Section 14.1 Dimensions & Dimensional Compatibility

Remarks

In many physical and engineering applications, most quantities can be expressed in terms of the three fundamental units: mass(M), Length(L) and time(T).

Each quantity should have a unit and an associated dimension. Otherwise, it is called a dimensionless unit.

Notation

Let us denote by [x], the dimension operator of x.

Example:

[distance] =
$$L$$
 [Area] = L^2

[density] =
$$\left[\frac{M}{V}\right] = \frac{M}{L^3}$$
 [speed] = $\frac{L}{T}$

[weight] = [mass × gravity] =
$$\left[M \frac{m}{s^2} \right] = M \frac{L}{T^2}$$

Remarks: Units and dimensions help to:

- (a) keep mathematical equations and models consistent. [LHS]=[RHS]
- (b) pinpoint missing terms or units
- (c) eliminate extra unrelated terms in equation

Remarks

$$[-x] = [x]$$

$$[xy] = [x][y]$$

$$[x/y] = [x]/[y]$$

$$[x^{\alpha}] = [x]^{\alpha}$$

$$[C] = 1, \text{ for any number } C$$

$$[Cx] = [x], \text{ for any number } C$$

$$\text{if } [x] = [y] = D, \text{ then } [x \pm y] = [x] = [y] = D$$

$$[0] = \text{any dimensions}$$

Dimensions of Derivatives

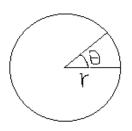
 $\left[\frac{dv}{dt}\right]$ = [change in velocity]/[change time] = [V]/T = [distance/time]/T = L/T/T = L/T²

$$\left[\frac{d^{2}v}{dx^{2}}\right] = \left[\frac{d}{dx}\left(\frac{dv}{dx}\right)\right] = \left[\frac{d\left(\frac{dv}{dx}\right)}{dx}\right] = \frac{\left[d\left(\frac{dv}{dx}\right)\right]}{\left[dx\right]} = \frac{\left[\frac{dv}{dx}\right]}{\left[dx\right]} = \frac{\left[\frac{dv}{dx}\right]}{\left[dx\right]} = \frac{\left[v\right]}{\left[dx\right]^{2}} = \frac{L}{L^{2}} = \frac{1}{LT}$$

In general:
$$\left[\frac{d^n f}{dz^n} \right] = \frac{[f]}{[z]^n}$$

$$\left[\frac{\partial^2 s}{\partial x \partial t}\right] = \left[\frac{\partial}{\partial x} \left(\frac{\partial s}{\partial t}\right)\right] = \frac{\left[\frac{\partial s}{\partial t}\right]}{\left[x\right]} = \frac{\left[s\right]}{\left[x\right]} = \frac{\left[s\right]}{\left[x\right]\left[t\right]} = \frac{\frac{M}{L^3}}{L \cdot T} = \frac{M}{L^4 T}$$

What is the dimension of an angle $[\theta]$?



$$[\theta] = \begin{bmatrix} arclength \\ radius \end{bmatrix} = \frac{[arclength]}{[radius]} = \frac{L}{L} = 1$$

Let P denote pressure and z denote length.

What is the dimension of $\frac{\partial P}{\partial z}$?

$$\left[\frac{\partial P}{\partial z}\right] = \frac{\left[\partial P\right]}{\left[\partial z\right]} = \frac{\left[P\right]}{\left[z\right]} = \frac{\left[Pascal\right]}{L} = \frac{\left[N/m^{2}\right]}{L} = \frac{\left[kg \cdot m/s^{2}m^{2}\right]}{L} = \frac{M}{T^{2}L^{2}}$$

Note: Pressure =
$$\frac{Force}{Area}$$

Example Find the dimension of the viscosity v, where

$$\frac{\partial v}{\partial t} = -v \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

v is velocity, t is time and x, y are spatial variables.

Definition of Model...

 A model (equation) is dimensionally correct, consistent, homogeneous, or compatible if all terms in the equation (model) have the same physical dimension.

Justify whether the model is dimensionally correct.

$$m\frac{dv}{dt}-F=0$$

where m \sim mass, v \sim velocity, t \sim time, F \sim force

Justify whether the model is dimensionally correct.

$$v^2 = \left(\frac{x}{t}\right)^2 + \left(\frac{1}{2}\right)gt^2$$

where $v \sim velocity$, $x \sim distance$, $t \sim time$, $g \sim gravity$

Justify whether the model is dimensionally correct.

$$\frac{de}{dt} = \frac{15}{18} \gamma \frac{Ne}{n} e \sqrt{1 - e^2} \sin^2(i) \sin(2\omega)$$

where e ~ eccentricity of satellite (dimensionless)

 $i \sim$ inclination angle of a satellite

 ω ~ angle of pengee

$$\gamma \sim \text{mass ratio} \quad \frac{M_{earth}}{M_{earth} + M_{moon}}$$

 $G \sim \text{universal gravitational constant } \left(\frac{L^3}{MT^2}\right)$

$$N_e = \sqrt{\frac{G(M_{earth} + M_{moon})}{a_{moon}^3}}$$
 $n = \sqrt{\frac{GM_{moon}}{a_{satellite}^3}}$

Find the dimension of k so that the model is dimensionally correct.

$$m\frac{d^2x}{dt^2} + kx = 0$$

Two types of fluid viscosity

a) Bulk Viscosity:
$$[\mu] = \frac{M}{LT}$$

b) Kinematic Viscosity:
$$[\nu] = \frac{[\mu]}{[\rho]} = \frac{M/LT}{M/L^3} = \frac{L^2}{T}$$

Specific Weights

Weight
$$=\frac{ML}{T^2} = \frac{M}{L^3}$$

Homework –Section 14.1

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