

Task

Create a `moveit_config` folder for one of the following robots if you haven't done that.
https://github.com/ros-industrial/universal_robot

Find which package does this command launch. Modify the package to control your robot.

```
roslaunch moveit_tutorials planning_scene_ros_api_tutorial.launch
```

Check this file :

```
/moveit_tutorials/blob/master/doc/planning_scene_ros_api/src/planning_scene_ros_api_tutorial.cpp
```

See

https://ros-planning.github.io/moveit_tutorials/doc/planning_scene_ros_api/planning_scene_ros_api_tutorial.html