- 1. For the following expressions, determine if they will evaluate as TRUE (logical 1) or FALSE (logical 0) in MATLAB, and explain why. Here  $eps = 2^{-52}$ .
  - (a) (1+2\*eps) 1 == 0

Solution. FALSE. 1+2\*eps evaluates as greater than 1, so (1+2\*eps)-1 is different from 0.  $\square$ 

(b) (1+eps/2) - 1 == 0

Solution. TRUE. 1+eps/2 evaluates as 1, so (1+eps/2)-1 evaluates as 0.

(c) eps/2 == 0

Solution. FALSE. eps is the distance from 1 to the next largest floating point number. eps/2 is  $2^{-52}/2 = 2^{-53}$  which is much larger than realmin. Thus, eps/2 does not evaluate to zero.

2. Assume that  $0 < \varepsilon < 2^{-52}$ . Consider the following system of equations.

$$\varepsilon x_1 + 2x_2 = 4$$
$$x_1 - x_2 = -1$$

(a) Find the exact solution.

Solution. Either by elimination or using the inverse, we get

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \varepsilon & 2 \\ 1 & -1 \end{pmatrix}^{-1} \begin{pmatrix} 4 \\ -1 \end{pmatrix} = \frac{1}{-\varepsilon - 2} \begin{pmatrix} -1 & -2 \\ -1 & \varepsilon \end{pmatrix} \begin{pmatrix} 4 \\ -1 \end{pmatrix} = \frac{1}{2 + \varepsilon} \begin{pmatrix} 2 \\ 4 + \varepsilon \end{pmatrix}$$
$$\boxed{x_1 = \frac{2}{2 + \varepsilon}, \quad x_2 = \frac{4 + \varepsilon}{2 + \varepsilon}}$$

(b) Determine what the solution will be if you solve this system on a machine using double precision arithmetic *without* partial pivoting.

Solution. Subtract  $1/\varepsilon$  times the first equation from the second to get

$$\varepsilon x_1 + 2x_2 = 4$$

$$-\left(1 + \frac{2}{\varepsilon}\right) x_2 = -1 - \frac{4}{\varepsilon}$$
or
$$-\frac{2 + \varepsilon}{\varepsilon} x_2 = -\frac{4 + \varepsilon}{\varepsilon}$$

In the computer the last equation evaluates to

$$-\frac{2}{\varepsilon}x_2 = -\frac{4}{\varepsilon}$$

which has the solution  $x_2 = 2$ . Substitution into the first equation gives us

$$\varepsilon x_1 + 2(2) = 4$$

which has the solution  $x_1 = 0$ . Thus, without partial pivoting we get |(0,2)|.

(c) Determine what the solution will be if you solve the system using double precision arithmetic with partial pivoting.

Solution. With partial pivoting we would put the largest element in the pivot position to get

$$x_1 - x_2 = -1$$

$$\varepsilon x_1 + 2x_2 = 4$$

Now subtract  $\varepsilon$  times equation one from equation two to get

$$x_1 - x_2 = -1$$
$$(2 + \varepsilon)x_2 = 4 + \varepsilon$$

The last equation evaluates to

$$2x_2 = 4$$

which has the solution  $x_2 = 2$ , as before. Substituting into the first equation, we have

$$x_2 - 2 = -1$$

which has the solution  $x_2 = 1$ . Thus, with partial pivoting, we get (1,2).

(d) Which method gave a better result?

Solution. The exact solution is close to (1,2), so partial pivoting gave us a much better approximation.

3. Consider the diagonal matrix

$$A = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix}$$

where the diagonal entries are positive and arranged in decreasing order:  $\sigma_1 \geq \sigma_2 > 0$ . Show that the norm  $||A||_1 = \sigma_1$ , the norm of the inverse is  $||A^{-1}||_1 = \frac{1}{\sigma_2}$ , and hence the condition number is the ratio of the largest to smallest diagonal element:

$$\kappa_1(A) = \frac{\sigma_1}{\sigma_n}$$

Solution. Consider the norm of the vector  $A\mathbf{x}$ :

$$||A\mathbf{x}||_{1} = ||(\sigma_{1}x_{1}, \sigma_{2}x_{2})||_{1} = |\sigma_{1}x_{1}| + |\sigma_{2}x_{2}| = \sigma_{1}|x_{1}| + \sigma_{2}|x_{2}|$$

$$= \sigma_{1}\left(|x_{1}| + \frac{\sigma_{2}}{\sigma_{1}}|x_{2}|\right)$$

$$\leq \sigma_{1}\left(|x_{1}| + |x_{2}|\right) \qquad \left(\text{since } \frac{\sigma_{2}}{\sigma_{1}} \leq 1\right)$$

$$= \sigma_{1}||\mathbf{x}||_{1}$$

Thus

$$\frac{\|A\mathbf{x}\|_1}{\|\mathbf{x}\|_1} \le \sigma_1$$

Moreover, when  $\mathbf{x} = (1,0)$ , we have

$$\frac{\|A\mathbf{x}\|_1}{\|\mathbf{x}\|_1} = \sigma_1$$

Thus, since  $||A\mathbf{x}||/||\mathbf{x}||$  is bounded by  $\sigma_1$ , and this bound is achieved, we have

$$||A||_1 = \max_{\mathbf{x} \neq \mathbf{0}} \frac{||A\mathbf{x}||_1}{||\mathbf{x}||_1} = \sigma_1$$

For  $A^{-1}$ , since A is diagonal,

$$A^{-1} = \begin{pmatrix} 1/\sigma_1 & 0\\ 0 & 1/\sigma_2 \end{pmatrix}$$

This is again a diagonal matrix whose largest diagonal element is  $1/\sigma_2$ . Thus, by the same reasoning as above,

$$||A^{-1}||_1 = \frac{1}{\sigma_2}$$

The condition number is

$$\kappa_1(A) = ||A||_1 ||A^{-1}||_1 = \frac{\sigma_1}{\sigma_2}$$

## 4. Consider the iteration scheme

$$x_{n+1} = x_n - hy_n$$
$$y_{n+1} = y_n + hx_n$$

Find the eigenvalues and explain why  $(x_n, y_n)$  will go to infinity (in norm) as  $n \to \infty$ , starting with any initial condition  $(x_0, y_0)$  as long as one of  $x_0$  or  $y_0$  is nonzero.

Solution. Write this as

$$\mathbf{x}_{n+1} = A\mathbf{x}_n$$

where

$$A = \begin{pmatrix} 1 & -h \\ h & 1 \end{pmatrix}$$

The eigenvalues satisfy

$$0 = \det(A - \lambda I) = \begin{vmatrix} 1 - \lambda & -h \\ h & 1 - \lambda \end{vmatrix} = (1 - \lambda)^2 + h^2$$

Thus the eigenvalues are

$$\lambda_{1,2} = 1 \pm hi$$

These have magnitude

$$|\lambda| = \sqrt{1 + h^2} > 1$$

The solution can be written as

$$\mathbf{x}_n = A^n \mathbf{x}_0$$

Since both eigenvalues satisfy  $|\lambda| > 1$ ,

$$||A^n\mathbf{x}_0|| \to \infty$$

as  $n \to \infty$ , as long as  $\mathbf{x}_0 \neq \mathbf{0}$ .

## 5. Show that the equation

$$e^x + \sin x = 4$$

has a solution in the interval [1,2]. Write out the first two steps of Netwon's method with starting guess  $x_0 = 1$ .

Solution. Write the equation as

$$0 = f(x) = e^x + \sin x - 4$$

Note that

$$f(1) = e + \sin 1 - 4 < 3 + \sin 1 - 4 < 0$$

$$f(2) = e^2 + \sin 2 - 4 > 8 + \sin 2 - 4 > 0$$

Thus f changes sign on [1,2]. Since  $e^x$  and  $\sin x$  are continuous, f is continuous. Thus, by the Intermediate Value Theorem, f must cross 0 somewhere in [1,2].

The Newton iteration is

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

which in this case is

$$x_{n+1} = x_n - \frac{e^{x_n} - \sin x_n - 4}{e^{x_n} - \cos x_n}$$

With  $x_0 = 1$ , we get

$$x_1 = 1 - \frac{e - \sin 1 - 4}{e - \cos 1}$$

$$x_2 = 1 - \frac{e - \sin 1 - 4}{e - \cos 1} - \frac{e^{x_1} - \sin x_1 - 4}{e^{x_1} - \cos x_1}$$