describes a "trajectory" in the space of all the possible coupling constants $[K]$, often called **Hamiltonian space**, or theory space; by varying the initial conditions, namely different initial Hamiltonians, one obtains a **flux of trajectories** (i.e. the set of all the trajectories that start from different initial conditions). In general, these trajectories can form strange attractors or complex limit cycles; however, it is almost always found that they are simply attracted towards or ejected from **fixed points** (cases where this doesn't occur are really exotic), so in the following we will assume that the flux of trajectories only exhibits fixed points.

The study of the properties of the flux of trajectories near these fixed points is crucial, since as we will see it is that that will allow us to actually explain universality and predict the values of the critical exponents (the scaling behaviour introduced by Widom is related to the behaviour of the trajectories close to some fixed points). We therefore proceed to study such points.

1.1.3 Zoology of the fixed points

Suppose we know \mathcal{R}_l . If $[K^*]$ is a fixed point of the flux of trajectories, by definition we have:

$$\mathcal{R}_l[K^*] = [K^*] \quad (1.5)$$

Then, in general from the Hamiltonian of a system we can determine the correlation length ξ , and if $[K'] = \mathcal{R}_l[K]$ we know that:

$$\xi[K'] = \frac{\xi[K]}{l} \equiv \xi_l$$

Therefore for a fixed point we have:

$$\xi[K^*] = \frac{\xi[K^*]}{l} \quad (1.6)$$

which implies two cases:

$$\xi[K^*] = \begin{cases} 0 & \text{trivial} \\ \infty & \text{critical} \end{cases} \quad (1.7)$$

A fixed point with $\xi = \infty$ is called *critical*, while if $\xi = 0$ *trivial*. Clearly, every fixed point $[K^*]$ can have its own **basin of attraction**, i.e. a set of points $\{[K]\}$ that under the action of the flux of trajectories tend to $[K^*]$:

$$\mathcal{R}_l^{(n)}[K] \xrightarrow{n \rightarrow \infty} [K^*] \quad (1.8)$$

An important result concerning the basin of attraction of critical fixed points is the following:

Theorem 1

All the points $[K]$ belonging to a basin of attraction of a critical fixed point have the correlation length $\xi = \infty$.

Proof. Call $[K]$ the initial set of coupling constants, after n iterations of the RG the correlation length of the system will be such that:

$$\xi[K] = l\xi[K^{(1)}] = \dots = l^n\xi[K^{(n)}] \Rightarrow \xi[K] = l^n\xi[K^{(n)}]$$

If we now take the limit $n \rightarrow \infty$ the right hand side diverges if $K^{(n)} \rightarrow K^*$, i.e. if $[K]$ belongs to the basin of attraction of $[K^*]$. Hence, $\xi[K^*] = \infty$, implies

$$\Rightarrow \xi[K] = l^n\xi[K^*] = \infty$$

Therefore, we have $\xi[K] = \infty$. ■

The set of $[K]$ that forms the basin of attraction of a critical fixed point is also called **critical manifold**.

Universality

All the critical models that belong to the critical manifold, have the same critical behaviour of the corresponding critical fixed point. Hence, we want to study the behaviour of \mathcal{R}_l close to the fixed points.

We can argue that the fact that all the points of a critical manifold flow towards the same fixed point (i.e. the same Hamiltonian) is the basic mechanism on which universality is based upon, but this is by no means a complete explanation, since universality involves the behaviour of systems near a critical point and we still have said nothing about that. We can however note the following fact: starting from any point in Hamiltonian space, iterating the RG transformation and identifying the fixed point towards which the system flows, the phase of the original point in Hamiltonian space (i.e. in the phase diagram) will be described by this fixed point. Therefore, every phase of the system is "represented" by a fixed point of the flux of trajectories.

As we will later see, critical fixed points describe the singular critical behaviour while trivial fixed points are related to the bulk phases of the system: therefore, the knowledge of the location and nature of the fixed points of the flux of trajectories can give us hints on the structure of the phase diagram of the system, and the behaviour of the flow near critical fixed points allows us to calculate the values of the critical exponents.

1.1.4 Linearization of RG close to the fixed points and critical exponents

In order to study the behaviour of the flux of trajectories near a fixed point $[K^*]$ of \mathcal{R}_l , let us take a slight perturbation from it, namely we set:

$$\vec{K} = \vec{K}^* + \delta\vec{K} \tag{1.9}$$

where $\delta\vec{K}$ is a small displacement. Applying the RG transformation, in components we will have:

$$K'_j = (\mathcal{R}_l)_j(\vec{K}^* + \delta\vec{K})_j = K_j^* + \sum_i \left(\frac{\partial K'_j}{\partial K_i} \right) \Big|_{\vec{K}^*} \delta K_i + O(\delta K_i^2)$$

Neglecting all the terms beyond the linear ones, we can write the action of the linearised RG transformation in terms of the displacements $\delta\vec{\mathbf{K}}$ and $\delta\vec{\mathbf{K}}'$ as:

$$\delta\vec{\mathbf{K}}' = \bar{\pi}\delta\vec{\mathbf{K}} \quad (1.10)$$

where

$$(\bar{\pi})_{ij} = \left(\frac{\partial K'_j}{\partial K_i} \right) \Big|_{\vec{\mathbf{K}}^*} \quad (1.11)$$

Of course $\bar{\pi}$ is a square matrix, but:

1. $\bar{\pi}$ is in general not symmetric, one has to distinguish between left and right eigenvectors;
2. $\bar{\pi}$ it is not always diagonalizable or sometimes its eigenvalues can be complex. For most of the physical system, however, $\bar{\pi}$ can be diagonalized and the eigenvalues are real.

However, we suppose $\bar{\pi}$ to be symmetric (which, as before, is almost always the case) so that it can be diagonalized. If we call $\lambda_l^{(\sigma)}$ and $\vec{\mathbf{e}}^{(\sigma)}$ the σ -th eigenvalue and relative eigenvector of $\bar{\pi}^{(l)}$ (where we are explicitly writing the length scale of the decimation), in components the action $\bar{\pi}^{(l)}$ will be:

$$\Rightarrow \bar{\pi}_{ij}^{(l)} \vec{\mathbf{e}}_j^{(\sigma)} = \lambda_l^{(\sigma)} \vec{\mathbf{e}}_i^{(\sigma)} \quad (1.12)$$

this is the eigenvalue equation. From the semigroup property of the RG transformation \mathcal{R}_l , we have:

$$\bar{\pi}^{(l)} \bar{\pi}^{(l')} = \bar{\pi}^{(ll')}$$

Hence, we have:

$$\lambda_l^{(\sigma)} \lambda_{l'}^{(\sigma)} = \lambda_{ll'}^{(\sigma)} \quad (1.13)$$

This is a functional equation which can be solved in the following way: if we write the eigenvalues explicitly as functions of l , namely $\lambda_l^{(\sigma)} = \lambda^{(\sigma)}(l)$, then differentiating with respect to l' :

$$\lambda^{(\sigma)}(l) \lambda'^{(\sigma)}(l') = l \lambda'^{(\sigma)}(ll')$$

where with λ' we mean that λ has been differentiated with respect to its argument. Setting now $l' = 1$ and defining $\lambda'^{(\sigma)}(1) = y_\sigma$ we get:

$$\frac{\lambda'^{(\sigma)}(l)}{\lambda^{(\sigma)}(l)} = \frac{y_\sigma}{l}$$

which is easily solved to give:

$$\lambda_l^{(\sigma)} = l^{y_\sigma} \quad (1.14)$$

where, as we have defined it, y_σ is a number (to be determined) independent of l (is the critical exponent). To see how $\delta\vec{\mathbf{K}}$ changes under the action of the linearized transformation $\bar{\pi}$ let us find out how its components along the directions determined by the eigenvectors $\vec{\mathbf{e}}^{(\sigma)}$ change. In other words, let us expand $\delta\vec{\mathbf{K}}$ in terms of $\vec{\mathbf{e}}^{(\sigma)}$ (that is a complete orthonormal base):

$$\delta\vec{\mathbf{K}} = \sum_{\sigma} a^{(\sigma)} \vec{\mathbf{e}}^{(\sigma)}, \quad a^{(\sigma)} = \vec{\mathbf{e}}^{(\sigma)} \cdot \delta\vec{\mathbf{K}} \quad (1.15)$$

and applying $\bar{\pi}^{(l)}$:

$$\delta\vec{\mathbf{K}}' = \bar{\pi}\delta\vec{\mathbf{K}} = \sum_{\sigma} a^{(\sigma)} \bar{\pi}(\vec{\mathbf{e}}^{(\sigma)}) = \sum_{\sigma} a^{(\sigma)} \lambda_l^{(\sigma)} \vec{\mathbf{e}}^{(\sigma)} \equiv \sum_{\sigma} a'^{(\sigma)} \vec{\mathbf{e}}^{(\sigma)} \quad (1.16)$$

where in the last step we have defined the components $a'^{(\sigma)}$ which is the projection of $\delta\vec{\mathbf{K}}'$ along $\vec{\mathbf{e}}^{(\sigma)}$.

Remark. Ortonormality is not always true since in general $\bar{\pi}$ is not symmetric!

We therefore see that the behaviour of $\delta\vec{\mathbf{K}}$ along the eigenvectors $\vec{\mathbf{e}}^{(\sigma)}$ depends on the magnitudes of the eigenvalues $\lambda_l^{(\sigma)}$: some components of $\delta\vec{\mathbf{K}}$ grow under the action of $\bar{\pi}$ while some others shrink. In particular, if we order the eigenvalues in descending order

$$|\vec{\lambda}_1| \geq |\vec{\lambda}_2| \geq |\vec{\lambda}_3| \geq \dots \geq |\vec{\lambda}_\sigma|$$

we can distinguish three cases:

1. case $|\lambda_l^{(\sigma)}| > 1$ (i.e. $y^\sigma > 0$): implies that $a^{(\sigma)}$ grows under $\bar{\pi}$. These are called **relevant** eigenvalues/eigenvectors;
2. case $|\lambda_l^{(\sigma)}| < 1$ (i.e. $y^\sigma < 0$): implies that $a^{(\sigma)}$ decreases under $\bar{\pi}$. These are called **irrelevant** eigenvalues/eigenvectors;
3. case $|\lambda_l^{(\sigma)}| = 1$ (i.e. $y^\sigma = 0$): implies that $a^{(\sigma)}$ remains constant under $\bar{\pi}$ (its behaviour can depend on the higher orders in the expansion that we have neglected). These are called **marginal** eigenvalues/eigenvectors.

The above analysis implies that: starting from a point close to a critical fixed point $[K^*]$ (but not on the critical manifold), the trajectory will abandon $[K^*]$ along the relevant directions whereas it will approach $[K^*]$ along the irrelevant directions. Hence, we have that:

- The *irrelevant* eigenvectors form the local basis of the basin of attraction of $[K^*]$. Hence, the number of irrelevant directions of a fixed point is equal to the dimension of its critical manifold.
- The *relevant* eigenvectors form a sub-space complementar to the basin of attraction of codimension C . Hence, the number of relevant directions is equal to its codimension.

Remark. Let us note that the eigenvalues, and their possible relevance, depend on the matrix $\bar{\pi}$, which in turn depends on the fixed point considered $[K^*]$: this means that the terms "relevant", "irrelevant" or "marginal" must always be specified with respect to the particular fixed point considered.

1.2 The origins of scaling and critical behaviour

Let us consider a fixed point of the flux of trajectories of a generic system, and assume that it has two relevant directions corresponding to the coupling constants that for simplicity we defined as

$$K_1 \rightarrow K_1(T) = T, \quad K_2 \rightarrow K_2(H) = H$$

where T is the temperature and H is the external field. We suppose that T and H are transformed under the RG such that:

$$T' = \mathcal{R}_l^T(T, H), \quad H' = \mathcal{R}_l^H(T, H)$$

where \mathcal{R}_l^T and \mathcal{R}_l^H are analytic functions given by the coarse graining procedure. The fixed points $\vec{\mathbf{K}}^* = (T^*, H^*)$ of the flux of trajectories will be given by the solutions of:

$$\begin{cases} T^* = \mathcal{R}_l^T(T^*, H^*) \\ H^* = \mathcal{R}_l^H(T^*, H^*) \end{cases}$$

with the correlation length that diverges, i.e. $\xi(T^*, H^*) = \infty$. Linearising the transformation around the fixed point (T^*, H^*) , in terms of the reduced variables (for standard magnetic systems $H^* = 0$)

$$t = \frac{(T - T^*)}{T^*}, \quad h = \frac{(H - H^*)}{H^*}$$

we have:

$$\begin{pmatrix} t' \\ h' \end{pmatrix} = \bar{\pi} \begin{pmatrix} t \\ h \end{pmatrix} \quad (1.17)$$

where:

$$\bar{\pi} = \begin{pmatrix} \partial \mathcal{R}_l^T / \partial T & \partial \mathcal{R}_l^T / \partial H \\ \partial \mathcal{R}_l^H / \partial T & \partial \mathcal{R}_l^H / \partial H \end{pmatrix}_{T^*, H^*} \quad (1.18)$$

Remark. In this case $\delta \vec{\mathbf{K}} = (t, h)$.

In general the eigenvectors $\vec{\mathbf{e}}^{(\sigma)}$ are linear combinations of t and h . When $\bar{\pi}$ can be diagonalized, t and h are not "mixed-up" by the transformation. Hence, as previously stated, we suppose $\bar{\pi}$ to be diagonalizable. We therefore write its eigenvalues as:

$$\lambda_l^{(t)} = l^{y_t}, \quad \lambda_l^{(h)} = l^{y_h} \quad (1.19)$$

This way we can write the linear transformation as:

$$\begin{pmatrix} t' \\ h' \end{pmatrix} = \begin{pmatrix} \lambda_l^{(t)} & 0 \\ 0 & \lambda_l^{(h)} \end{pmatrix} \begin{pmatrix} t \\ h \end{pmatrix} \Rightarrow \begin{pmatrix} t' \\ h' \end{pmatrix} = \begin{pmatrix} l^{y_t} t \\ l^{y_h} h \end{pmatrix} \quad (1.20)$$

After n iterations we will have:

$$\begin{cases} t^{(n)} = (l^{y_t})^n t \\ h^{(n)} = (l^{y_h})^n h \end{cases} \quad (1.21)$$

On the other hand, since in general we know that

$$\xi' \equiv \xi(t', h') = \frac{\xi(t, h)}{l}$$

after n iterations we have

$$\xi(t, h) = l^n \xi(l^{ny_t} t, l^{ny_h} h) \quad (1.22)$$

This is the scaling law of the correlation length. From this we can determine the critical exponent ν . In fact, setting $h = 0$ ($H = H^*$) for simplicity, we have

$$\xi(t, 0) = l^n \xi(l^{ny_t} t, 0)$$

Since l is arbitrary, choosing it so that $l^{ny_t} t = b \gg 1$, with b a positive real number ($b \in \mathbb{R}^+$, l is not an integer any more), we have:

$$l^n = \left(\frac{b}{t}\right)^{1/y_t} \Rightarrow \xi(t) = \left(\frac{t}{b}\right)^{-1/y_t} \xi(b, 0)$$

Since for $t \rightarrow 0$ in general $\xi \sim t^{-\nu}$, we get:

$$\nu = \frac{1}{y_t} \quad (1.23)$$

This is an extremely important result! In fact, we see that once the RG transformation \mathcal{R} is known, y_t is straightforward to compute as:

$$y_t = \frac{\log \lambda_l^{(t)}}{\log l}$$

and so we are actually able to calculate ν and predict its value! We can do even something more (including giving y_h a meaning) from the scaling law of the free energy density. After n iterations of the RG we have:

$$f_s(t, h) = l^{-d} f_s(t', h') = l^{-nd} f_s(t^{(n)}, h^{(n)}) = l^{-nd} f_s(l^{ny_t} t, l^{ny_h} h) \quad (1.24)$$

and choosing again l so that $l^{ny_t} t = b^{y_t}$, then:

$$f_s(t, h) = t^{d/y_t} b^{-d} f_s\left(b^{y_t}, \frac{b^{y_h} h}{t^{y_h/y_t}}\right)$$

Comparing this to what we have seen in Eq.(??) we get:

$$\begin{cases} 2 - \alpha = d\nu = \frac{d}{y_t} \\ \Delta = \frac{y_h}{y_t} \end{cases} \quad (1.25)$$

where y_h and y_t can be computed as

$$y_t = \frac{\log \lambda_l^{(t)}}{\log l}, \quad y_h = \frac{\log \lambda_l^{(h)}}{\log l} \quad (1.26)$$

Hence, we have all we need for the computation!

1.3 Real space renormalization

Let us start from the most general form of the Ising model where $\sigma_i = \pm 1$ and the two body interaction is

$$w(\sigma_i, \sigma_j) = -\hat{g} - \frac{\hat{h}}{z}(\sigma_i + \sigma_j) - \hat{J}\sigma_i\sigma_j \quad (1.27)$$

1.3.1 Decimation procedure for $D = 1$

Decimation means summing up over all spins. $D = 1$ the procedure is clearly exact. Idea: pass from a N - spins system to one with $\frac{N}{b}$ spins by summing the remaining $N - \frac{N}{b}$ spins.

Case $b=3$ (see Figure 1.1).

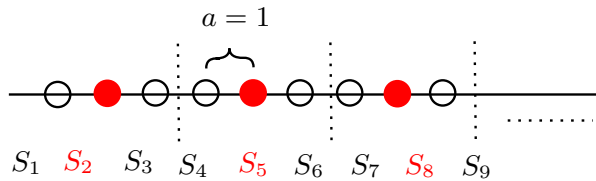
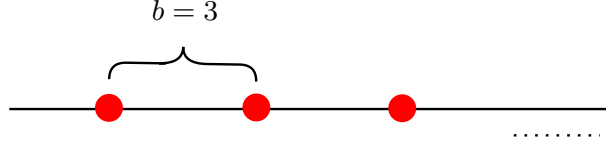


Figure 1.1: Description.

Sum over the spins with the empty circle at the border of each clock, keeping the spins full circle untouched. We obtain Figure 1.2.

**Figure 1.2:** Description.

Let us see how it works for the two blocks $[S_1, S_2, S_3]$ and $[S_4, S_5, S_6]$. Let us call

$$S_2 \equiv S'_1, \quad S_5 = S'_2 \quad \text{fixed} \quad (1.28)$$

$$\sum_{S_3=\pm 1} \sum_{S_4=\pm 1} \exp[kS'_1 S_3 + kS_3 S_4 + kS_4 S'_2] \quad (1.29)$$

Since

$$e^{kS_3 S_4} = \cosh(k)(1 + xS_3 S_4) \quad (1.30)$$

with

$$x \equiv \tanh k \quad (1.31)$$

we have

$$\sum_{S_3, S_4} (\cosh k)^3 (1 + xS'_1 S_3)(1 + xS_3 S_4)(1 + xS_4 S'_2) \quad (1.32)$$

Performing the expansion and summing over S_3, S_4 it is easy to show that (to do)

$$Z'_{N'}(k') = \text{Tr}_{\{S'_I\}} \left[2^{2N'} (\cosh k)^{3N'} (1 + x^3 S'_I S'_{I+1}) \right] \quad (1.33)$$

This must have the same form of $Z_N(k)$. Hence, we should rewrite equation (1.33) as

$$Z'_{N'}(k') = \text{Tr}_{\{S'_I\}} \exp[-\beta \mathcal{H}'(k')] \quad (1.34)$$

with

$$-\beta \mathcal{H}' = N' g(k, k') + k' \sum_I S'_I S'_{I+1} \quad (1.35)$$

We note that

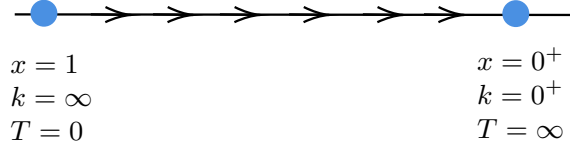
$$\begin{aligned} 2^2 (\cosh k)^3 (1 + x^3 S'_I S'_{I+1}) &= 2^2 \frac{\cosh k'}{\cosh k'} (\cosh k)^3 (1 + x^3 S'_I S'_{I+1}) \\ &= 2^2 \frac{(\cosh k)^3}{\cosh k'} (\cosh k') (1 + x' S'_I S'_{I+1}) \\ &= 2^2 \frac{(\cosh k)^3}{\cosh k'} \exp(k' S'_I S'_{I+1}) \\ &= \exp \left[2 \ln 2 + \ln \left[\frac{(\cosh k)^3}{\cosh k'} \right] + k' S'_I S'_{I+1} \right] \end{aligned} \quad (1.36)$$

It is ok with

$$\begin{cases} g(k, k') = 2 \ln 2 + \ln \left[\frac{(\cosh k)^3}{\cosh k'} \right] \\ x' = x^3 \iff k' = \tanh^{-1} [(\tanh k)^3] \Rightarrow k' = R_{b=3}(k) \\ N' = \frac{N}{b} \end{cases} \quad (1.37)$$

For $x' = x^3$, we have two fixed points

$$\begin{cases} x^* = 0 \iff k \rightarrow 0 \iff T \rightarrow \infty \\ x^* = 1^- \iff k \rightarrow \infty \iff T \rightarrow 0 \end{cases} \quad (1.38)$$

**Figure 1.3:** Description.

For $\forall x_0 < 1$, we have $R^{(n)} \xrightarrow{n \rightarrow \infty} 0^+$, $x = 1$ is an unstable fixed point, as shown in Figure 1.3. We have

$$\xi(x') = \frac{\xi(x)}{b}, \quad \text{with } x' = x^b \quad (1.39)$$

where b is arbitrary. Let us choose $b = c/\ln x$:

$$\xi(x^b) = \xi(e^{b \ln x}) = \xi(e^c) = \frac{\xi(x)}{b} = \left(\frac{c}{\ln x}\right)^{-1} \xi(x) \quad (1.40)$$

Finally,

$$\xi(e^c) = \frac{\ln x}{c} \xi(x) \Rightarrow \xi(x) = \frac{c \xi(e^c)}{\ln x} = \frac{\text{const}}{\ln x} \quad (1.41)$$

$$\xi(k) = \frac{\text{const}}{\ln(\tanh k)} \quad (1.42)$$

equal to the exact model in $D = 1$. $k \rightarrow \infty$ ($x \rightarrow 1$), we have

$$\xi \sim e^{\text{const}/T} \quad (1.43)$$

finite $\forall k \neq \infty$.

1.3.2 Decimation procedure for $D > 1$ (proliferation of interactions)

Ioing on a square lattice, block transformation (length b). There are problems with the spins at the boundaries. In order to get $Z'_{N'}(k') = Z_N(k)$, at least an additional term in the Hamiltonian must be introduced

$$\mathcal{H} \rightarrow \mathcal{H}' = \mathcal{H}'(k', k'_2) \quad (1.44)$$

This unfortunately occurs at each iteration! There is an uncontrolled proliferation and approximations are necessary.

Example 1: Decimation of Ising on square lattice

x : spin to sum over

$$\begin{cases} k' = \frac{1}{4} \ln \cosh 4k \\ L' = \frac{1}{8} \ln \cosh 4k \\ Q' = \frac{1}{8} \ln \cosh 4k - \frac{1}{2} \ln \cosh 2k \end{cases} \quad (1.45)$$

(4 spins). The approximations are:

1. Neglect Q' term.
2. Omit explicit dependence on L' . Hence, assuming $k' + L' \rightarrow k'$. 1 recursion

$$k' = \frac{3}{8} \ln \cosh 4k \quad (1.46)$$

$$\begin{cases} k^{(n)} \xrightarrow{n \rightarrow \infty} \infty & k_0 > k_c \\ k^{(n)} \xrightarrow{n \rightarrow \infty} 0 & k_0 < k_c \end{cases} \quad (1.47)$$

where $\infty, 0$ are stable fixed point.

$$\delta k' = \lambda_t \delta k = l^{Y_t} \delta k \quad (1.48)$$

where

$$\lambda_t = \left. \frac{dk'}{dk} \right|_{k=k_c} \quad (1.49)$$

For $l = \sqrt{2}$,

$$\begin{aligned} Y_t &= \frac{\ln \lambda_t}{\ln l} = \frac{1}{\ln \sqrt{2}} \ln \left(\left. \frac{dk'}{dk} \right|_{k=k_c} \right) \\ &= \frac{1}{\ln \sqrt{2}} \ln \left(\frac{d}{dk} \left(\frac{3}{8} \ln (\cosh 4k) \right) \right) = 1.070 \end{aligned} \quad (1.50)$$

so, this is actual a relevant eigenvalue. We have also the critical exponents

$$\nu = \frac{1}{Y_t} = 0.9345, \quad \alpha = 2 - \frac{d}{Y_t} = 0.1313 \quad (1.51)$$