Kevin Xiang Li

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SKILLS

Machine Learning: SGLang, vLLM, Unsloth, Nsight, Gymnasium, HuggingFace, PyTorch, Python Mobile Dev: Flutter, SQLite, Rust AR/VR: Unreal, Unity, C# Web: TypeScript, JavaScript, HTML, CSS

EDUCATION

• Stanford University

Stanford, CA, U.S.A

2024. 9 - 2026. 6

M.S. in Computer Science; GPA: 4.0

o Course Highlights: Reinforcement Learning, Deep RL, Spoken Language Processing, Machine Learning with Graphs, Infrastructure at Scale, Computer Networking

• University of Michigan

Ann Arbor, MI, U.S.A

B.S. in Computer Science, Minor in Linguistics; GPA: 3.87, Summa Cum Laude.

2020. 9 - 2024. 5

o Course Highlights: Intro to ML, Intro to NLP, Computer Vision, XR & Society, Programming Languages, Compiler Construction, Intro to Operating Systems, Computer Security

EXPERIENCES

• LLM Inference Workload Performance

Santa Clara, U.S.A.

2025. 6 - 2025. 9

ML Engineer at Nvidia

- Benchmarked VLMs on large GPU clusters: Measured throughput and latency of the Qwen 2.5 VL family (3B-72B) across H200 and B200 clusters.
- Pinpointed and reported inference bottlenecks: Used Nsight, NVTX markers, and PyTorch Profiler to pinpoint kernel-level bottlenecks in SGLang and vLLM; dissected framework performance gaps under varying concurrency and provided detailed reports well received by both SGLang and vLLM multimodal teams.
- Submitted 5 PRs to SGLang that boosted Qwen 2.5 VL throughput by 1.6x end-to-end on MMMU: (1) Doubled Qwen 2.5 VL vision prefill speed via automatic attention backend selection, (2) Accelerated rotary embedding with CUDA rotary kernels, boosting vision prefill throughput by 21%, (3) Identified and removed redundant device-to-host visual feature transfers to enable accelerated GPU hashing, yielding 7.5% end-to-end speedup on MMMU, (4) Fused SwiGLU in ViT to double peak TensorCore utilization, resulting in 4.5% vision prefill throughput gain, (5) Unified VLM benchmarking to support reliable cross-framework comparisons.
- VideoMultiAgents: A Multi-Agent Framework for Video QA

Stanford University, U.S.A.

2024. 10 - 2025. 3

Researcher, in collaboration with Panasonic

- o Designed multi-agent framework with modality-specific agents for video QA: Enhanced video understanding by leveraging strengths of video, text, and graph modalities through multi-agent collaboration.
- o Discovered that modality-specific multi-agent architectures benefit from structure and independence: Showed that our Report architecture performs the best by aggregating opinions from independent modality-specific agents through an organizer agent and weighing strength of evidence from each modality.
- Achieved SOTA accuracy on popular video QA benchmarks: Improved previous SOTA on Intent-QA by +6.2%, EgoSchema subset +3.4%, and NExT-QA by +0.4%.

• Live-It: Image-to-3D Scene Generation

Berkeley, U.S.A.

Team Lead, UC Berkeley AI Hackathon 2025

2025. 6

- Led a team of 3 to win at the world's largest AI Hackathon: Developed Live-it, a project that transforms any image into an explorable 3D world by combining the strengths of video diffusion model with Gaussian Splatting. Won the Nitrode Turbo Mode Award amongst 1,400+ hackers and 350 projects.
- Architected a real-time image-to-3D pipeline integrating multiple models: Orchestrated a workflow using Veo 3 for video generation and 3D Gaussian Splatting for reconstruction. Leveraged Visual Geometry Grounded Transformer (VGGT) for its fast feed-forward inference of camera trajectories and 3D point clouds, enabling an instant 3D scene preview which was then continuously refined in real-time.
- Featured by Google DeepMind staff on LinkedIn: Project featured by Google's hackathon judge on LinkedIn, received 171 upvotes.