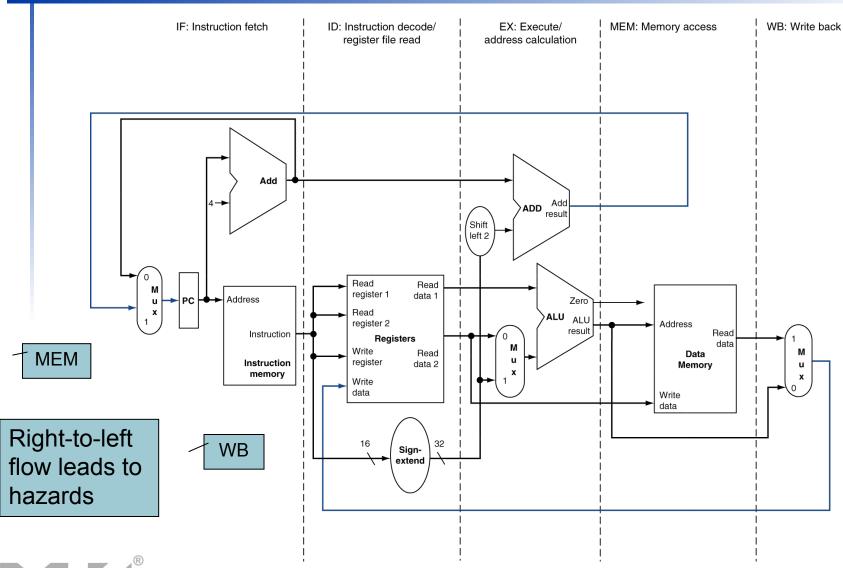
CPSC 440

Chapter 4: The Processor (part 3)*



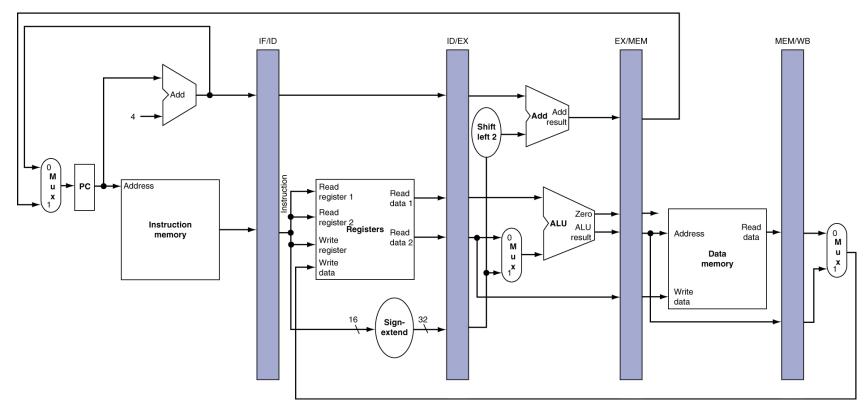
MIPS Pipelined Datapath





Pipeline registers

- Need registers between stages
 - To hold information produced in previous cycle



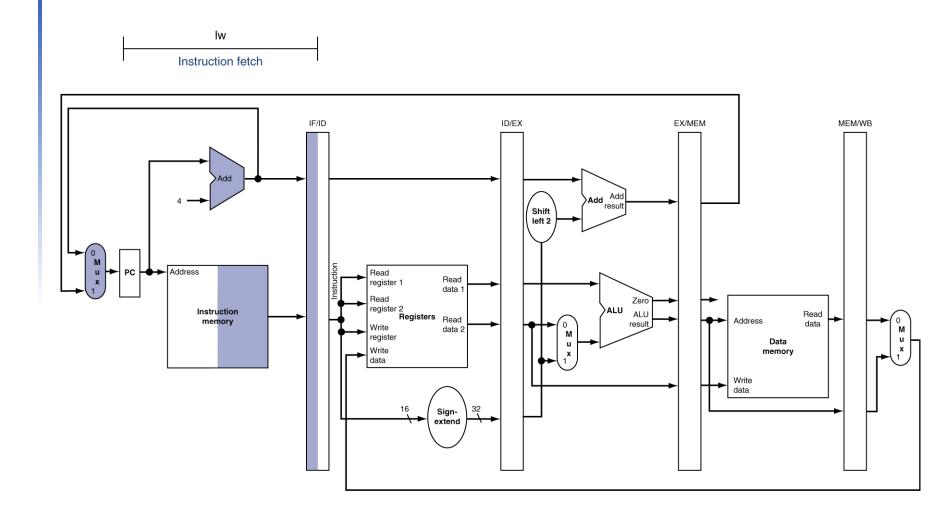


Pipeline Operation

- Cycle-by-cycle flow of instructions through the pipelined datapath
 - "Single-clock-cycle" pipeline diagram
 - Shows pipeline usage in a single cycle
 - Highlight resources used
 - c.f. "multi-clock-cycle" diagram
 - Graph of operation over time
- We'll look at "single-clock-cycle" diagrams for load & store

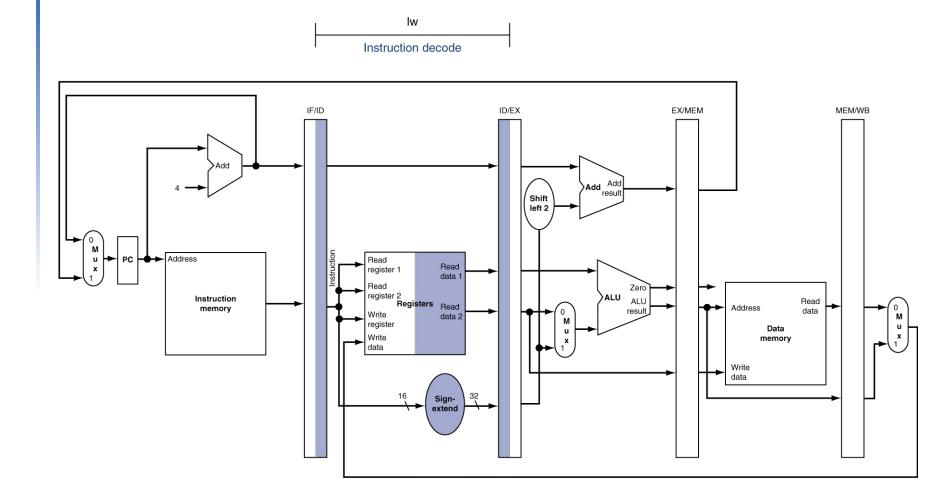


IF for Load, Store, ...



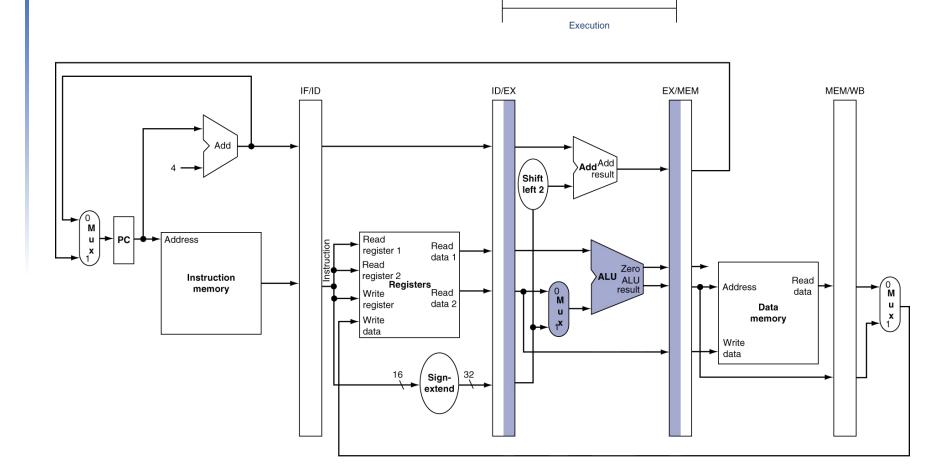


ID for Load, Store, ...





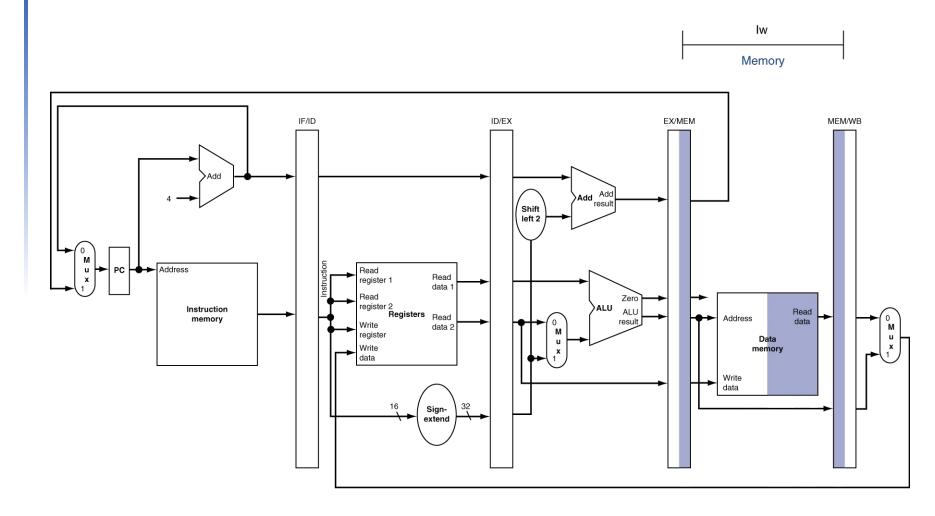
EX for Load



lw

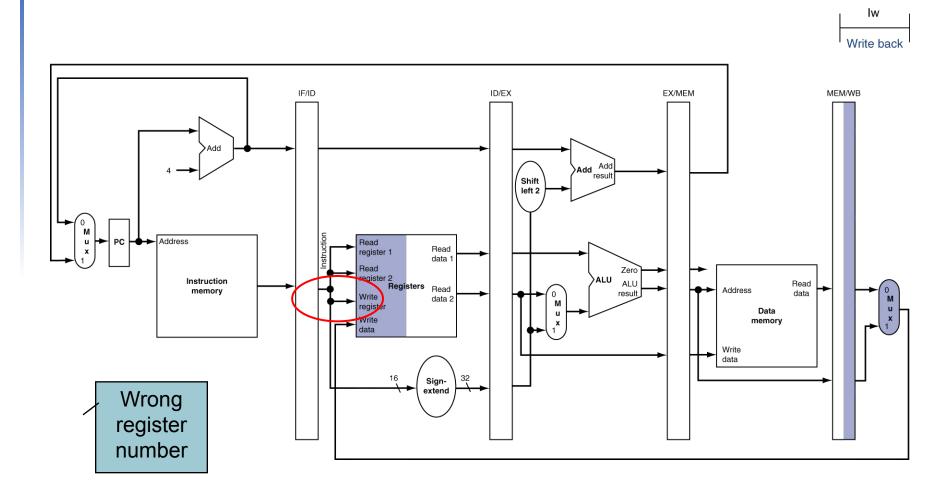


MEM for Load



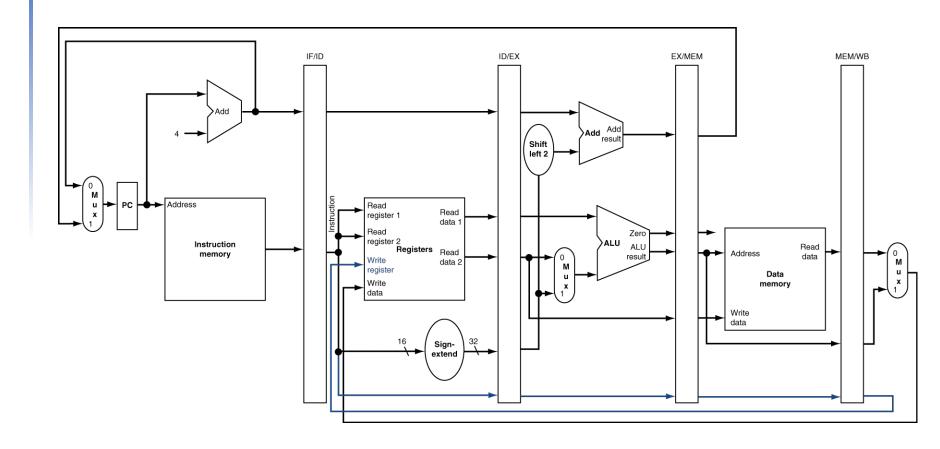


WB for Load





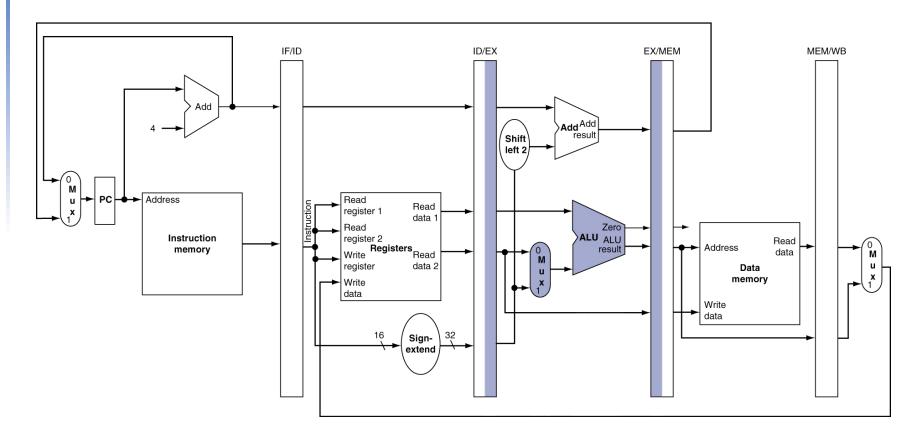
Corrected Datapath for Load





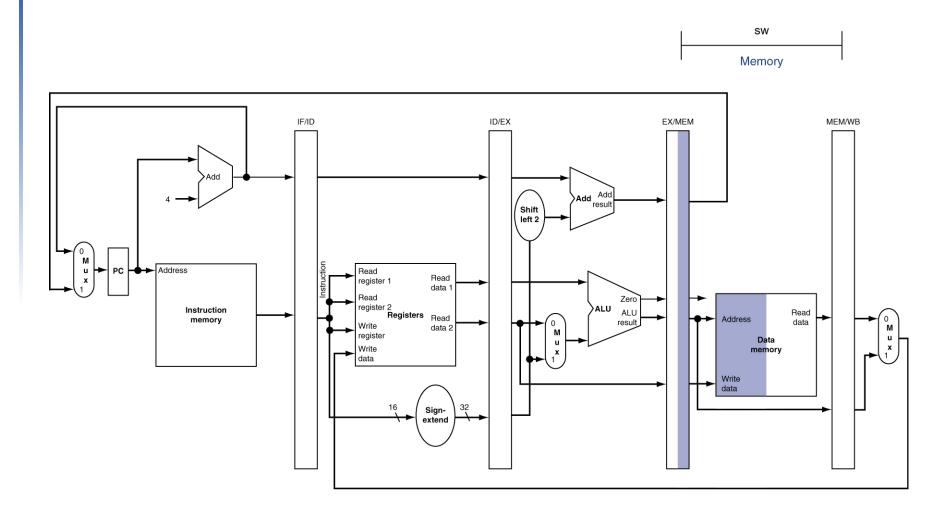
EX for Store





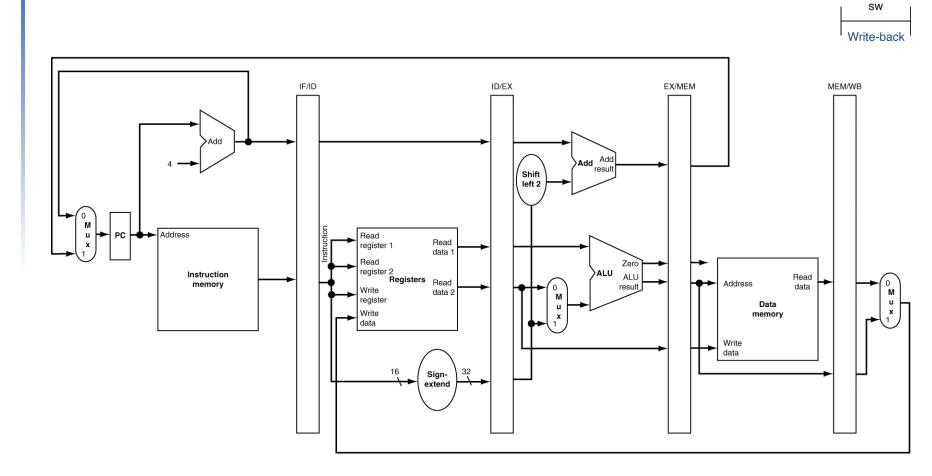


MEM for Store





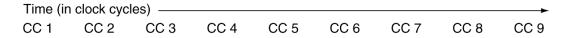
WB for Store

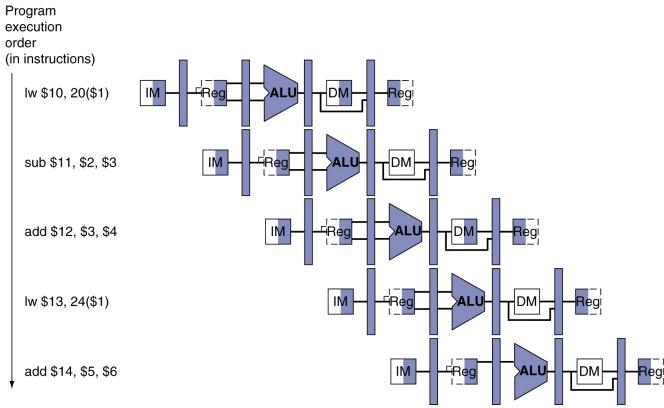




Multi-Cycle Pipeline Diagram

Form showing resource usage

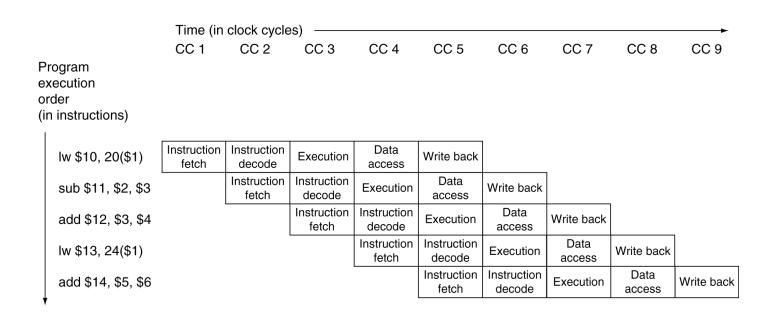






Multi-Cycle Pipeline Diagram

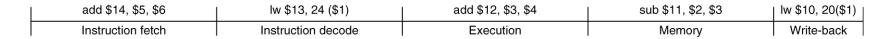
Traditional form

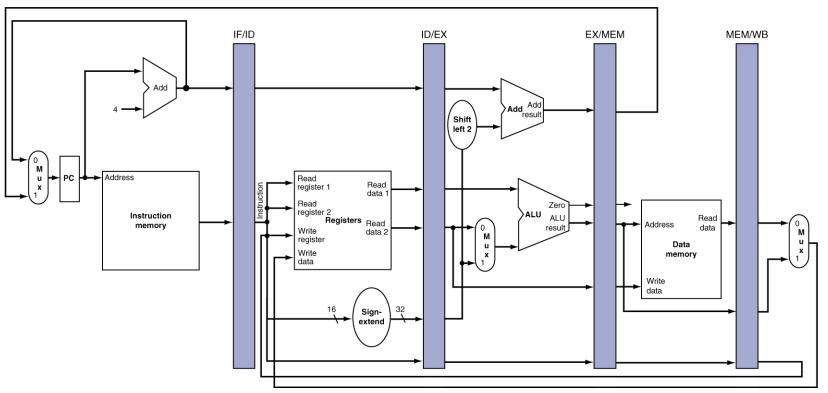




Single-Cycle Pipeline Diagram

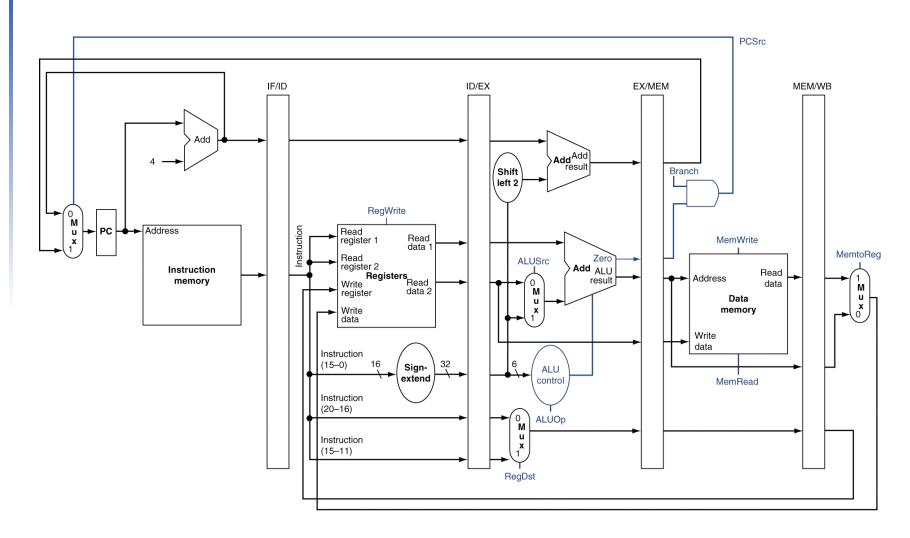
State of pipeline in a given cycle







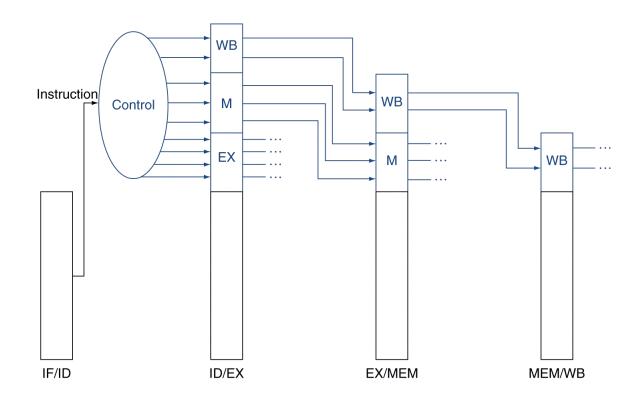
Pipelined Control (Simplified)





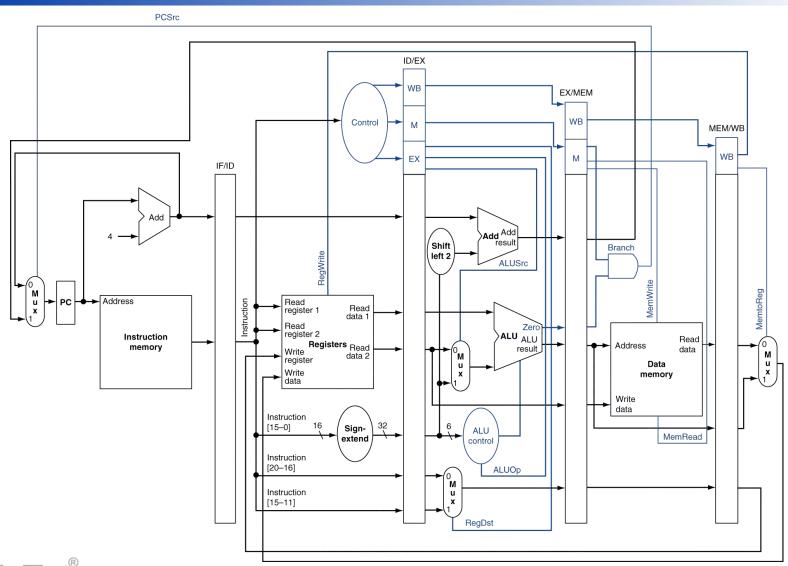
Pipelined Control

- Control signals derived from instruction
 - As in single-cycle implementation





Pipelined Control





Data Hazards in ALU Instructions

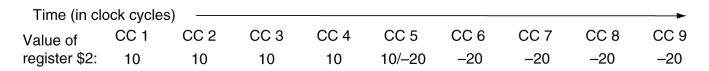
Consider this sequence:

```
sub $2, $1,$3
and $12,$2,$5
or $13,$6,$2
add $14,$2,$2
sw $15,100($2)
```

- We can resolve hazards with forwarding
 - How do we detect when to forward?



Dependencies & Forwarding

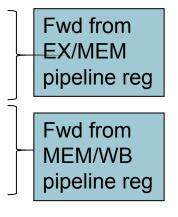


Program execution order (in instructions) sub \$2, \$1, \$3 IM and \$12, \$2, \$5 or \$13, \$6, \$2 add \$14, \$2,\$2 sw \$15, 100(\$2)



Detecting the Need to Forward

- Pass register numbers along pipeline
 - e.g., ID/EX.RegisterRs = register number for Rs sitting in ID/EX pipeline register
- ALU operand register numbers in EX stage are given by
 - ID/EX.RegisterRs, ID/EX.RegisterRt
- Data hazards when
 - 1a. EX/MEM.RegisterRd = ID/EX.RegisterRs
 - 1b. EX/MEM.RegisterRd = ID/EX.RegisterRt
 - 2a. MEM/WB.RegisterRd = ID/EX.RegisterRs
 - 2b. MEM/WB.RegisterRd = ID/EX.RegisterRt



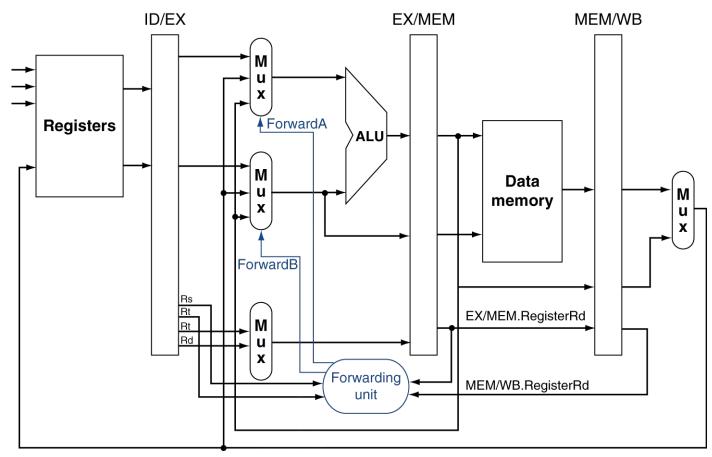


Detecting the Need to Forward

- But only if forwarding instruction will write to a register!
 - EX/MEM.RegWrite, MEM/WB.RegWrite
- And only if Rd for that instruction is not \$zero
 - EX/MEM.RegisterRd ≠ 0, MEM/WB.RegisterRd ≠ 0



Forwarding Paths



b. With forwarding



Forwarding Conditions

EX hazard

if (EX/MEM.RegWrite and (EX/MEM.RegisterRd ≠ 0) and (EX/MEM.RegisterRd = ID/EX.RegisterRs)) ForwardA = 10

if (EX/MEM.RegWrite and (EX/MEM.RegisterRd ≠ 0) and (EX/MEM.RegisterRd = ID/EX.RegisterRt)) ForwardB = 10

MEM hazard

if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0) and (MEM/WB.RegisterRd = ID/EX.RegisterRs)) ForwardA = 01

if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0) and (MEM/WB.RegisterRd = ID/EX.RegisterRt)) ForwardB = 01



Double Data Hazard

Consider the sequence:

```
add $1,$1,$2
add $1,$1,$3
add $1,$1,$4
```

- Both hazards occur
 - Want to use the most recent
- Revise MEM hazard condition
 - Only fwd if EX hazard condition isn't true



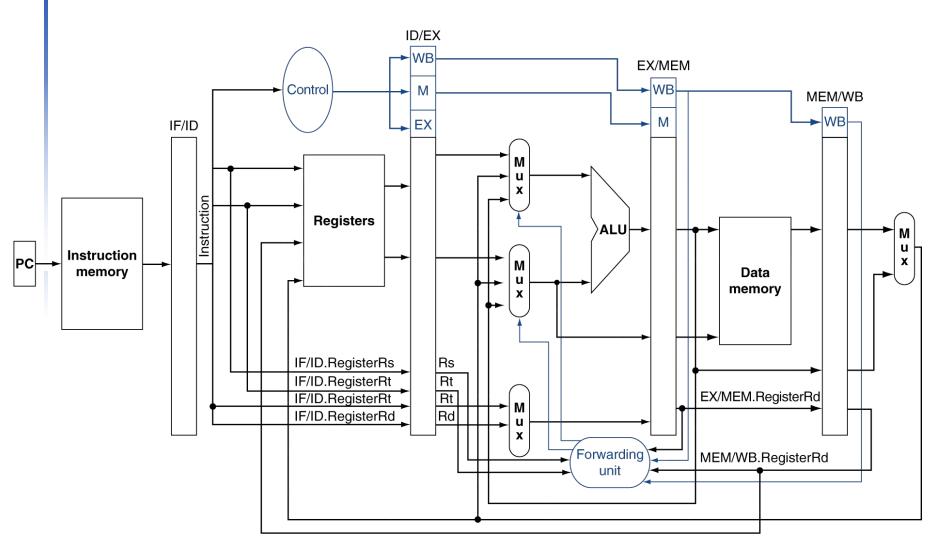
Revised Forwarding Condition

- MEM hazard
 - if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0)

if (MEM/WB.RegWrite and (MEM/WB.RegisterRd ≠ 0)

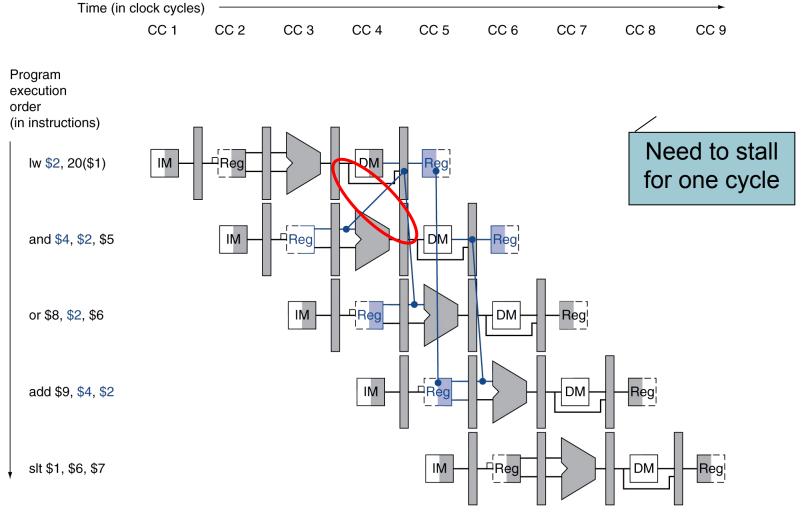


Datapath with Forwarding





Load-Use Data Hazard





Load-Use Hazard Detection

- Check when using instruction is decoded in ID stage
- ALU operand register numbers in ID stage are given by
 - IF/ID.RegisterRs, IF/ID.RegisterRt
- Load-use hazard when
 - ID/EX.MemRead and ((ID/EX.RegisterRt = IF/ID.RegisterRs) or (ID/EX.RegisterRt = IF/ID.RegisterRt))
- If detected, stall and insert bubble

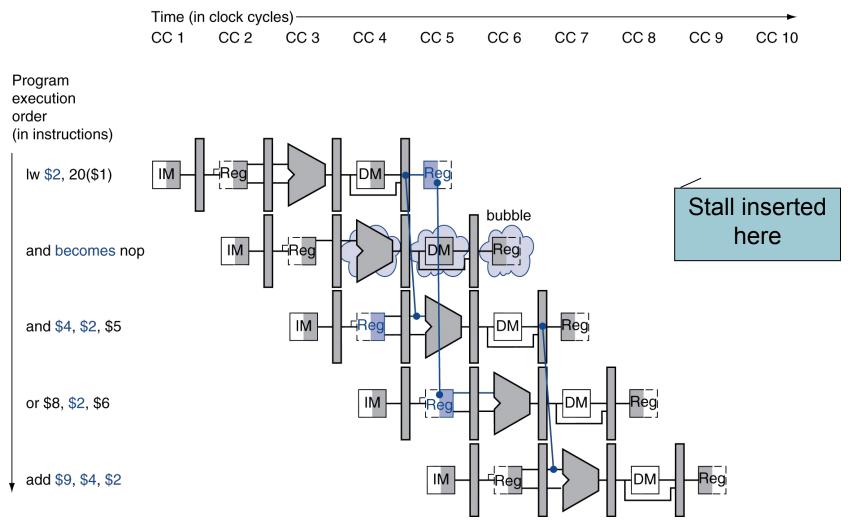


How to Stall the Pipeline

- Force control values in ID/EX register to 0
 - EX, MEM and WB do nop (no-operation)
- Prevent update of PC and IF/ID register
 - Using instruction is decoded again
 - Following instruction is fetched again
 - 1-cycle stall allows MEM to read data for 1w
 - Can subsequently forward to EX stage

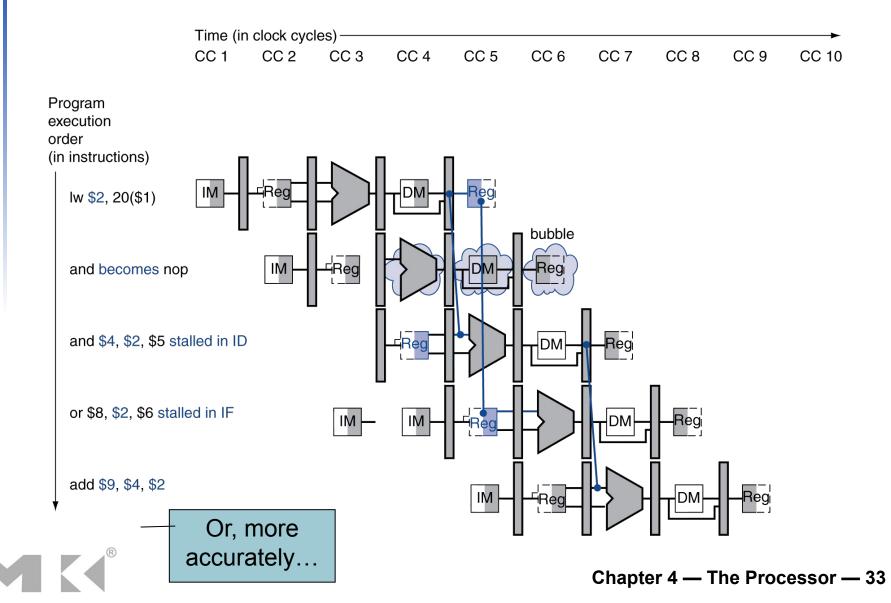


Stall/Bubble in the Pipeline

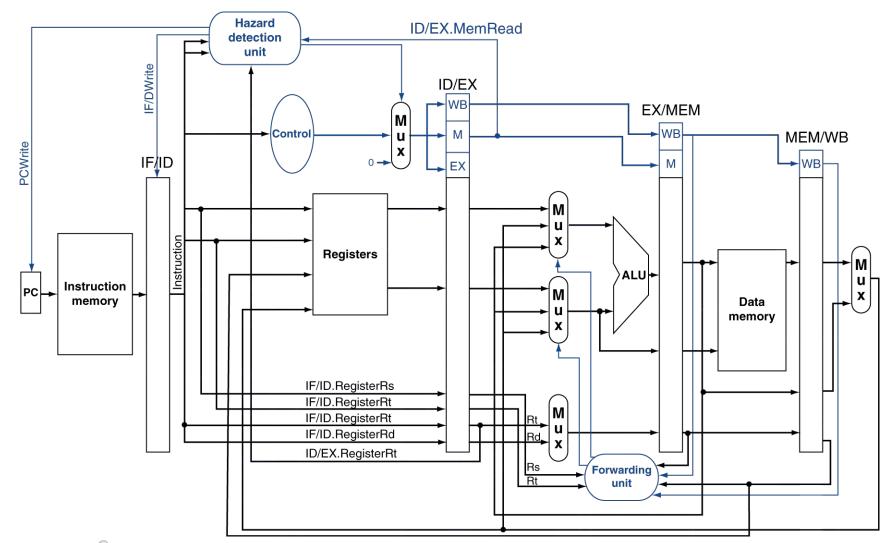




Stall/Bubble in the Pipeline



Datapath with Hazard Detection





Stalls and Performance

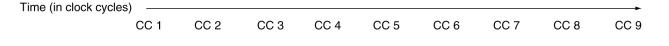
The BIG Picture

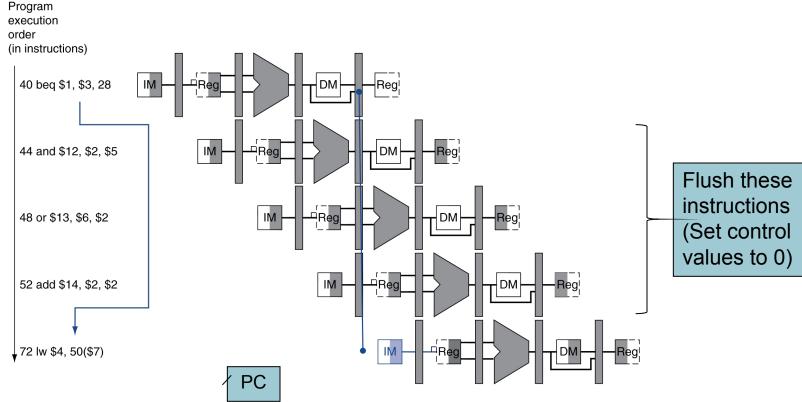
- Stalls reduce performance
 - But are required to get correct results
- Compiler can arrange code to avoid hazards and stalls
 - Requires knowledge of the pipeline structure



Branch Hazards

If branch outcome determined in MEM







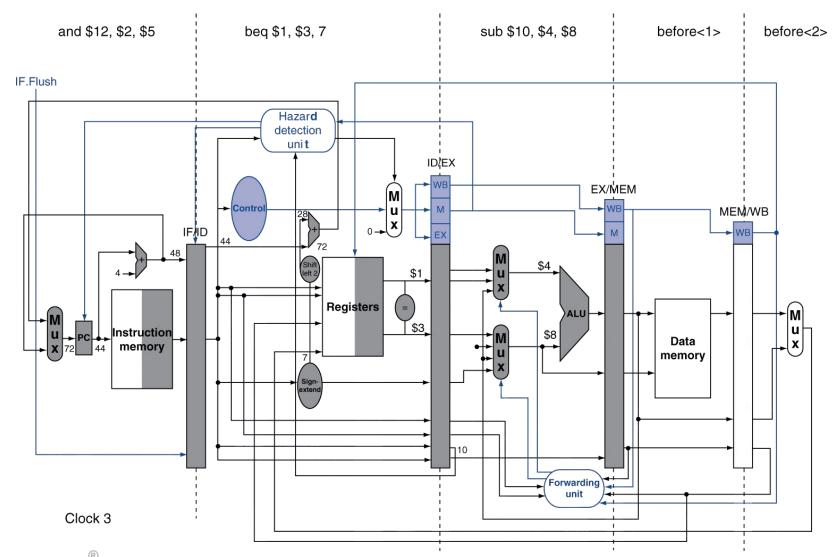
Reducing Branch Delay

- Move hardware to determine outcome to ID stage
 - Target address adder
 - Register comparator
- Example: branch taken

```
36: sub $10, $4, $8
40: beq $1, $3, 7
44: and $12, $2, $5
48: or $13, $2, $6
52: add $14, $4, $2
56: slt $15, $6, $7
...
72: lw $4, 50($7)
```

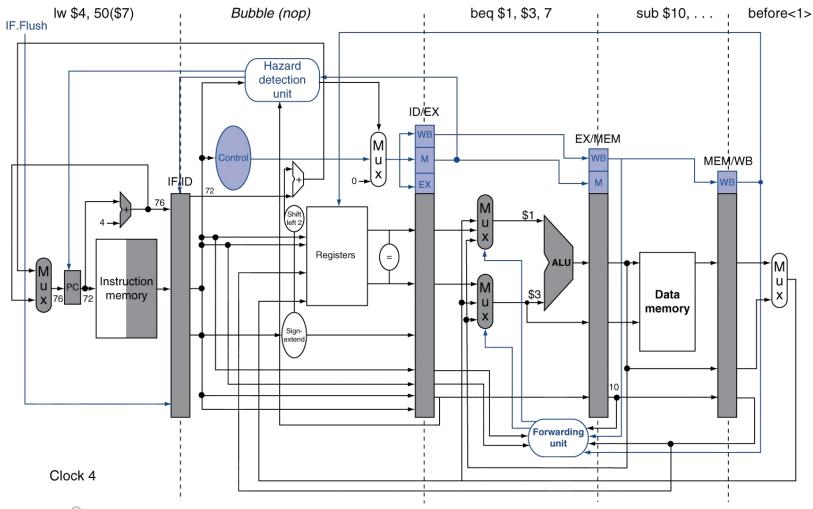


Example: Branch Taken





Example: Branch Taken





Data Hazards for Branches

If a comparison register is a destination of 2nd or 3rd preceding ALU instruction

Can resolve using forwarding



Data Hazards for Branches

- If a comparison register is a destination of preceding ALU instruction or 2nd preceding load instruction
 - Need 1 stall cycle



Data Hazards for Branches

- If a comparison register is a destination of immediately preceding load instruction
 - Need 2 stall cycles



Dynamic Branch Prediction

- In deeper and superscalar pipelines, branch penalty is more significant
- Use dynamic prediction
 - Branch prediction buffer (aka branch history table)
 - Indexed by recent branch instruction addresses
 - Stores outcome (taken/not taken)
 - To execute a branch
 - Check table, expect the same outcome
 - Start fetching from fall-through or target
 - If wrong, flush pipeline and flip prediction



1-Bit Predictor: Shortcoming

Inner loop branches mispredicted twice!

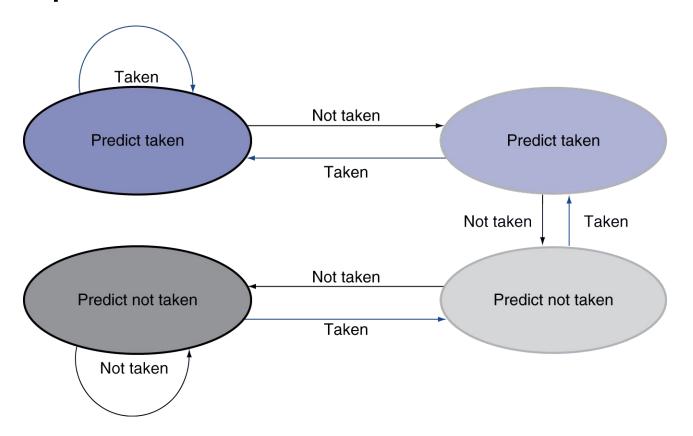
```
outer: ...
inner: ...
beq ..., ..., inner
beq ..., outer
```

- Mispredict as taken on last iteration of inner loop
- Then mispredict as not taken on first iteration of inner loop next time around



2-Bit Predictor

 Only change prediction on two successive mispredictions





Calculating the Branch Target

- Even with predictor, still need to calculate the target address
 - 1-cycle penalty for a taken branch
- Branch target buffer
 - Cache of target addresses
 - Indexed by PC when instruction fetched
 - If hit and instruction is branch predicted taken, can fetch target immediately

