

### CPSC 481 Artificial Intelligence

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### What we will cover this week

- Artificial Neural Network (ANN)
- Convolutional Neural Network (CNN)



#### **BIOLOGICAL NEURAL NETWORK**



### **Brain and Machine**

- Brain
  - Pattern Recognition
  - Association
  - Complexity
  - Noise Tolerance
- Computation
  - Many, Slow,
    Unreliable Processors acting in Parallel



- Machine
  - Calculation
  - Precision
  - Logic
- Von Neumann architecture uses a Single Processing Unit.
  - Tens of Millions of Operations per second
  - Absolute Arithmetic Precision





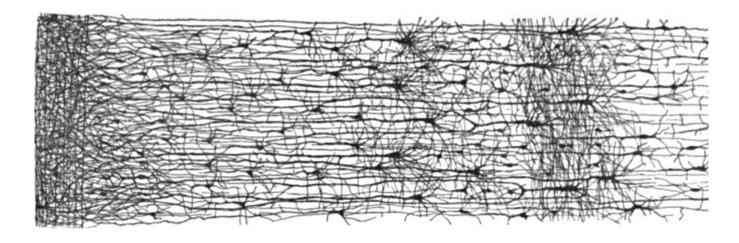
### Features of Brain

- # of Neurons: ~ 10<sup>10</sup> (10 Billion)
- Connections per Neuron: about 7,000
- Neuron Switching Time: ~ 0.001 Second
  - On average, several thousand connections.
- Compensates for Complex Problems Massive Parallelism
- Scene Recognition Time: ~ 0.1 second
- Die Off Frequently, Never Renewed
  - 2 special places in brain can give birth to new neurons.



# Biological Neural Networks (BNN)

- Group of biological neurons interconnected by the ends of the neuron
- Multi Layer of Neural Networks, i.e., Neural Circuit





### **ARTIFICIAL NEURON**



#### Definition

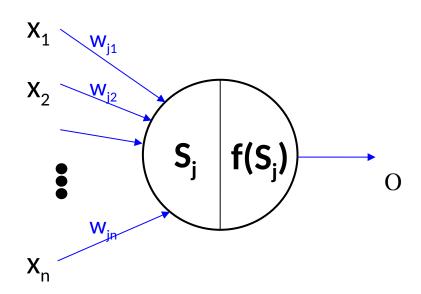
- Mathematical Function based on Concept of Biological Neuron
- Artificial Unit of activating computation with input

#### Characteristics

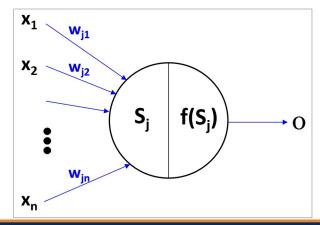
- It uses <u>activation functions</u> to activate neuron.
  - If the result of a function is high enough, the neuron becomes activated.
- The type of output in neuron is numeric.



- Called Perceptron
- Input
  - Composed of artificial inputs
- Output
  - Producing an output

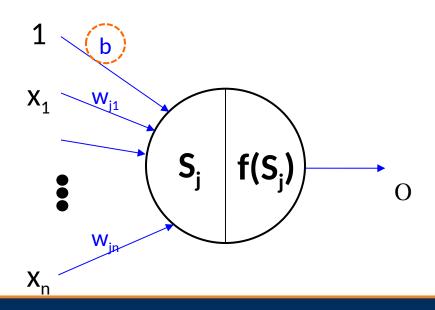


- Each neuron has <u>weighted inputs</u> from other neurons
- Each neuron has a <u>threshold</u> value.
- If the activation level exceeds the threshold, the neuron fires.
  - The unit performs a weighted sum of its inputs, subtracts its threshold value, and gives its activation level.
    - Linear Threshold





- Weight, w<sub>i</sub>
  - Strength of the connection for a neuron
  - Can be updated during training neural network.
  - Backpropagation
    - To update the weight using value of errors (or loss) in each training step.
- Bias, b
  - Weight from Bias Neuron
  - Can be updated by backpropagation.





# Example) Possibility of rain

- Predicting the possibility of rain based on the barometric pressure.
- We have a dataset that includes days with the barometric pressure and whether it rained or not on those days.
- Input Layer Input x: Barometric pressure reading
- Hidden Layer:
  - Weight w: Weight assigned to our input x. It determines how much influence the barometric pressure will have on the prediction.
    - Example: If w=0.8, and our barometric pressure is x=0.5, the product is 0.8\*0.5=0.4.
  - Bias b: An offset or intercept added to the weighted input before it is passed through the activation function.
    - Example: If the bias b=0.2, it is added to the weighted input to give 0.4+0.2=0.6.

#### Output Layer:

• The final activation that decides if it will rain or not, let's say using a sigmoid function to output a probability.



# Example) Possibility of rain

#### Output = $f(w \cdot x + b)$ , where:

- f is the activation function, such as a sigmoid function.
- $w \cdot x$  is the weighted input.
- b is the bias.

#### **Initial Scenario:**

- initially, w=0.5 and b=0
- The input barometric pressure x=0.8. The weighted sum is 0.5\*0.8=0.4
- Since the bias is 0, the total input to the activation function is 0.4
- After passing through an activation function, suppose our output is 0.6, indicating a 60% chance of rain.

#### **Learning Process:**

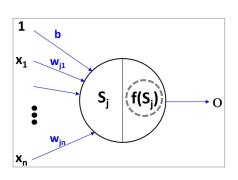
- Through training, we discover that the prediction is not accurate. The network should have predicted a higher chance of rain based on the data.
- Backpropagation will calculate the gradient of the loss (error) and update w and b accordingly.
- Let's say after one round of backpropagation, w is updated to 0.6 and b to 0.1

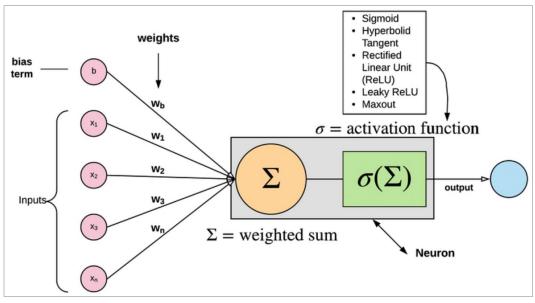
#### **Updated Scenario:**

- Now, the weighted sum is 0.6\*0.8=0.48
- Adding the bias, we get 0.48+0.1=0.58
- The activation function might now output 0.641, indicating a 64.1% chance of rain,



- Activation Function
  - It defines an output of a neuron for the given inputs.
  - The output judges whether activating the neuron or not.
    - Value of 0 does not activate the neuron.

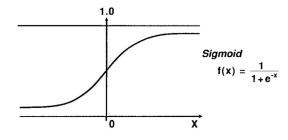


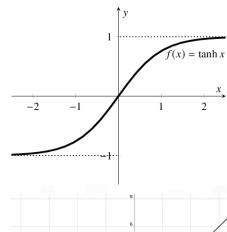


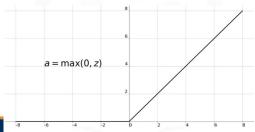
- Representative Activation Functions
  - Sigmoid Function
    - Range of Value: [0, 1]

- Hyperbolic Tangent
  - Range of Value: [-1, 1]

- Relu (Rectified Linear Unit)
  - Range of Value: [0, ∞]



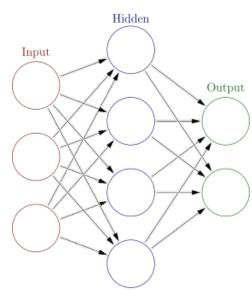






# Artificial Neural Network (ANN)

- ANN, also called Neural Network
  - A supervised learning system computing system consisting of artificial neurons, that simulates the biological neural network.
  - Each neuron makes a simple decision and feeds the decisions to other neurons.
- ANN consists of Layers.
  - Input Layer
    - Accepts the inputs of the model.
  - Hidden Layer
    - The layers between input layer and output layer
  - Output Layer
    - Generates predictions.

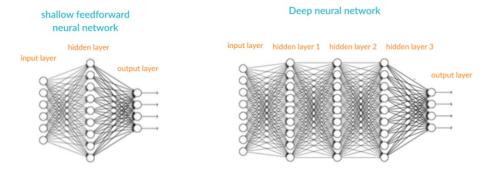




# Deep Neural Network (DNN)

#### DNN

Has 2 or more hidden layers that process inputs.



#### Benefits

- DNN are more accurate than Shallow Neural Networks.
- Can improve the accuracy with more hidden layers.
- Additional layers are useful up to a limit of 9-10.
  - Beyond that, their predictive power starts to decline.



# **Applications of ANN**

Commonly used in supervised learning where the model is trained on a labeled dataset.

- **1. Image and Visual Recognition** Used for facial recognition, image classification, and object detection in images and videos.
- 2. Natural Language Processing (NLP) Used for machine translation, sentiment analysis, text summarization, and chatbots.
- **3. Medical Diagnosis -** Can process medical images for diagnostic purposes, identify patterns in patient data to predict diseases, and assist in personalized medicine.
- **4. Autonomous Vehicles** Can process inputs from various sensors to perceive the environment and make driving decisions in self-driving cars.
- **5. Gaming and Entertainment** Used in the development of AI in games for non-player character (NPC) behavior, and game outcome prediction.
- **6. Weather Forecasting** Analyze datasets to improve the accuracy of weather predictions
- **7. Manufacturing and Production** Used for predictive maintenance, quality control, supply chain optimization, and manufacturing process control.



# CONVOLUTIONAL NEURAL NETWORK (CNN)



### Convolutional Neural Network (CNN)

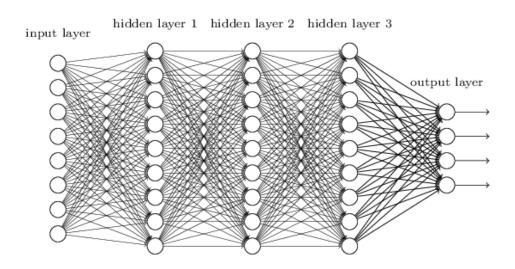
- Convolutional Neural Network (CNN)
  - A type of Neural Network used to make predictions on spatial information of input data.
- Spatial Information
  - Information the Topological, Geometric, or Geographic properties







- Small Neural Network Model is good for;
  - Training Efficiency
  - Prediction Efficiency
- Do we really need all the edges of a Fully Connected NN Model?
  - For some application problems, we may not need to use all the edges.





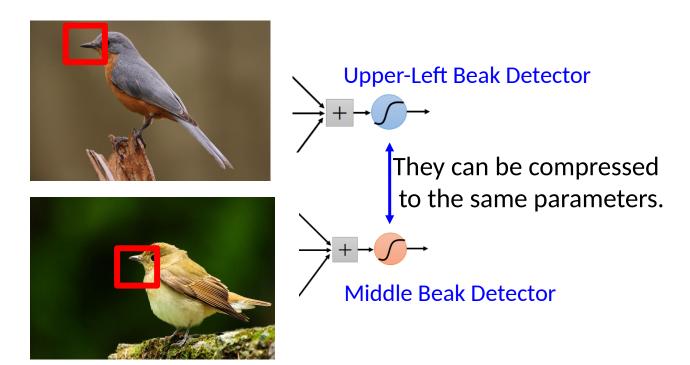
- Consider the problem of 'Learning an Image'
  - Some patterns in an image are much smaller than the whole image.
  - Some patterns are useful and sufficient enough to recognize an image.
    - Beak for Birds



A small region is represented with fewer parameters.



- Observation on Images
  - A same pattern could appear in different places in the image.
  - They can be compressed!





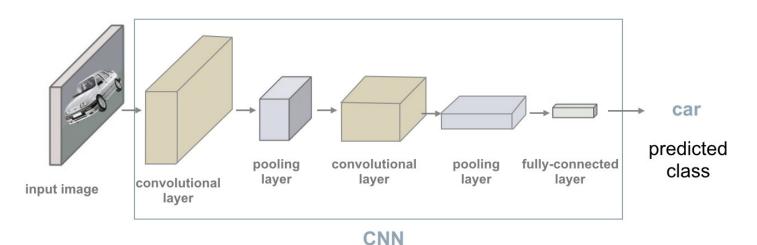
- What about training a lot of such "small" detectors?
- What about letting each detector move around the image?
- Convolutional Neural Network (CNN)
  - To apply the two observations



### Convolutional Neural Network (CNN)

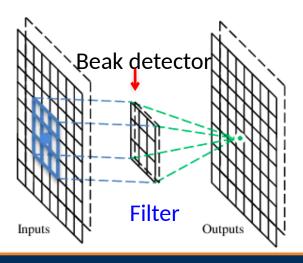
#### Layers in CNN

- Convolutional Layer Applies filters to the input to create feature maps, highlighting important visual features
- Pooling Layer Reduces the spatial dimensions (height and width) of the feature maps
- Flattening Layer Converts the 2D feature maps into a 1D vector
- Fully Connected Layer Receives the flattened vector and perform classification



# Convolutional Layer

- Layer performing Convolutional Operation
- What is Convolution?
  - A convolution is a linear operation that involves the multiplication of a set of weights with the input, much like a traditional neural network
  - A convolutional layer applies a convolution operation to the input and passes the result to the next layer.
  - A convolution is to convert all the pixels in its Receptive Field into a single value.
- Filter (kernel)





# Input Image and Filters

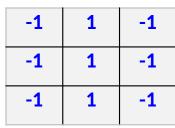
6 x 6 image

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Each filter detects a small pattern (3 x 3).

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



Filter 2



#### Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
$\overline{}$	4			4	
0	1	0	0	1	0

Filter 1

Dat	1	-1	-1
Dot Product	-1	1	-1
	-1	-1	1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 1

Dat	1	-1	-1
Dot Product	-1	1	-1
	-1	-1	1



#### Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 1

Dat	1	-1	-1
Dot Product	-1	1	-1
	-1	-1	1



1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	0	0	0	1	0

Filter 1

Dat	1	-1	-1
Dot Product	-1	1	-1
	-1	-1	1





Dot **Product** 

#### Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 1

Б. /	1	-1	-1
Dot Product	-1	1	-1
	-1	-1	1



1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 1

1	-1	-1
-1	1	-1
-1	-1	1



Dot

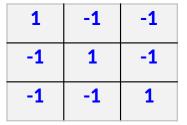
**Product** 

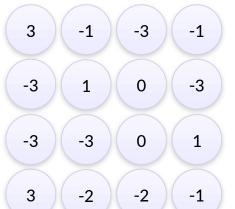
Stride=1

•

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 1





Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Filter 2

-1	1	-1
-1	1	-1
-1	1	-1

-1	-1	-1	-1
-1	-1	-2	1





# Feature Map

#### Stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

#### Filter 1

1	-1	-1
-1	1	-1
-1	-1	1

#### Filter 2

-1	1	-1
-1	1	-1
-1	1	-1

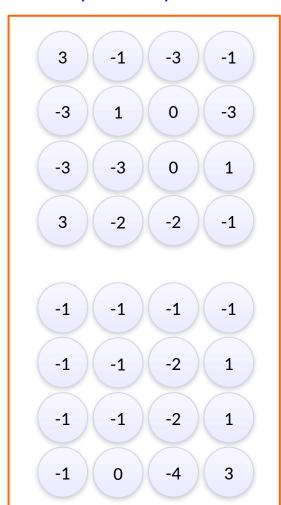
3 -1 -3 -1
-3 1 0 -3
-3 -3 0 1
3 -2 -2 -1
(-1)(-1)(-1)
-1 -1 -2 1
-1 -1 -2 1

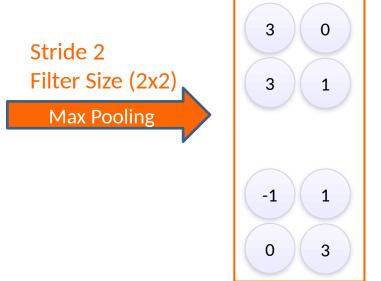
(2 x 4 x 4) Matrix

# **Applying Max Pooling**

Feature Map after Convolution (2 x 4 x 4) Matrix

Feature Map after Max Pooling (2 x 2 x 2) Matrix





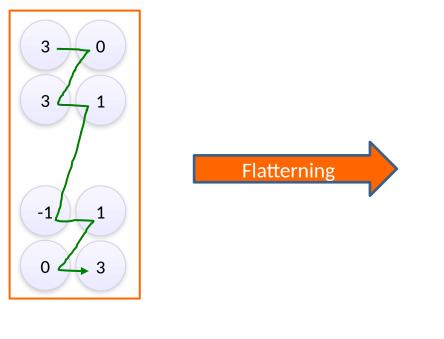
May repeat 'Convolution & Pooling' many several times.



# **Applying Flattening**

Feature Map after Max Pooling (2 x 2 x 2) Matrix

Feature Map after Flattening (1 x 8) Matrix







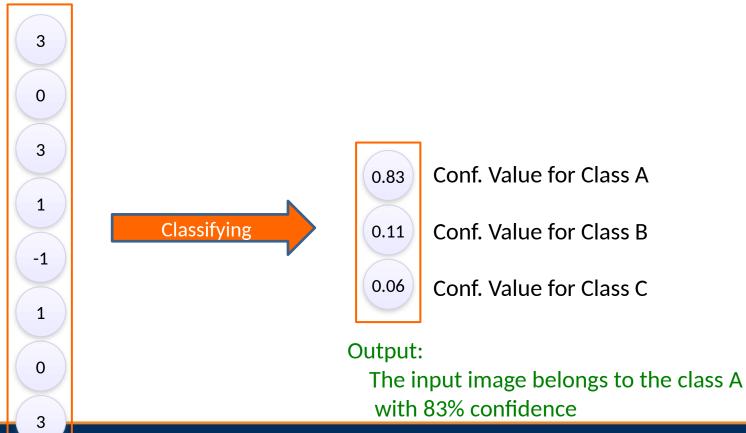
### Feeding into Neural Network

- Feed the Flattening Result
  - Into a Neural Network Model that classifies.
- Example
  - To classify the input image among 3 classes
  - Fully Connected Layer
    - # of Neurons: 3 (Same as the # of Classes)
    - Each neuron returns the probability of each class to classify, i.e., Confidence Value of each class.



# Feeding into Neural Network

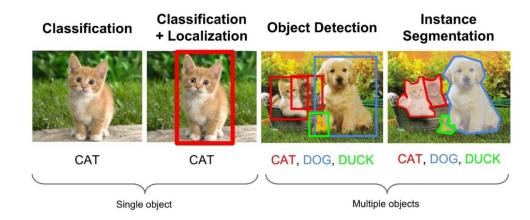
 To return the highest confidence value from the 1<sup>st</sup> neuron Feature Map after Flattening





### **Applications of CNN**

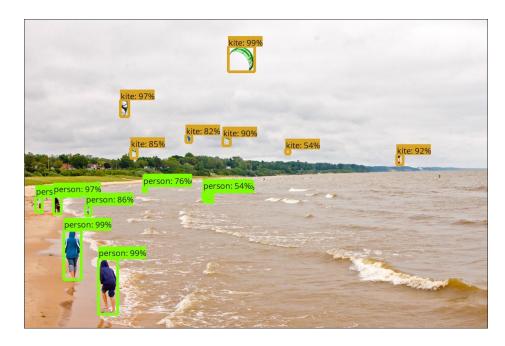
- CNN can be used for
  - Classification
  - Localization
  - Object Detection
  - Instance Segmentation
  - Image Generation
- Types of Data processed
  - Image
  - Video
  - Text





# **Applications of CNN**

- Object Detection
  - To detect object's location in input image
    - To detect people and kits in input image





### References

Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow:
 Concepts, Tools, and Techniques to Build Intelligent Systems 3rd Edition