

# Task

| Create a `moveit_config` folder for one of the following robots  
[https://github.com/ros-industrial/universal\\_robot](https://github.com/ros-industrial/universal_robot)

| You have to find the description folder and verify it then use the command

```
roslaunch moveit_setup_assistant setup_assistant.launch
```

See

[http://docs.ros.org/en/melodic/api/moveit\\_tutorials/html/doc/setup\\_assistant/setup\\_assistant\\_tutorial.html](http://docs.ros.org/en/melodic/api/moveit_tutorials/html/doc/setup_assistant/setup_assistant_tutorial.html)

```
roslaunch YOUR-ROBOT-NAME_moveit_config demo.launch
```